Adapting Neuron Count During Training A Bayesian Nonparametric View

Mark van der Wilk Invited Talk 14th International Conference on Bayesian Nonparametrics





Coauthors

From Imperial College London







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Based on a True Story

Adjusting Model Size in Continual Gaussian Processes: How Big is Big Enough?

Guiomar Pescador-Barrios¹ **Sarah Filippi**¹ **Mark van der Wilk**²

Spotlight at ICML 2025.

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Adjusting Model Size in Continual Gaussian Processes: How Big is Big Enough?

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A Bayesian Nonparametric View on Adapting Neuron Count During Training

In submission, soon to be on arxiv.

Thesis of the Talk

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Ideas from Bayesian Nonparametrics may help with new capabilities in deep learning

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Reason 2:

- Data can arrive in a streaming fashion.
- We don't know a priori how large a dataset we have.

? Can we grow a NN's size as we see more data?

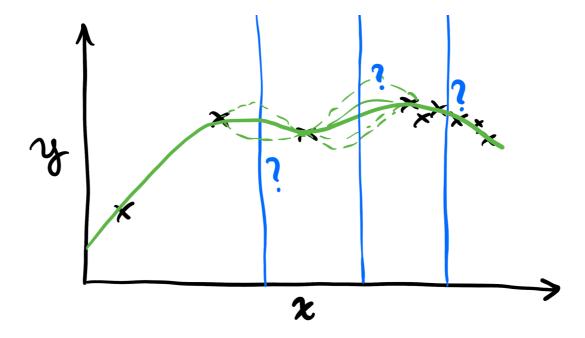
To avoid poor performance, from constant/restricted model size.

© Minimise model size, while maintaining near-optimal predictions.

Most of Machine Learning is just Curve Fitting Dataset: $(x_n, y_n)_{n=1}^N$.

Inputs $x_n \in \mathcal{X}$, outputs $y_n \in \mathcal{Y}$.

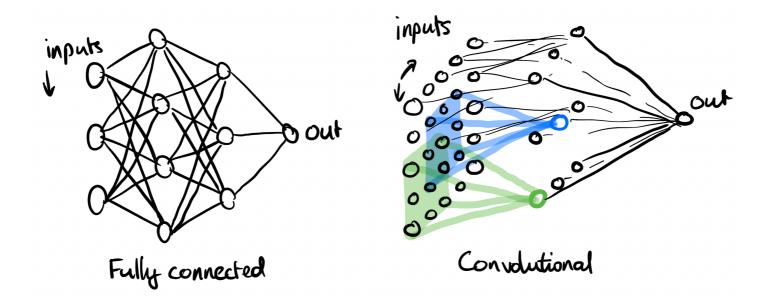
Goal: Find $f : \mathcal{X} \to \mathcal{Y}$, that predicts well for new x.



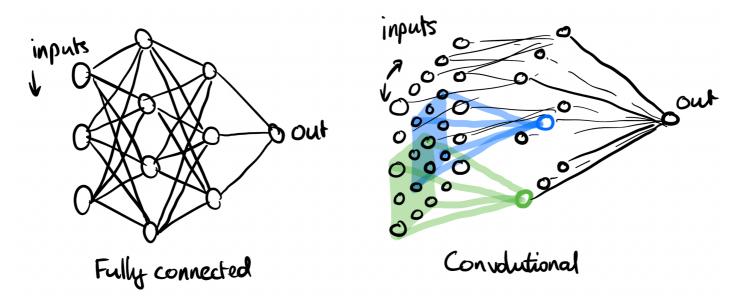
Neural networks just parameterise functions $f_w(x)$.

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• Inductive bias: **connectivity structure** (architecture)

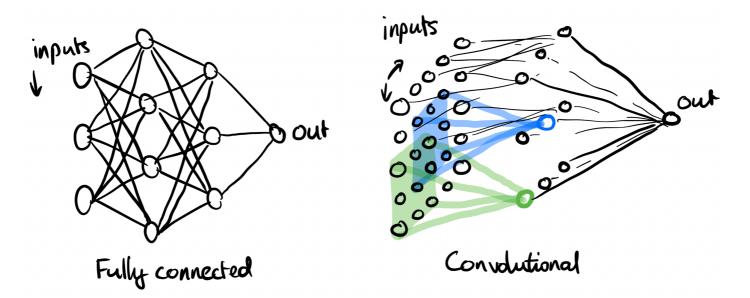


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- Choose network **size** (how *many* neurons)
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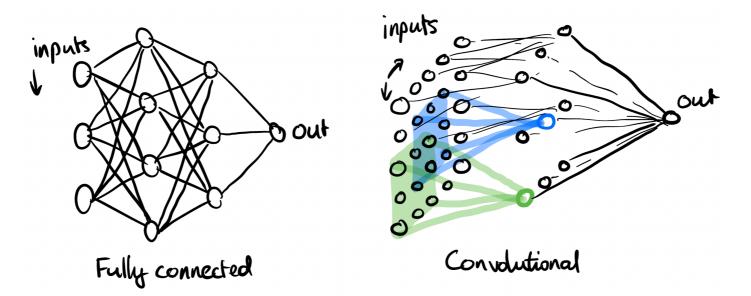
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These problems should be tackled *together*.

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• Hyperparameters Inductive bias.

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Start by finding *clear* answers for single-layer NNs.

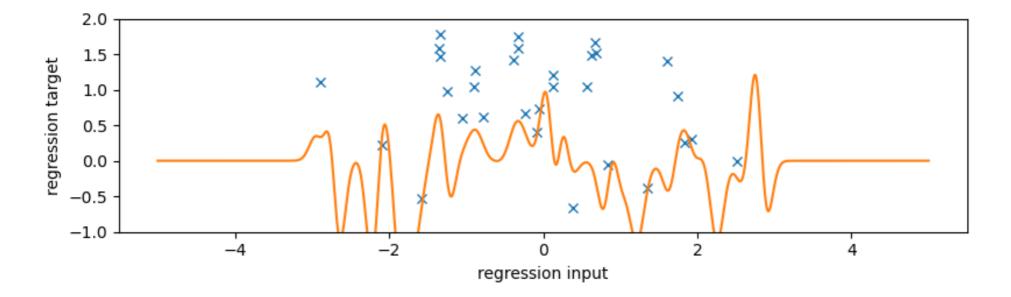
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1. What is wrong with minimising losses?

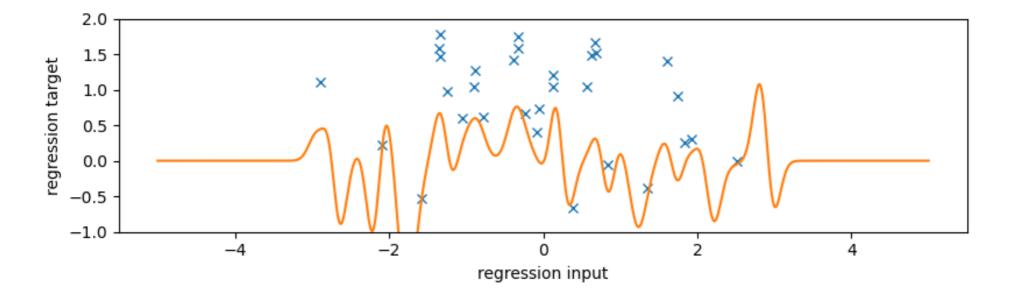
- 2. Bayesian Model Selection
- 2. Model Selection over Model Size? Or Nonparametrics?
- **3.** A principle for selecting size

$$f^* = \mathop{\rm argmin}_W \ {\rm const} + \sum_n (f(x_n) - y_n))^2$$

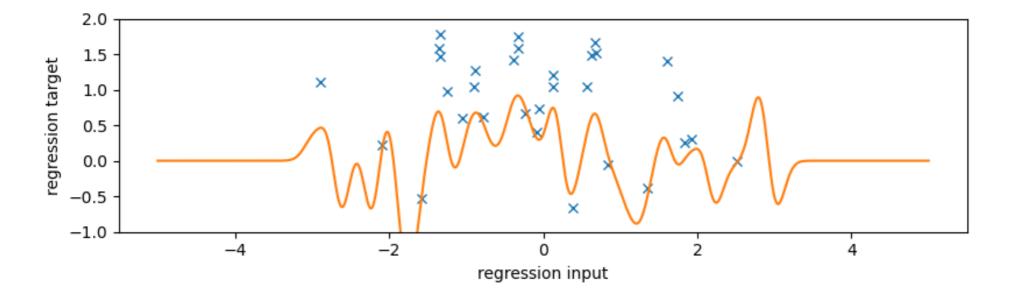


If we train weights W only, given (θ,M) by

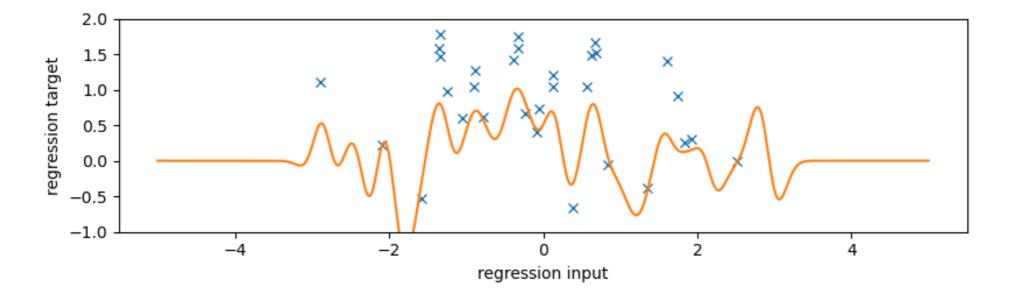
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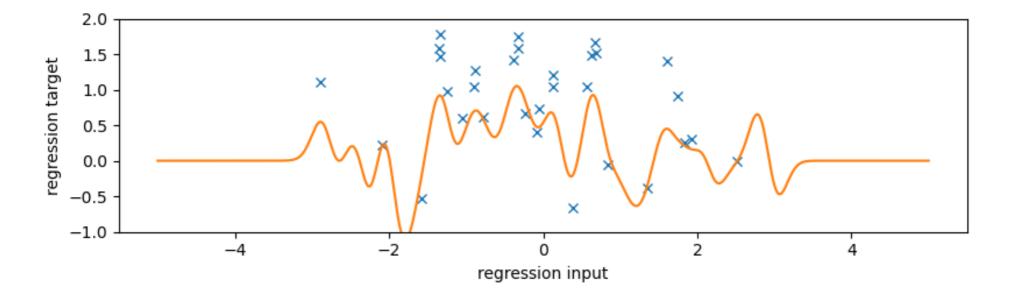
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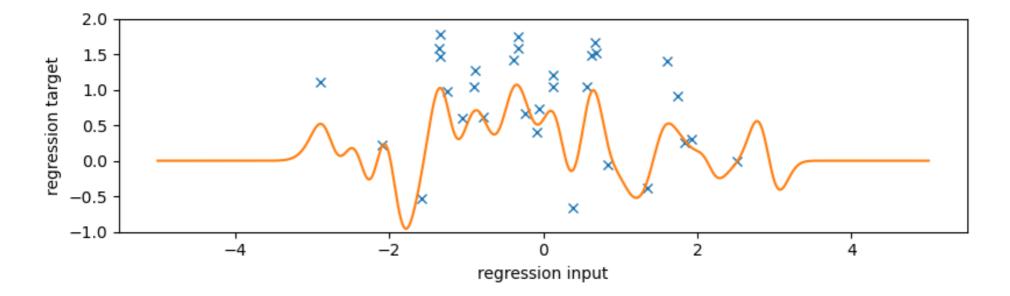
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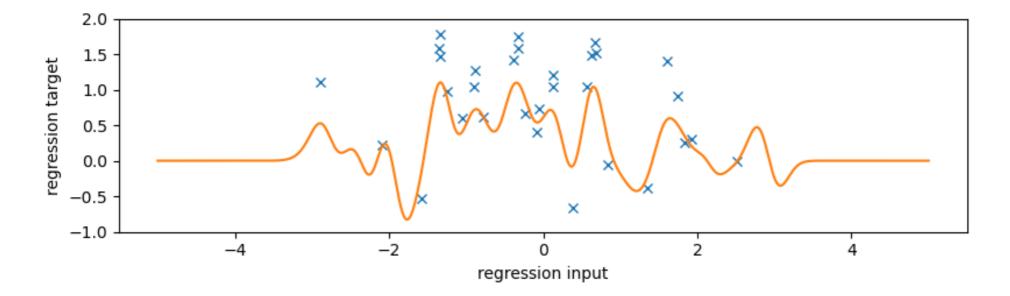
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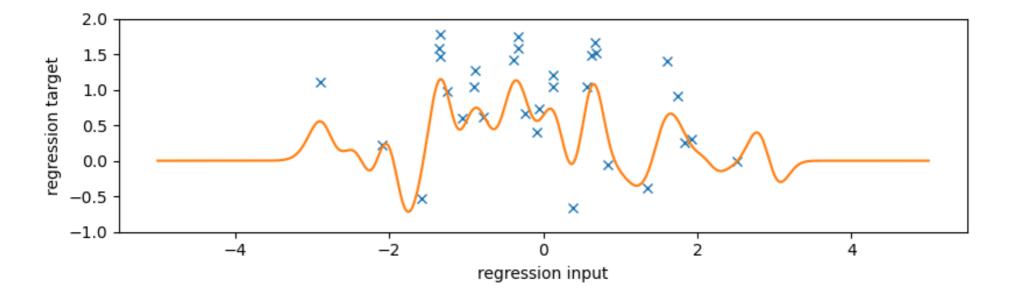
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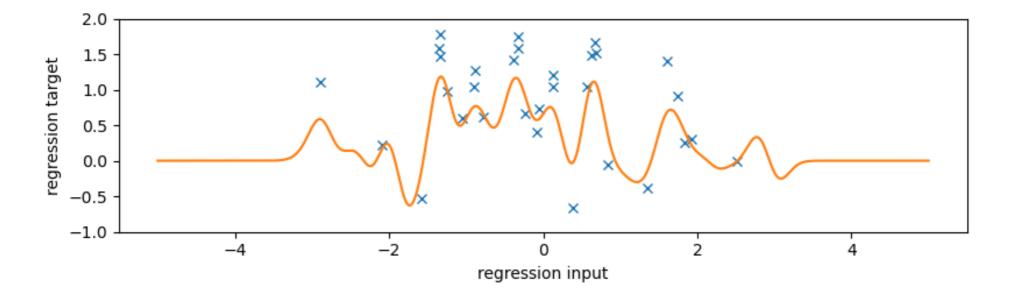
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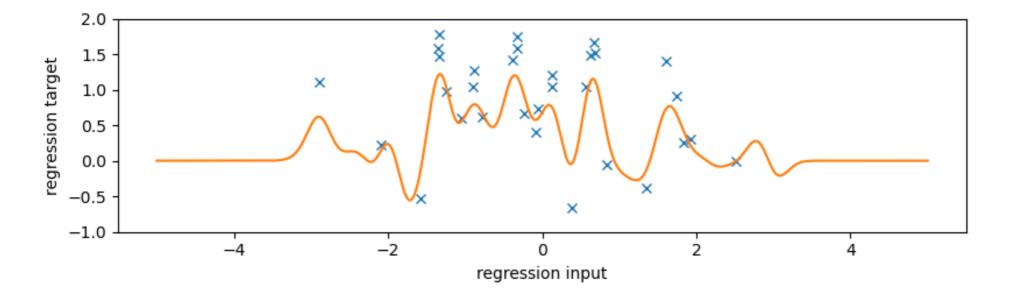
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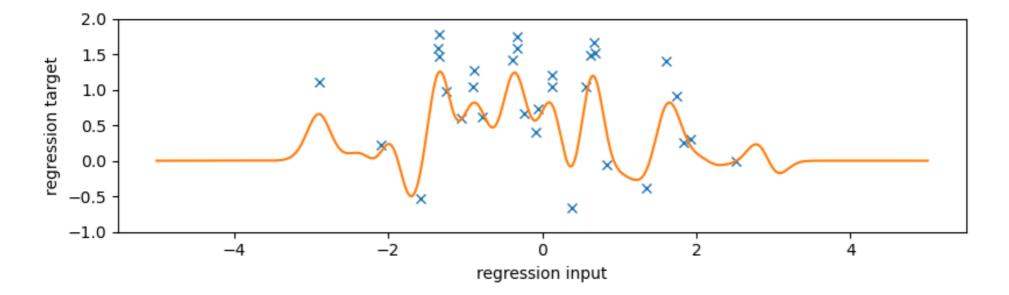
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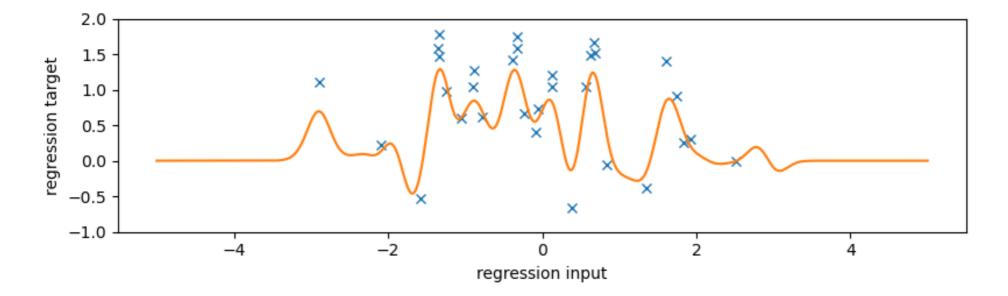
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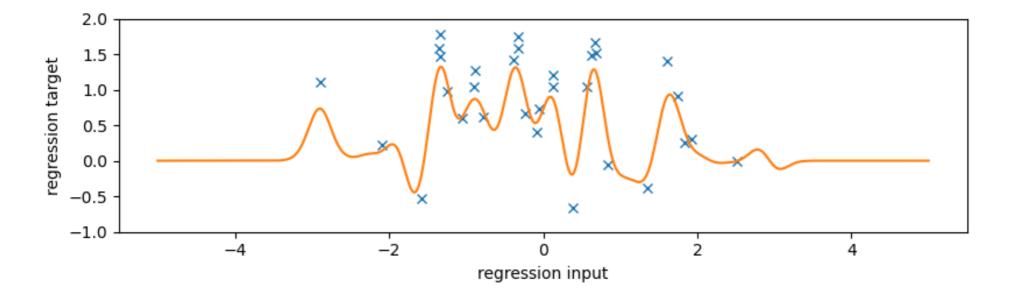
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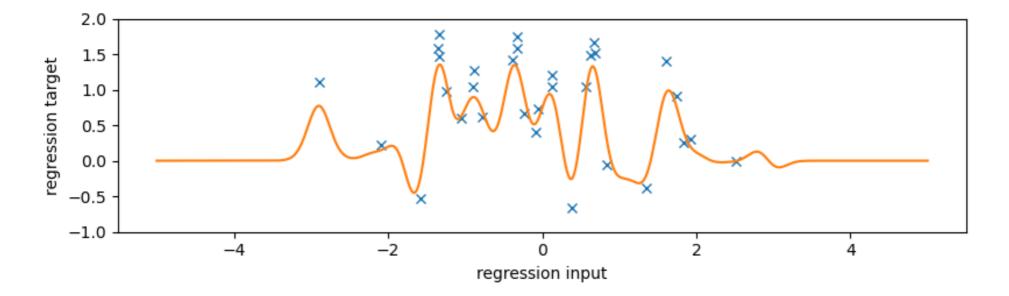
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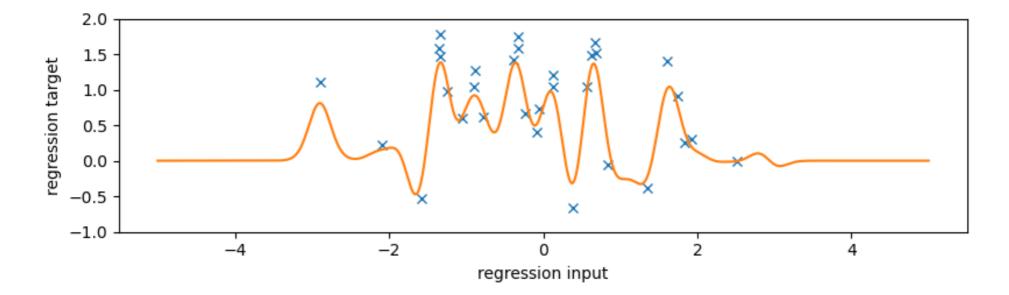
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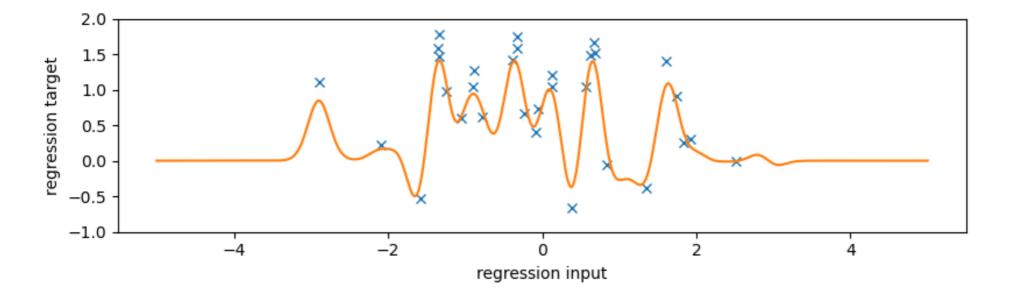
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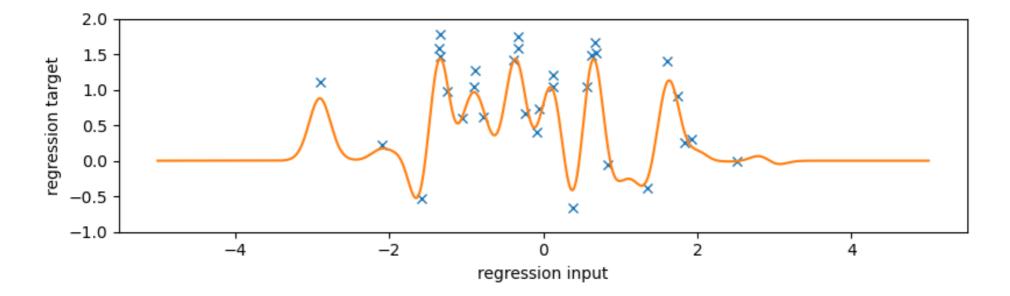
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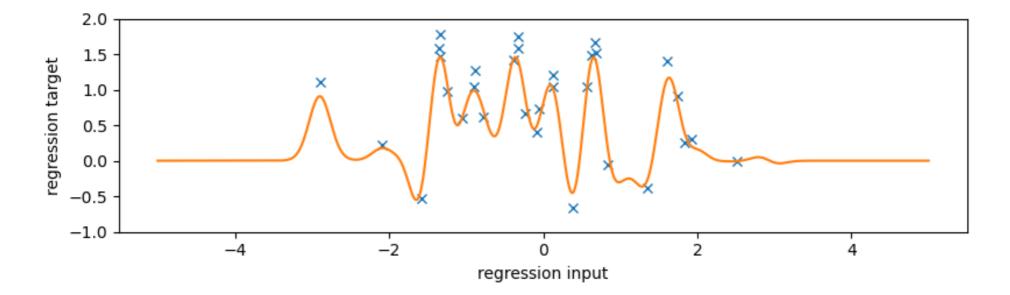
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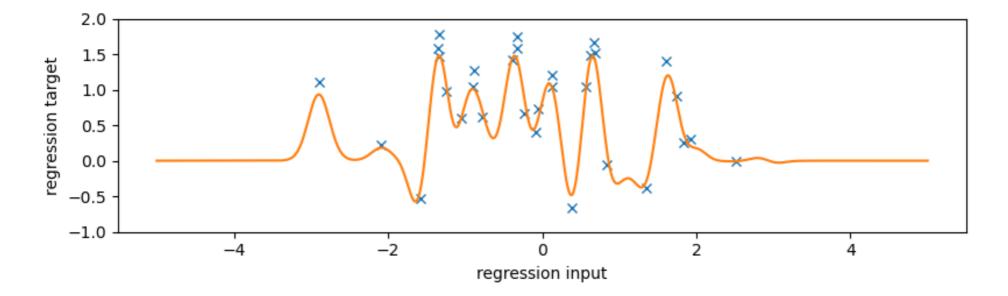
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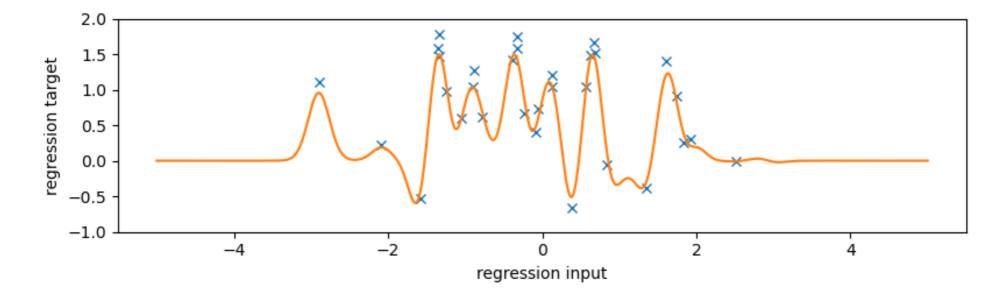
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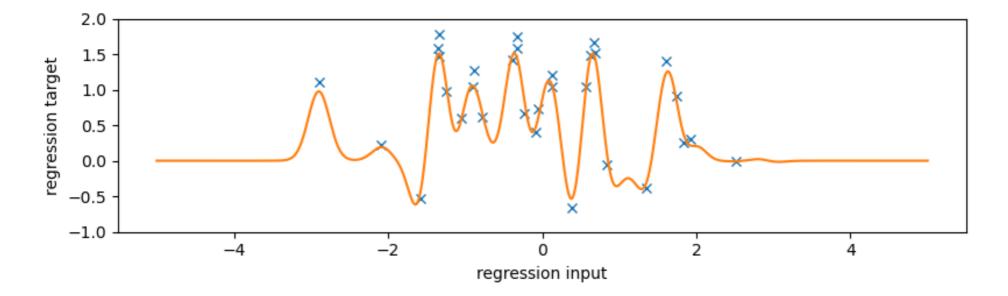
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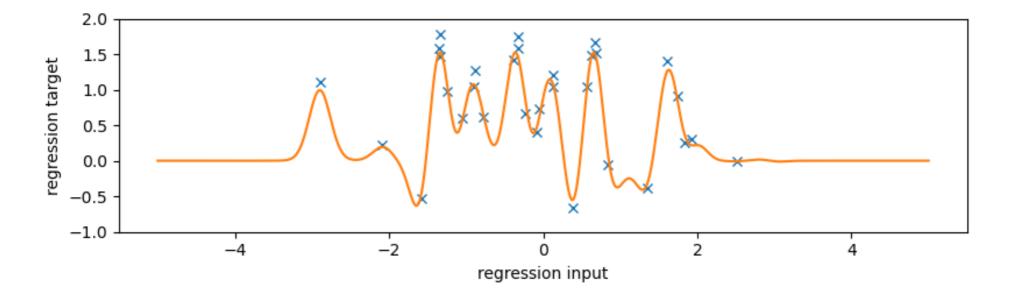
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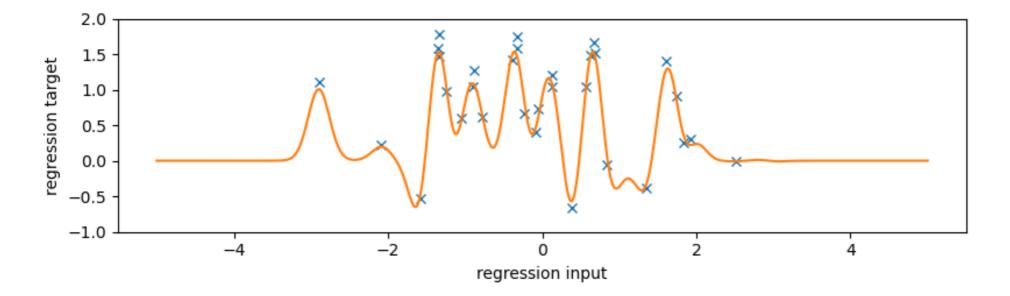
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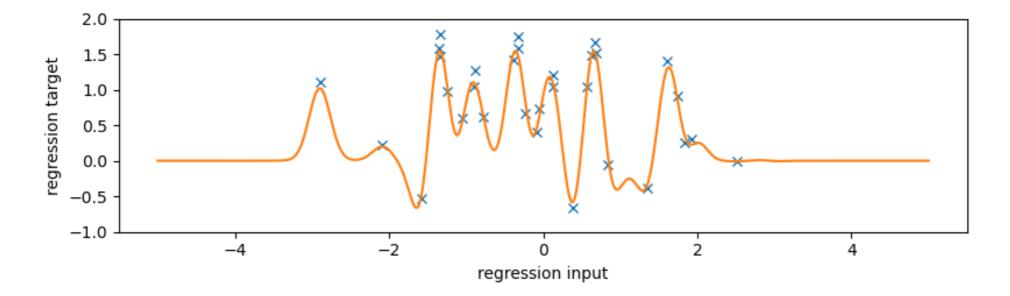
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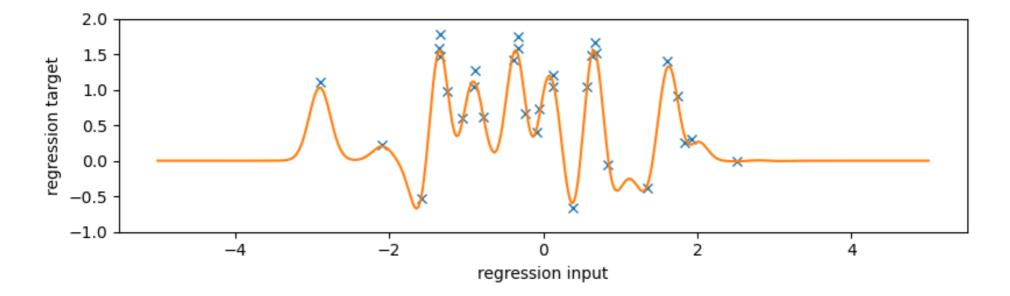
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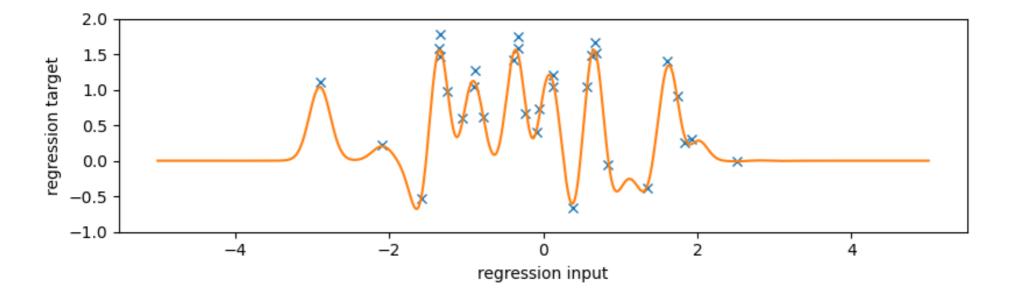
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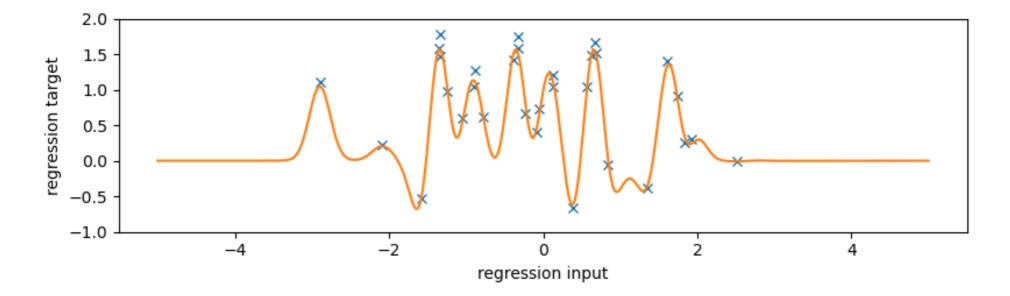
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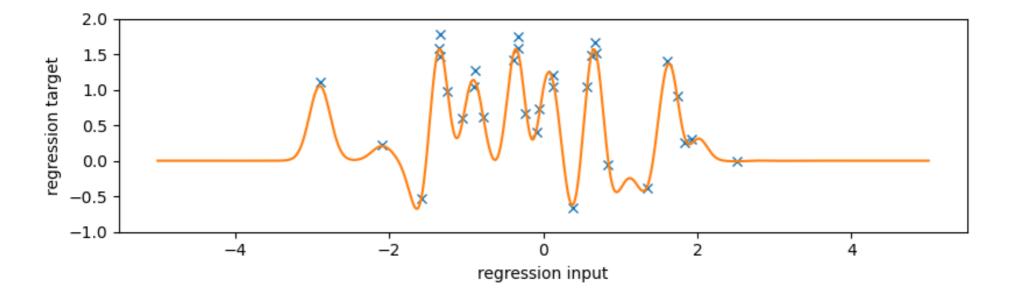
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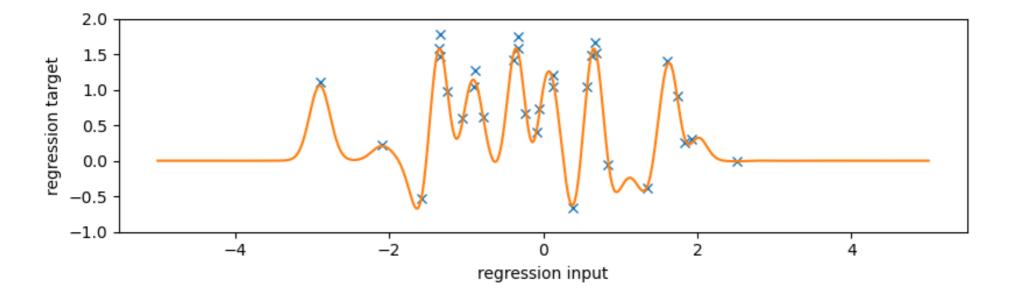
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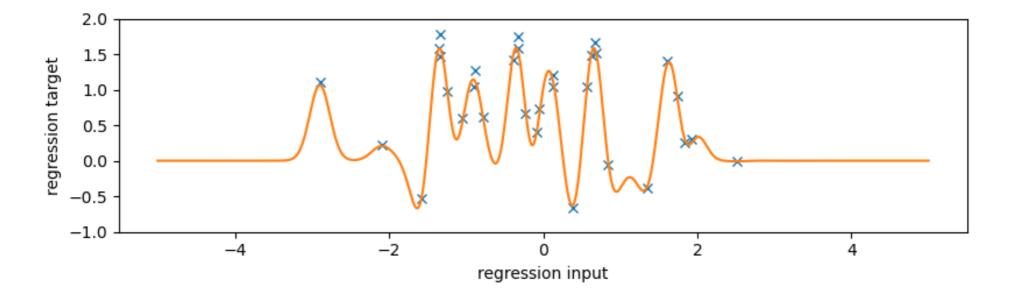
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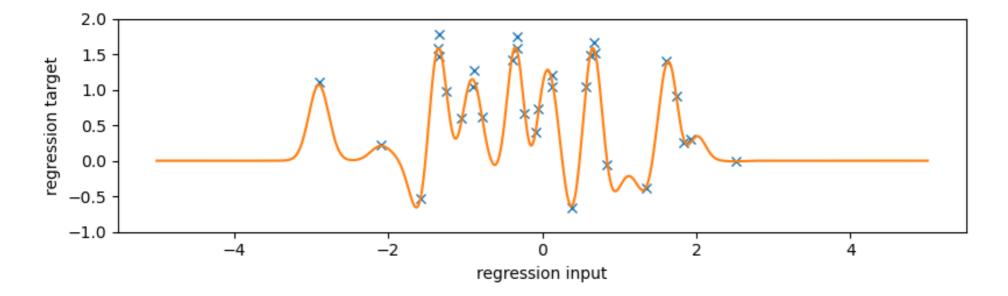
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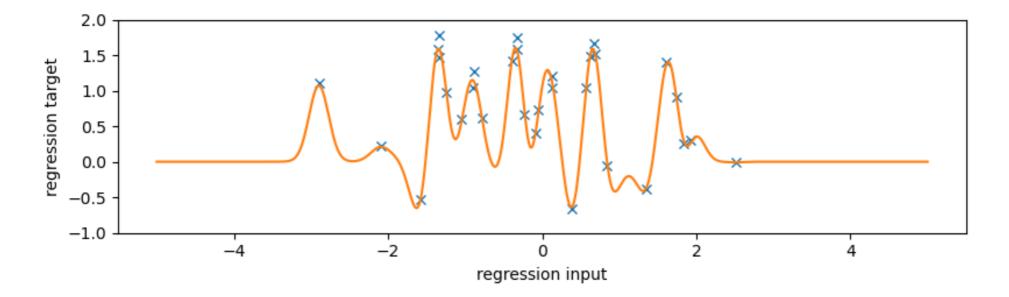
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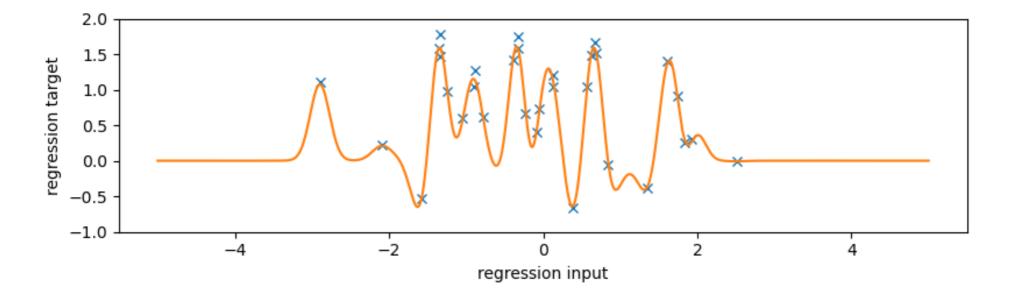
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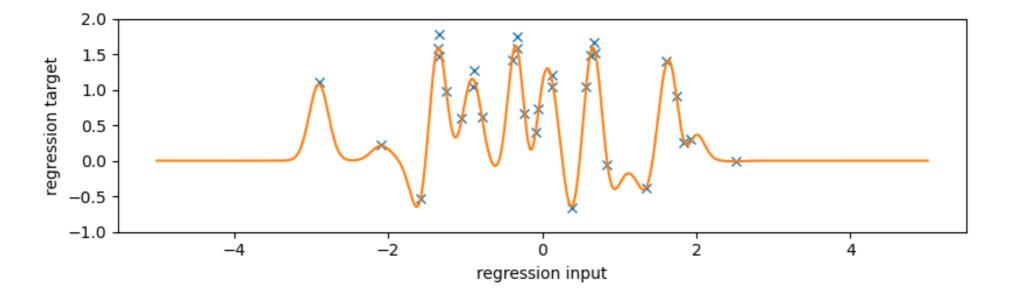
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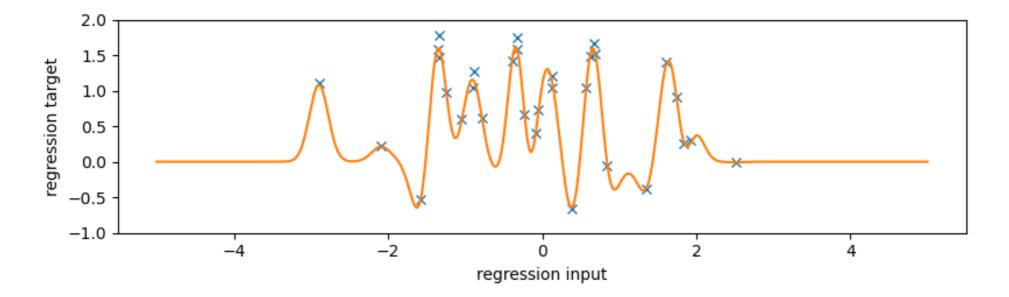
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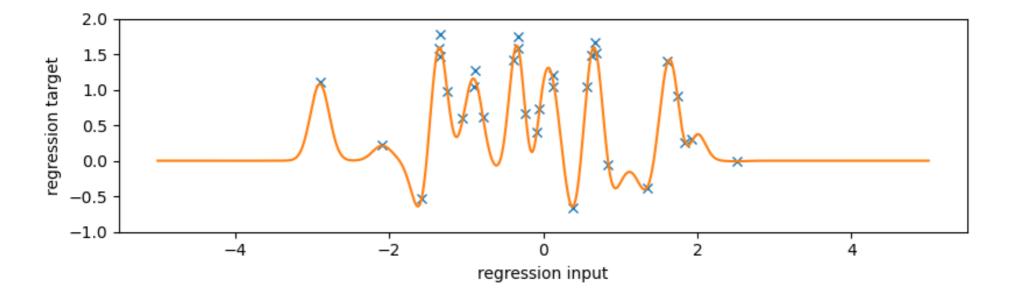
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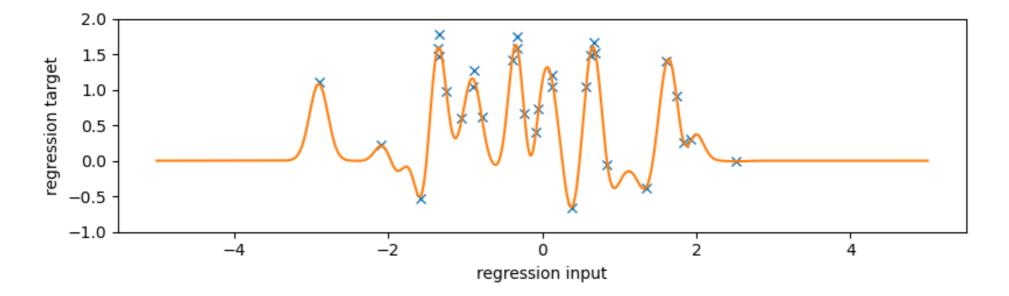
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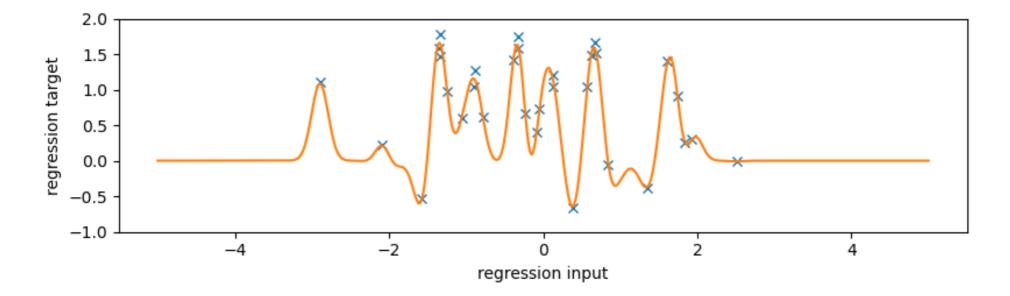
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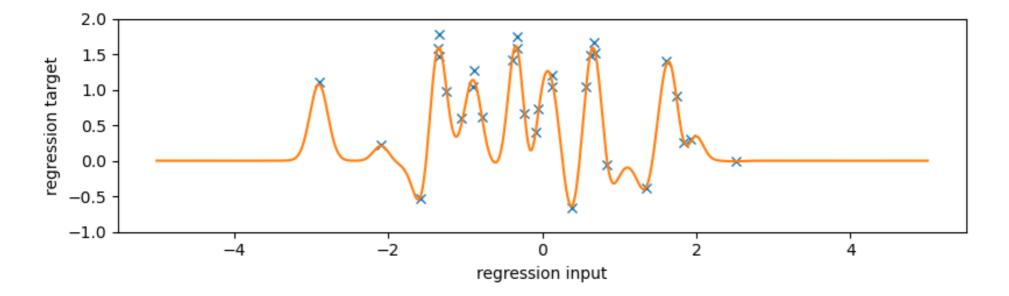
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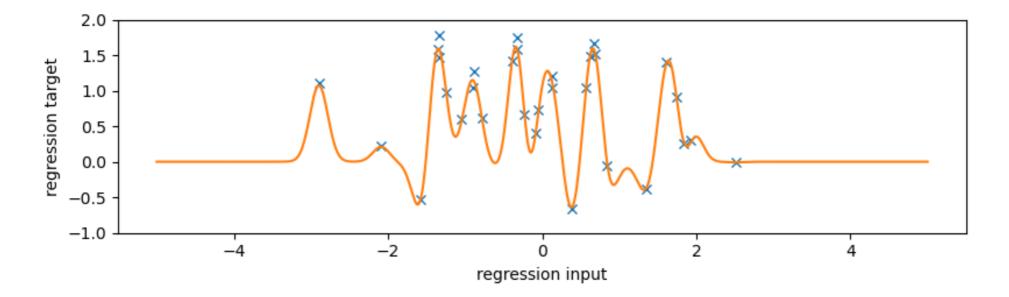
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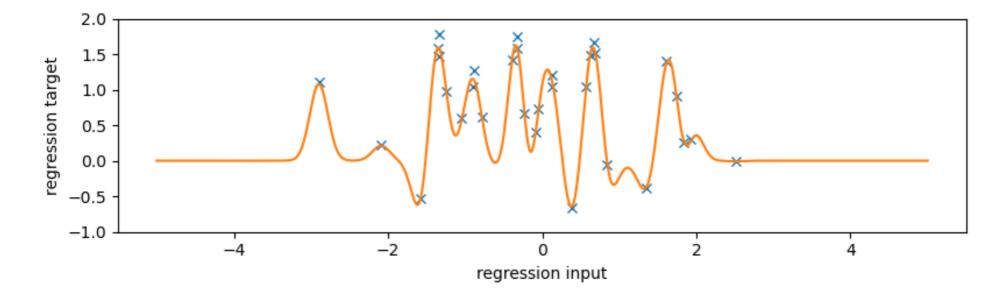
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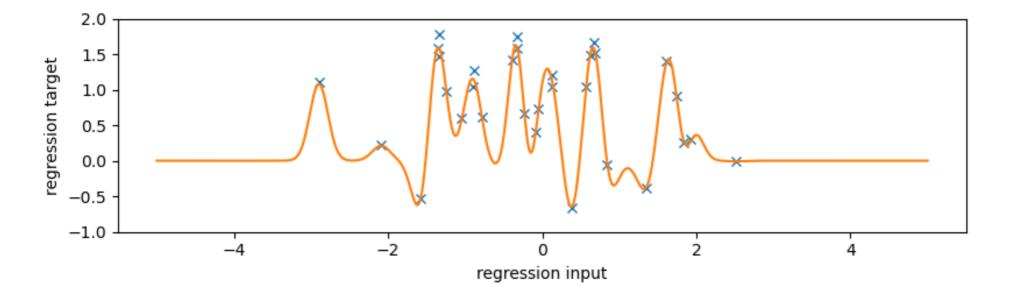
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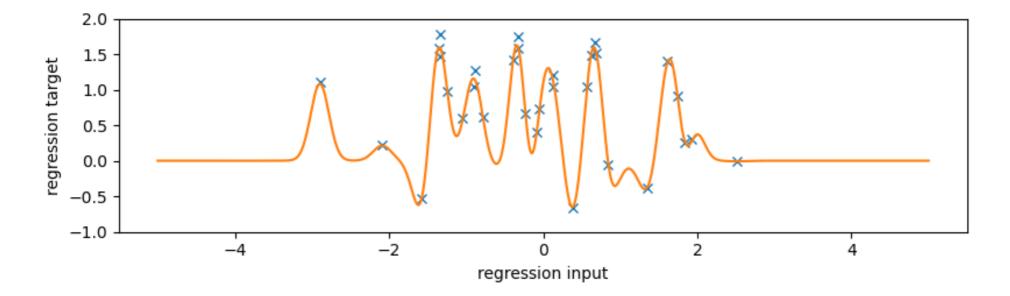
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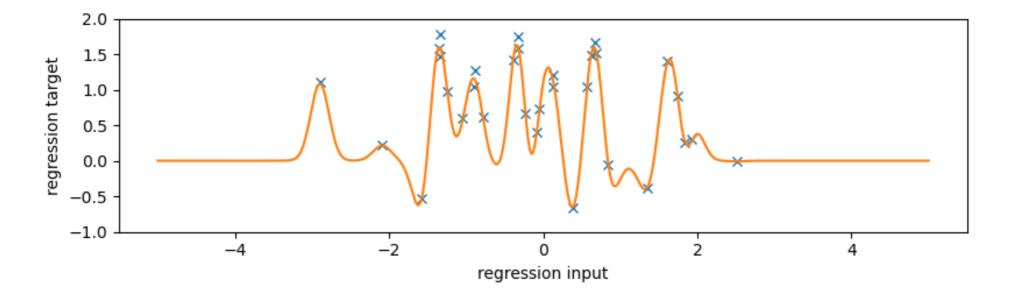
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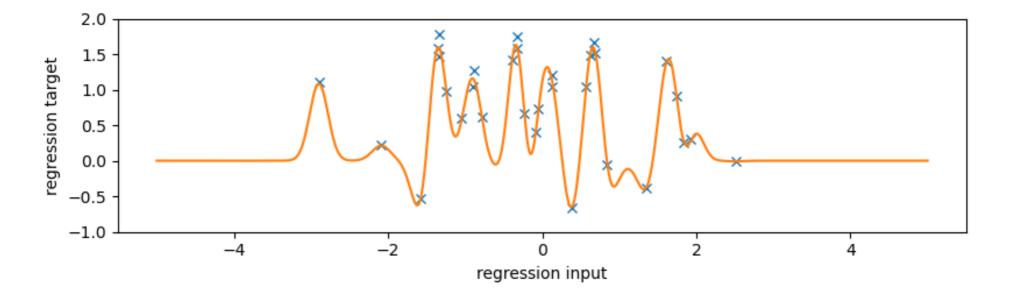
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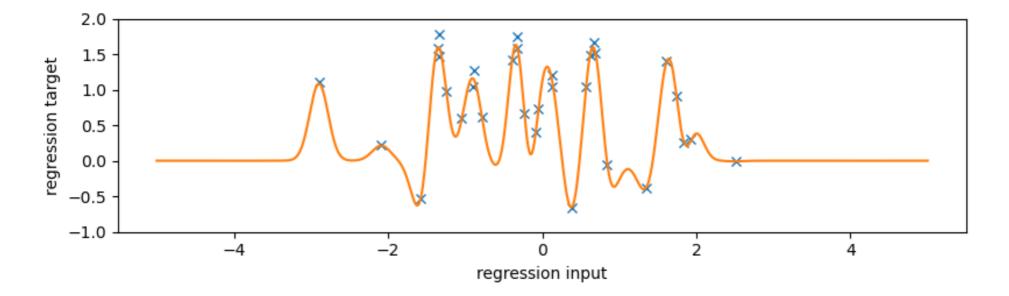
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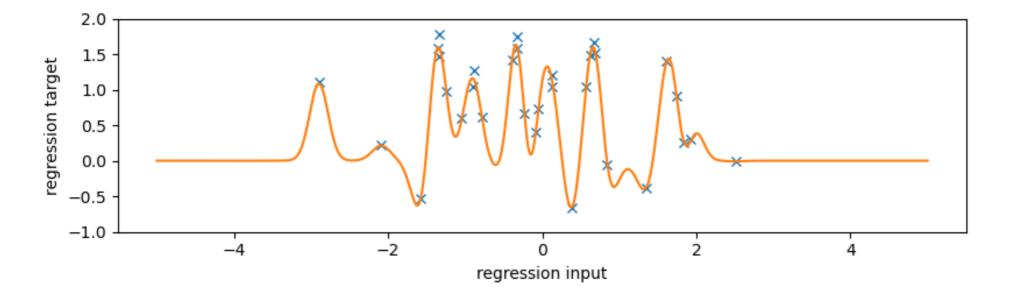
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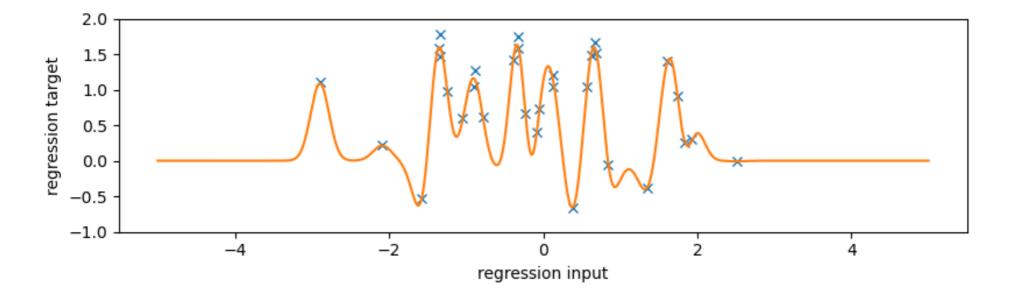
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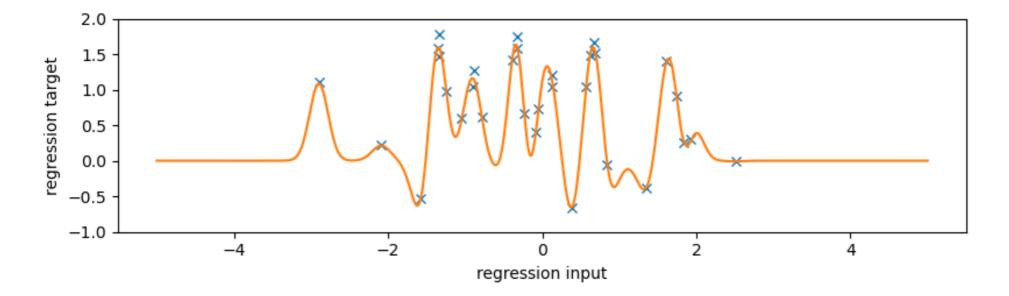
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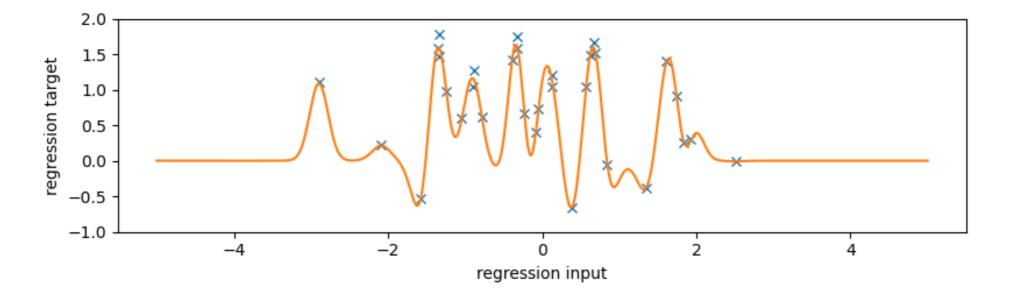
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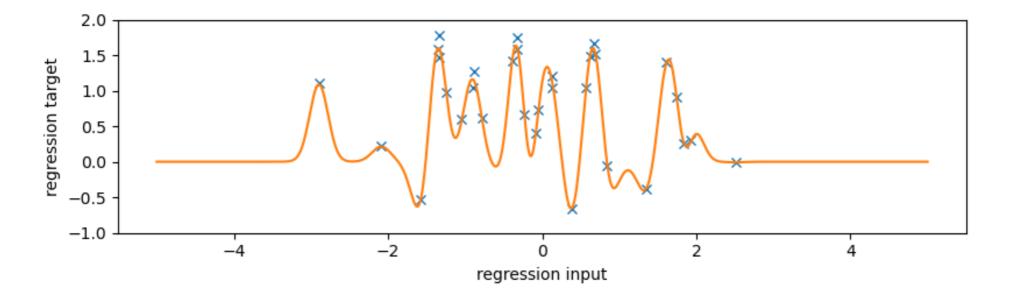
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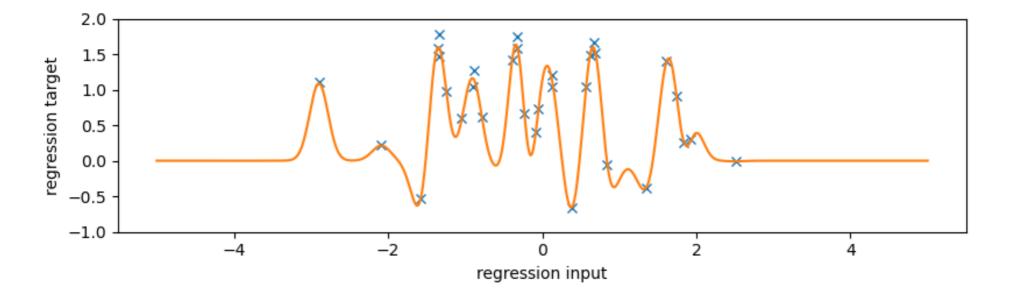
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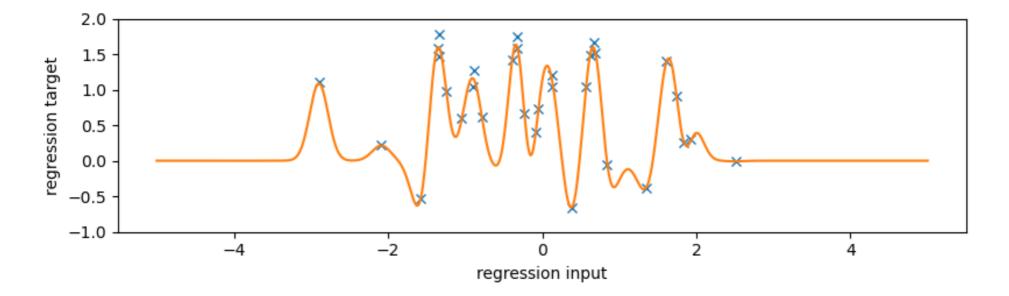
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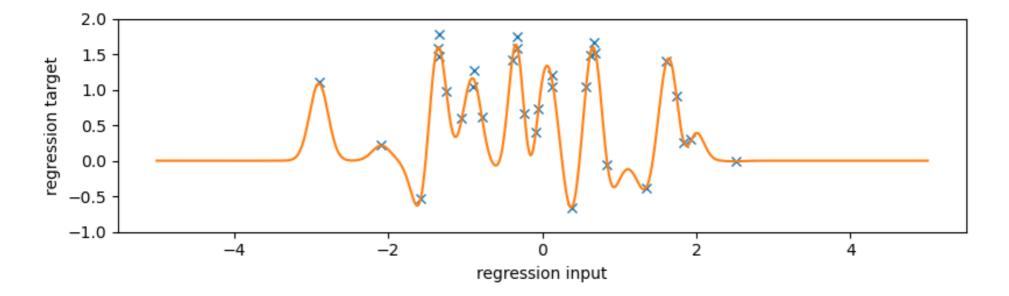
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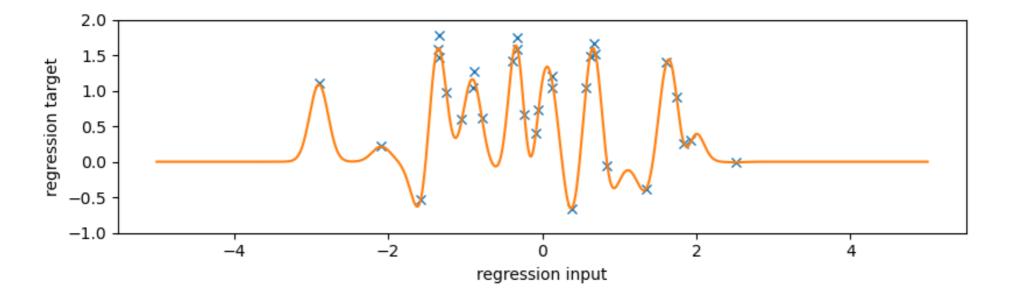
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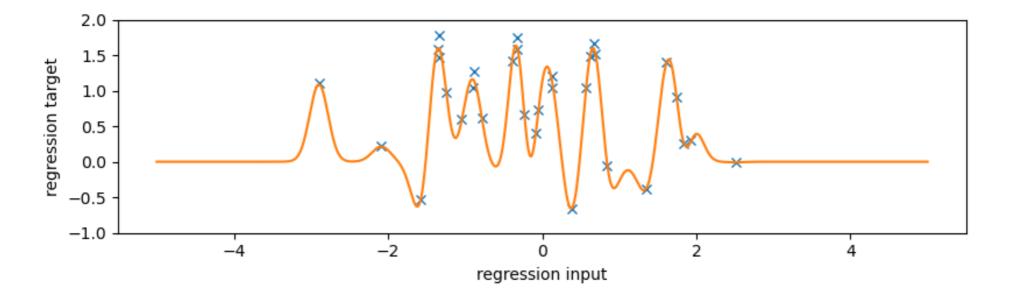
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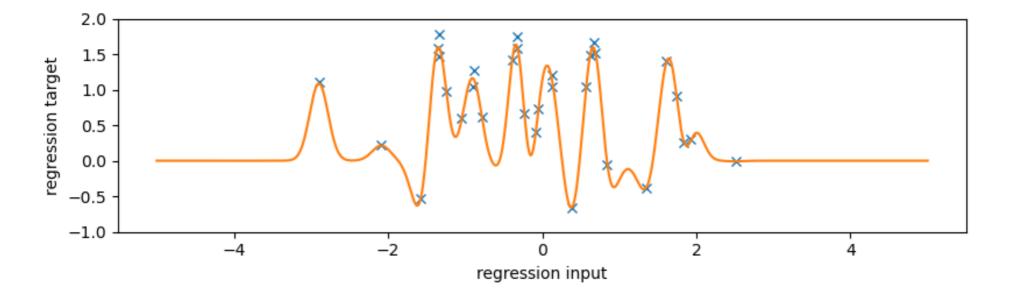
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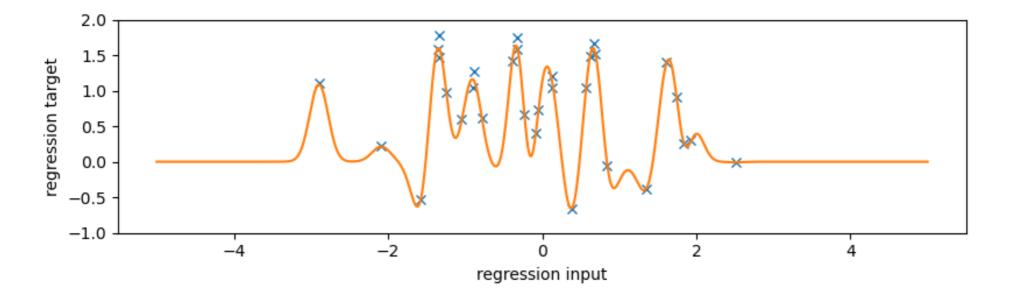
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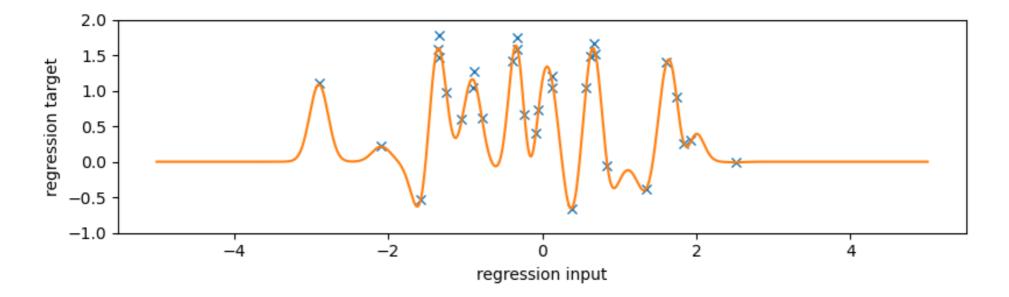
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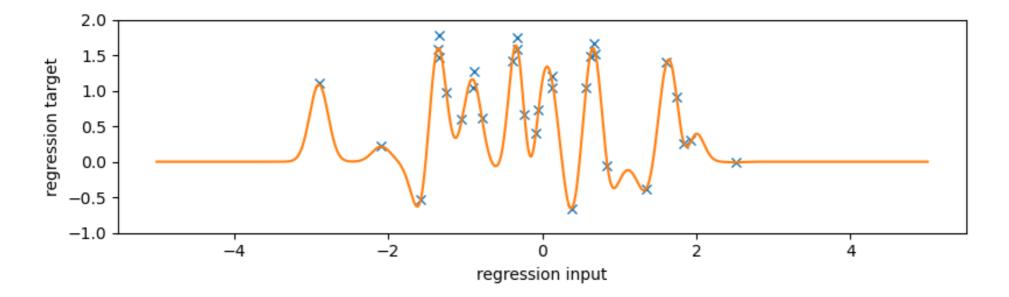
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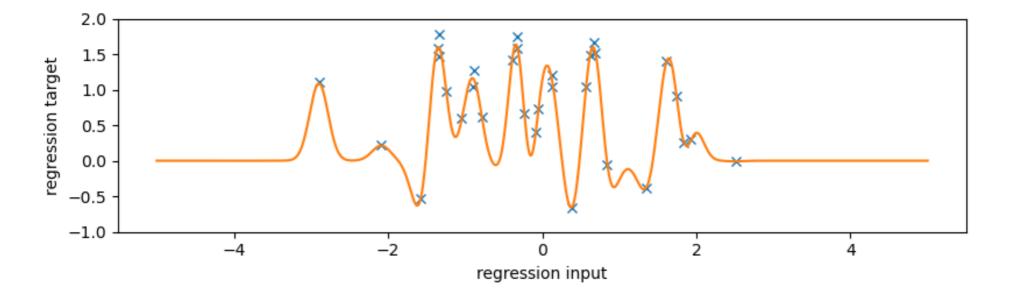
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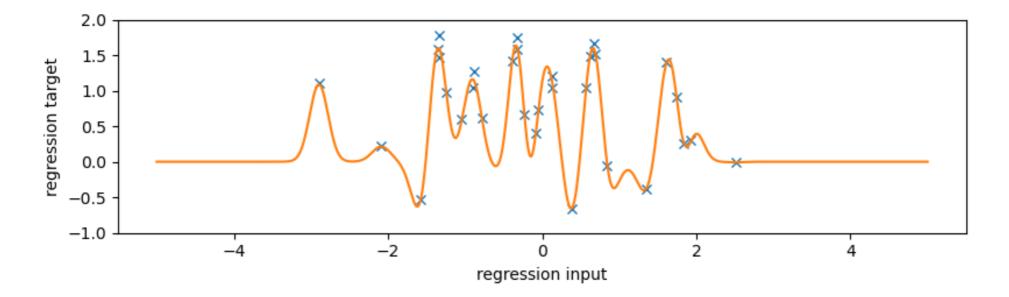
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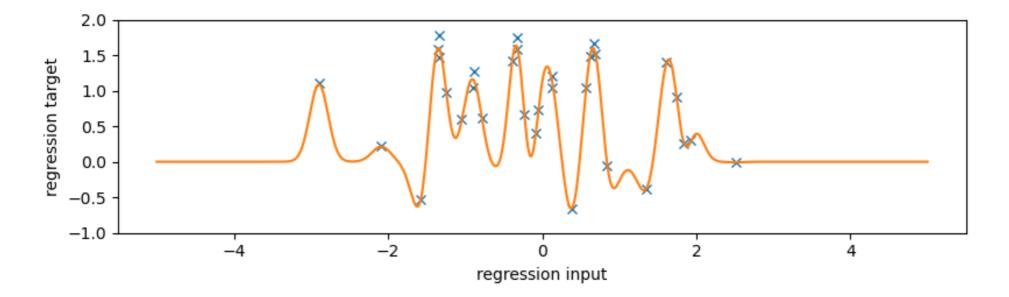
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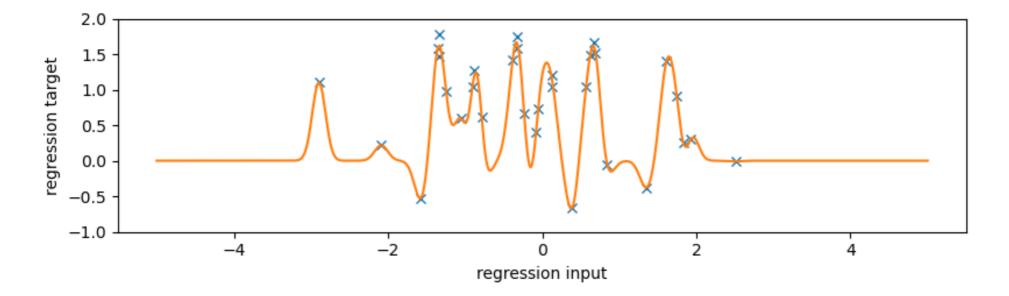
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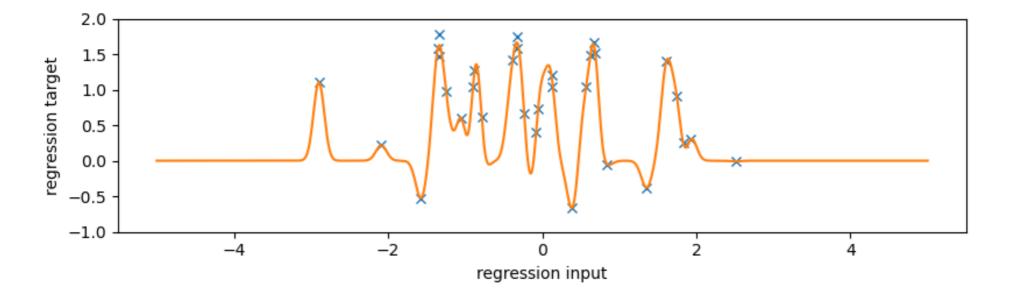
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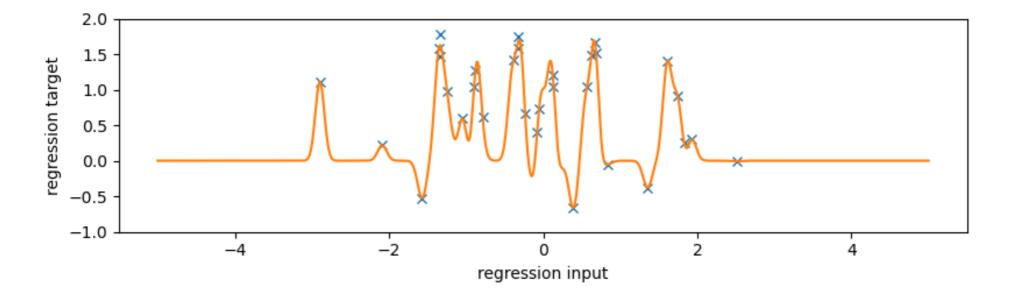
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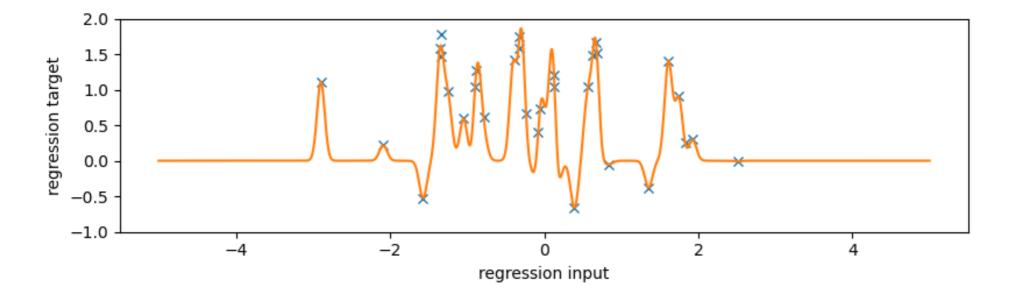
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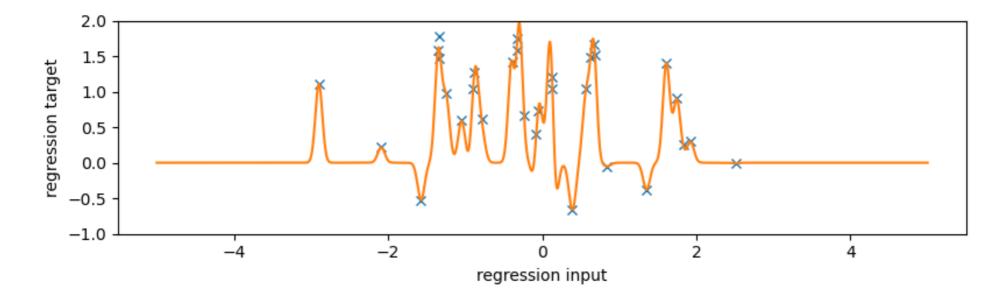
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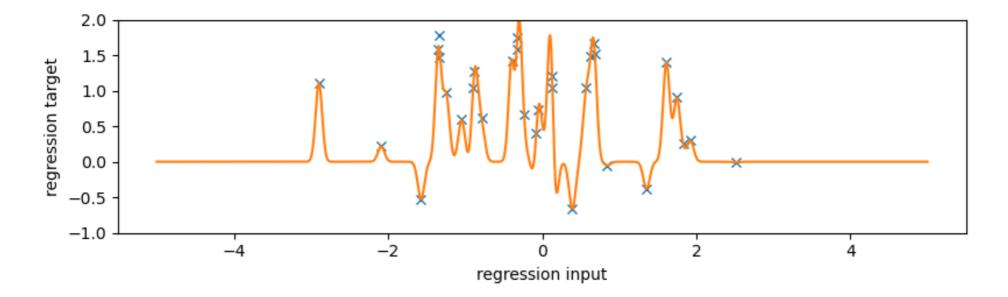
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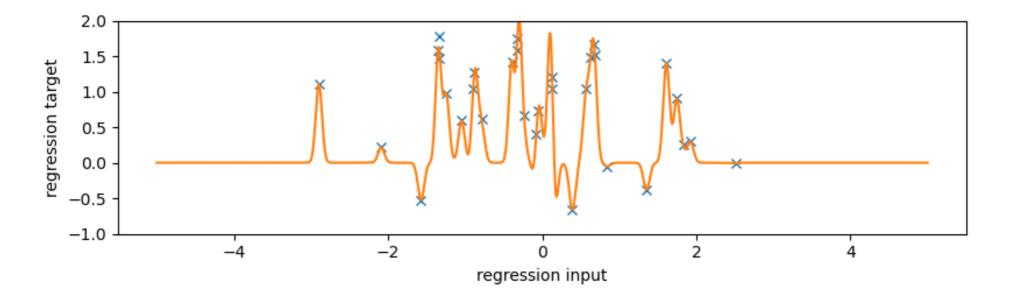
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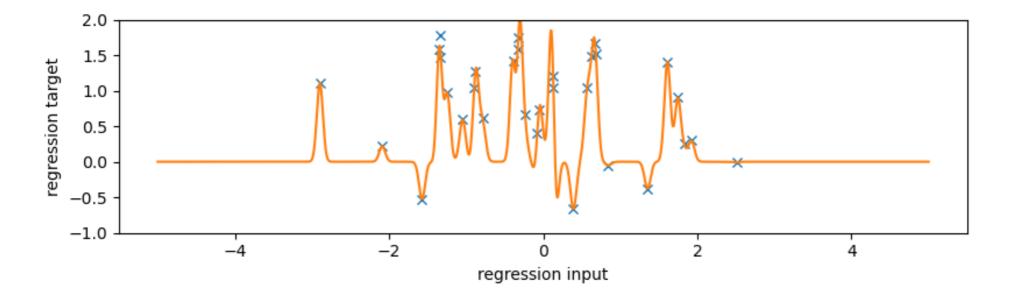
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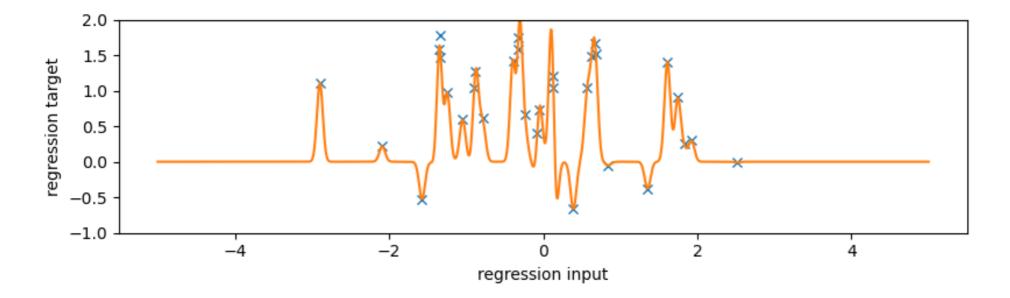
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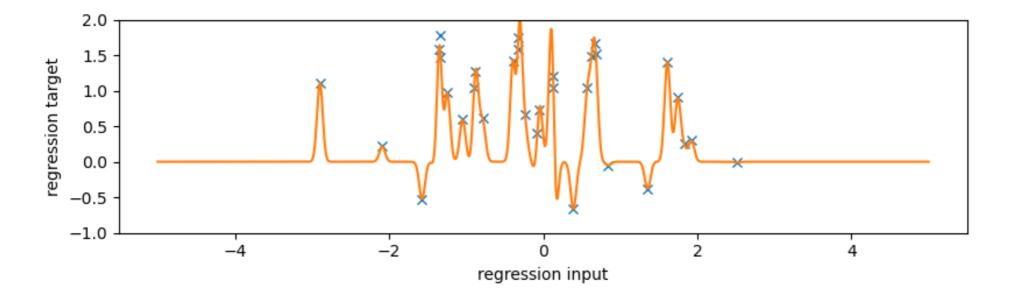
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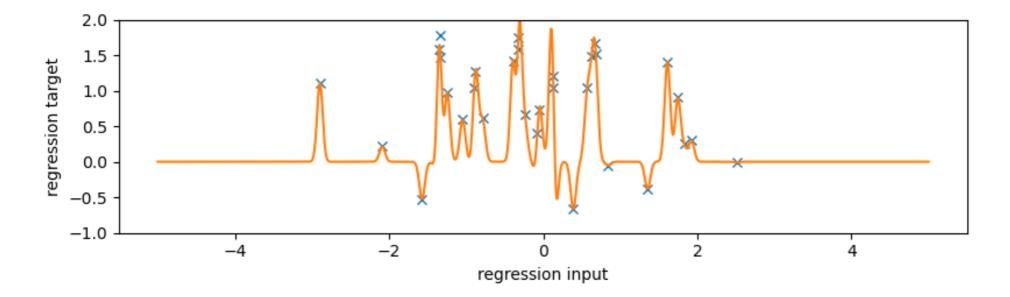
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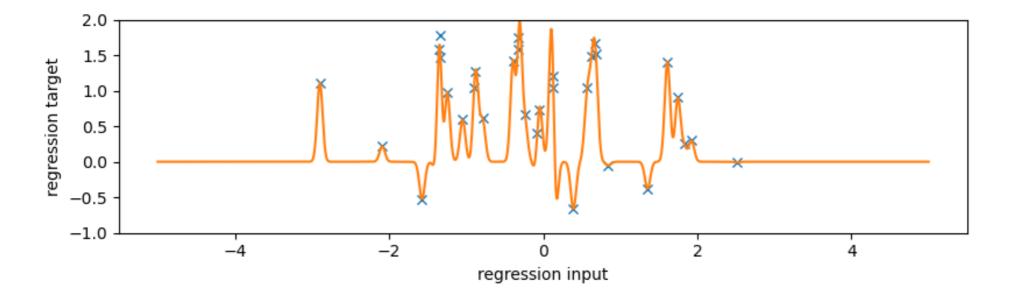
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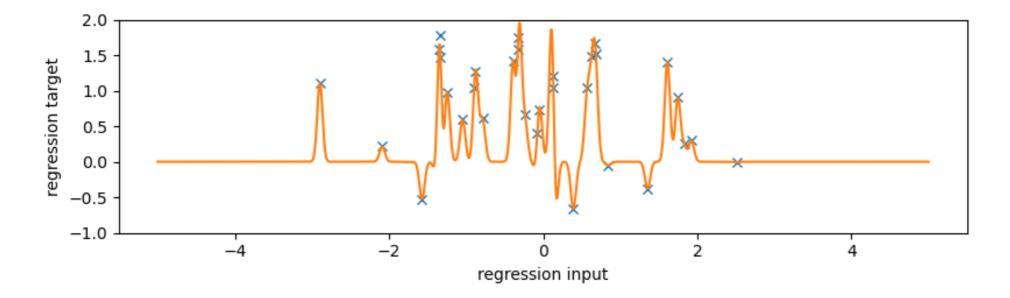
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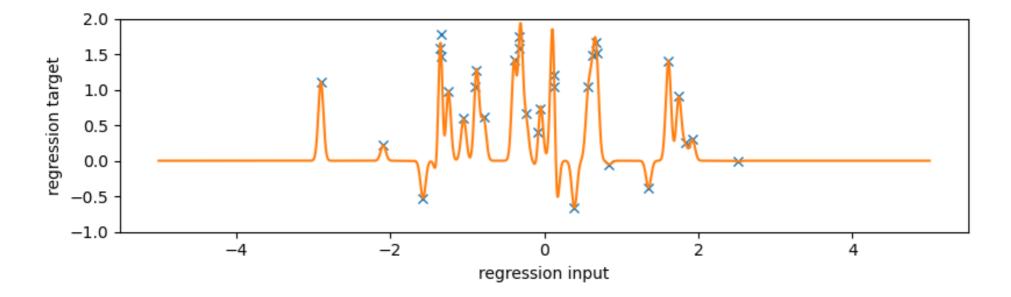
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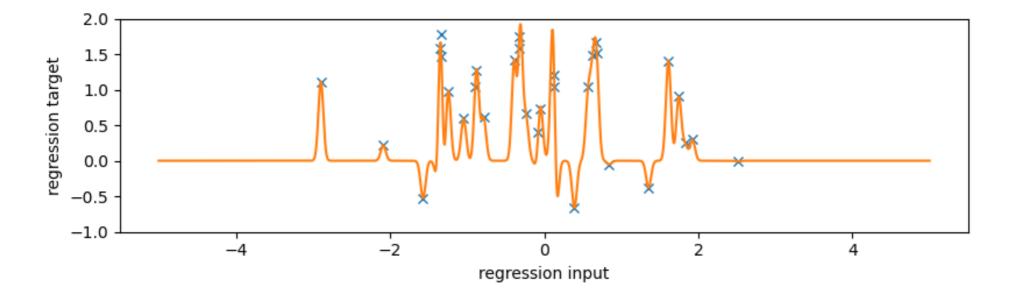
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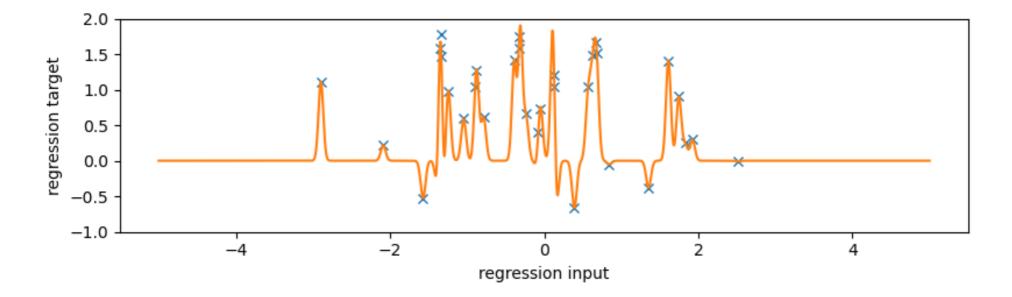
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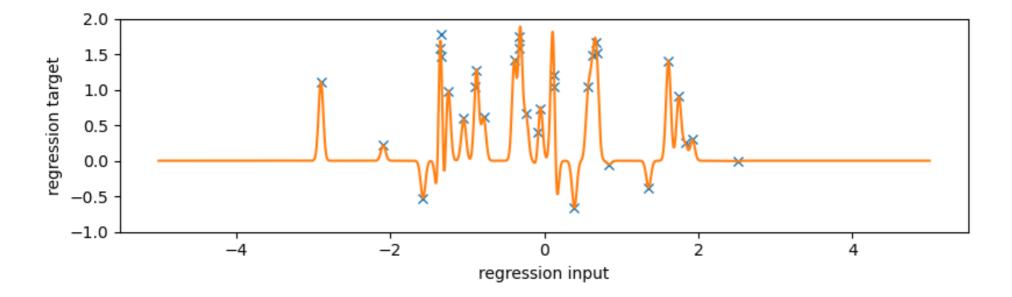
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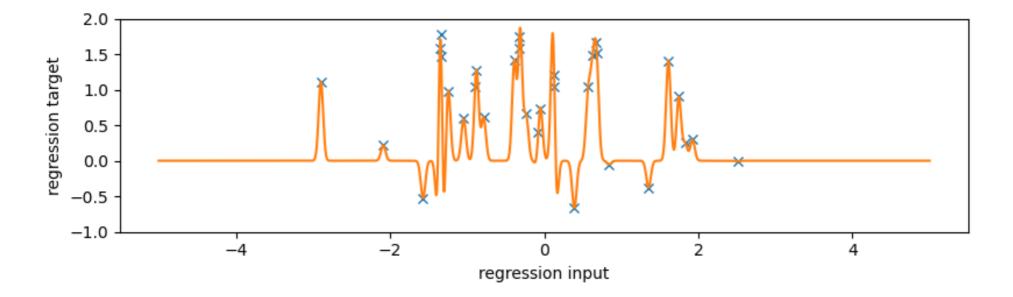
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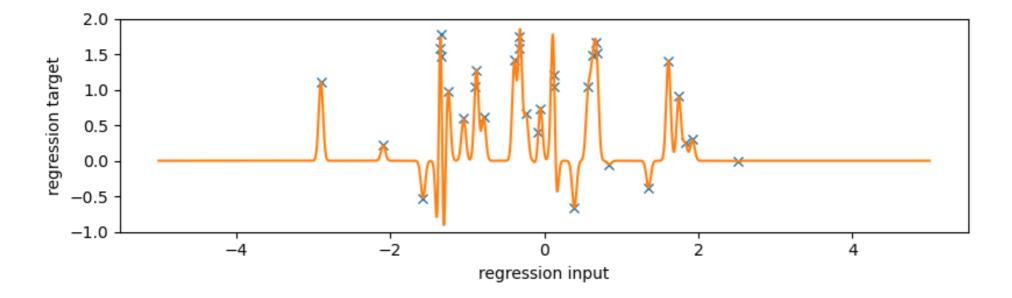
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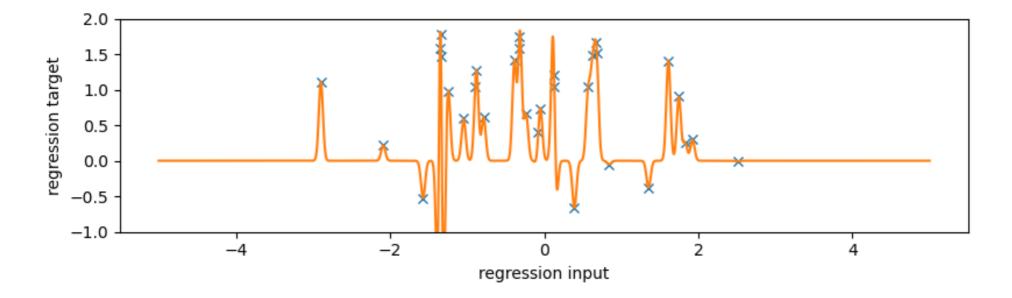
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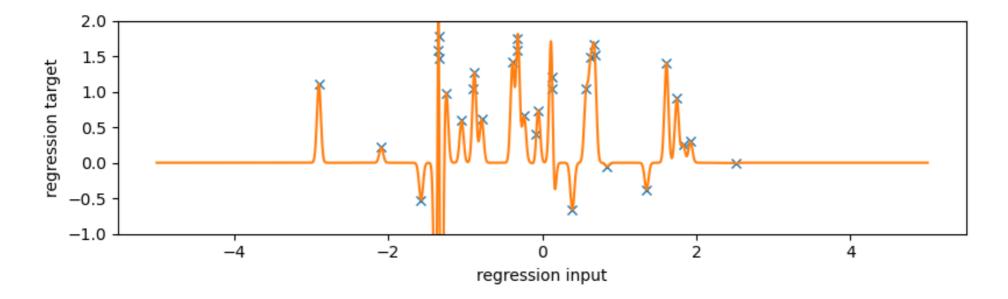
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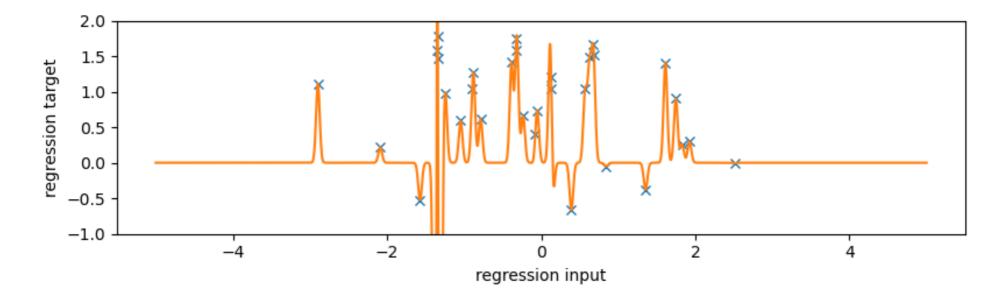
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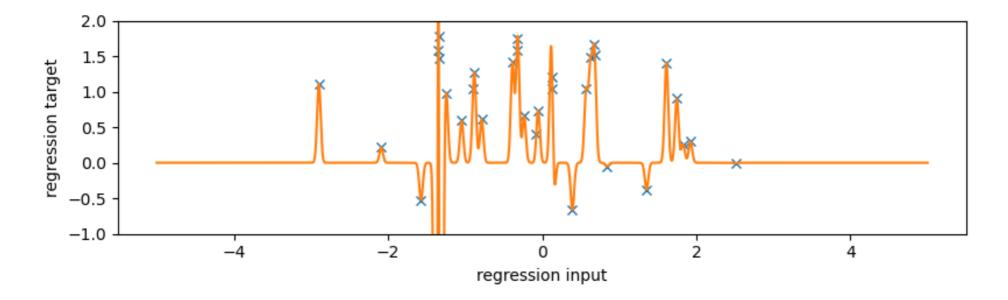
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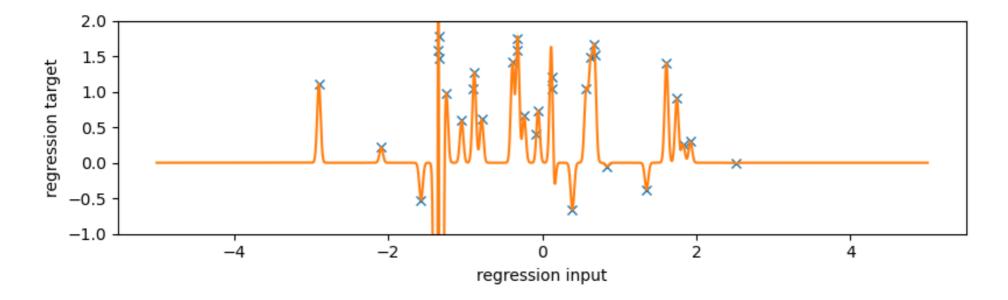
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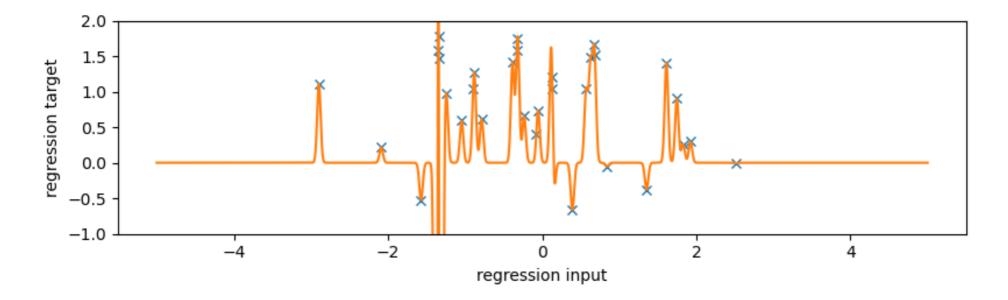
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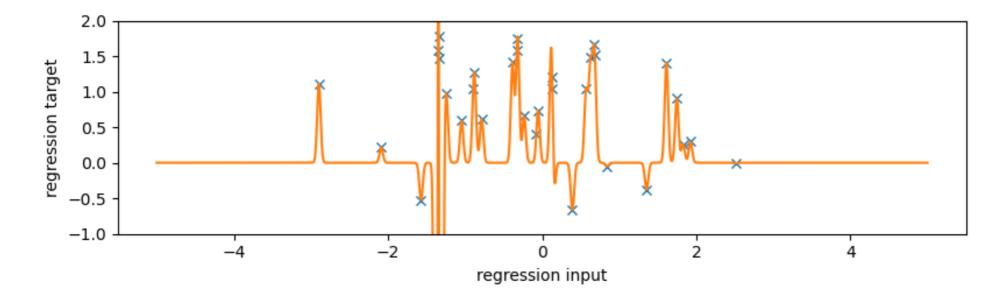
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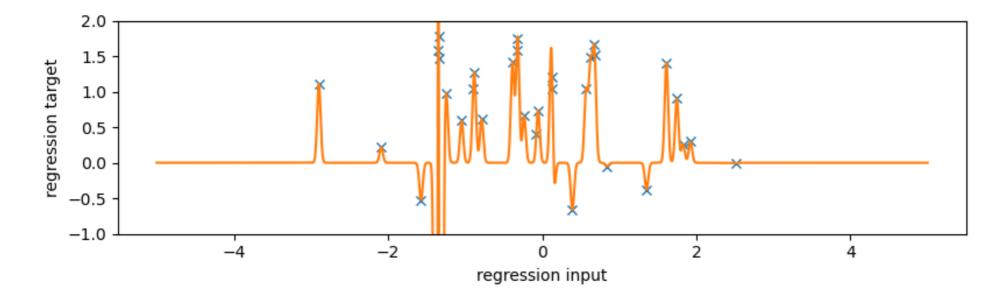
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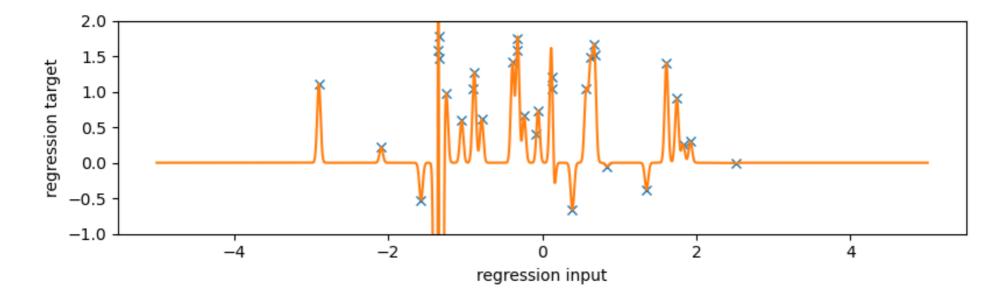
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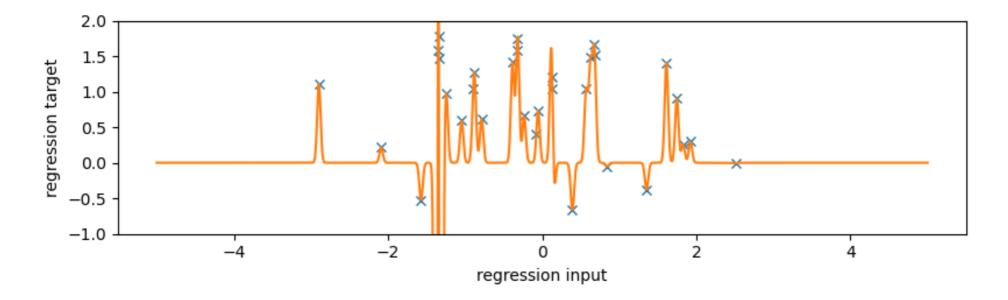
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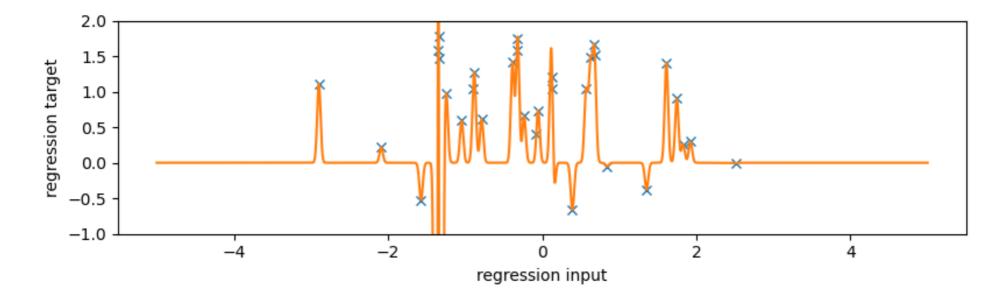
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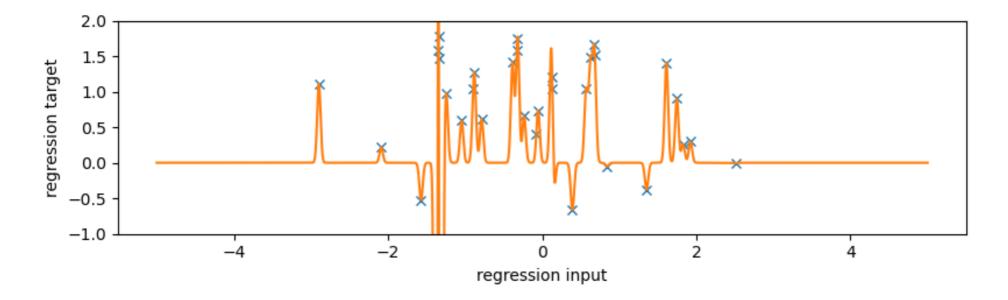
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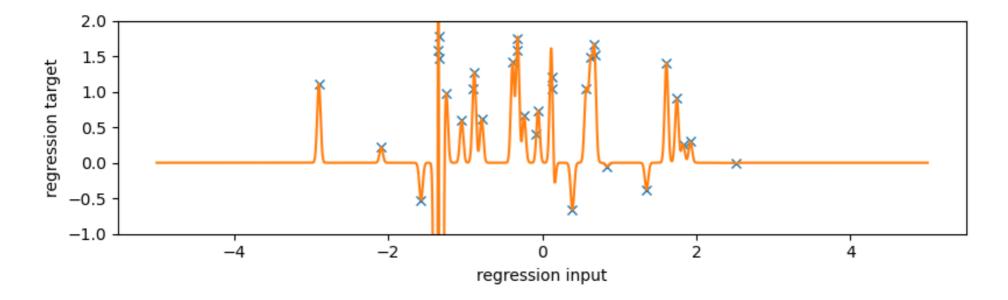
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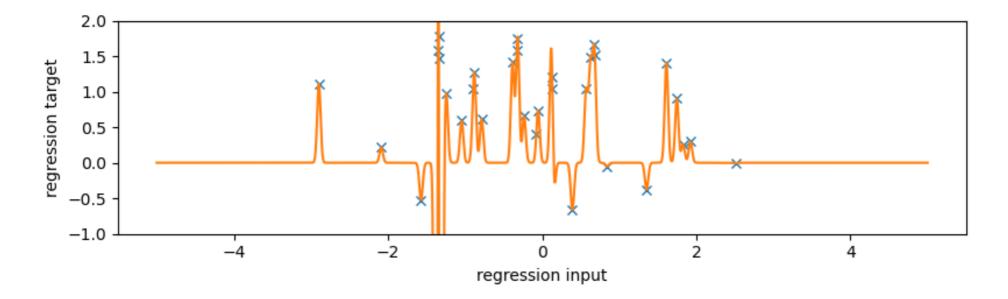
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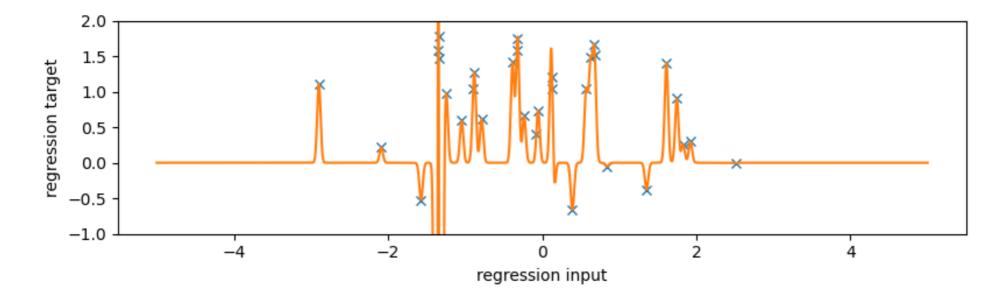
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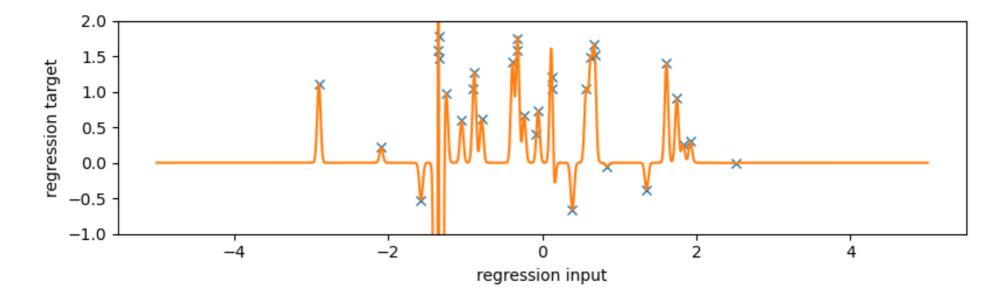
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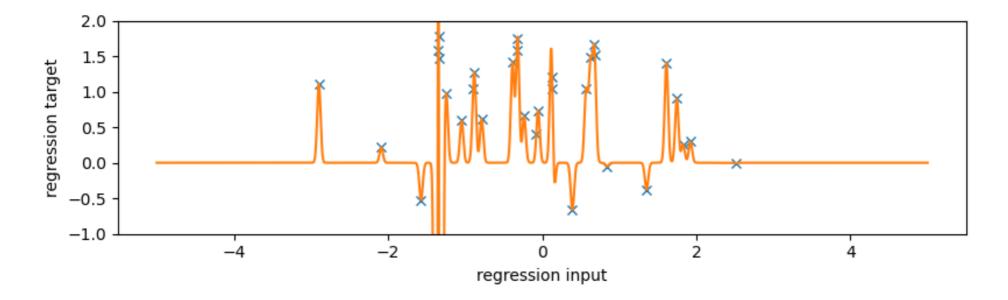
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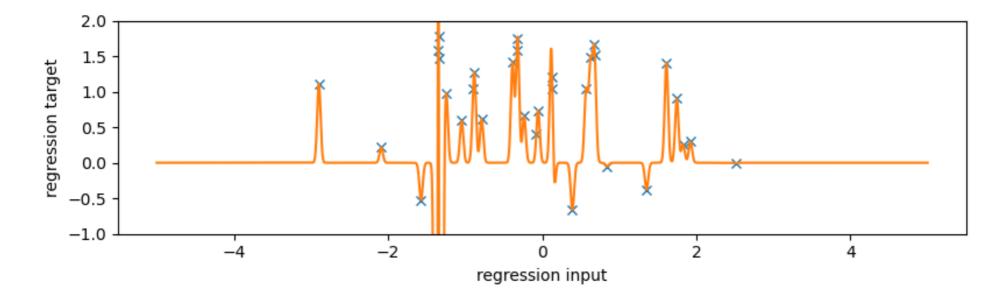
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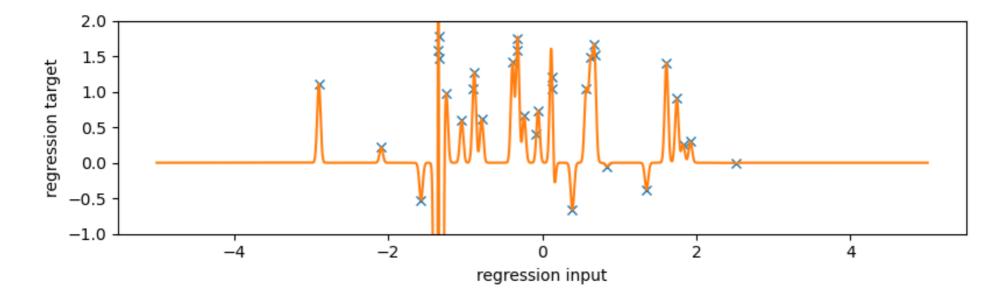
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- Restricting model size never improves $\text{loss} \Rightarrow M \rightarrow N$
- Narrower basis functions to allow more flexible functions
- "Overfitting"

1. What is wrong with minimising losses.

2. Bayesian Model Selection?

- 2. The Bayesian answer to model size: Nonparametrics.
- 3. A principle for selecting size

Let's accept the "large" number of basis functions for now, and solve the overfitting problem.

Bayesian inference is rumoured to be "robust to overfitting".

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Benefit #1: **Uncertainty** estimates on your parameters

$$p(W|\mathcal{D}, \theta) = \frac{p(\mathcal{D}|W, \theta)p(W|\theta)}{p(\mathcal{D}|\theta)}$$

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Benefit #1: **Uncertainty** estimates on your parameters Benefit #2: **Hyperparameter selection**

$$\begin{split} p(W,\theta|\mathcal{D}) &= \frac{p(\mathcal{D}|W,\theta)p(W|\theta)}{p(\mathcal{D}|\theta)}\frac{p(\mathcal{D}|\theta)p(\theta)}{p(\mathcal{D})}\\ p(\mathcal{D}|\theta) &= \int p(\mathcal{D}|W,\theta)p(W|\theta) \,\mathrm{d}W \end{split}$$

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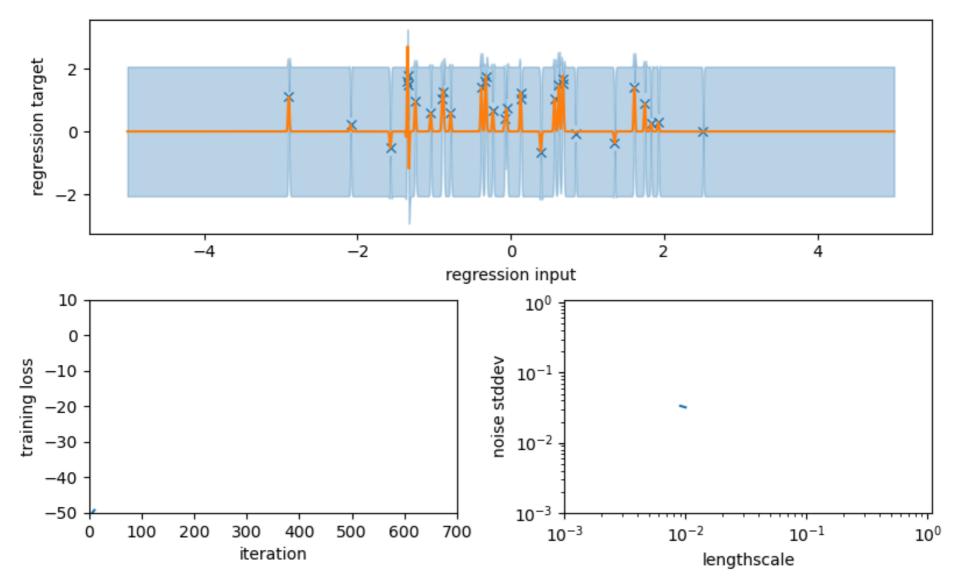
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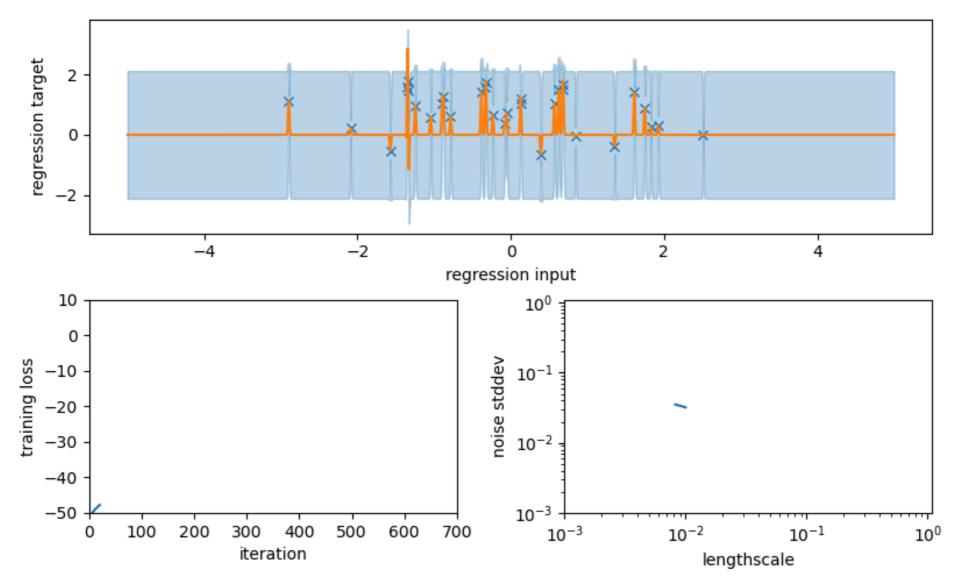
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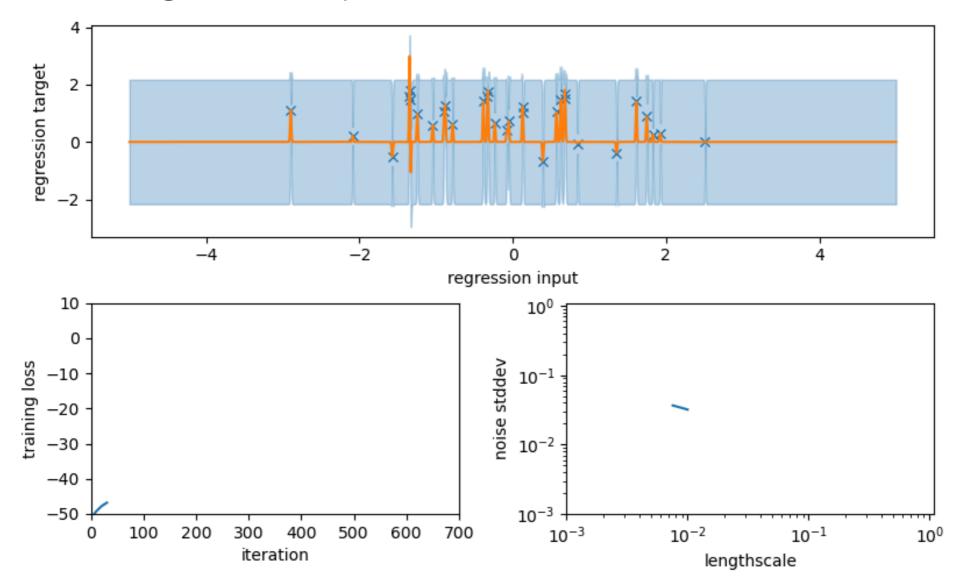
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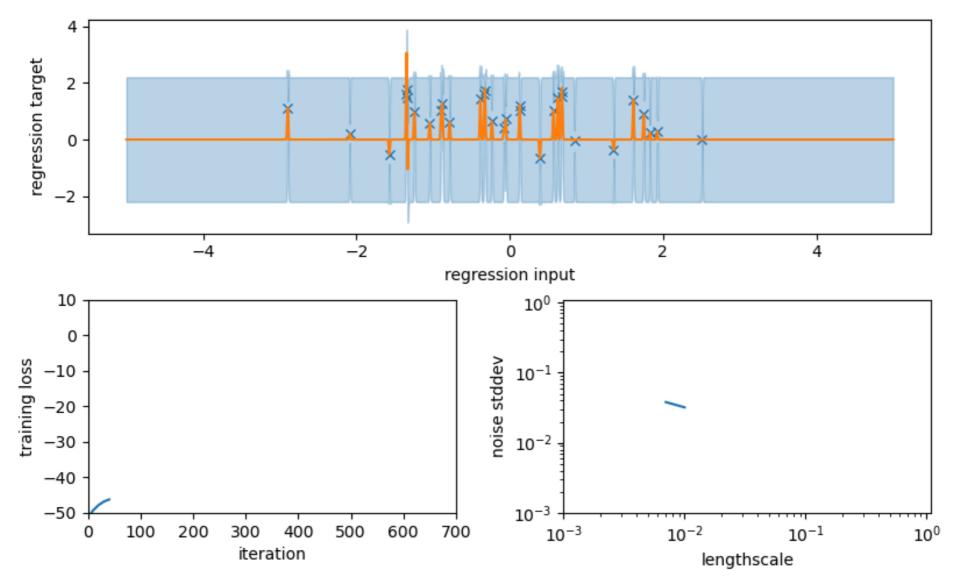
Bayesian computations are often intractable. \Rightarrow Approximating $p(\mathcal{D}|\theta)$ is hard enough, let alone for many different values of θ !

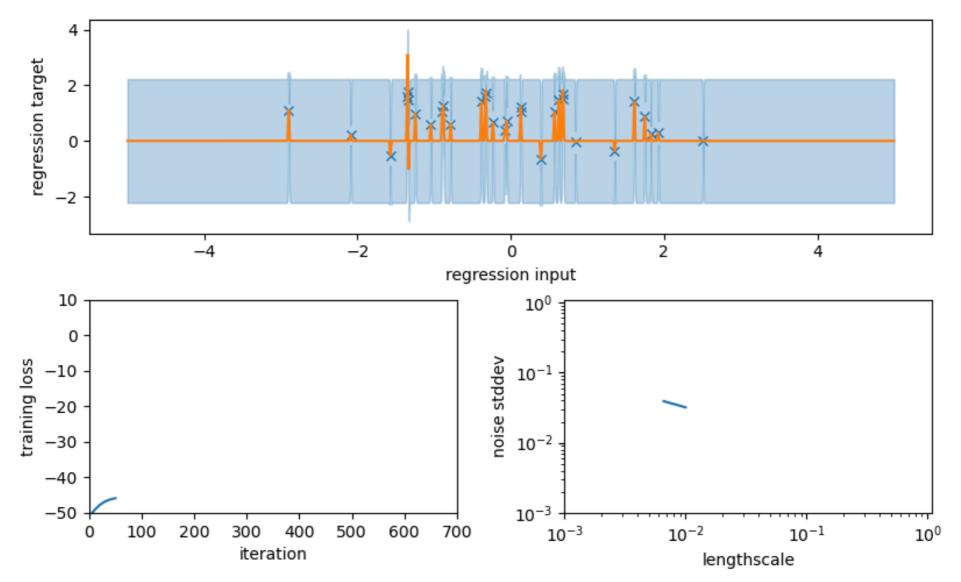
$$\begin{split} \theta^* &= \operatorname*{argmin}_{\theta} \log p(\mathcal{D} \mid \theta) \\ p(W | \mathcal{D}, \theta) &= \frac{p(\mathcal{D} | W, \theta) p(W | \theta)}{p(\mathcal{D} | \theta)} \end{split}$$

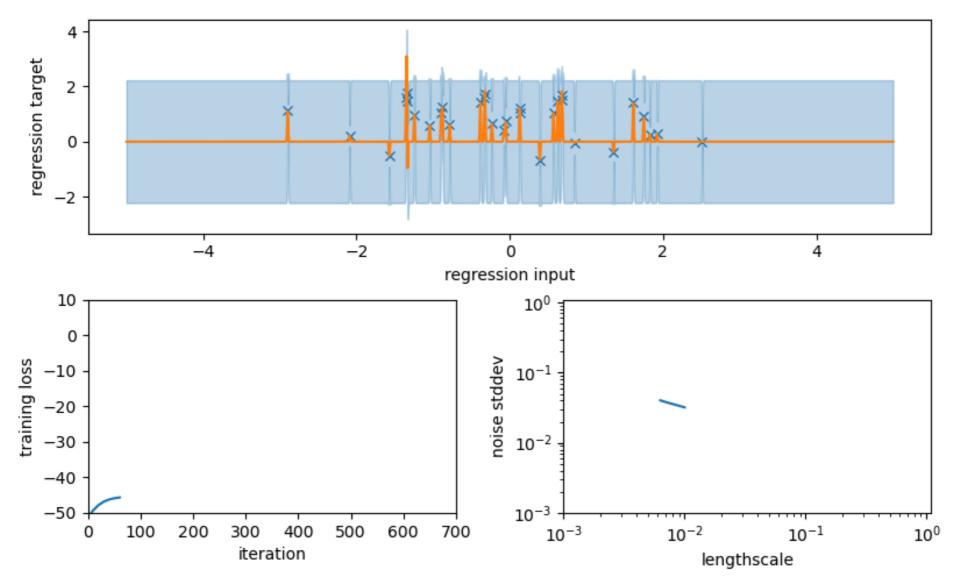


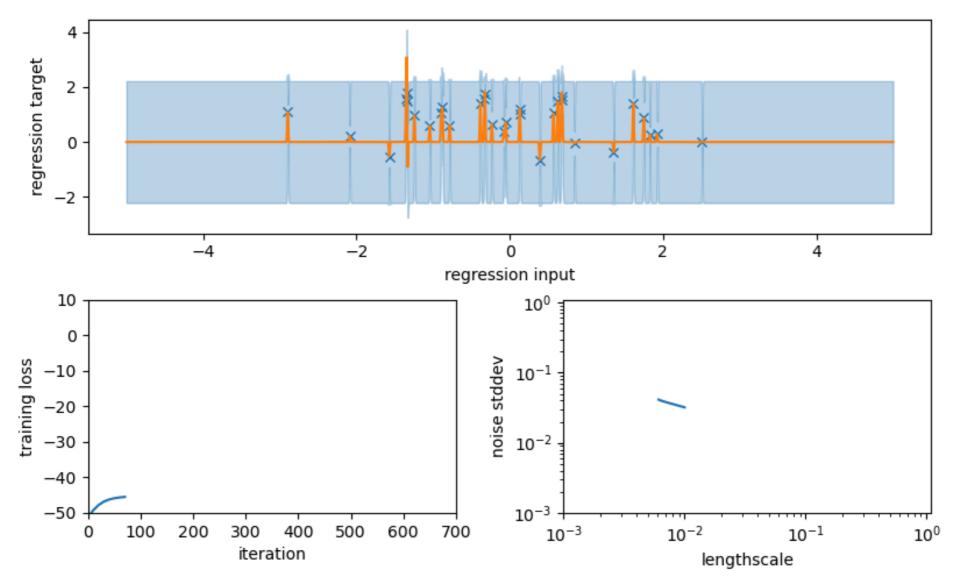


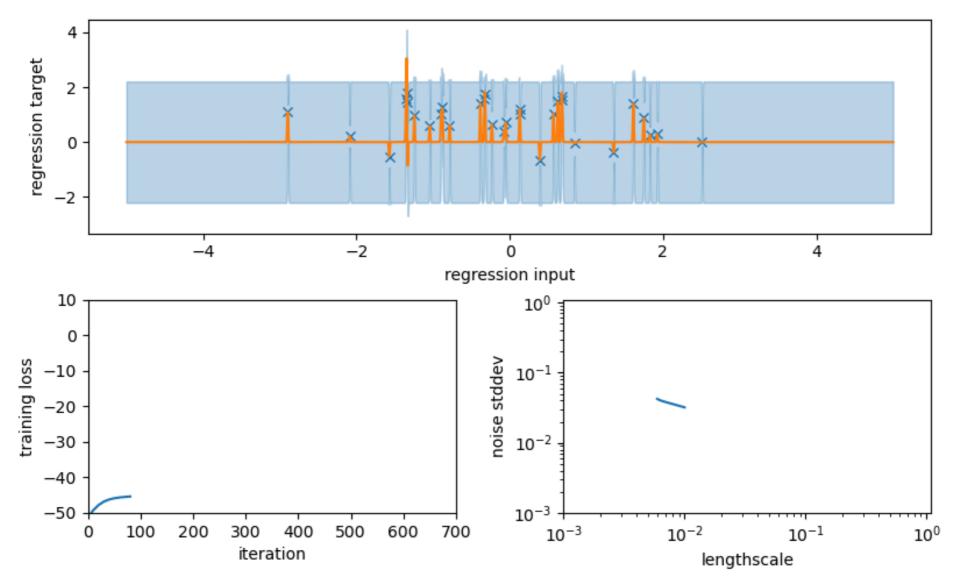


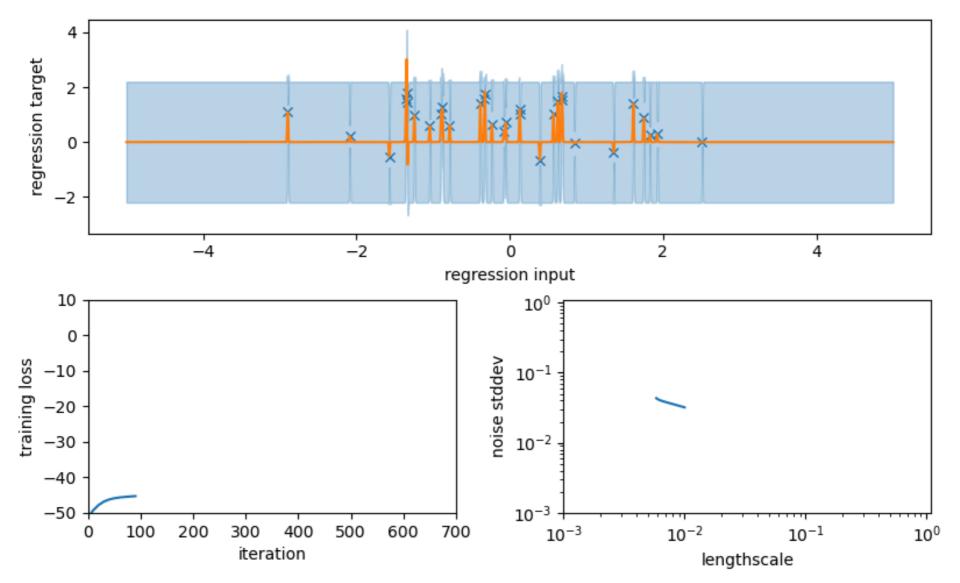


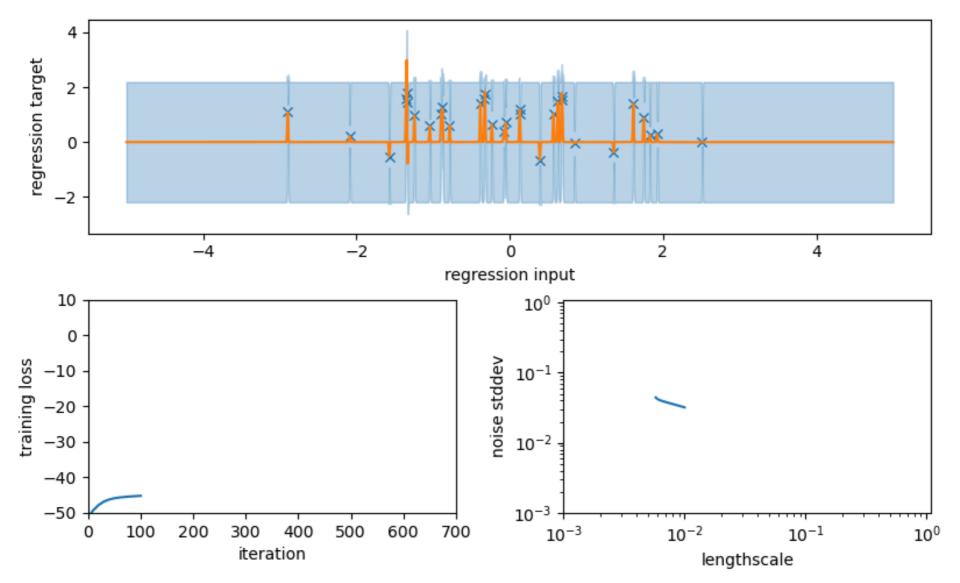


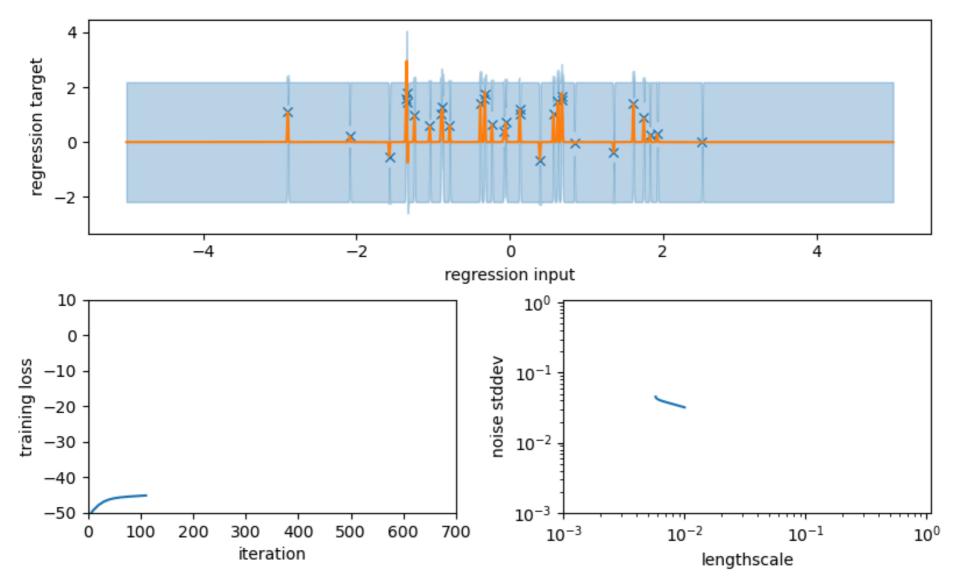


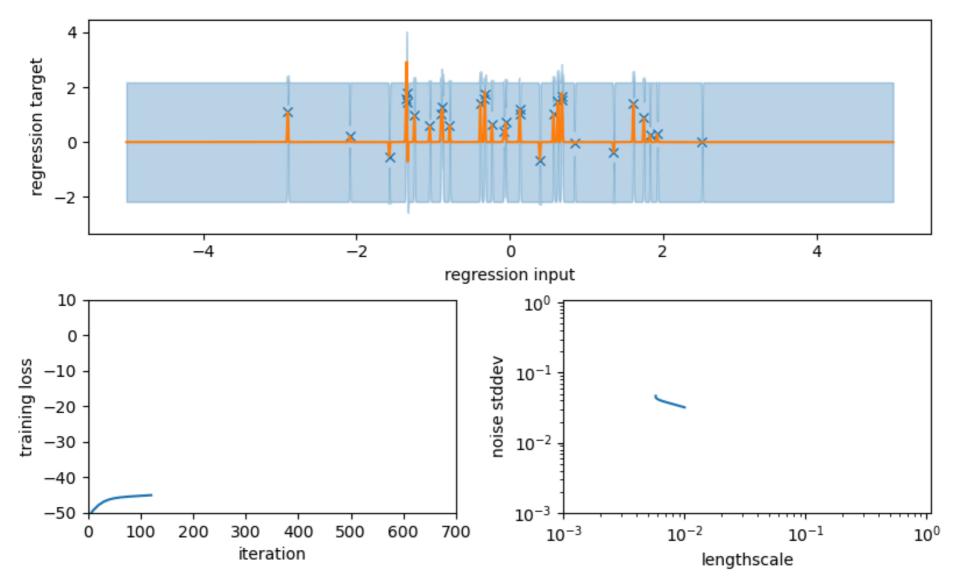


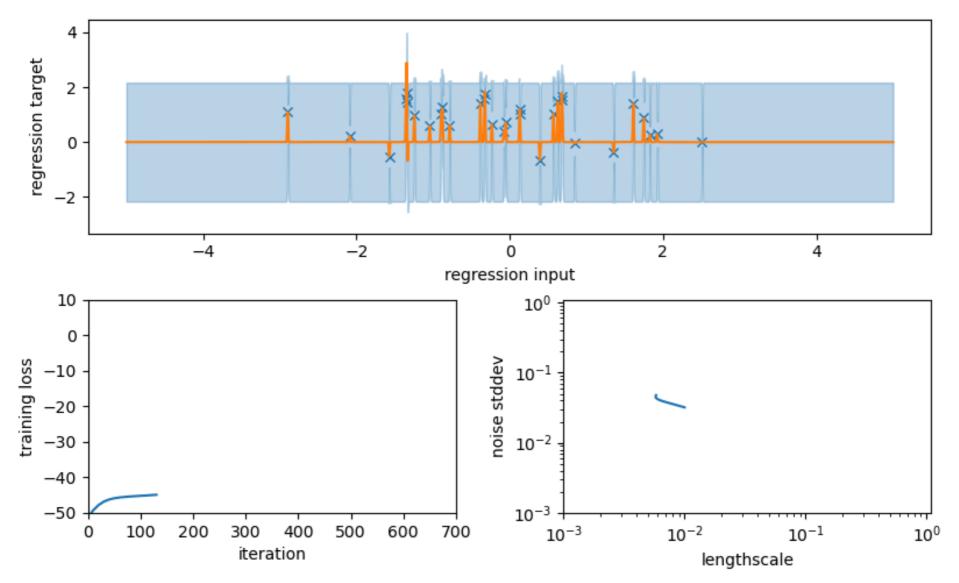


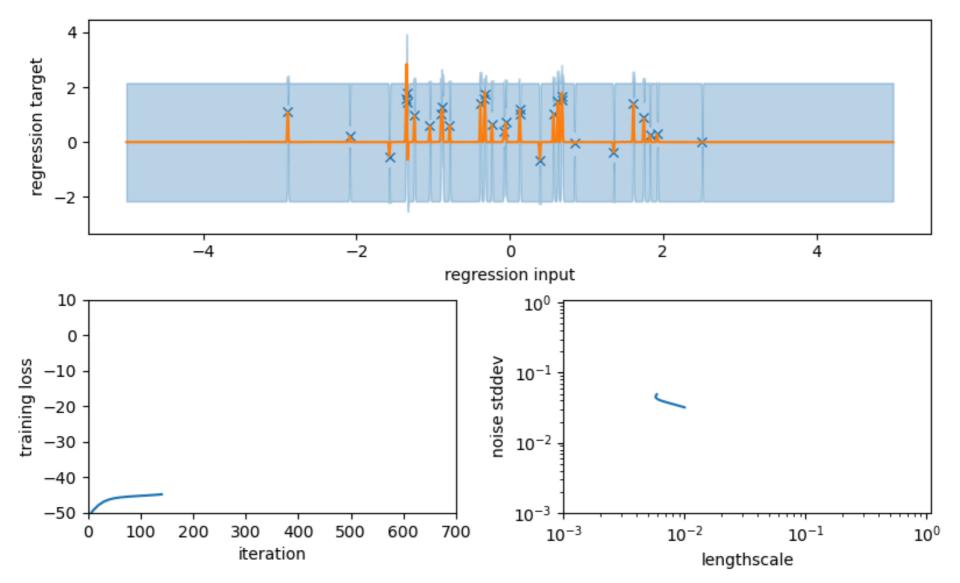


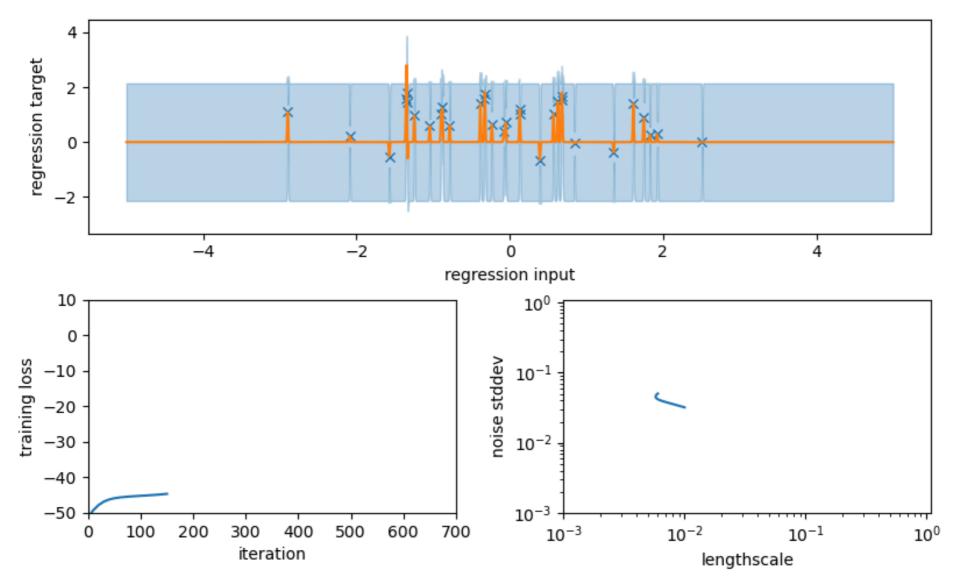


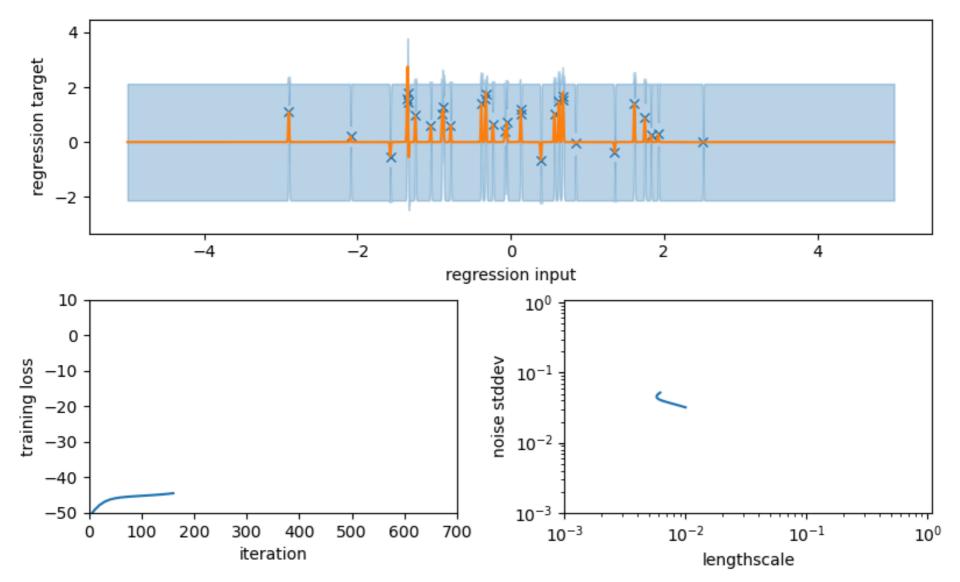


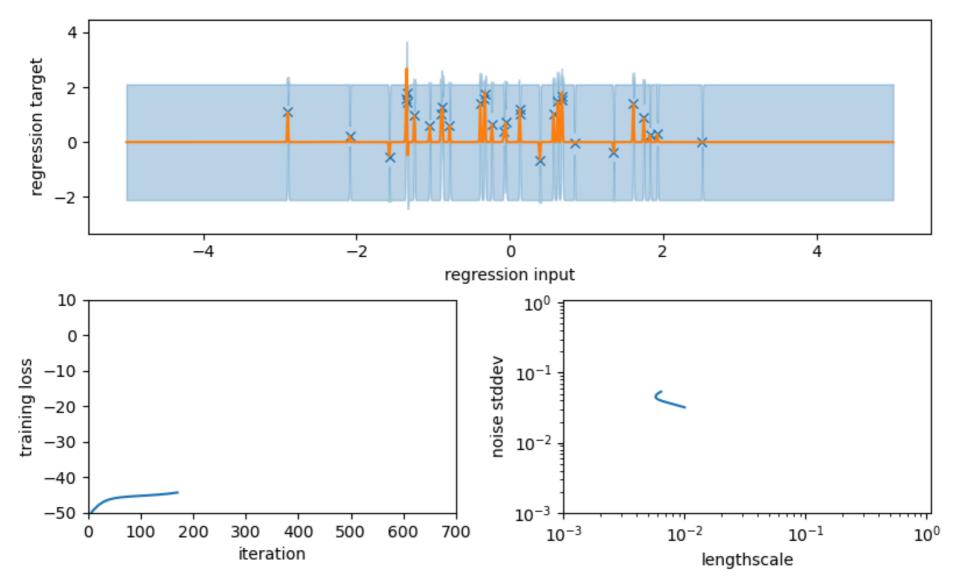


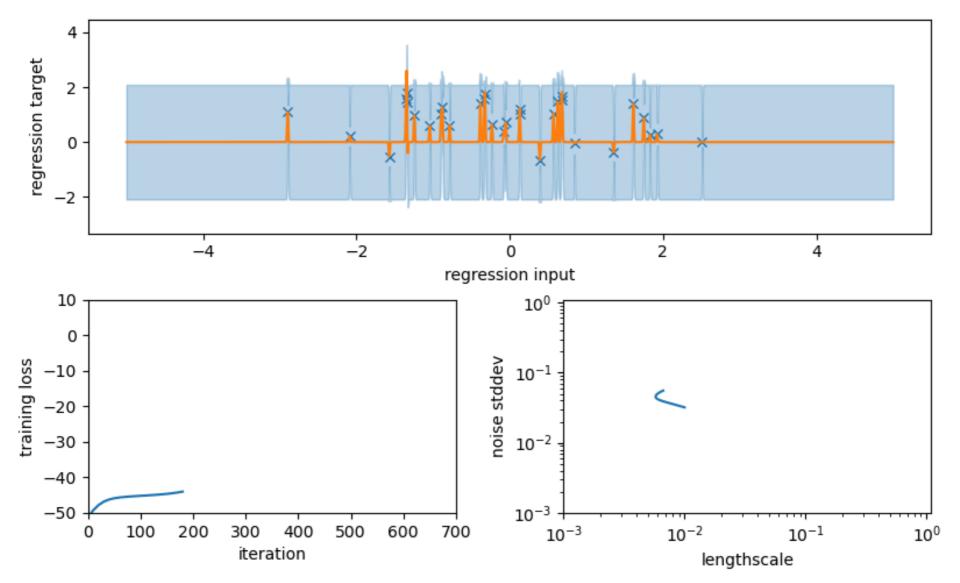


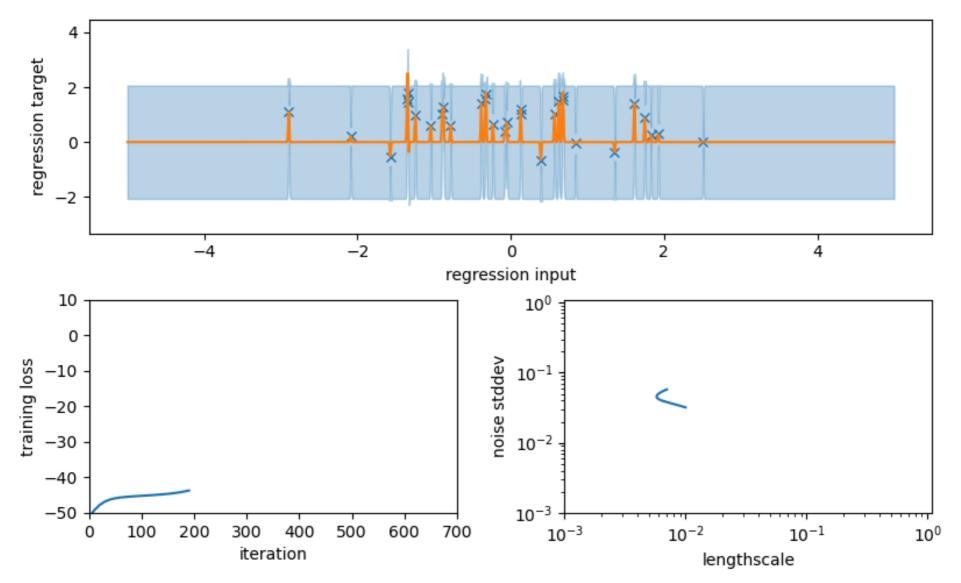


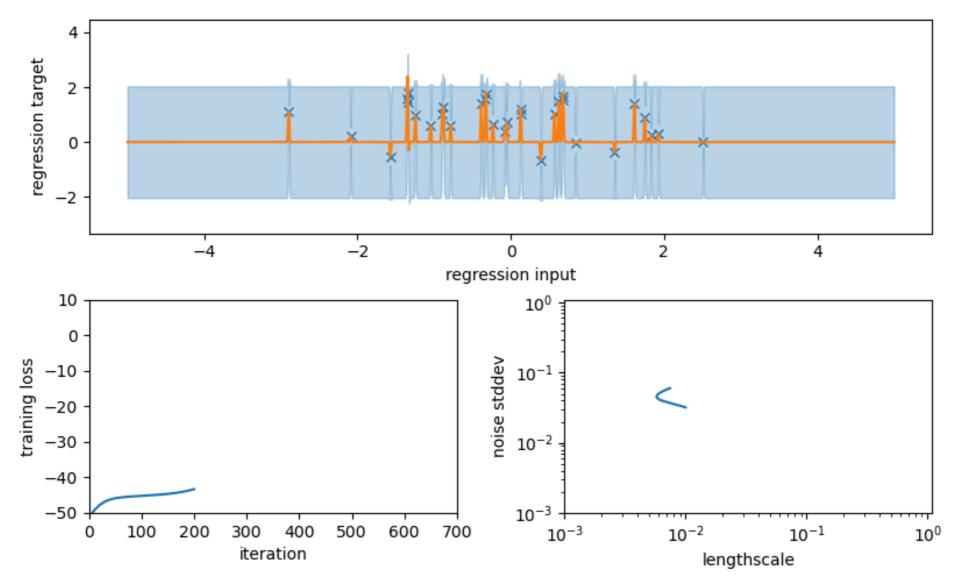


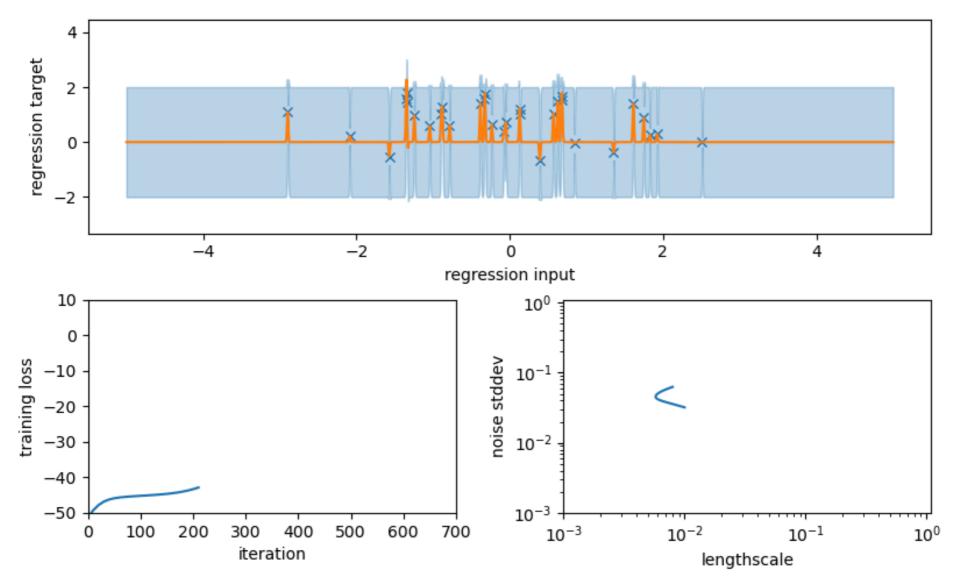


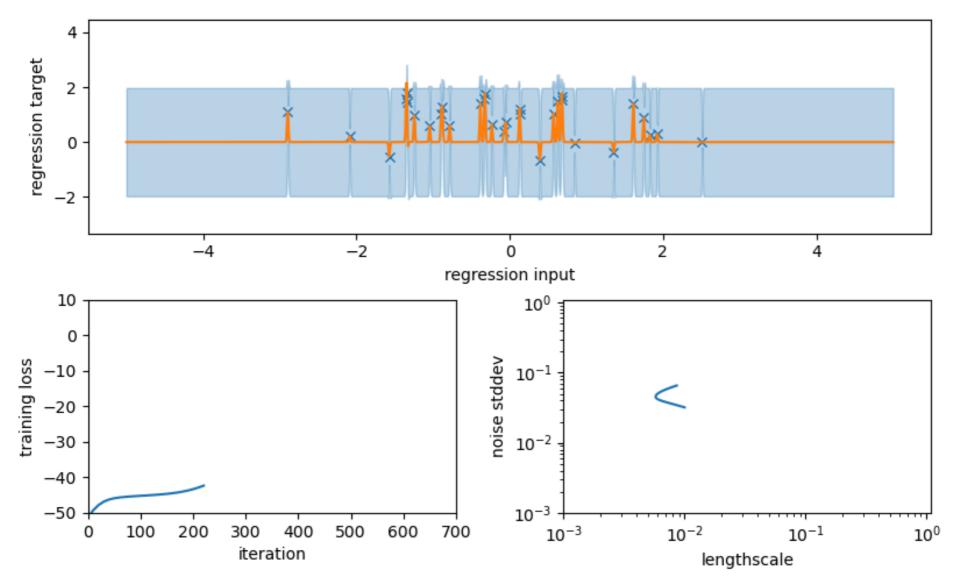


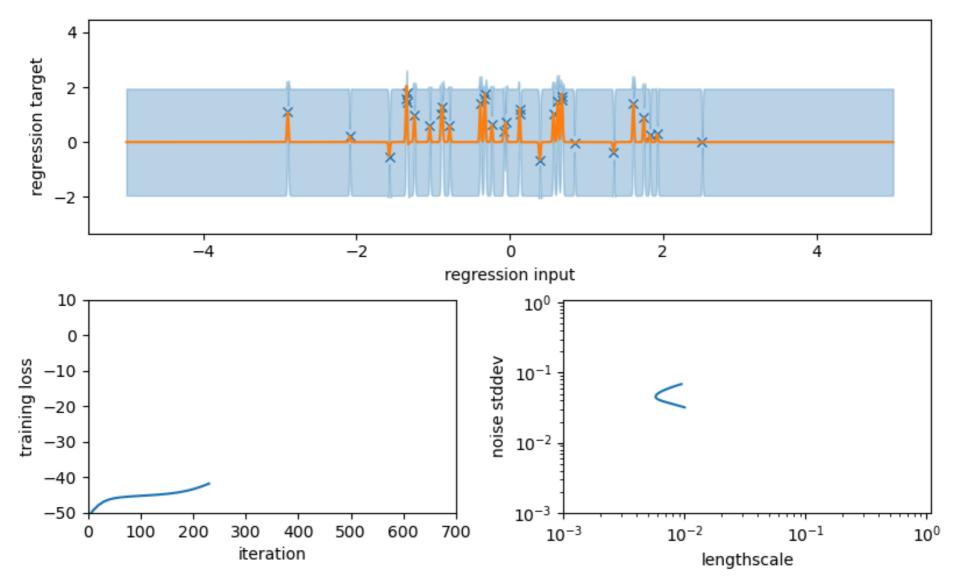


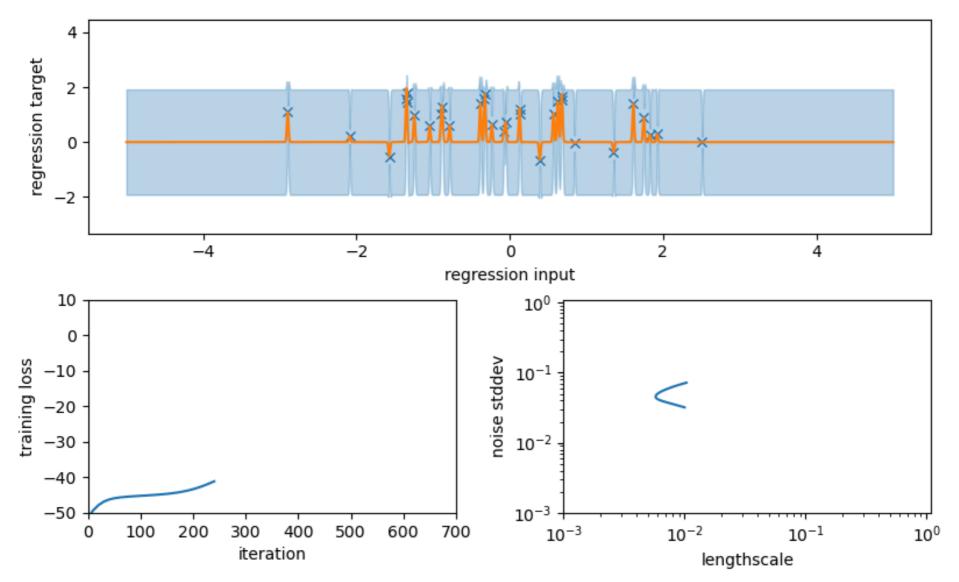


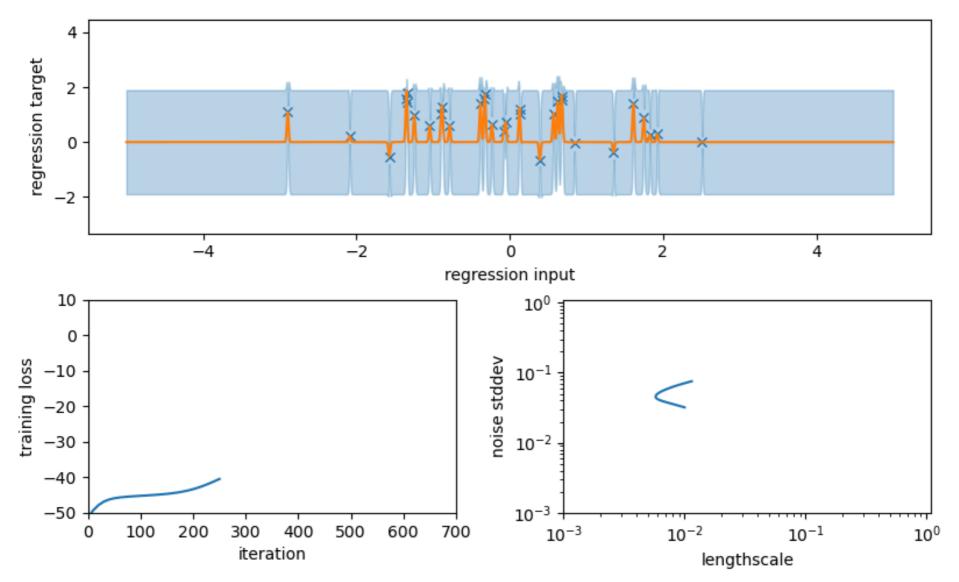


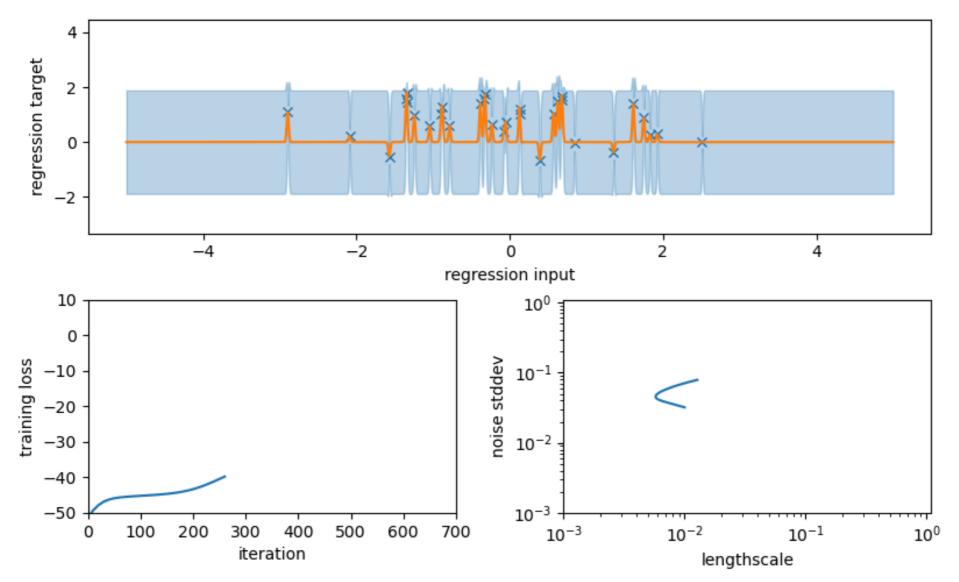


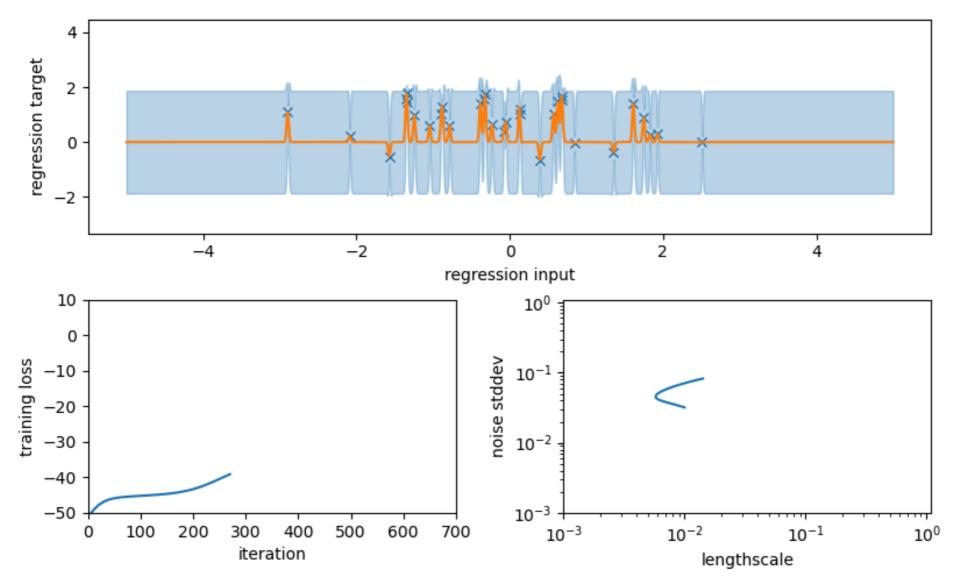


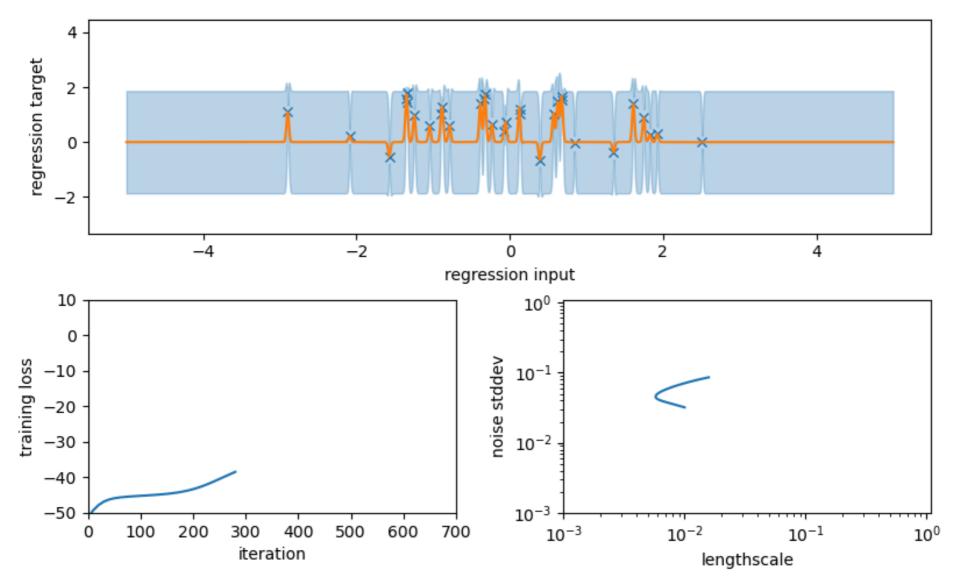


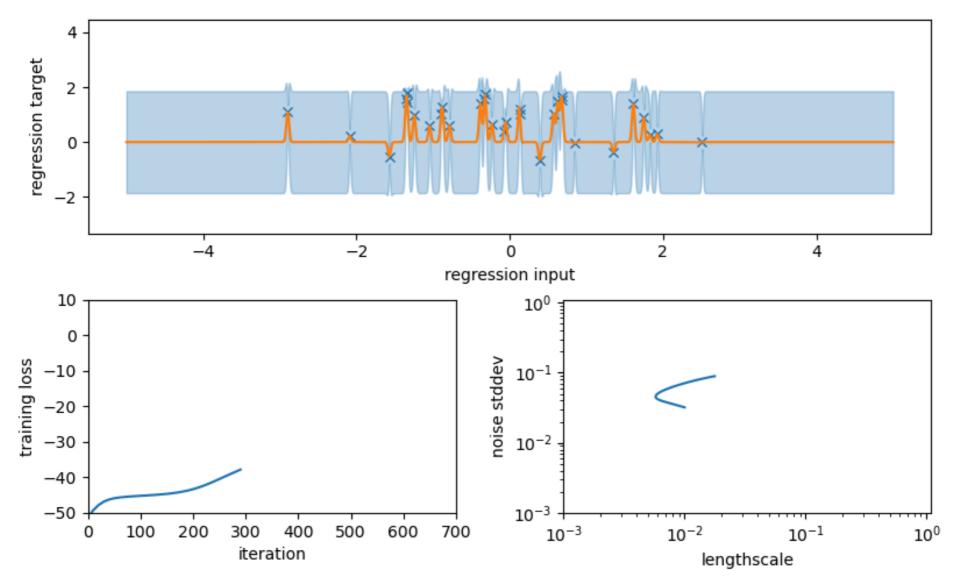


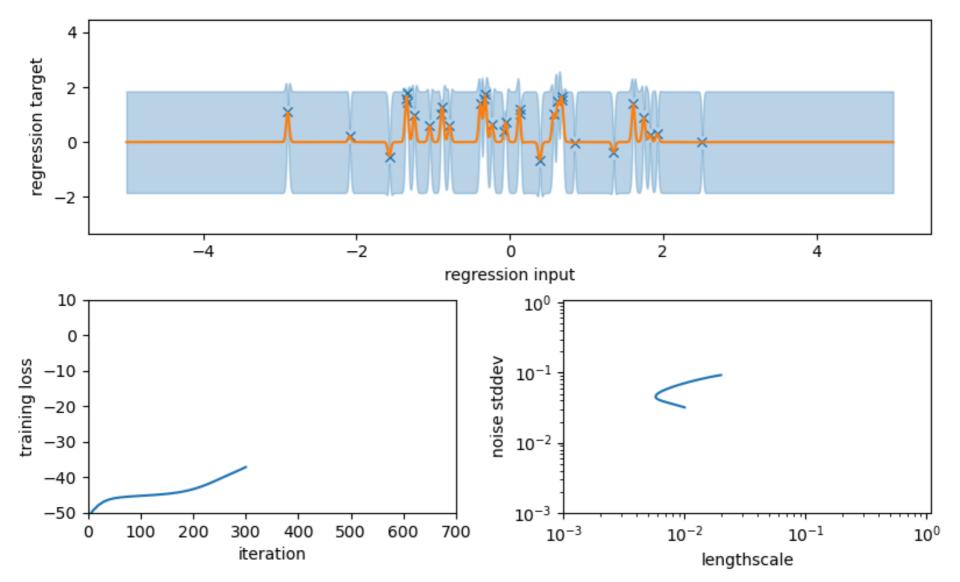


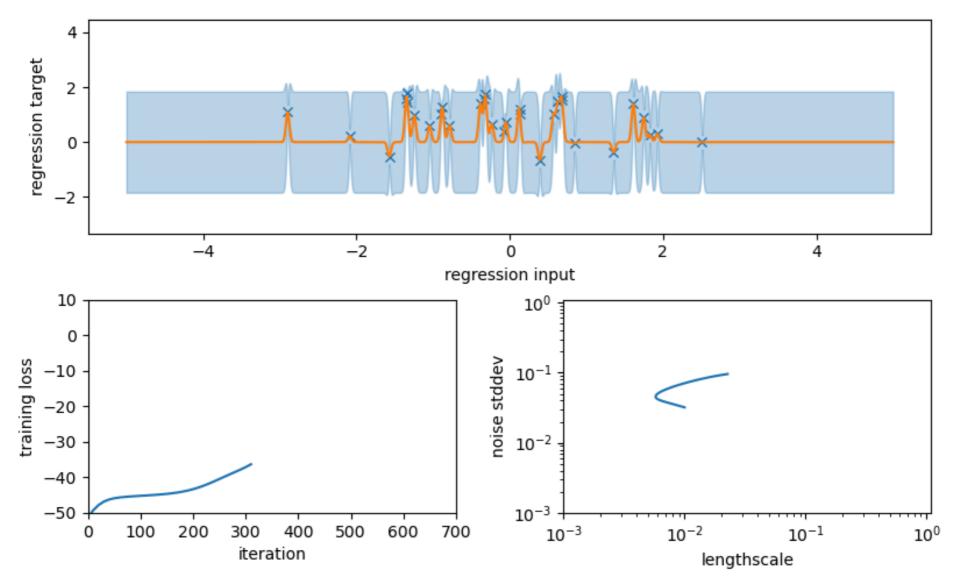


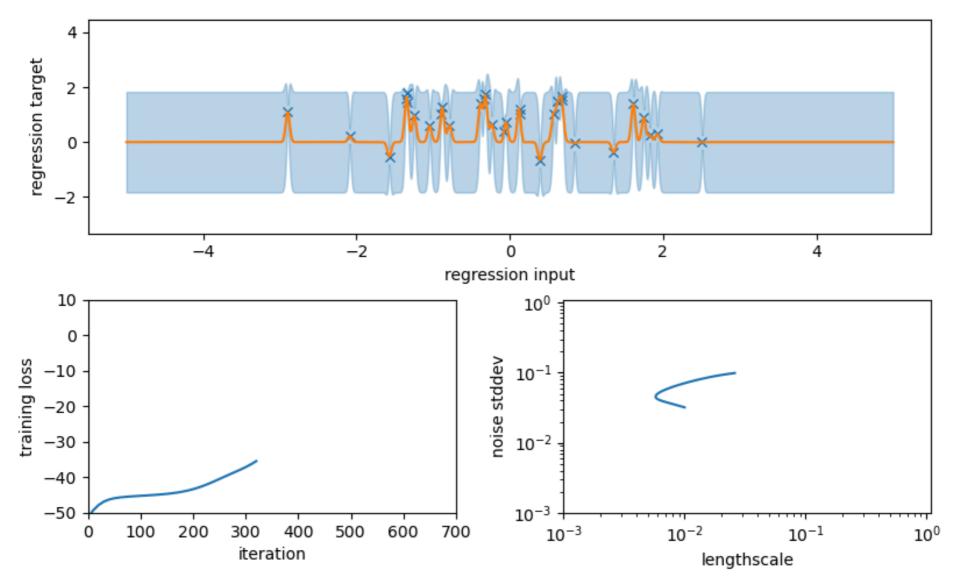


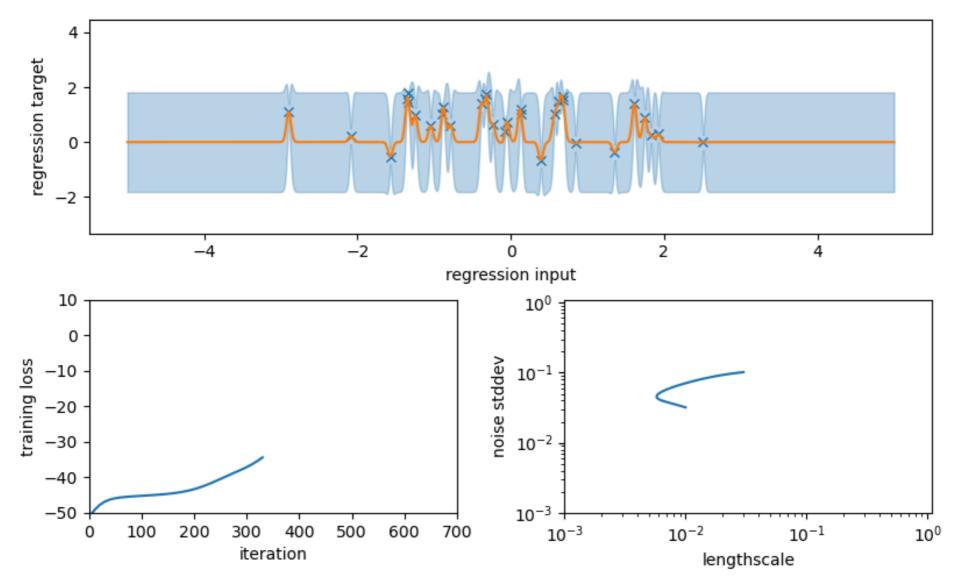


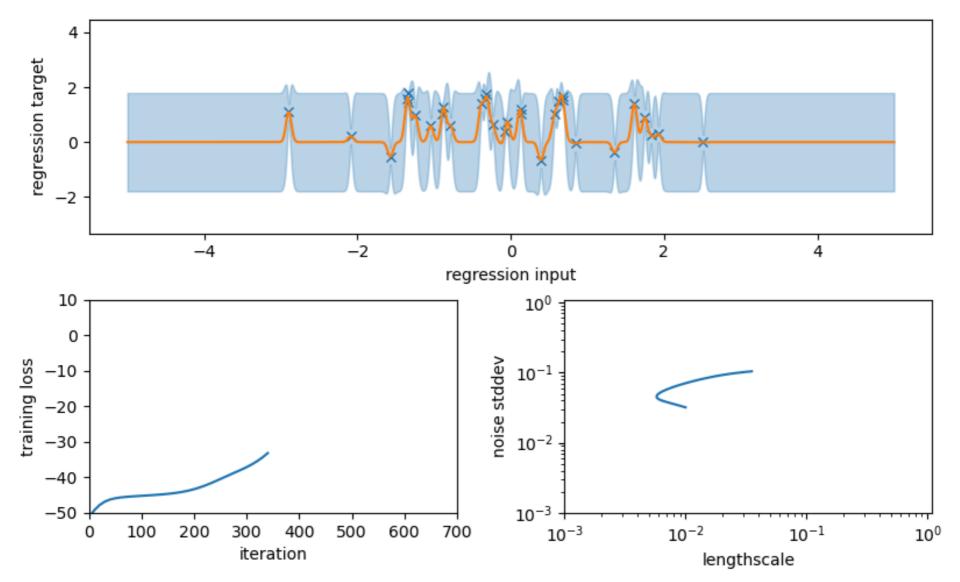


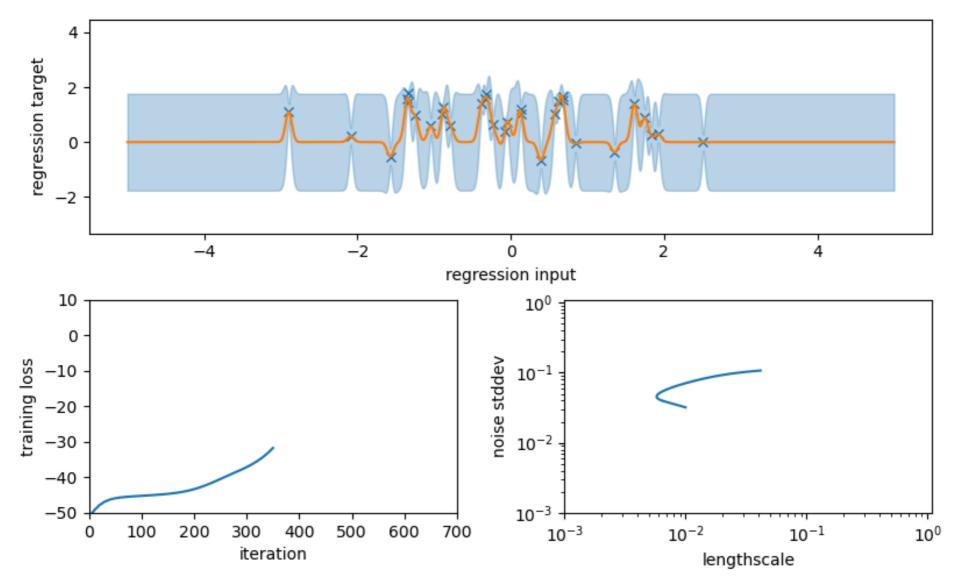


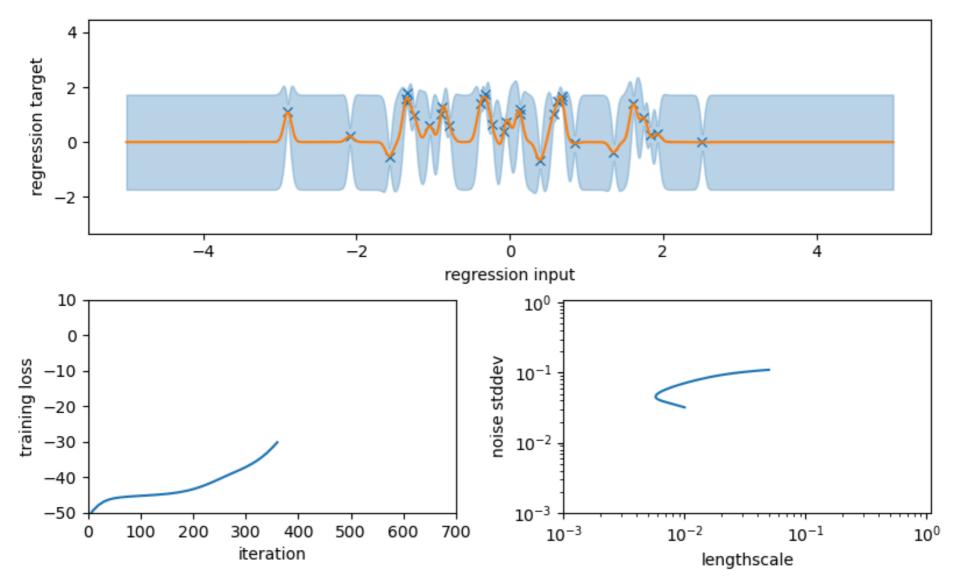


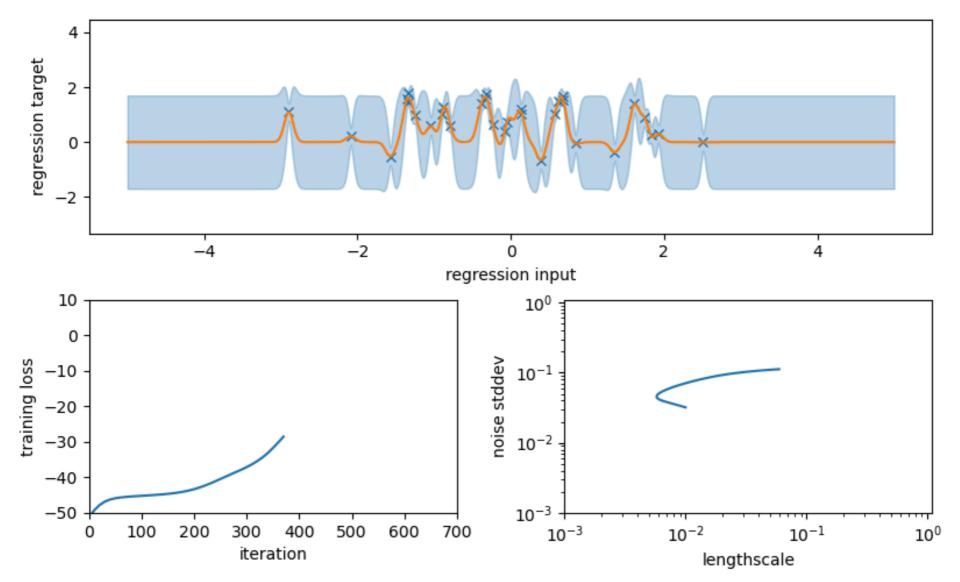


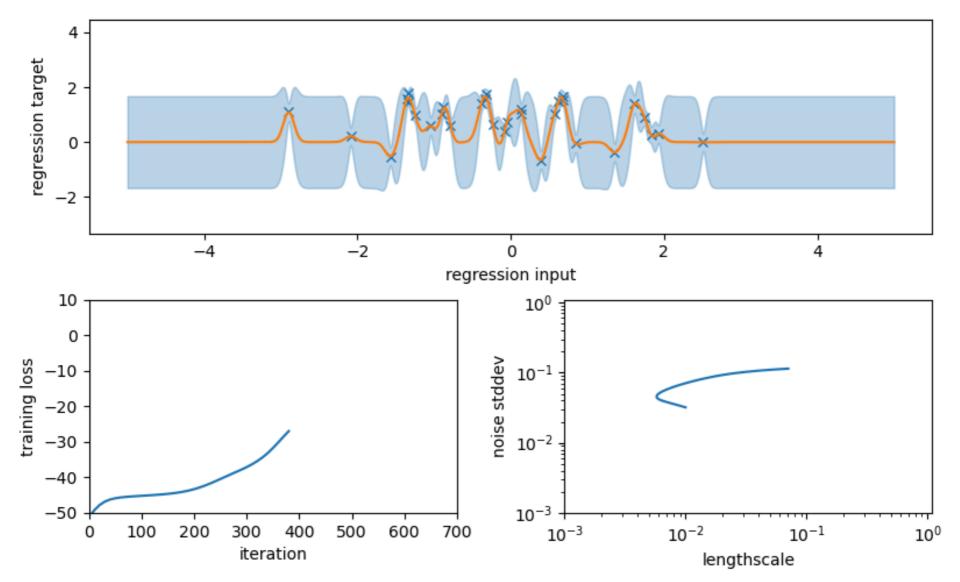


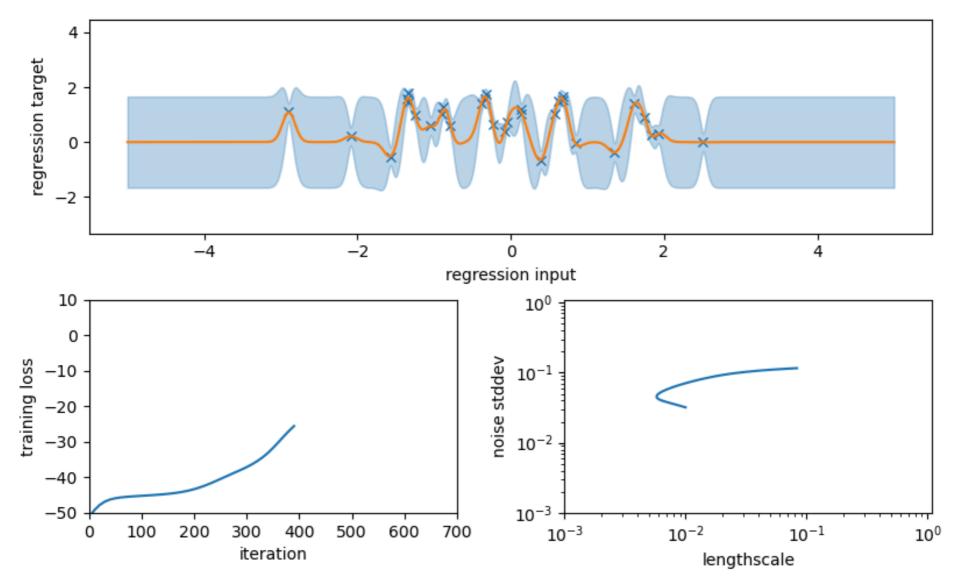


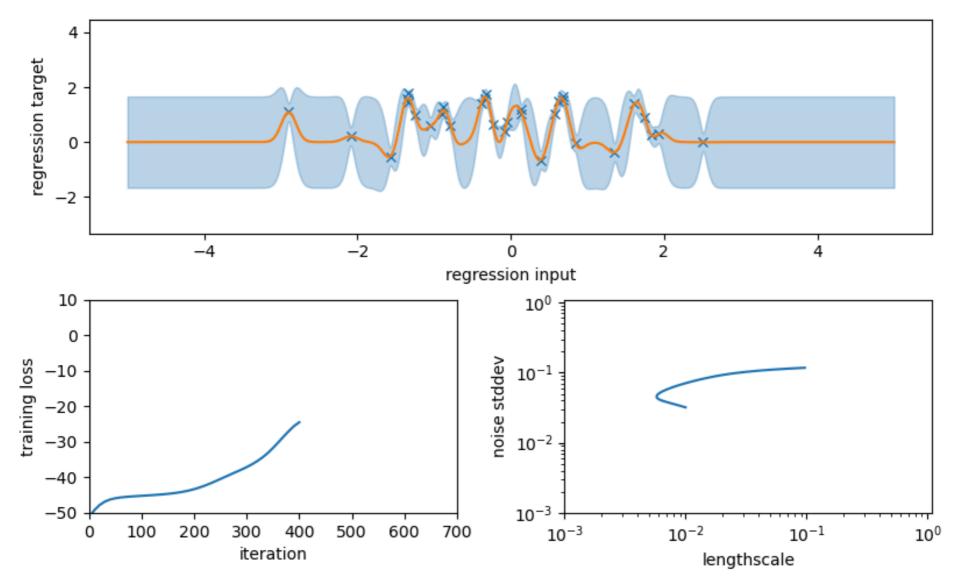


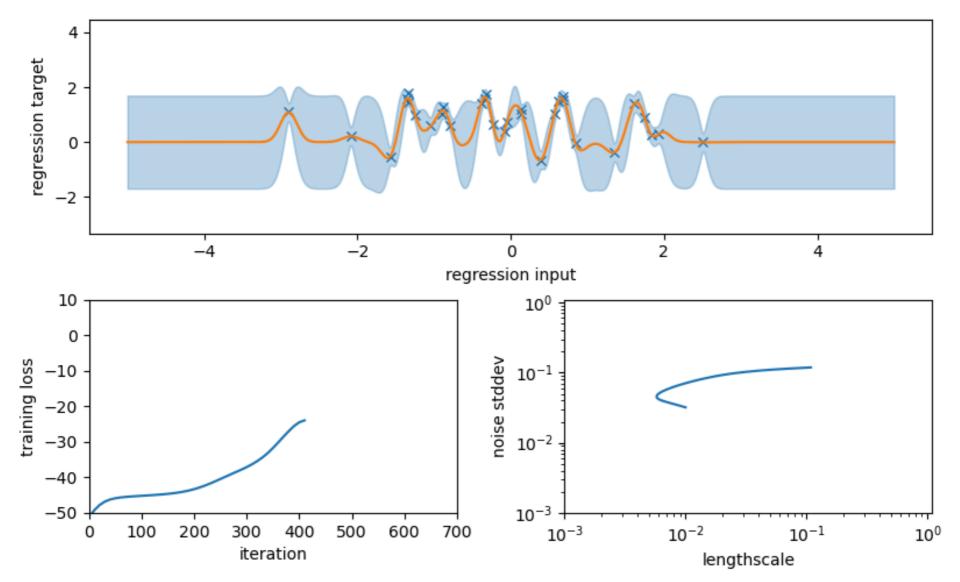


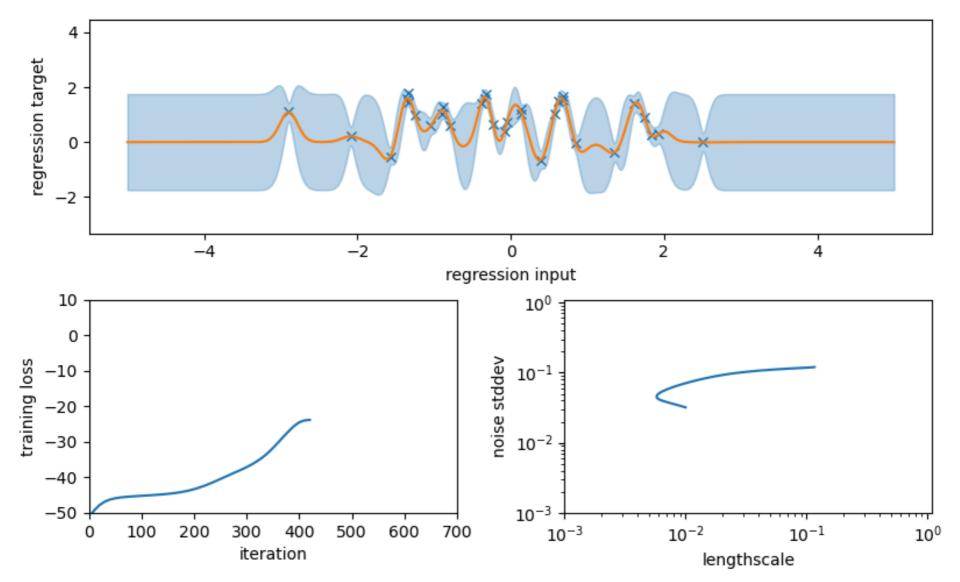


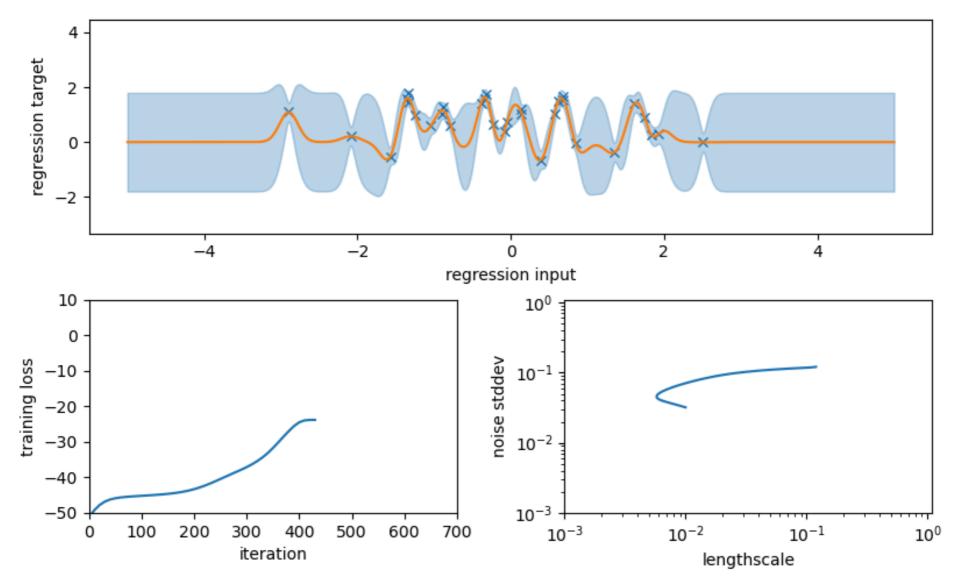


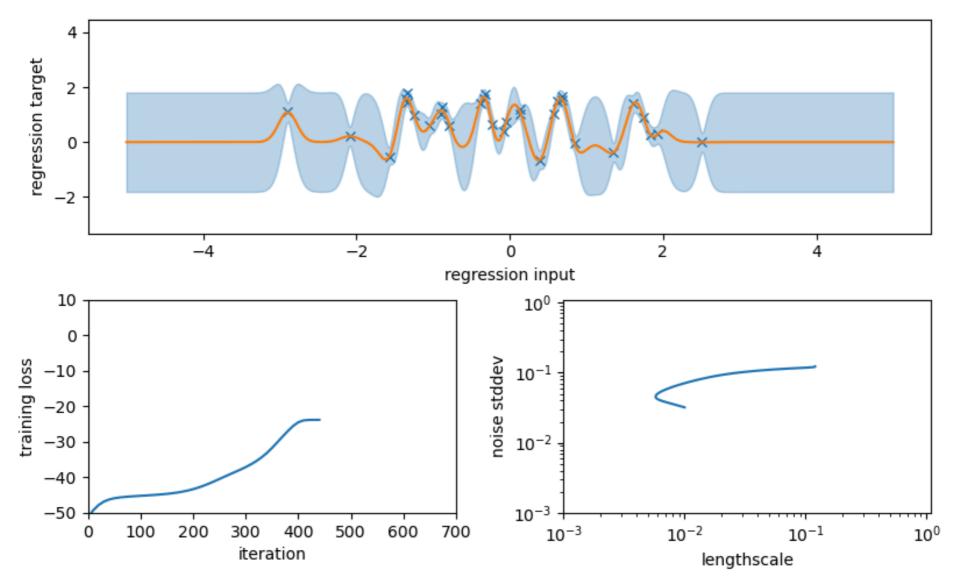


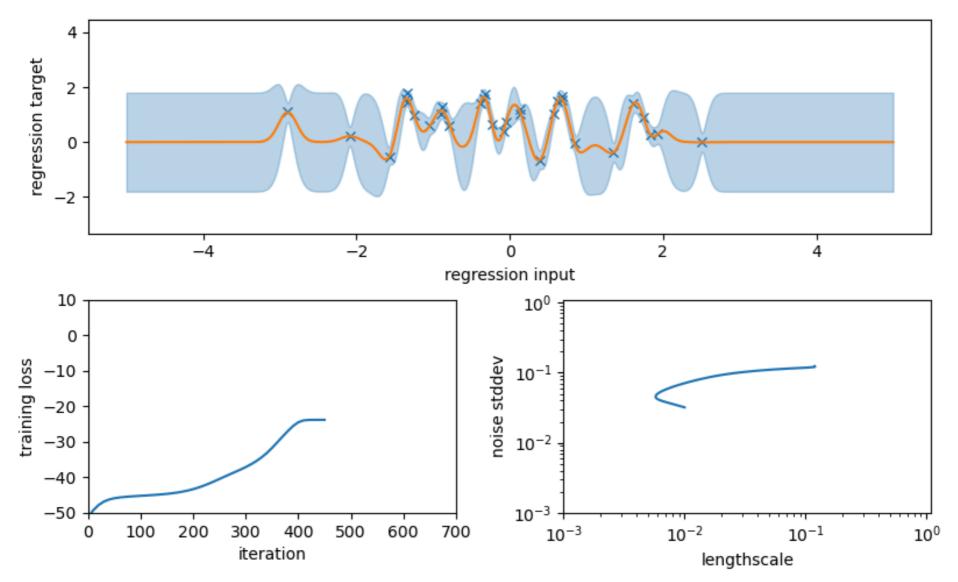


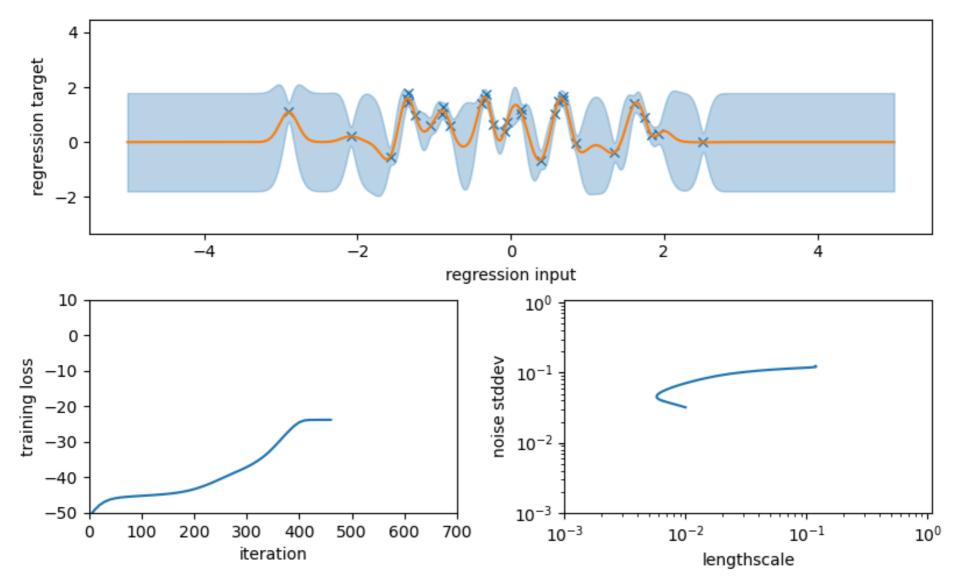


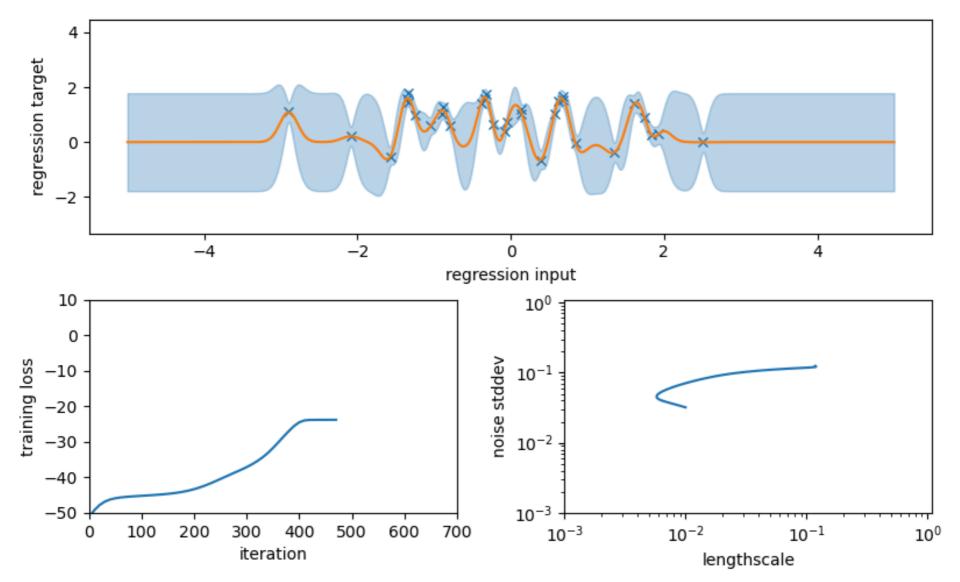


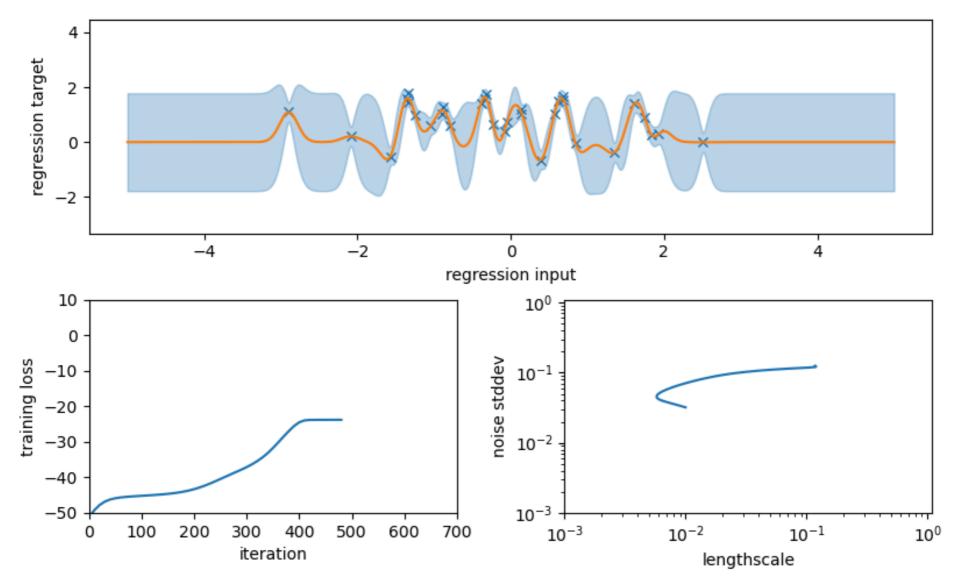


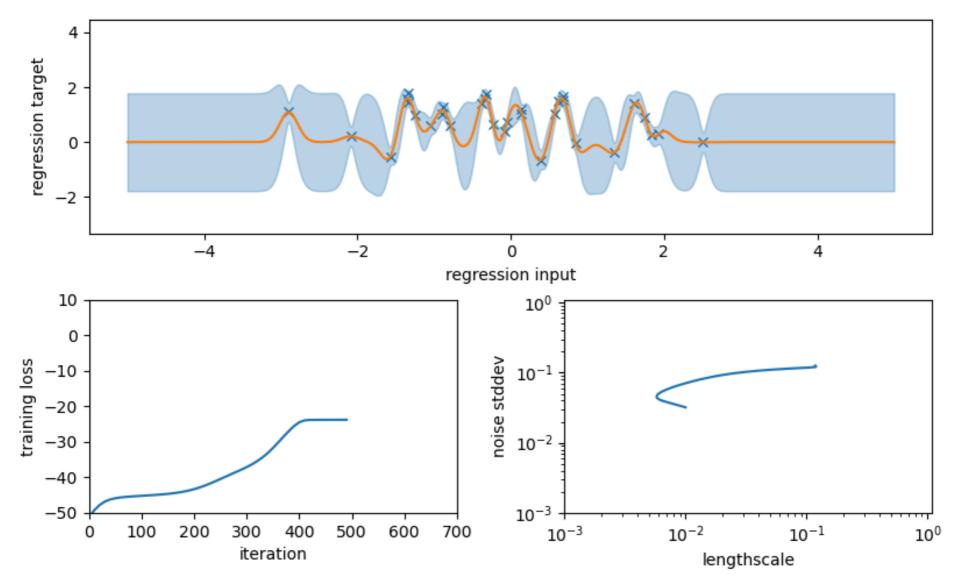


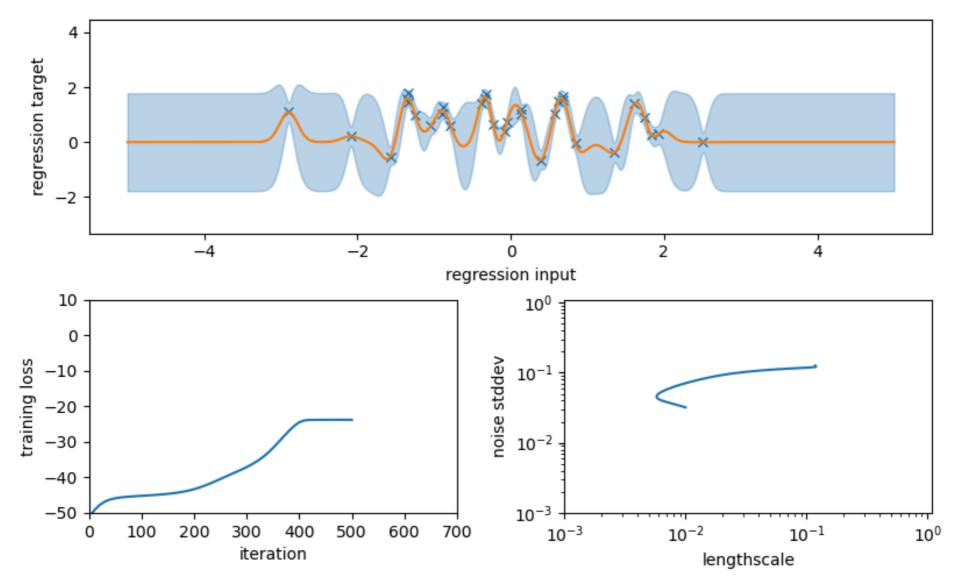


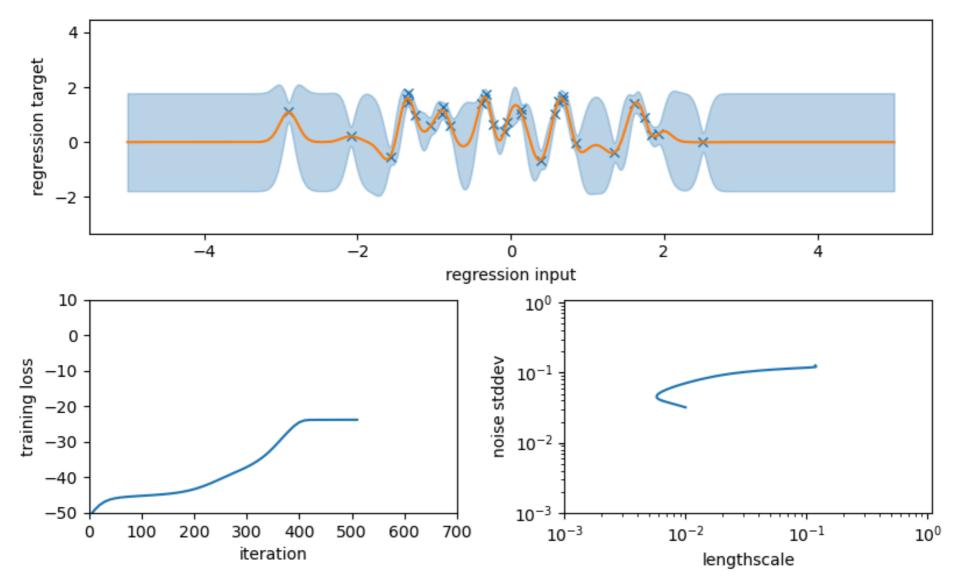


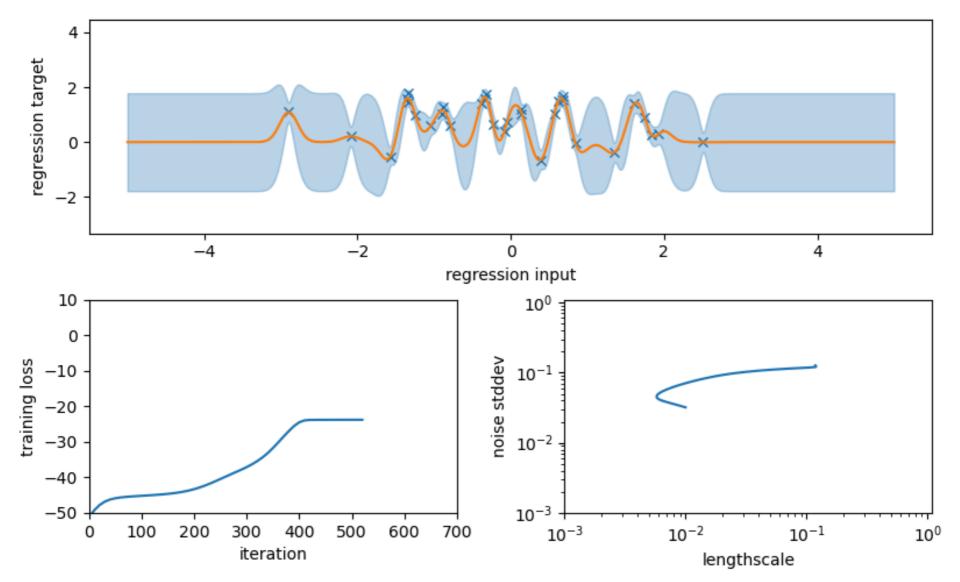


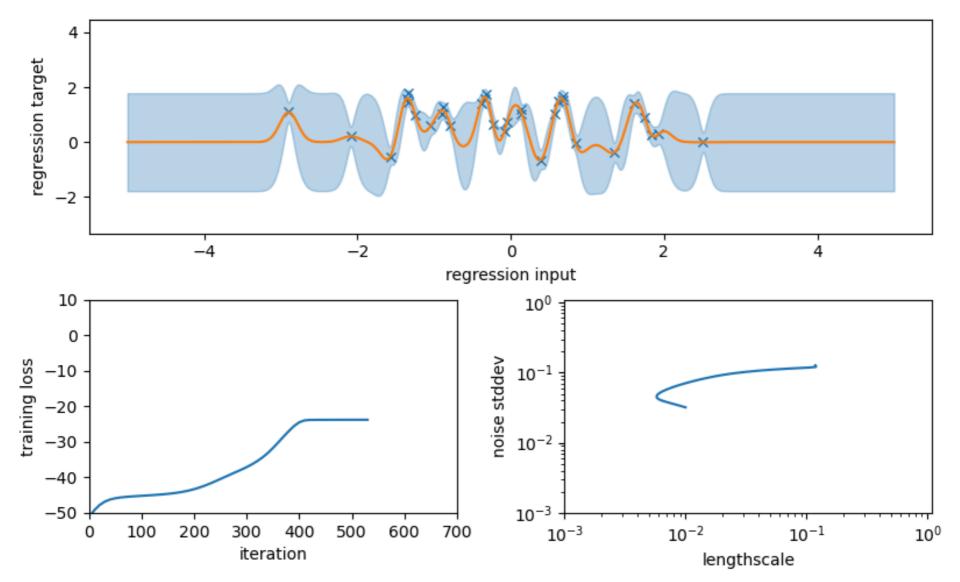


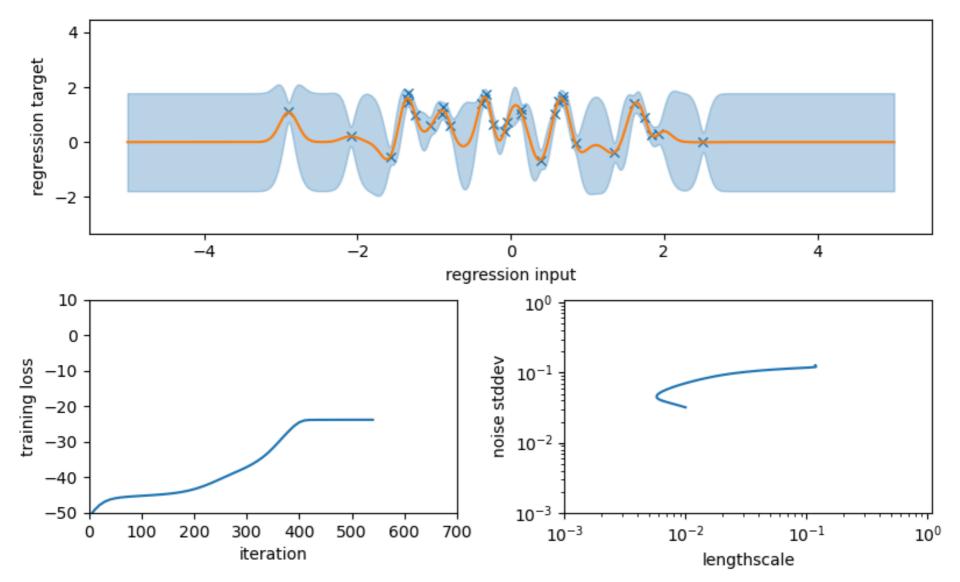


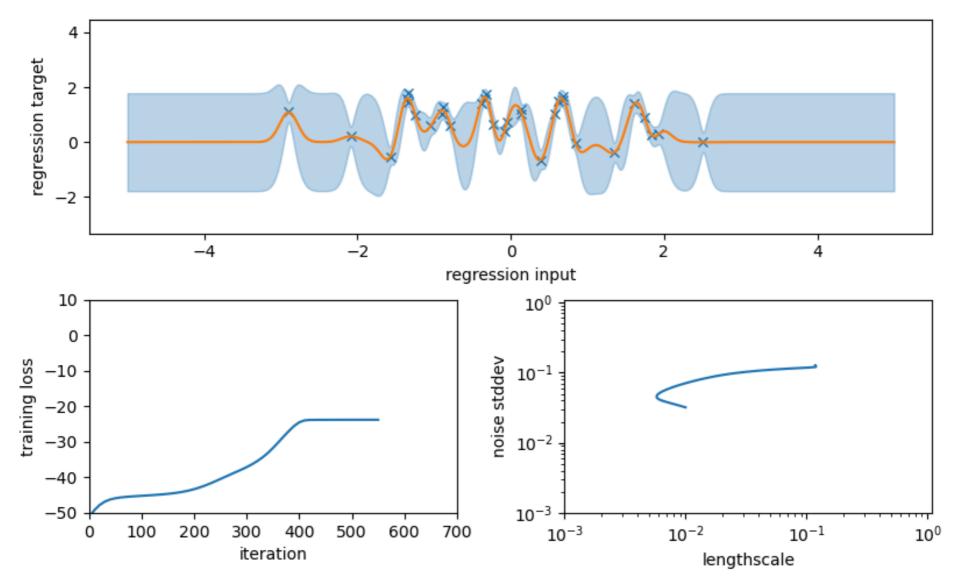


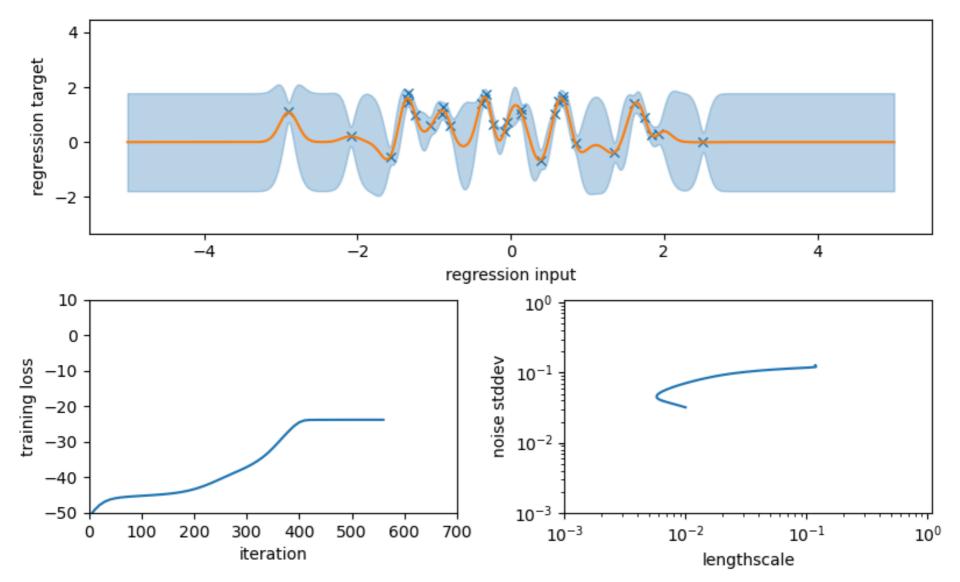


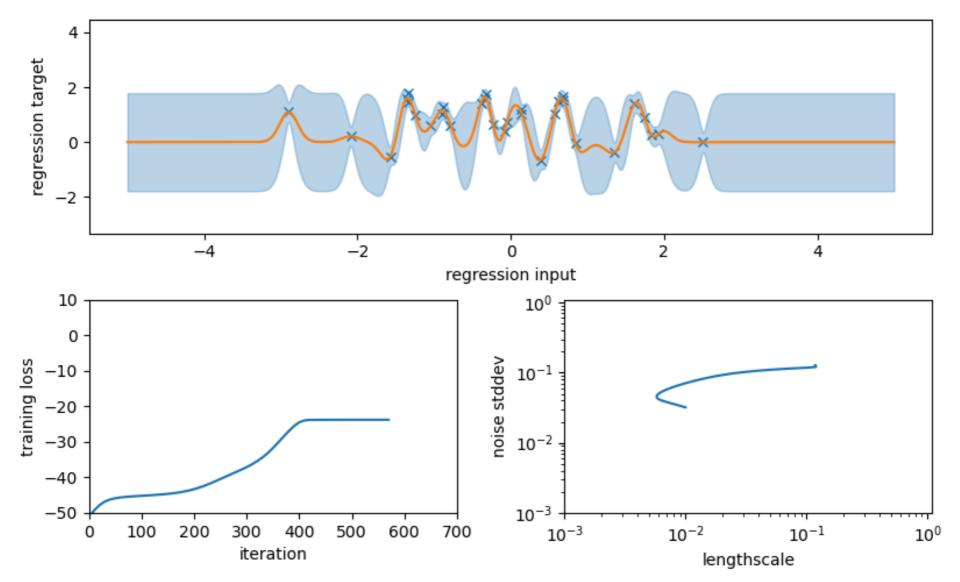


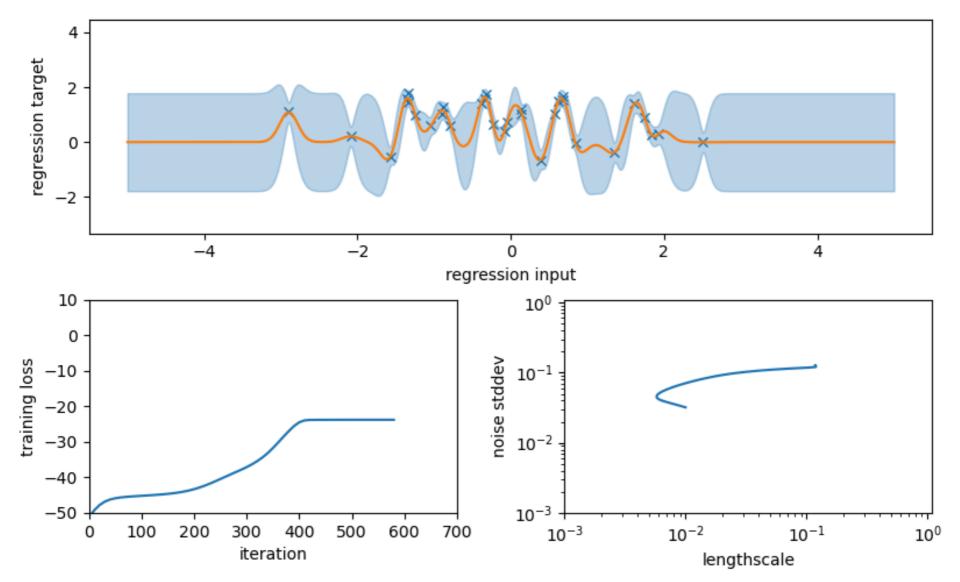


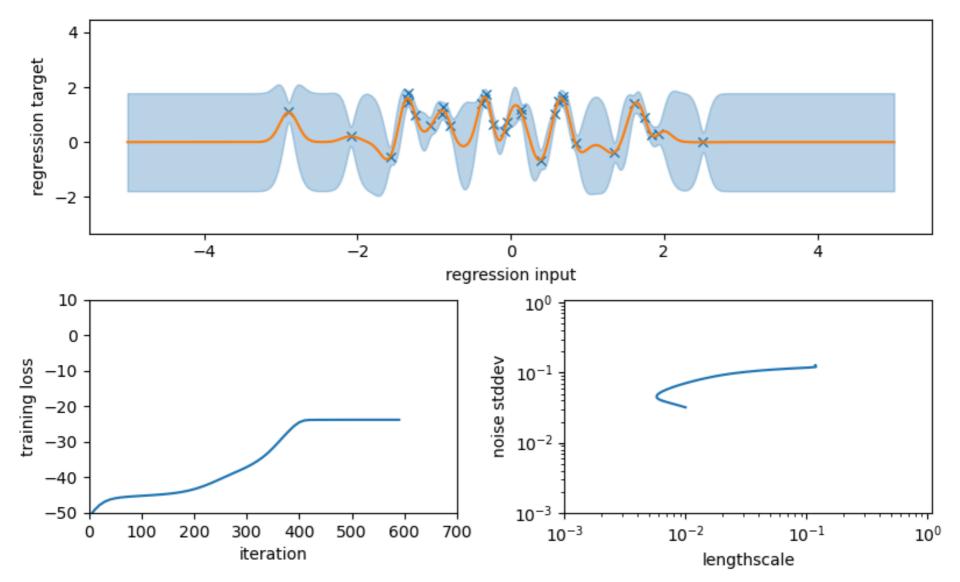


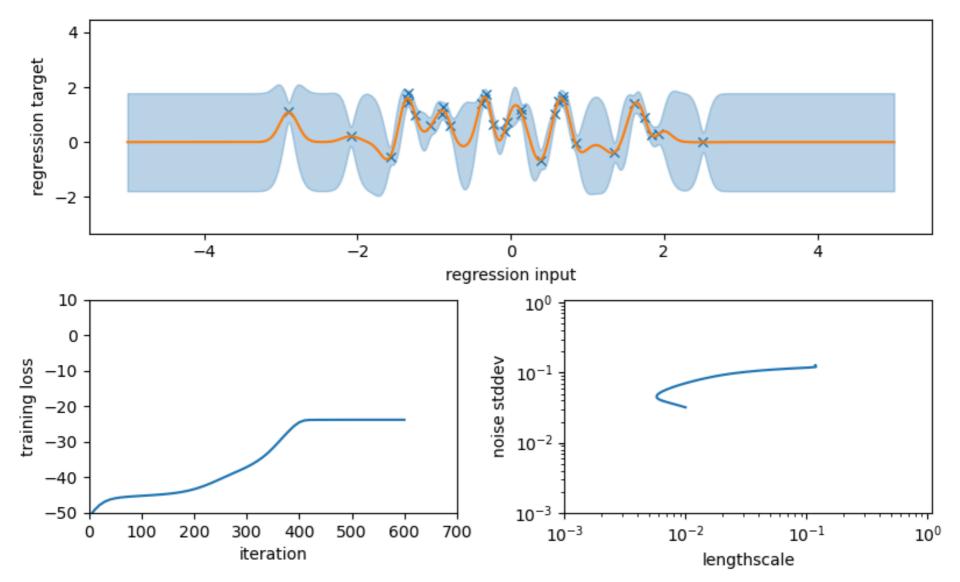


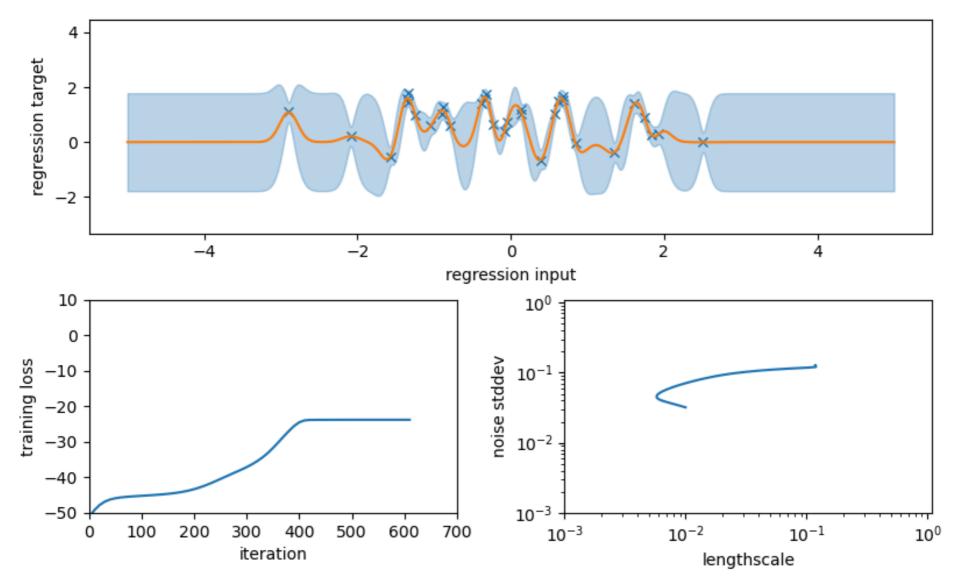


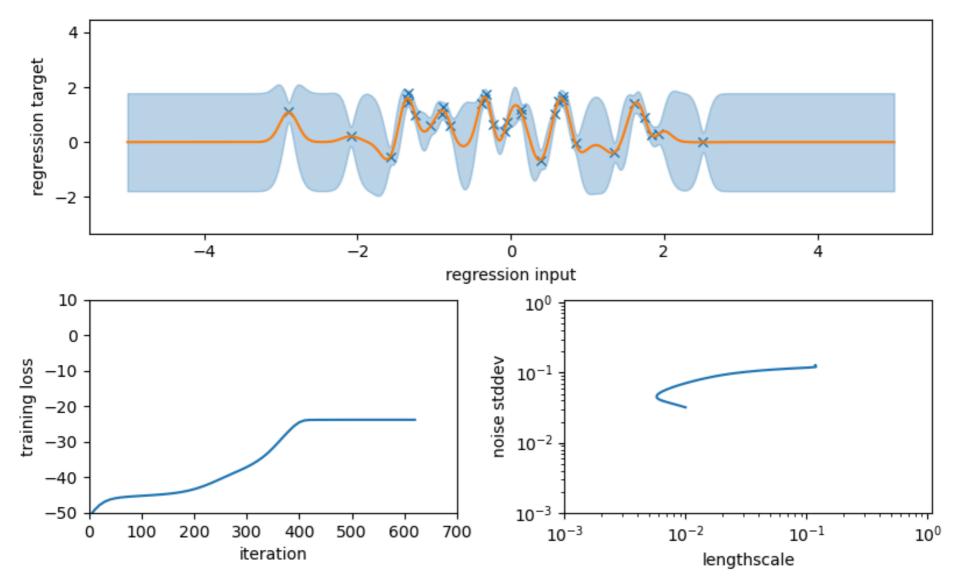


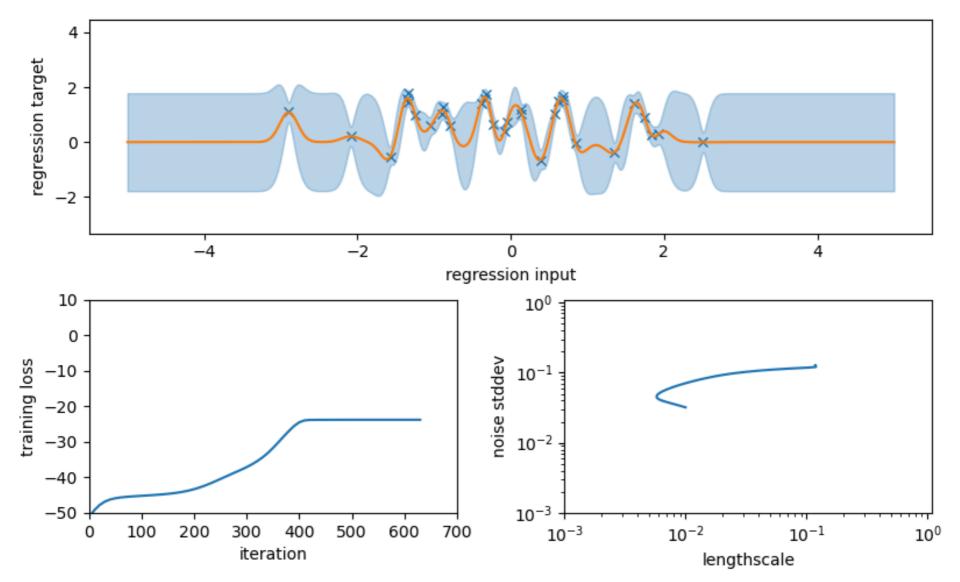


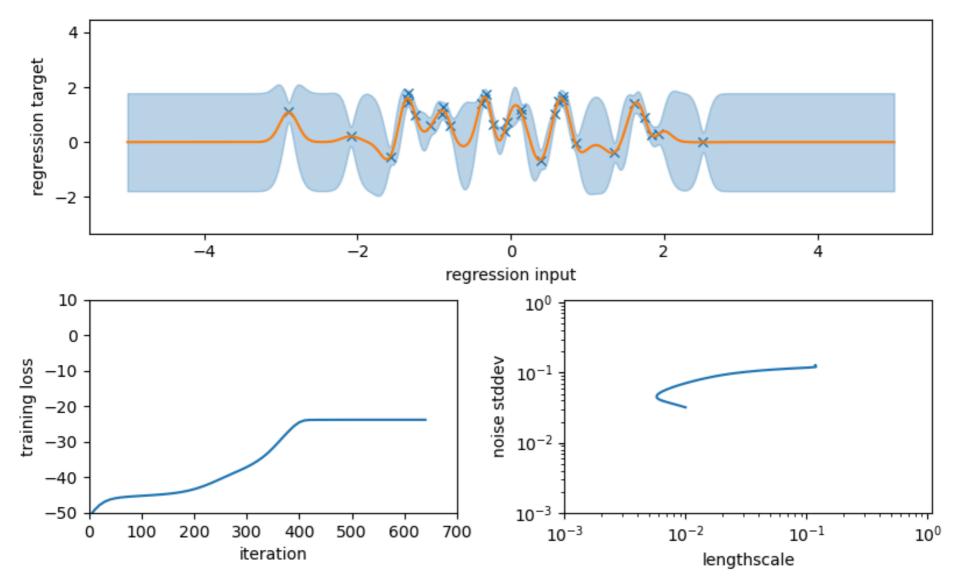


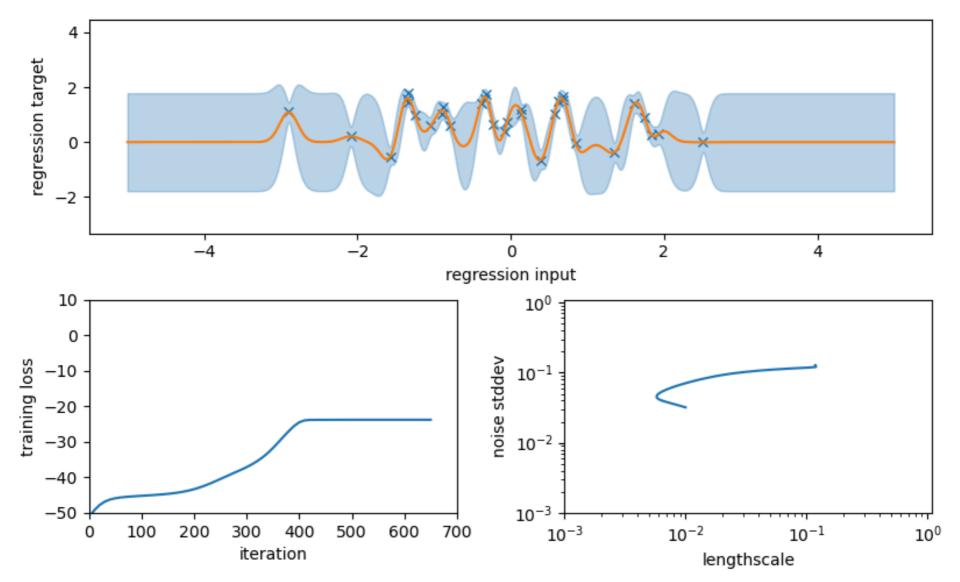


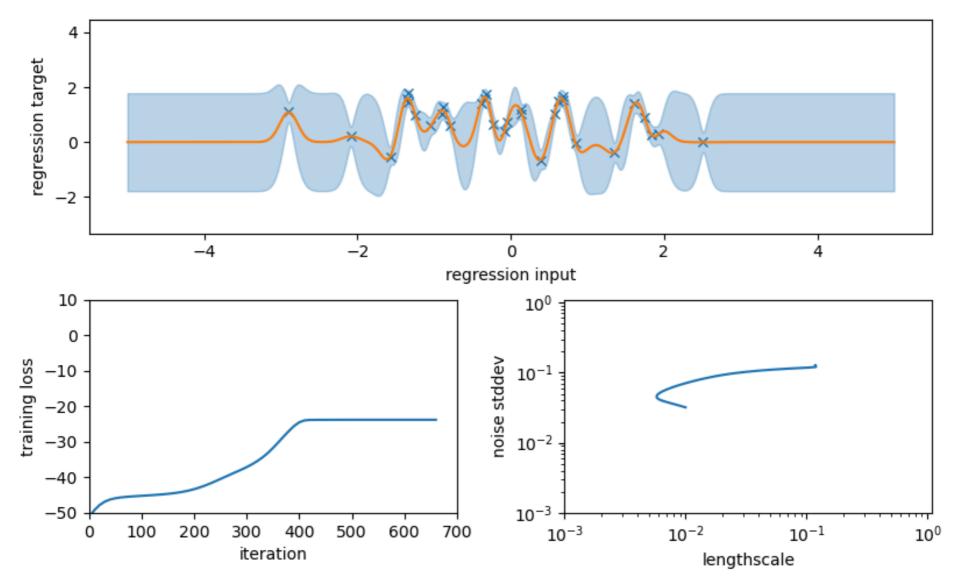


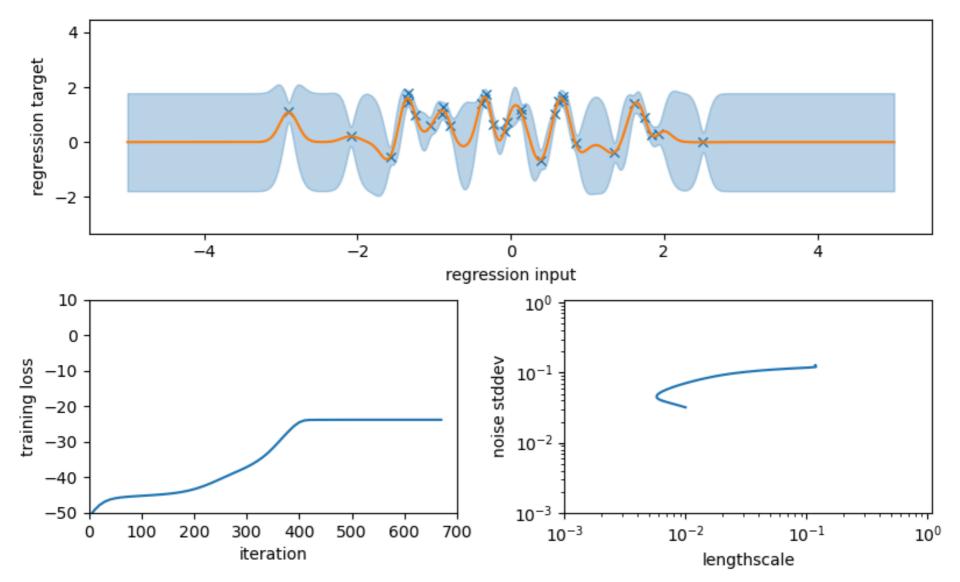


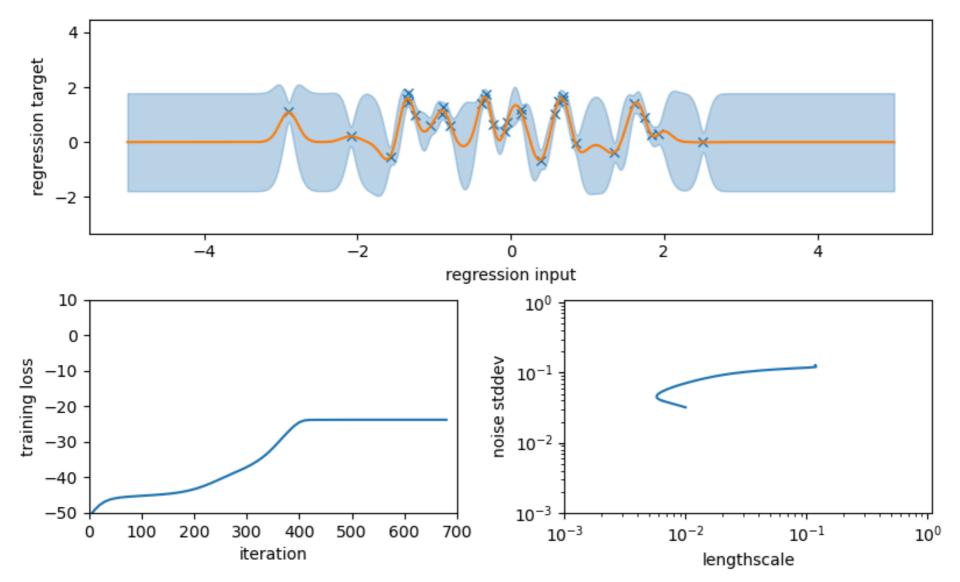












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- You may have noticed this was a Gaussian process.
- Interestingly, form of predictor is still single-layer NN:

$$f(x) = \sum_{m=0}^N \varphi(x; \theta, Z_m) w_m$$

 $\varphi(x;\theta,Z_m) = k_{\theta}(x,X_m)$ $\boldsymbol{w} = (K(X,X) + \sigma^2 I)^{-1} \boldsymbol{y}$

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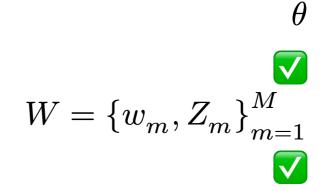
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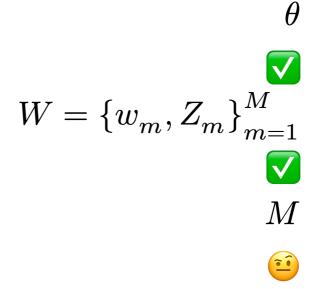
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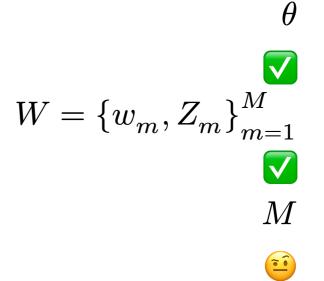
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\land Our model grows, but by memorising *all* data!

- 1. What is wrong with minimising losses.
- 2. Bayesian Model Selection?

2. The Bayesian answer to model size: Nonparametrics.

3. A principle for selecting size

We stumbled into using "large" models, but *why* do we use nonparametric models?

Classic arguments:

1. 2.

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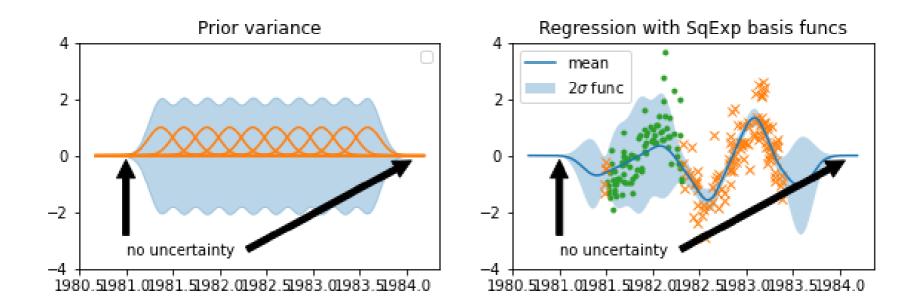
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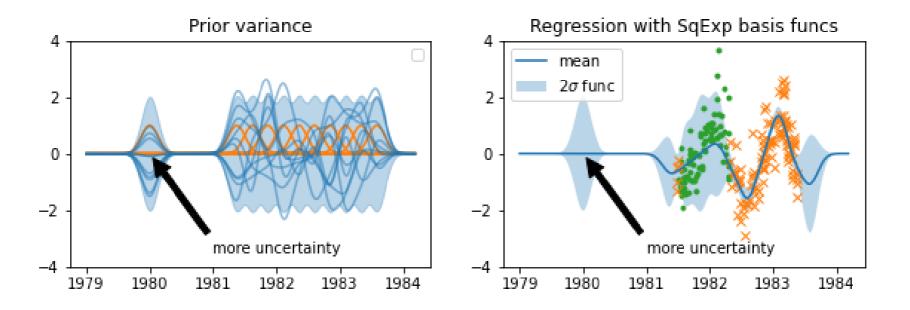
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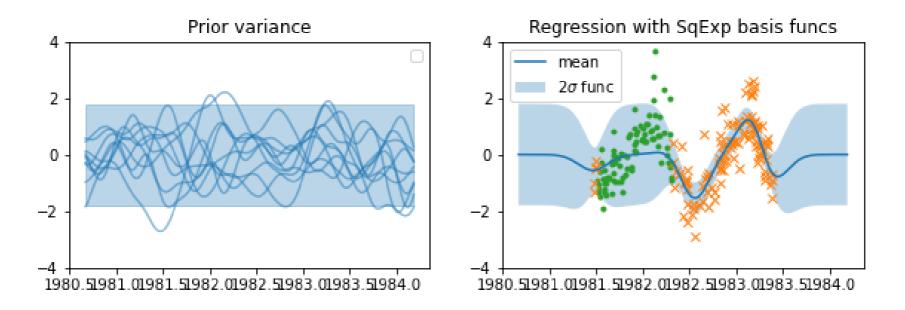


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We could do model selection over the model size...

$$\begin{split} p(W,\theta,M|\mathcal{D}) &= \frac{p(\mathcal{D}|W,\theta,M)p(W|\theta,M)}{p(\mathcal{D}|\theta,M)} \frac{p(\mathcal{D}|\theta,M)p(\theta)}{p(\mathcal{D})}\\ \theta^*, M^* &= \operatorname*{argmax}_{\theta,M} \log p(\mathcal{D}|\theta,M) \end{split}$$

1.

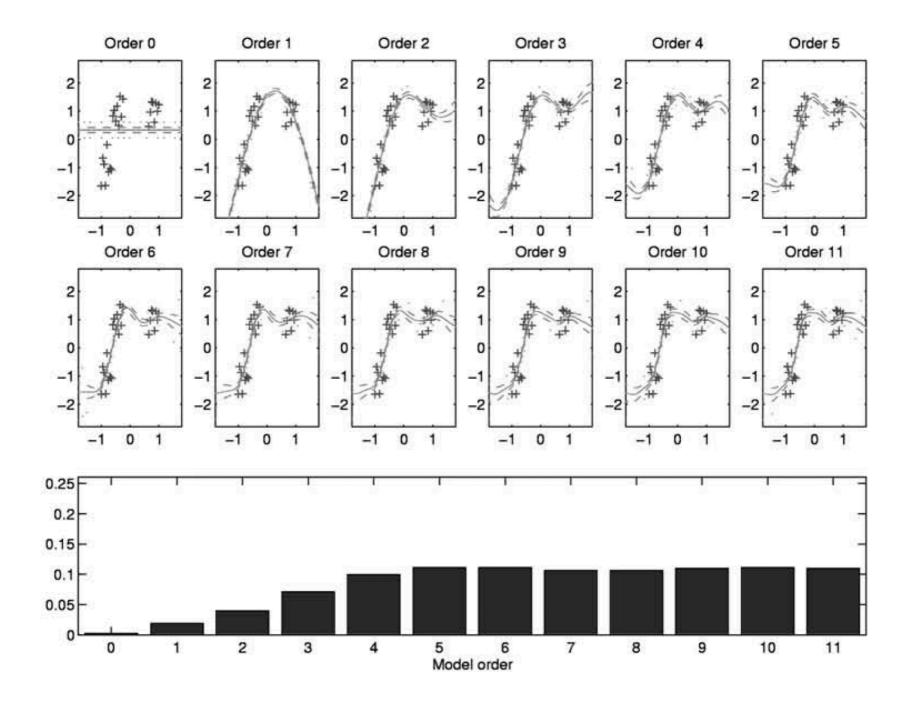
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 Bayes doesn't even distinguish between models of different sizes!

See *Occam's Razor* (Rasmussen & Ghahramani, 2000). One of my favourite papers.



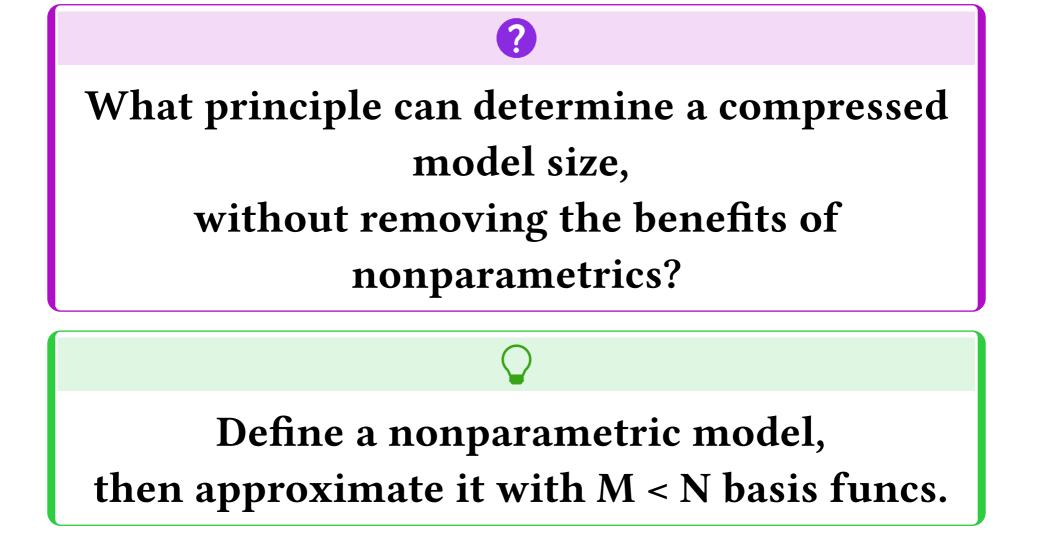
Bayes selects a nonparametric model!

- Bayes itself is pushing us to use "large" nonparametric models!
- Cannot rely on Bayes to choose a "small" model!

- 1. What is wrong with minimising losses?
- 2. Bayesian Model Selection
- 2. Model Selection over Model Size? Or Nonparametrics?
- 3. A Principle for Selecting Model Size

What principle can determine a compressed model size, without removing the benefits of nonparametrics?

?



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Since KL > 0... ELBO $\leq \log p(\mathcal{D}|\theta)$.

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i ELBO is a *unified objective* for all our questions!

- Optimising w.r.t. w, Z: finds weights (min KL)
- Optimising w.r.t. θ : finds hyperparameters (max $\log p(\mathcal{D}|\theta))$
- Select M large enough, that more gives diminishing returns!

More basis functions is always better:

 $\mathrm{KL}\big[q_{M+1}(f) \parallel p(f|\mathcal{D},\theta)\big] \leq \mathrm{KL}[q_M(f) \parallel p(f|\mathcal{D},\theta)]$

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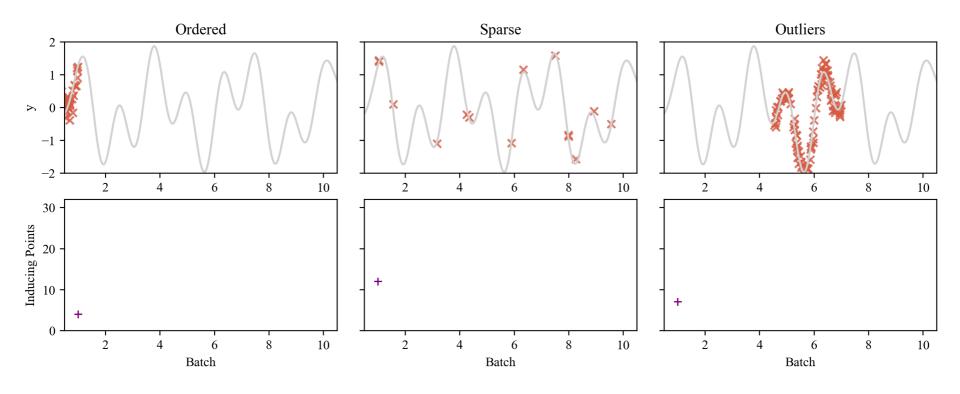
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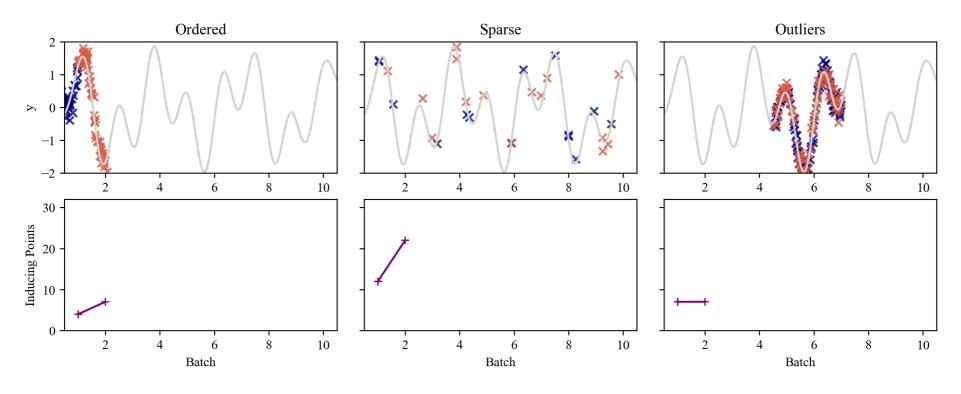
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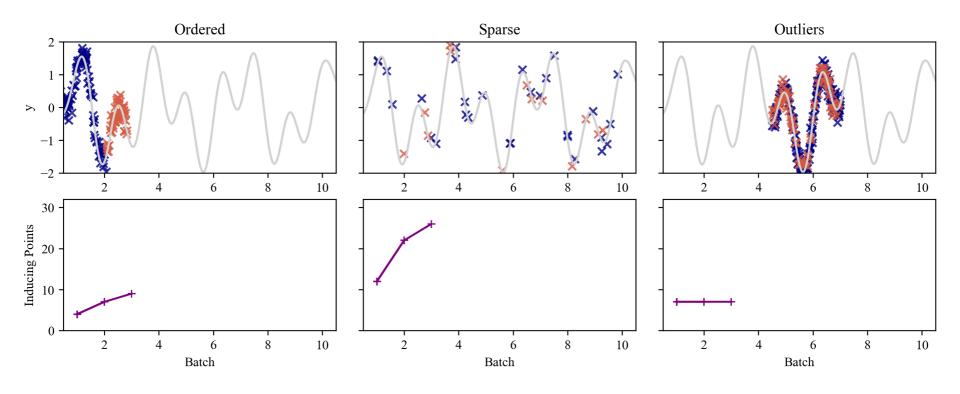
i) Simple Rule, Interesting Adaptive Behaviour!



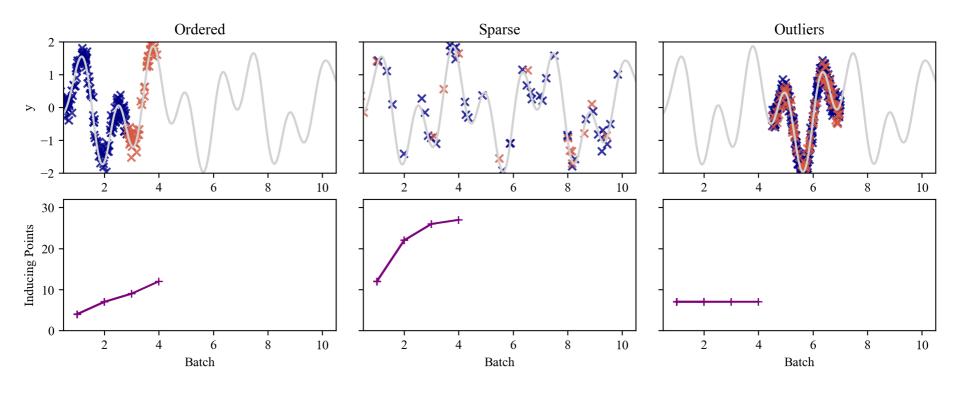
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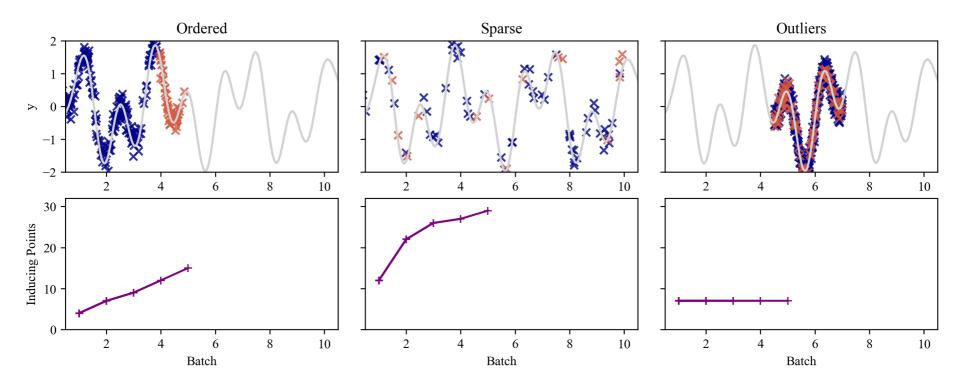
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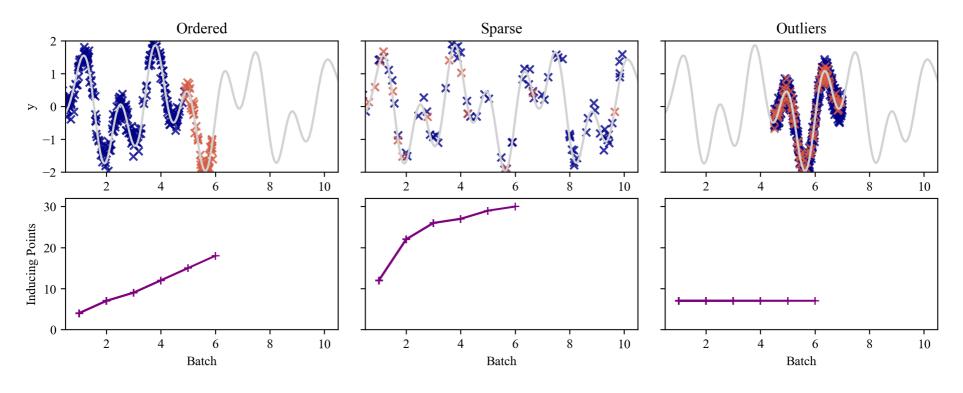
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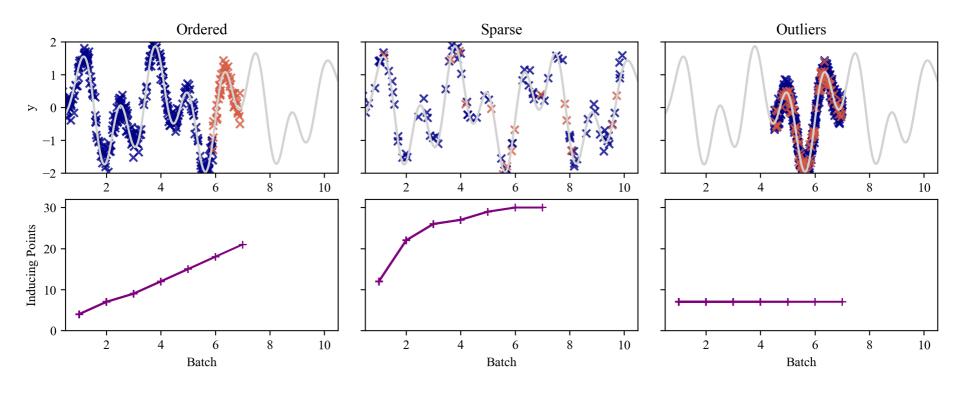
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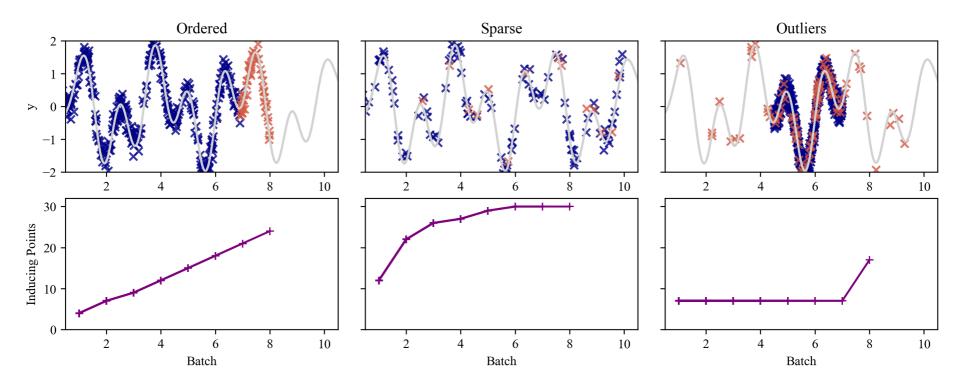
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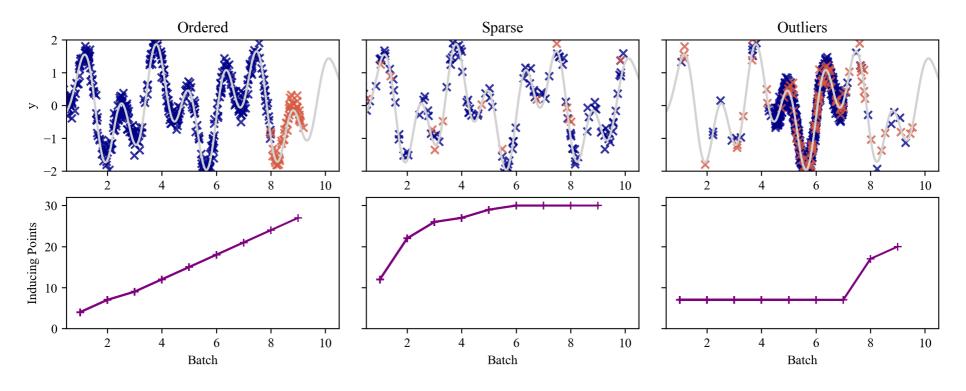
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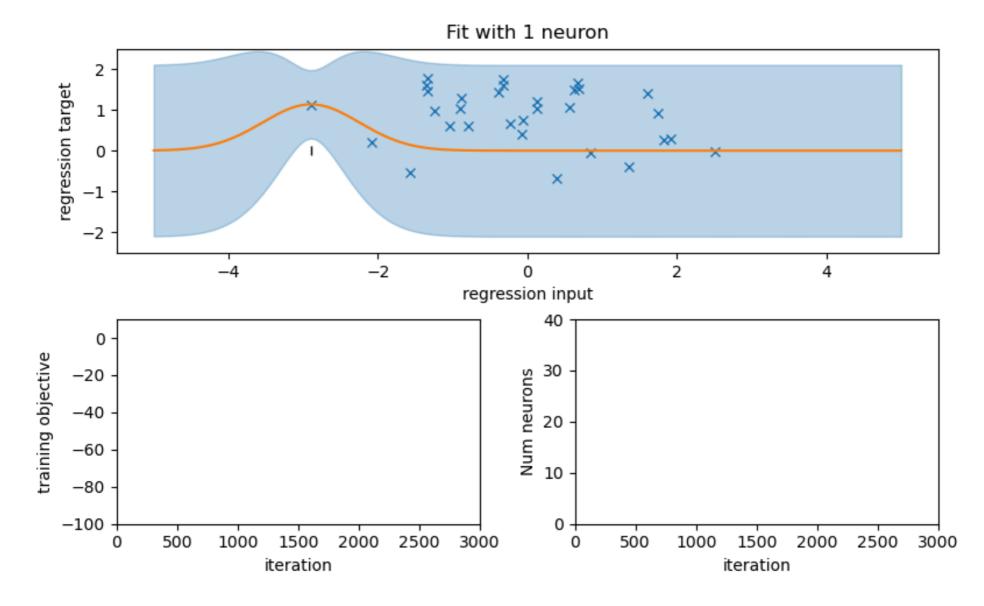
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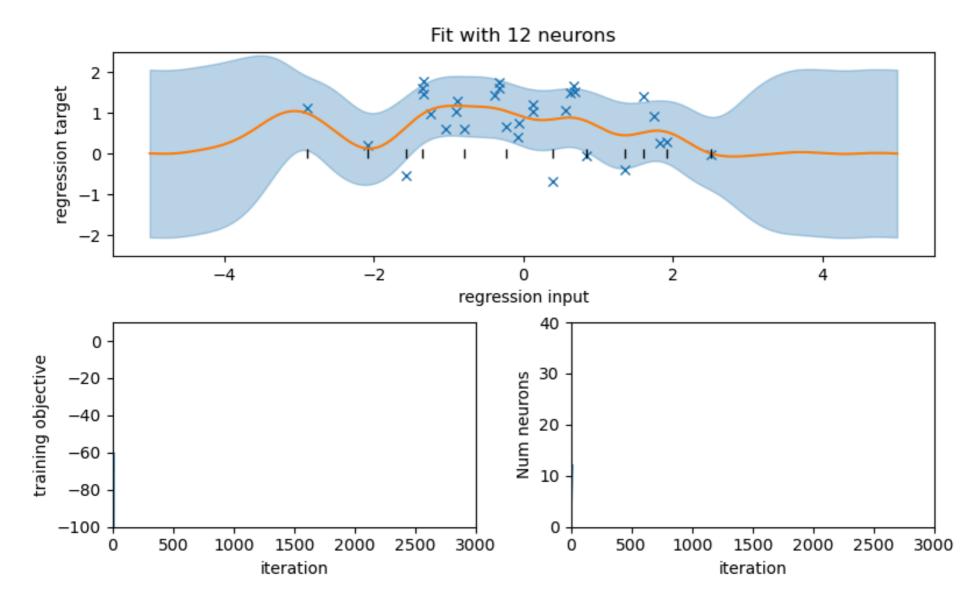


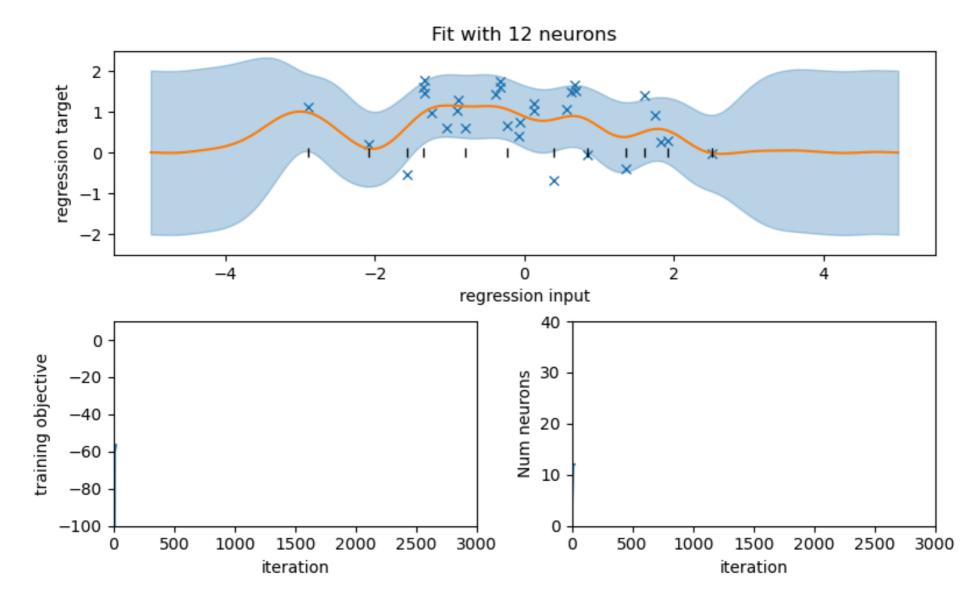
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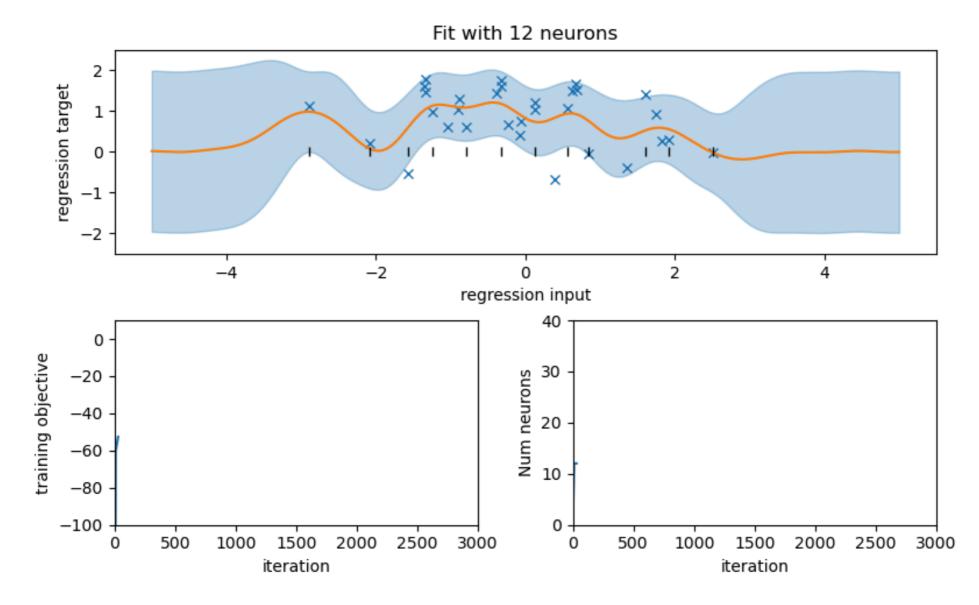


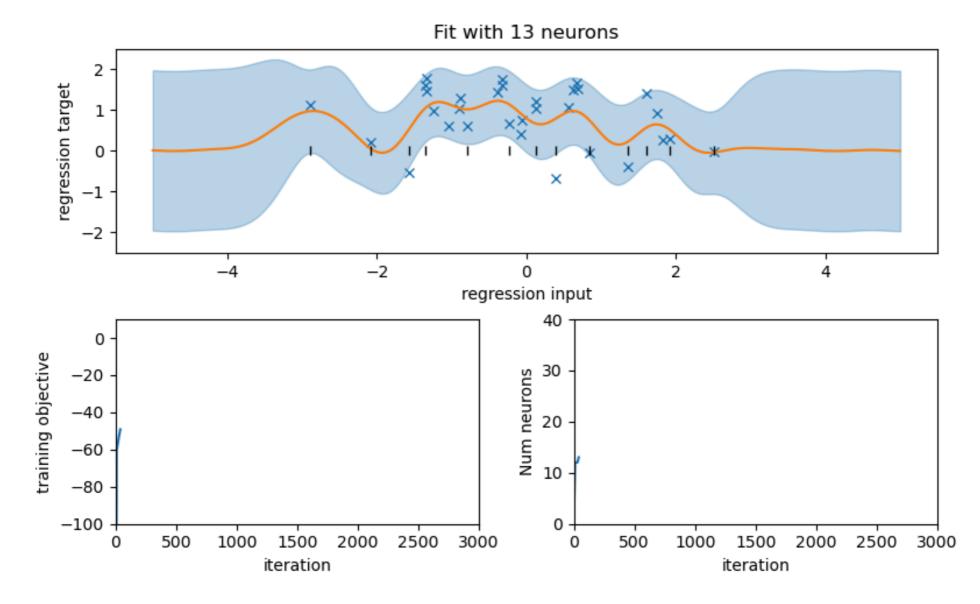
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- Heavy tailed inputs (occasional novelty)

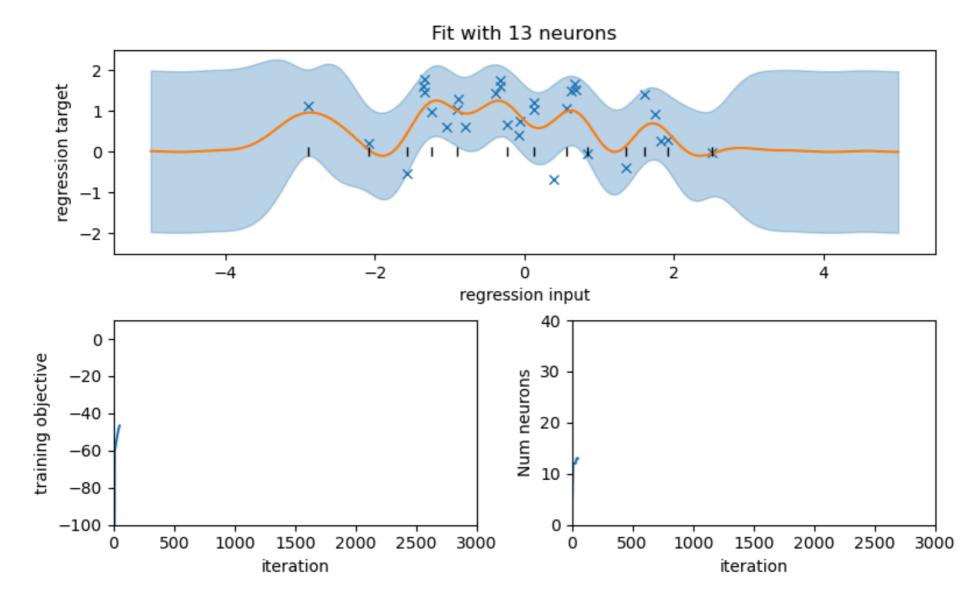


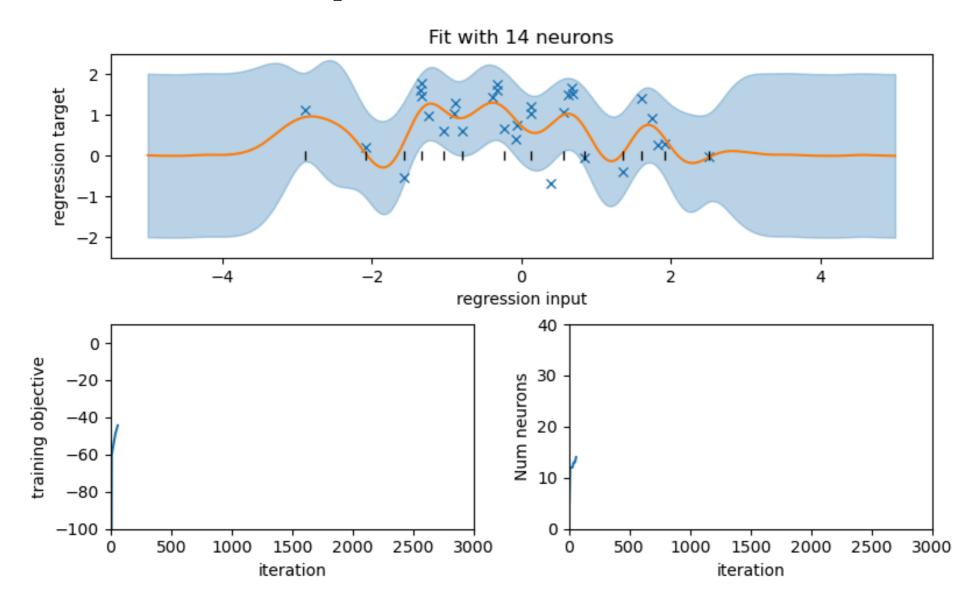


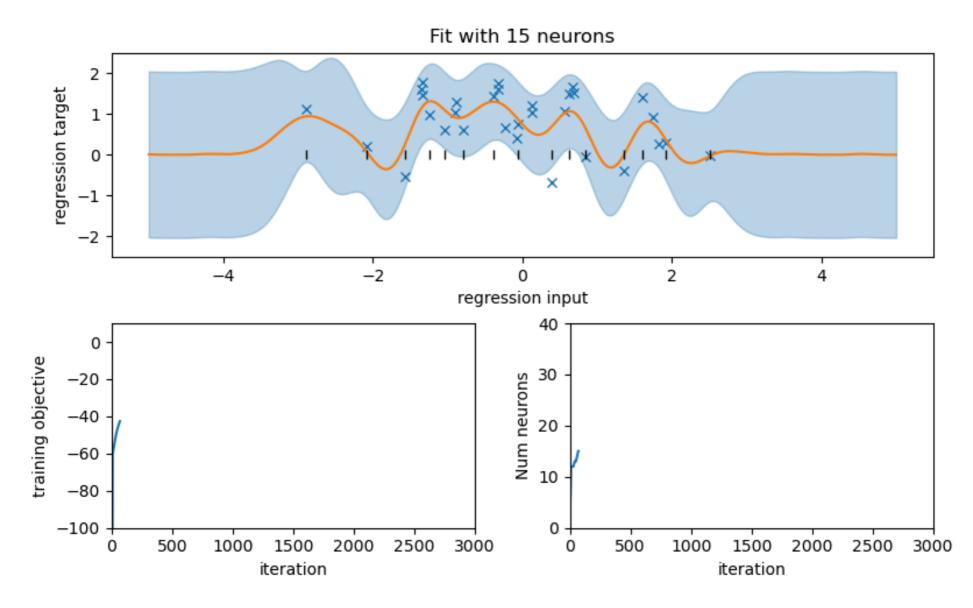


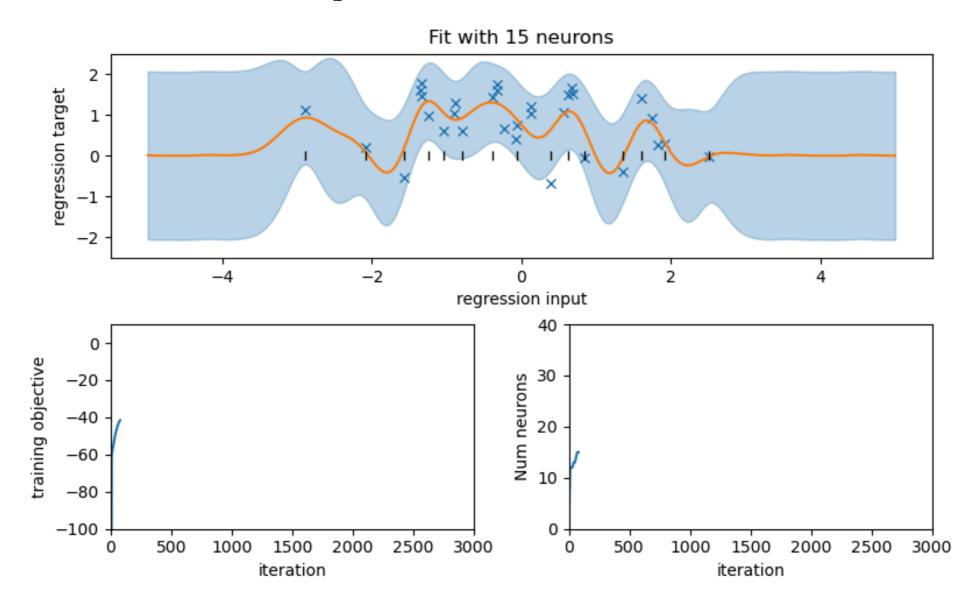


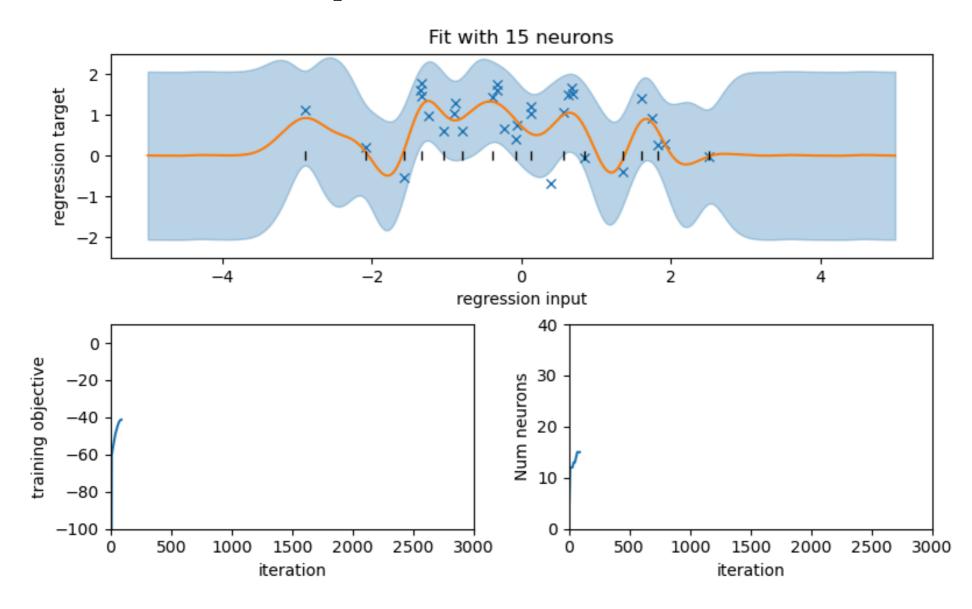


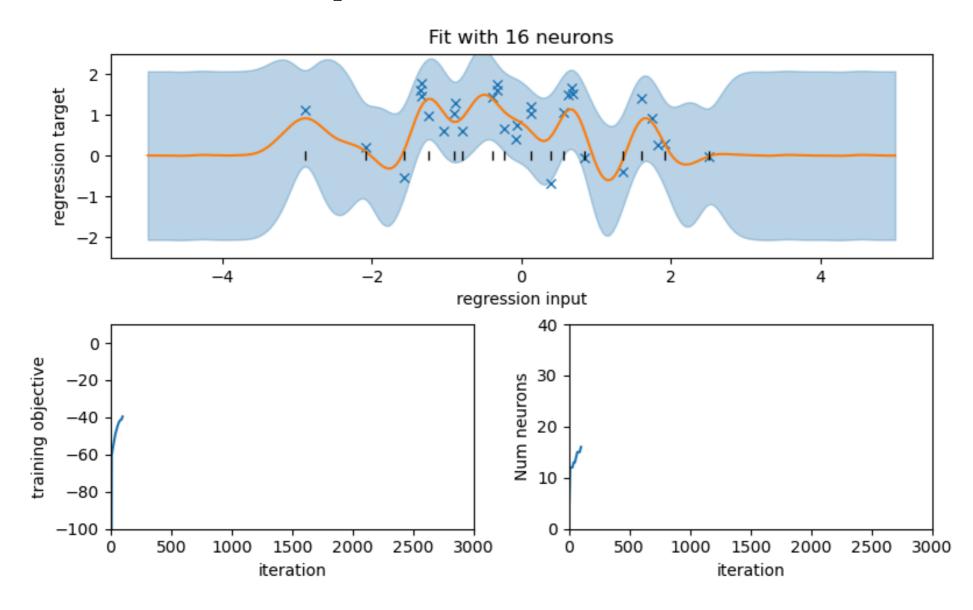


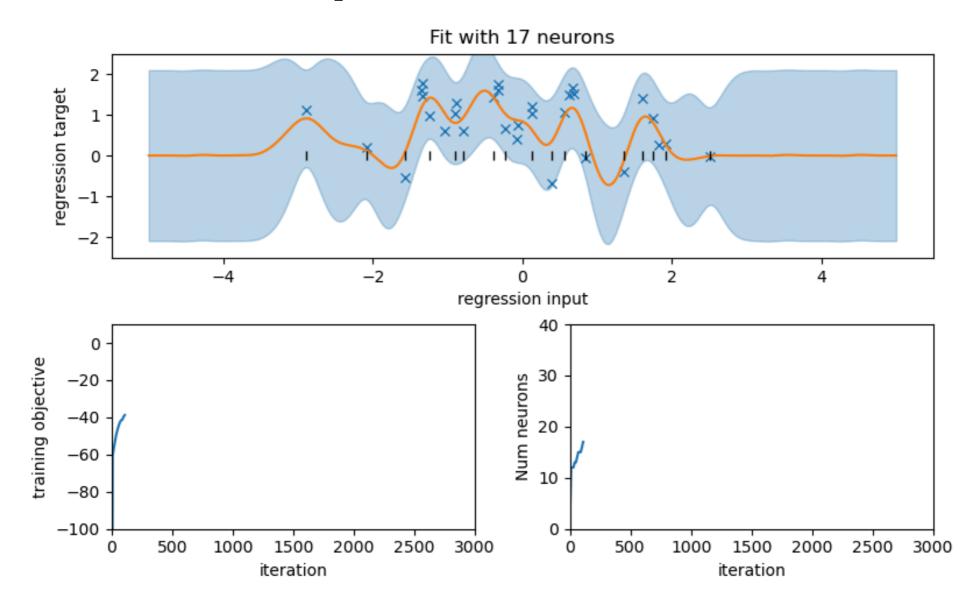


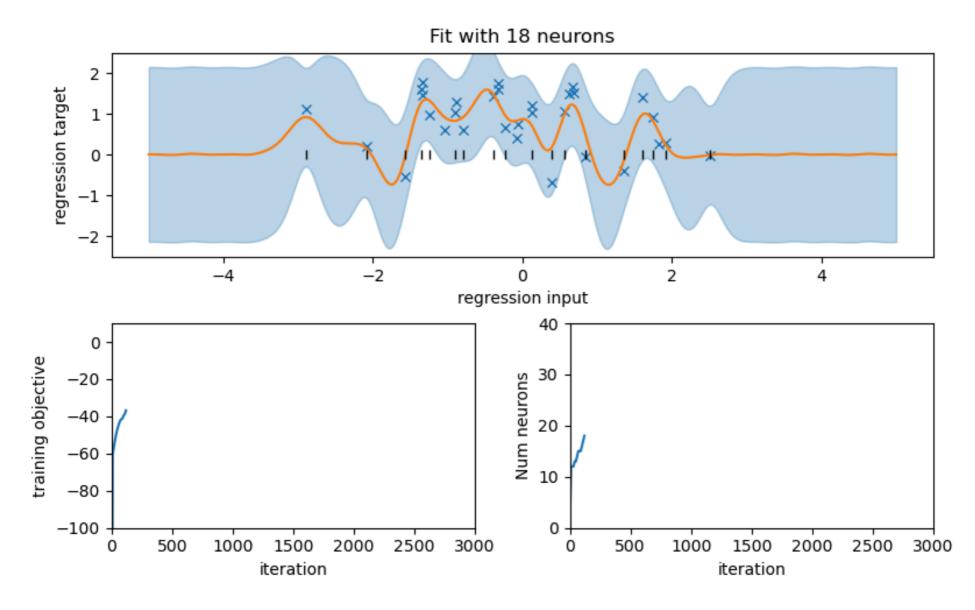


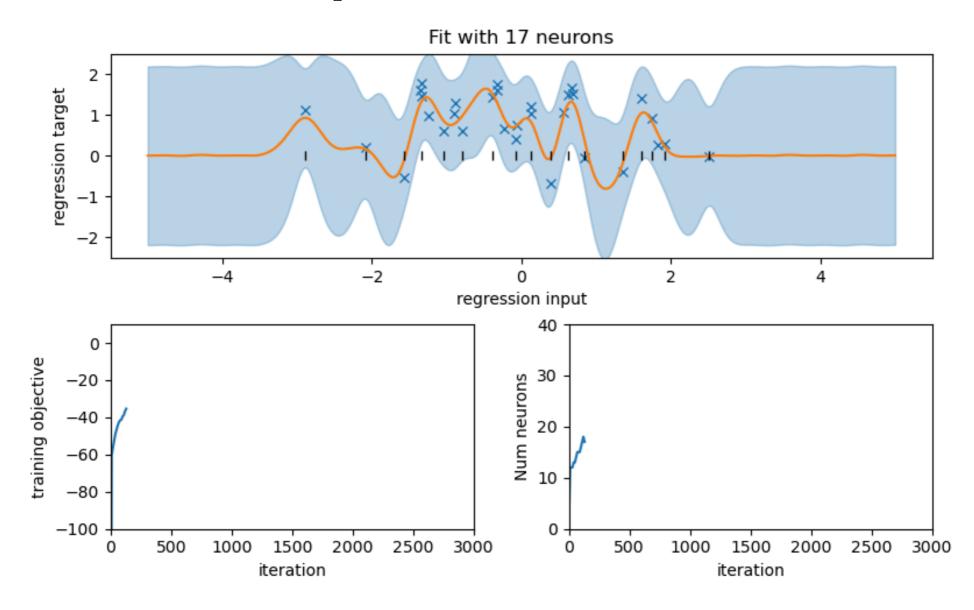


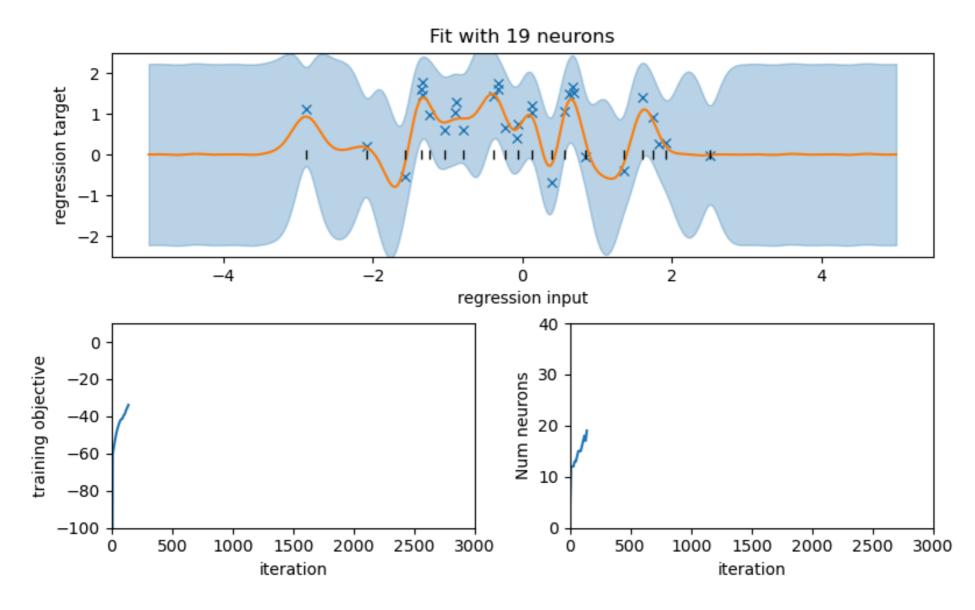


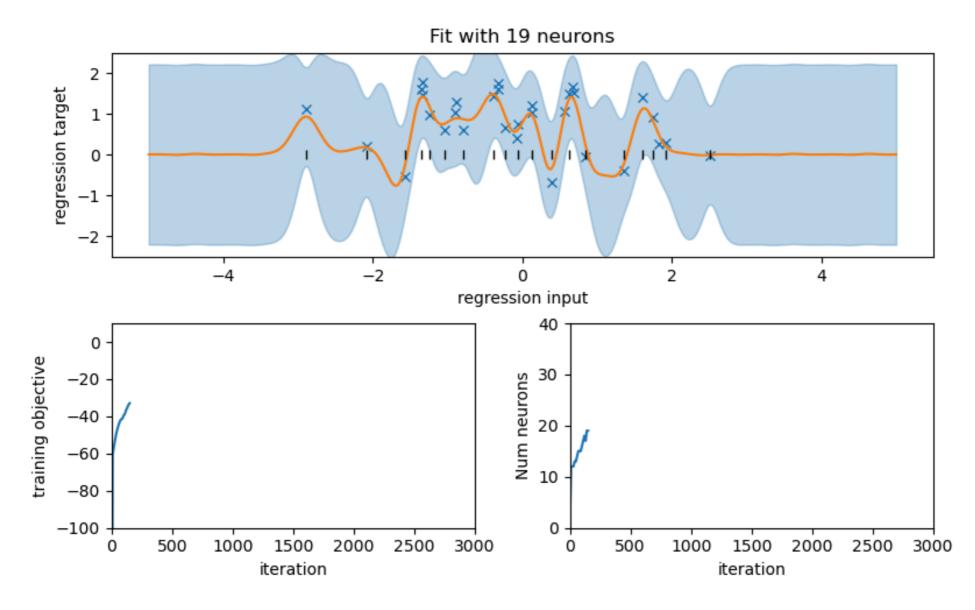


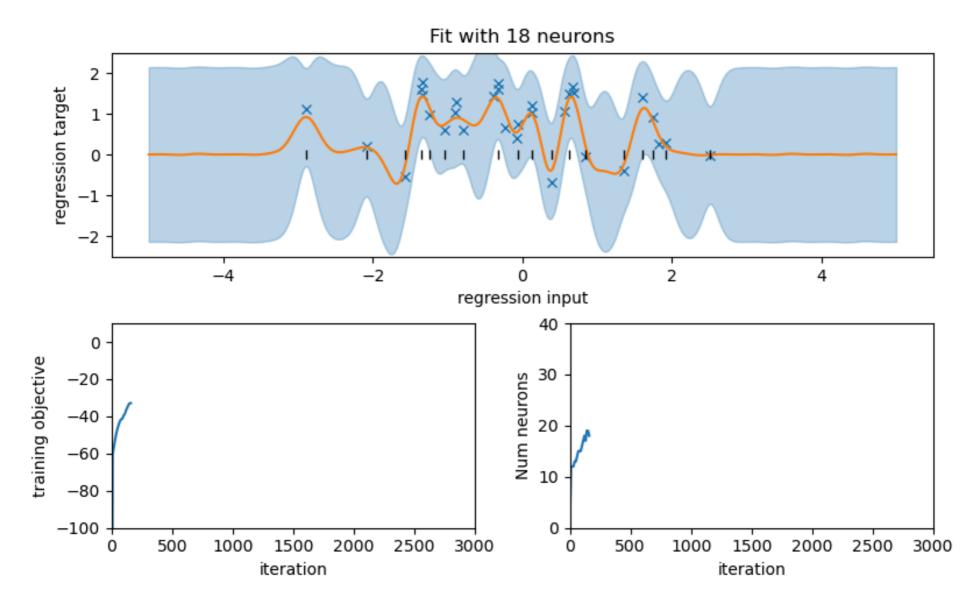


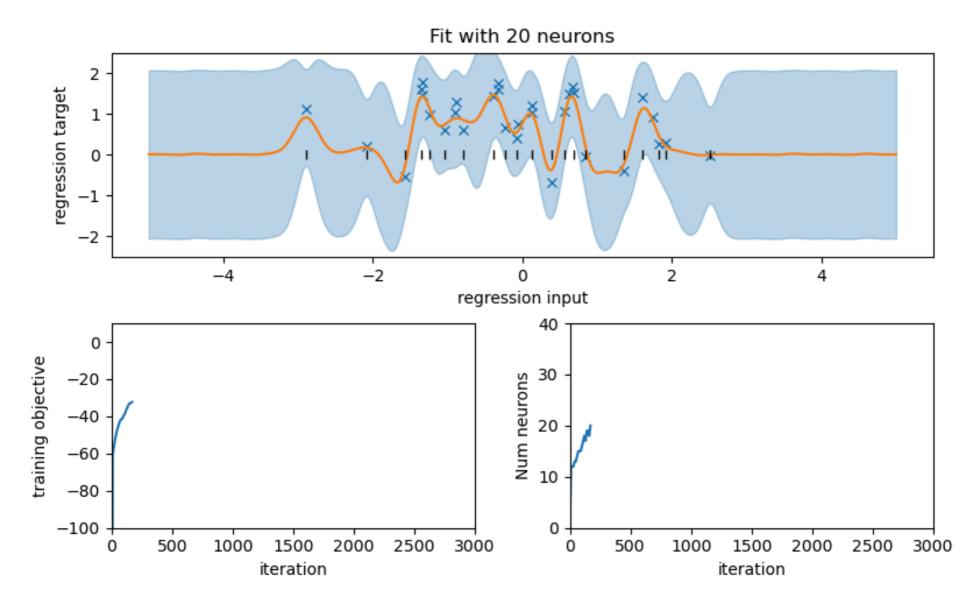


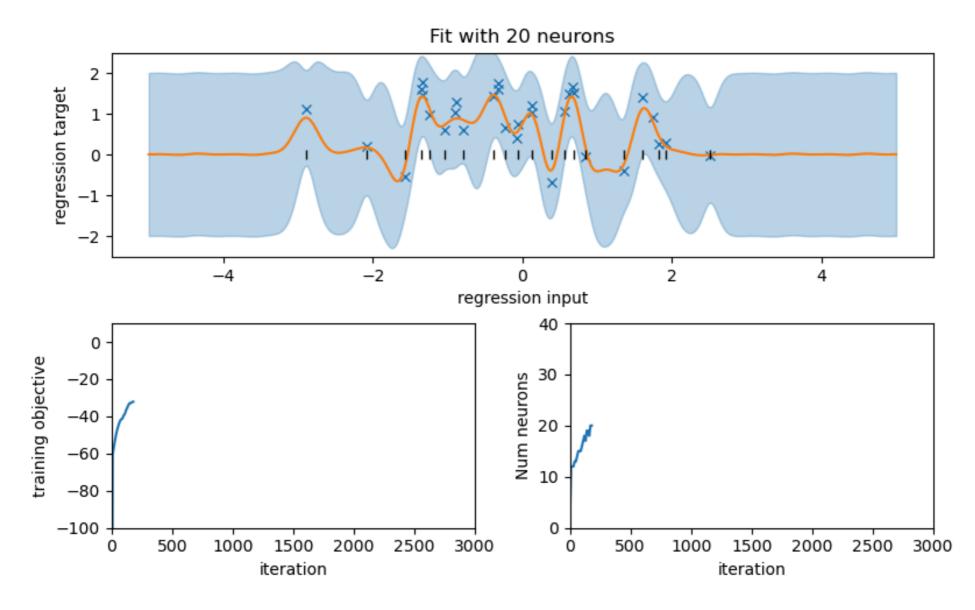


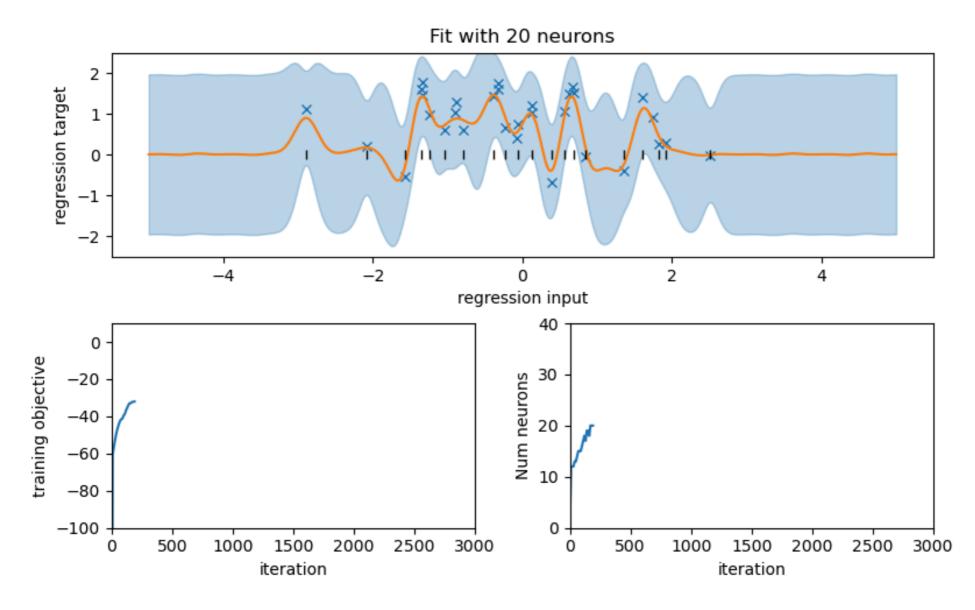


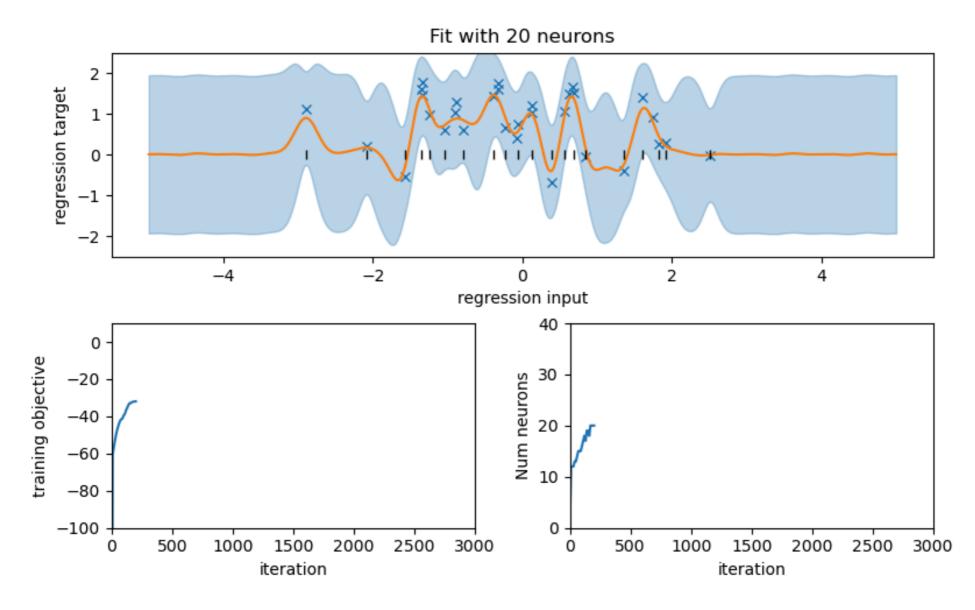


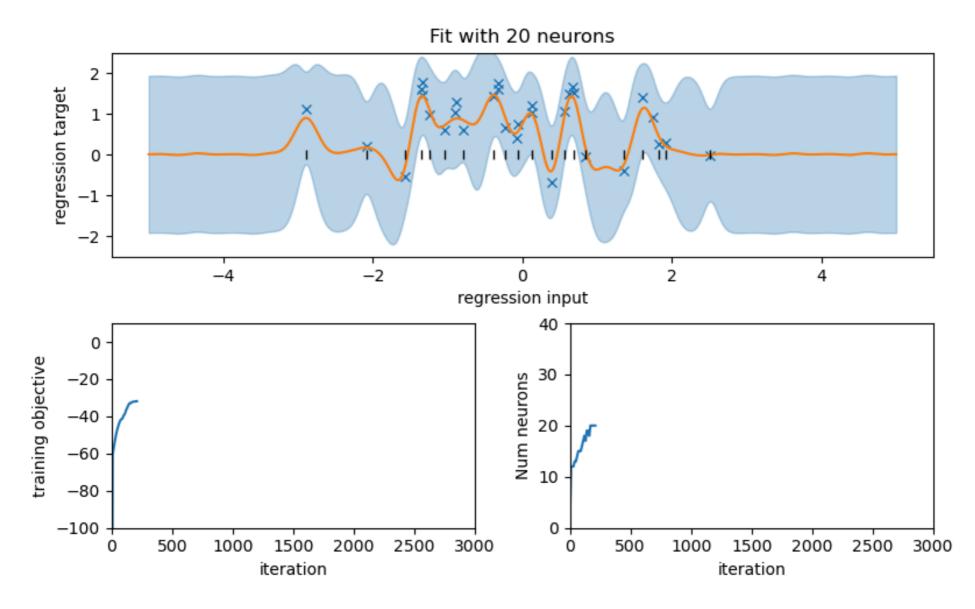


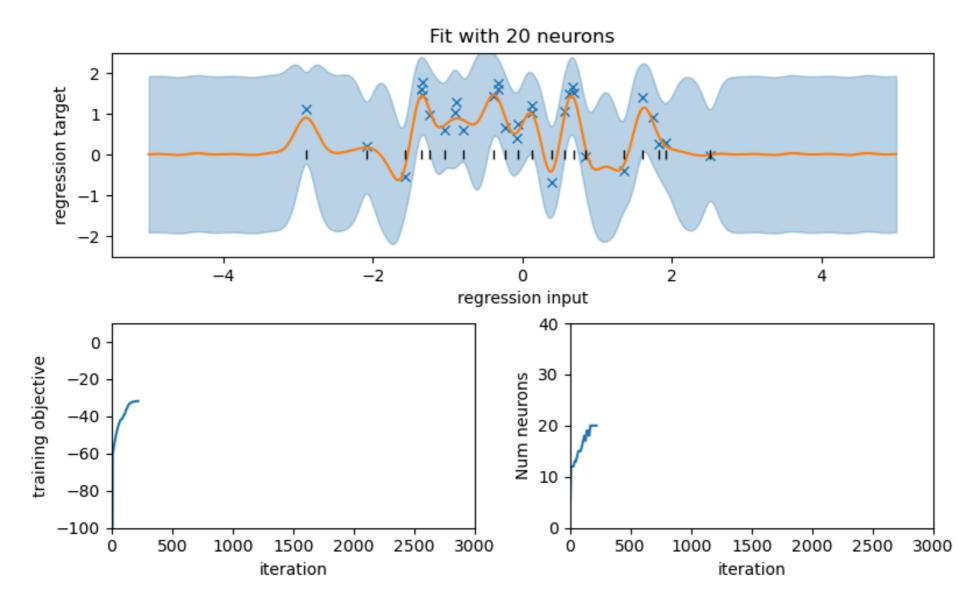


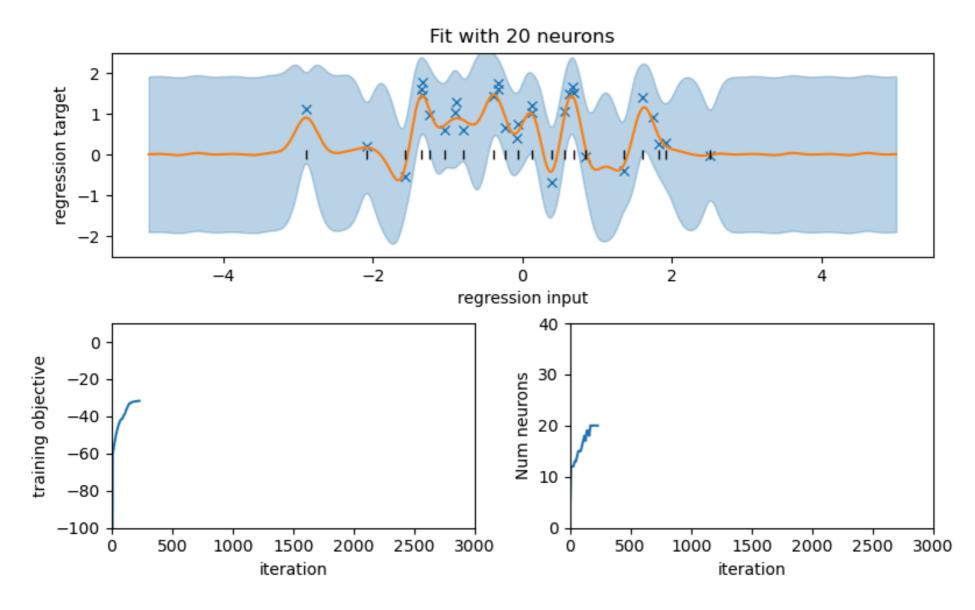


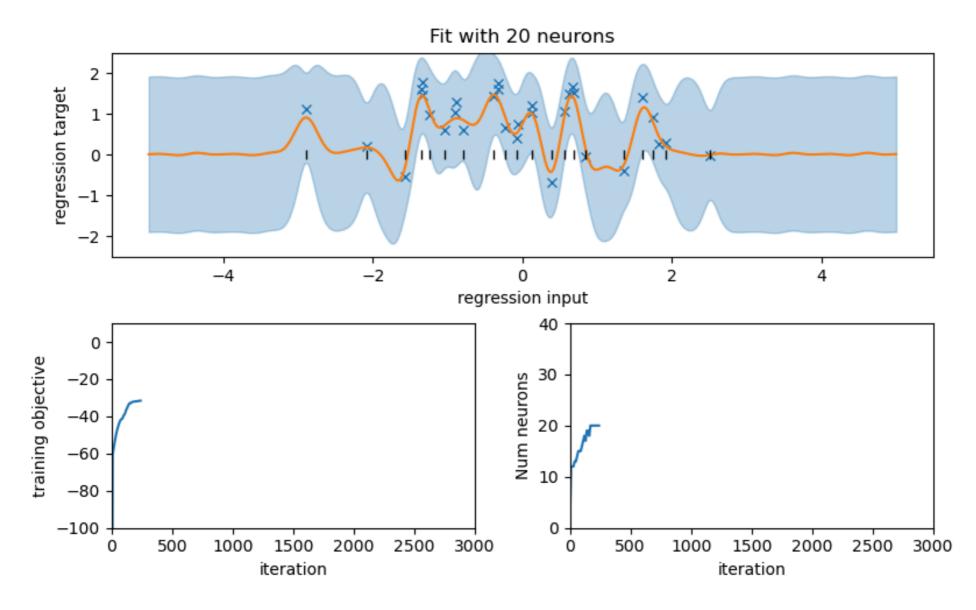


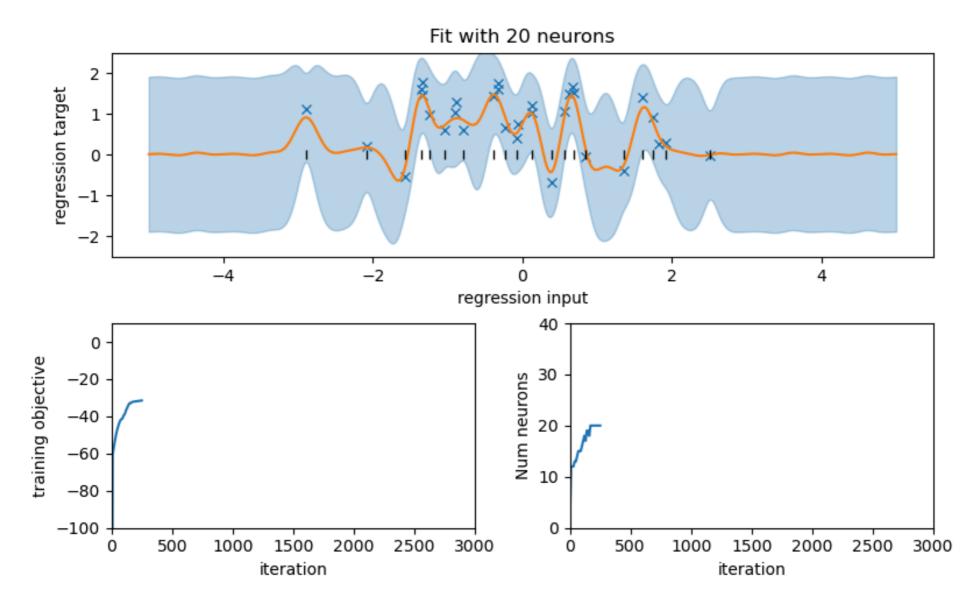


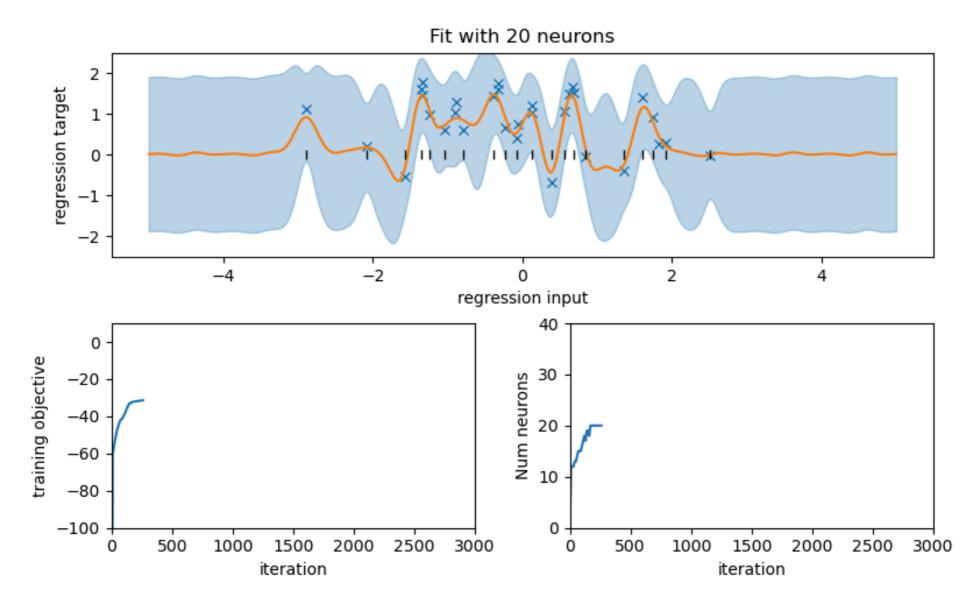


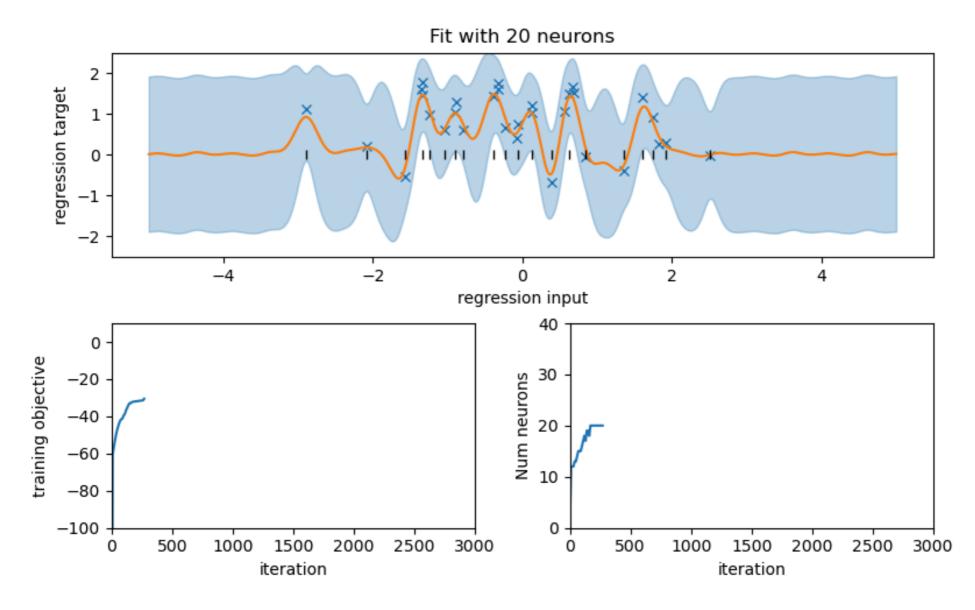


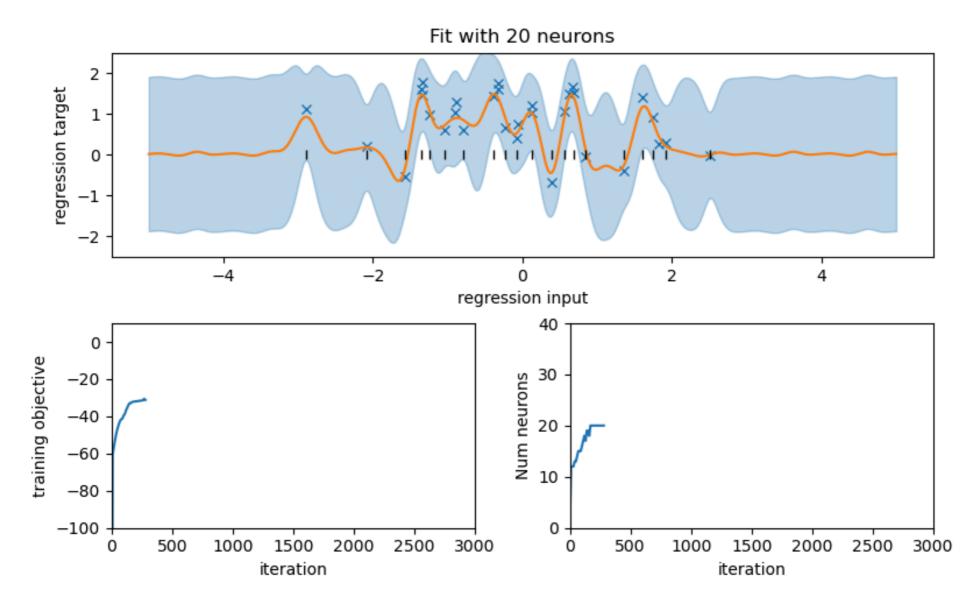


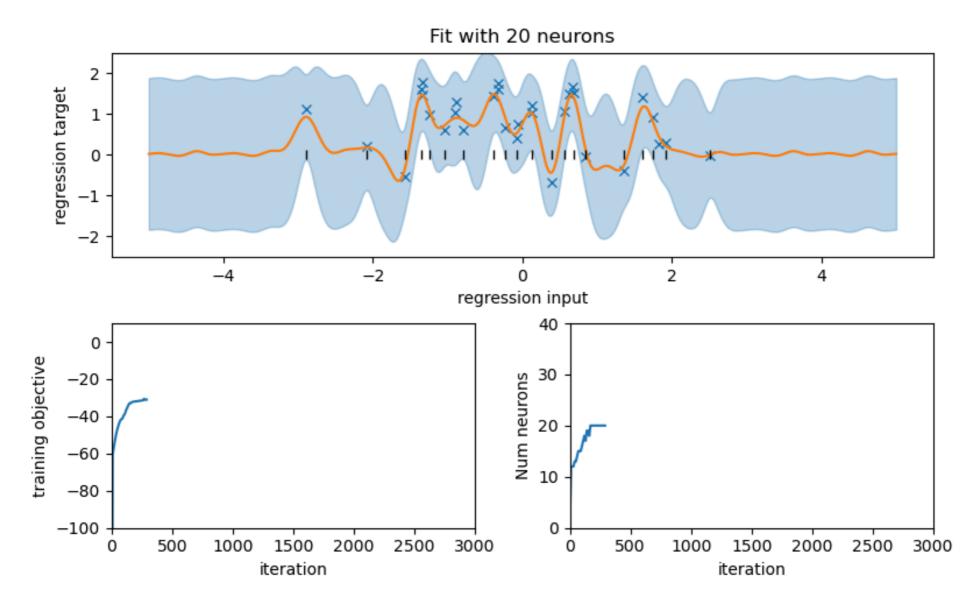


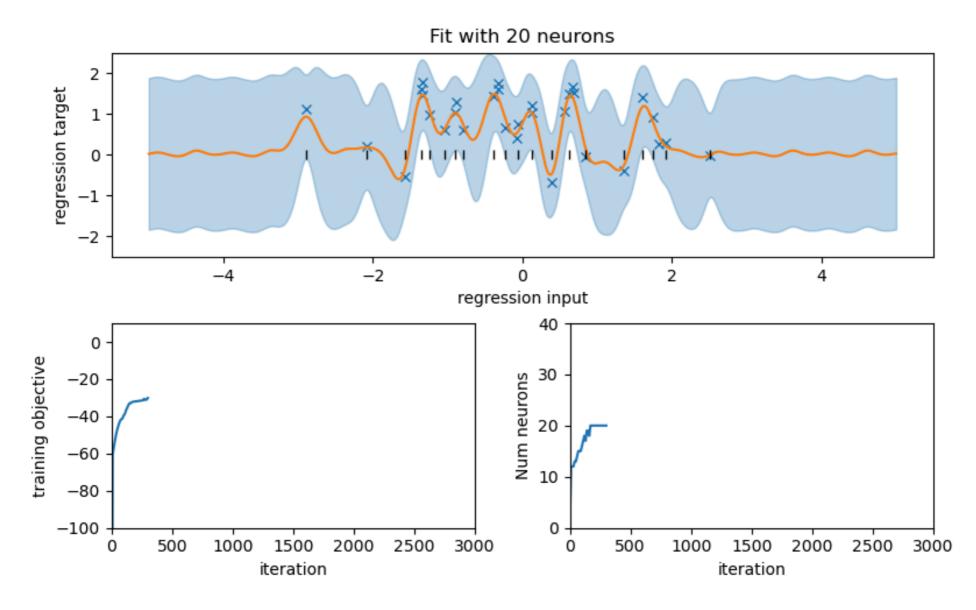


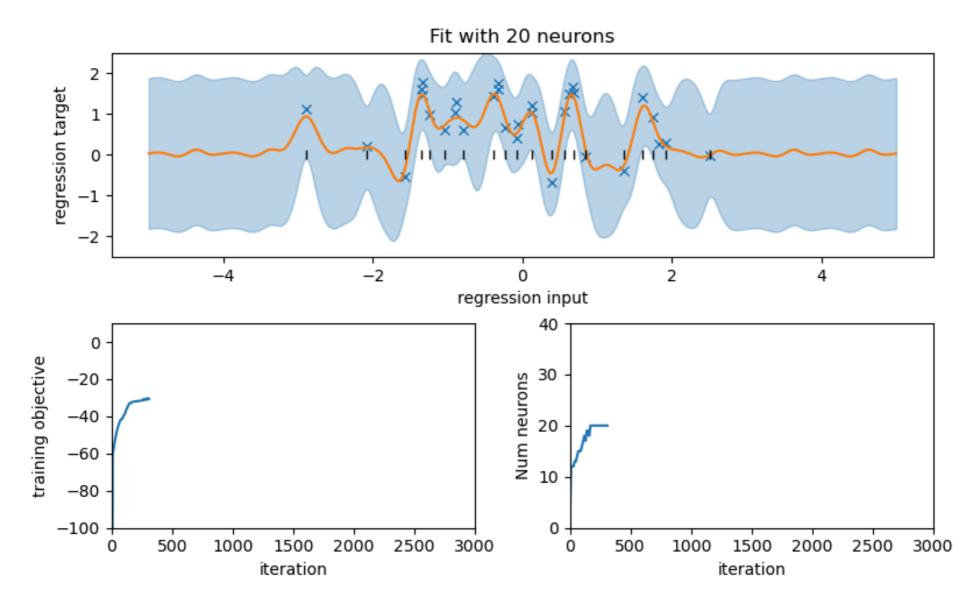


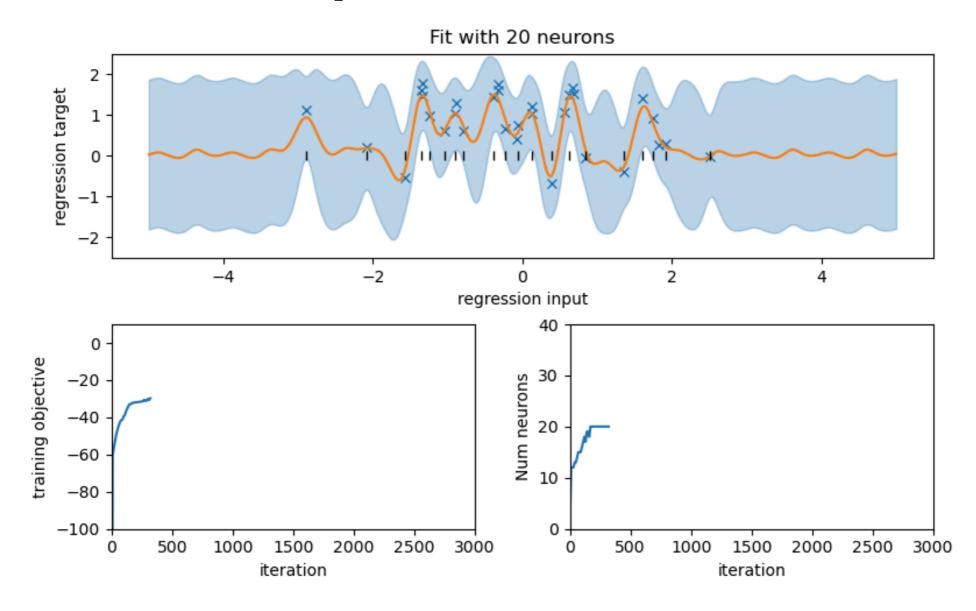


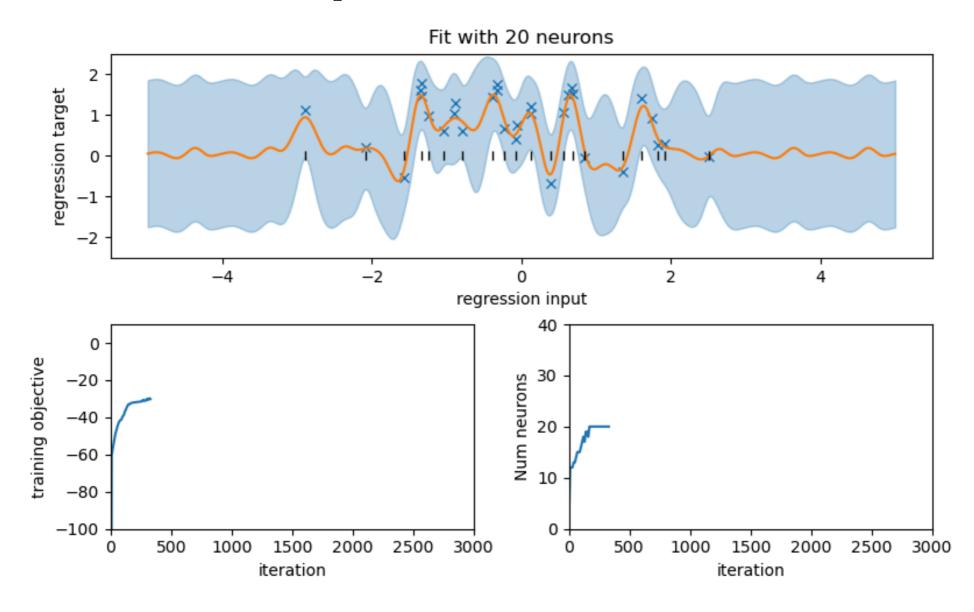


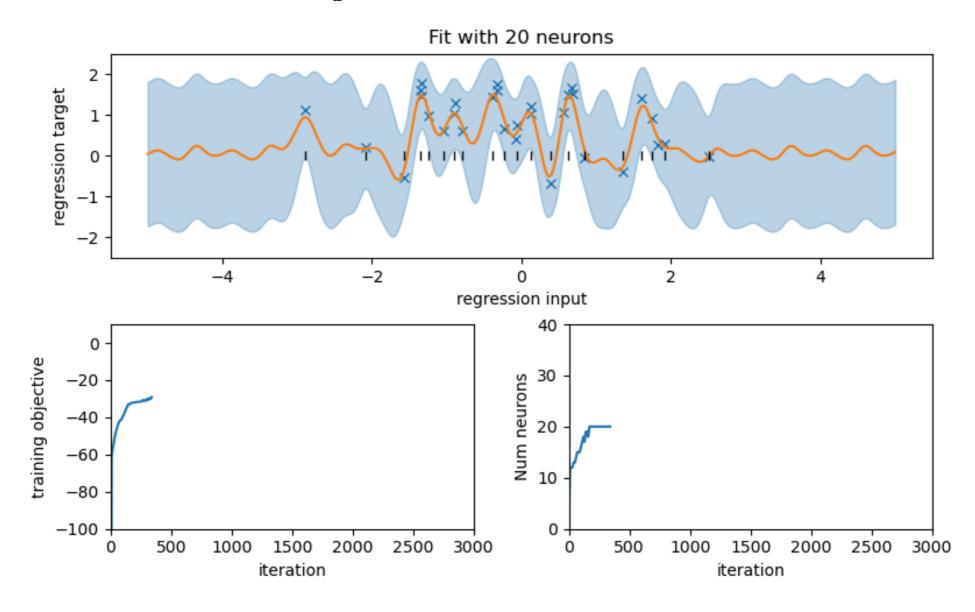


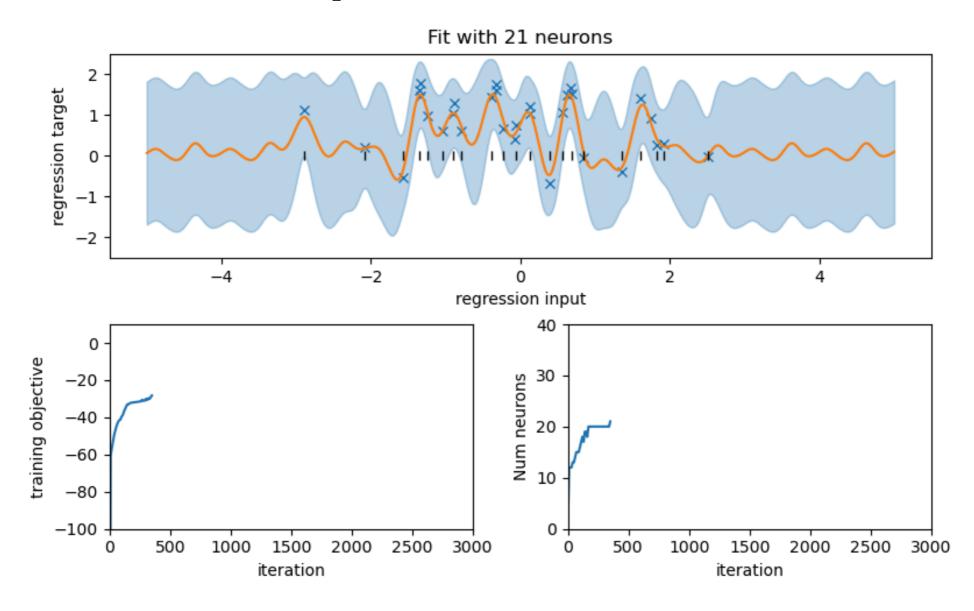


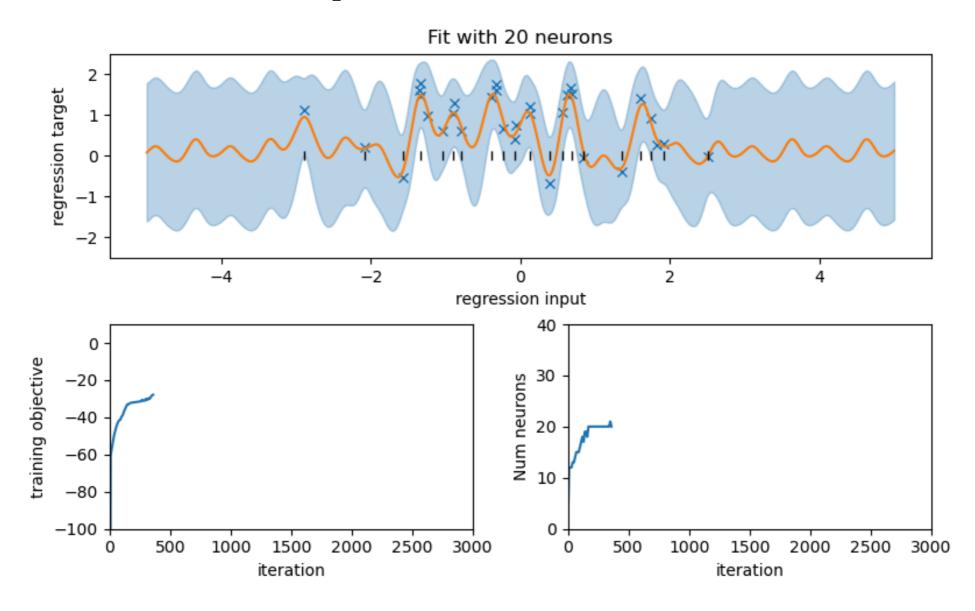


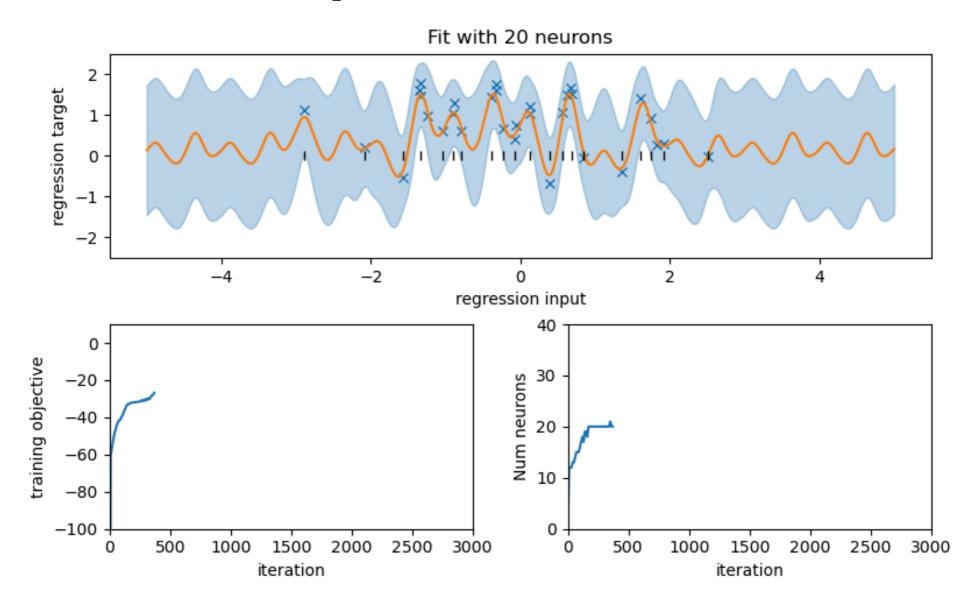


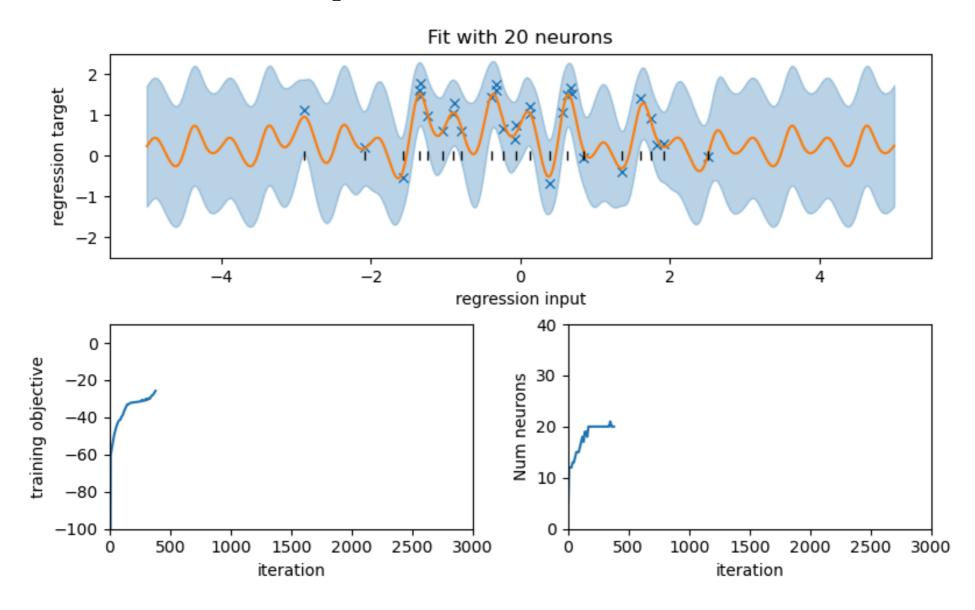


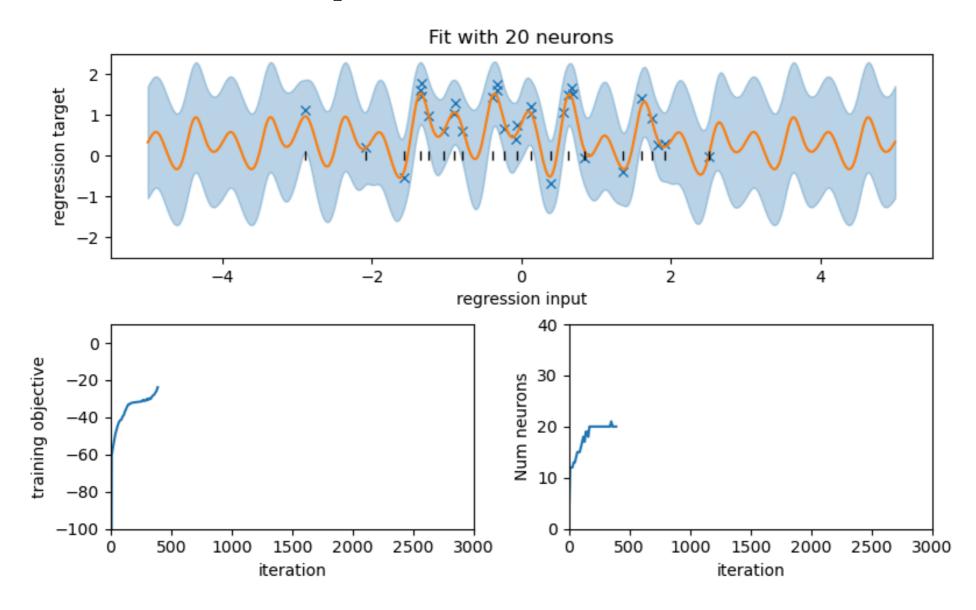


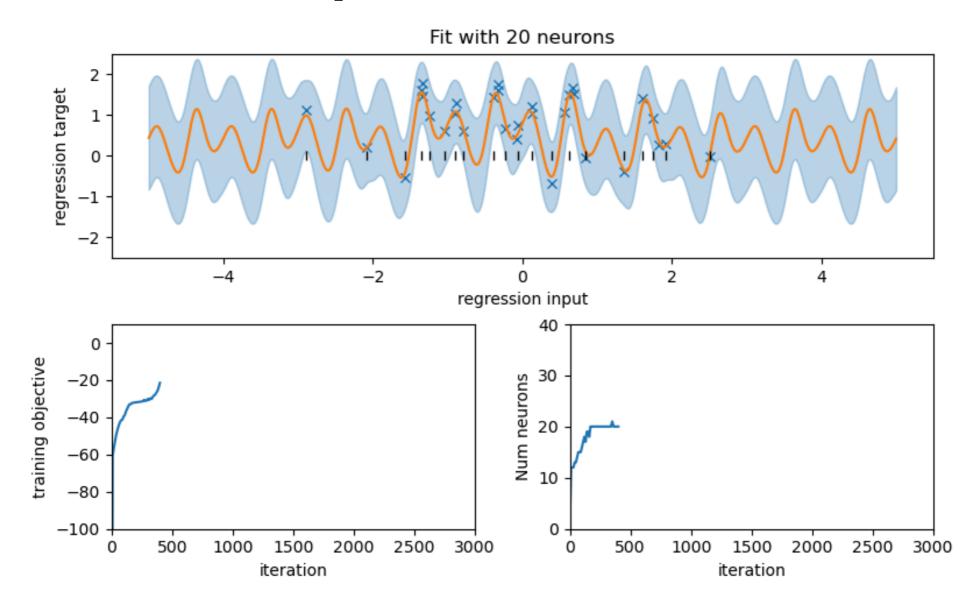


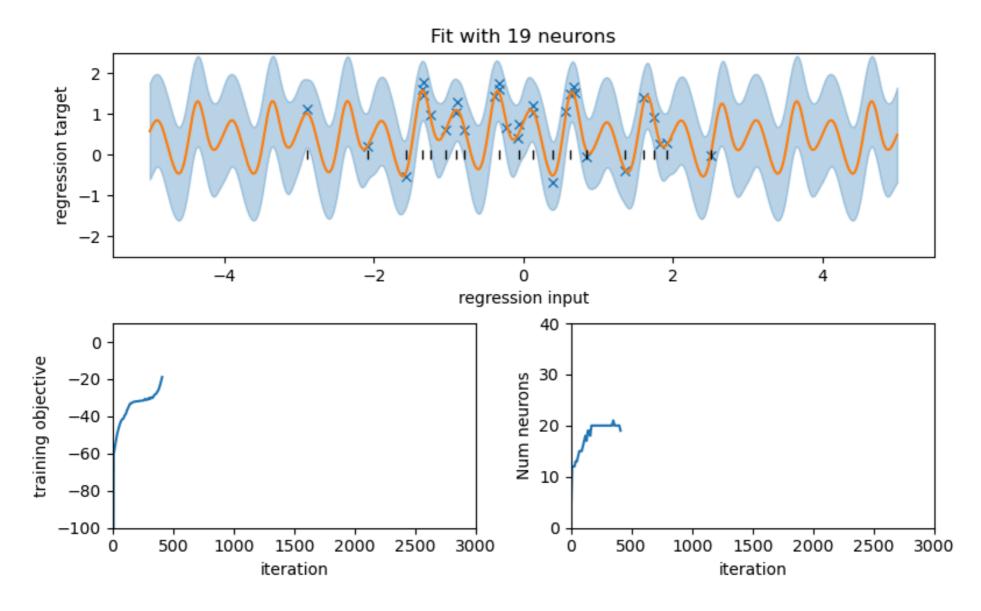


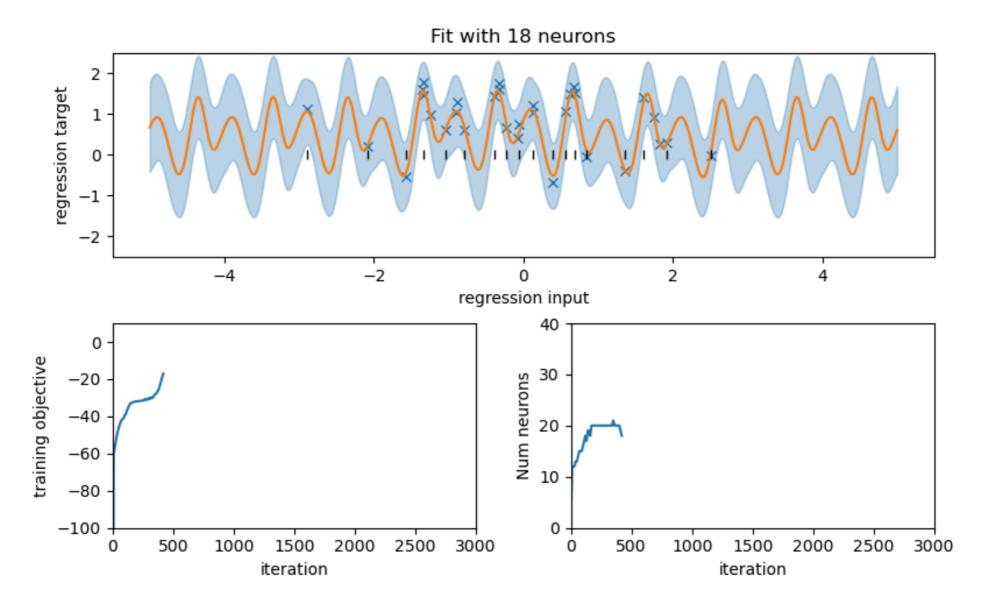


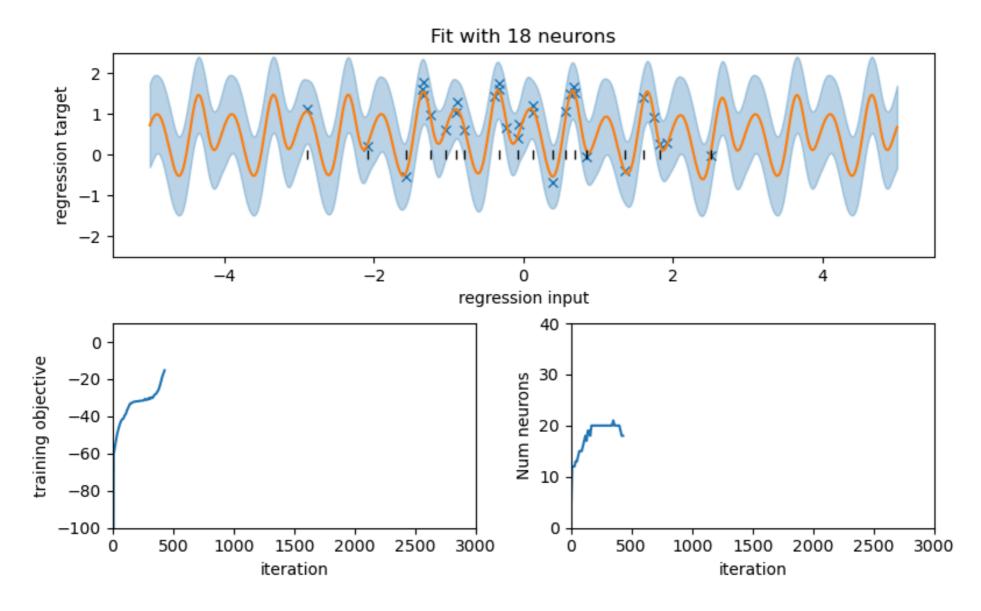


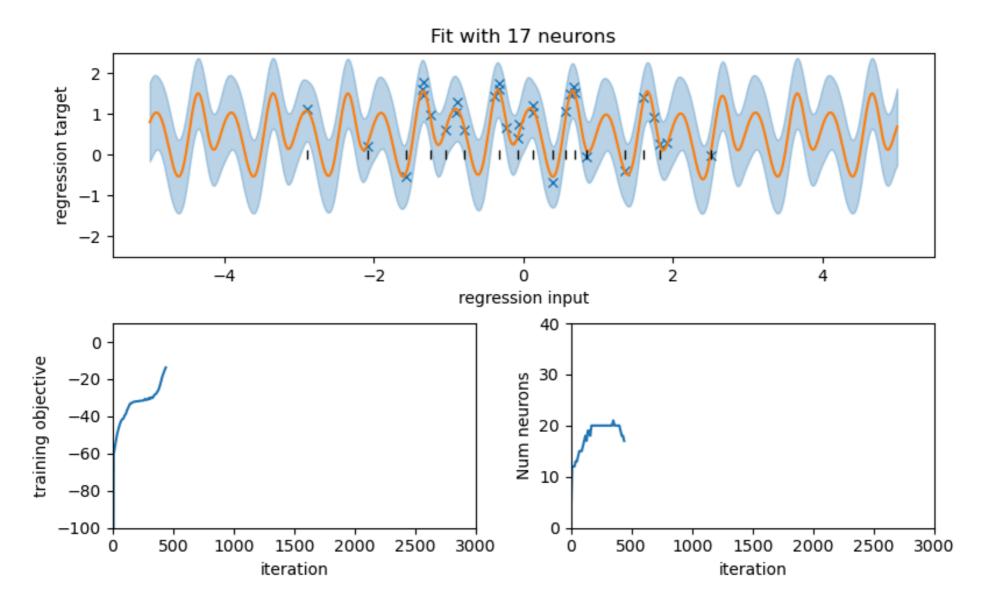


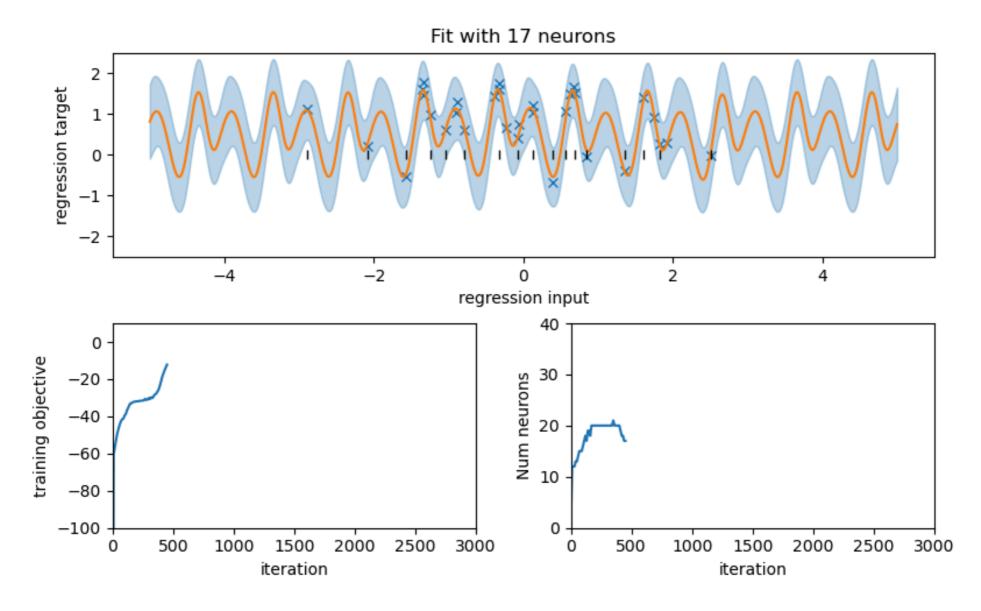


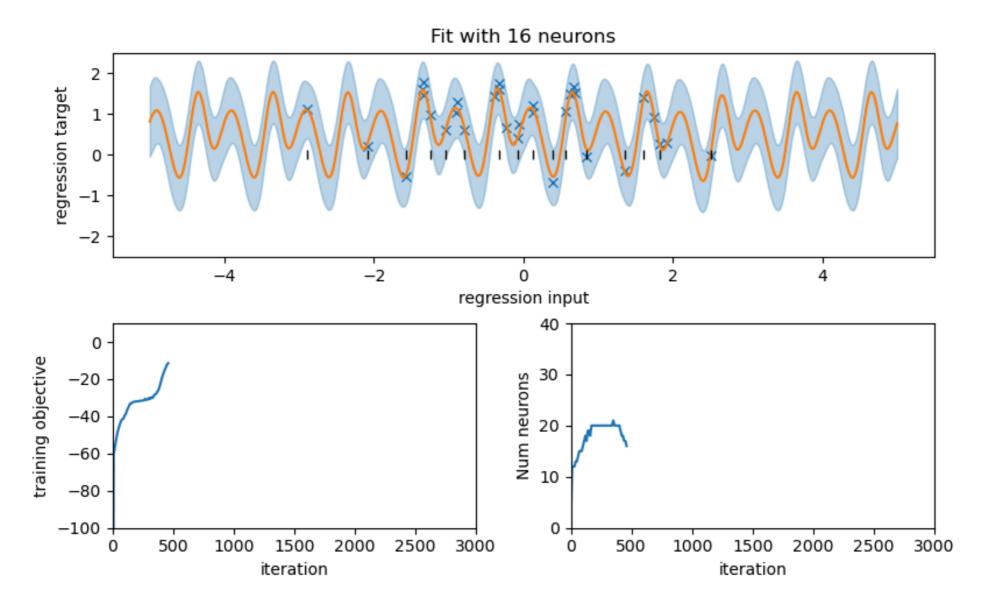


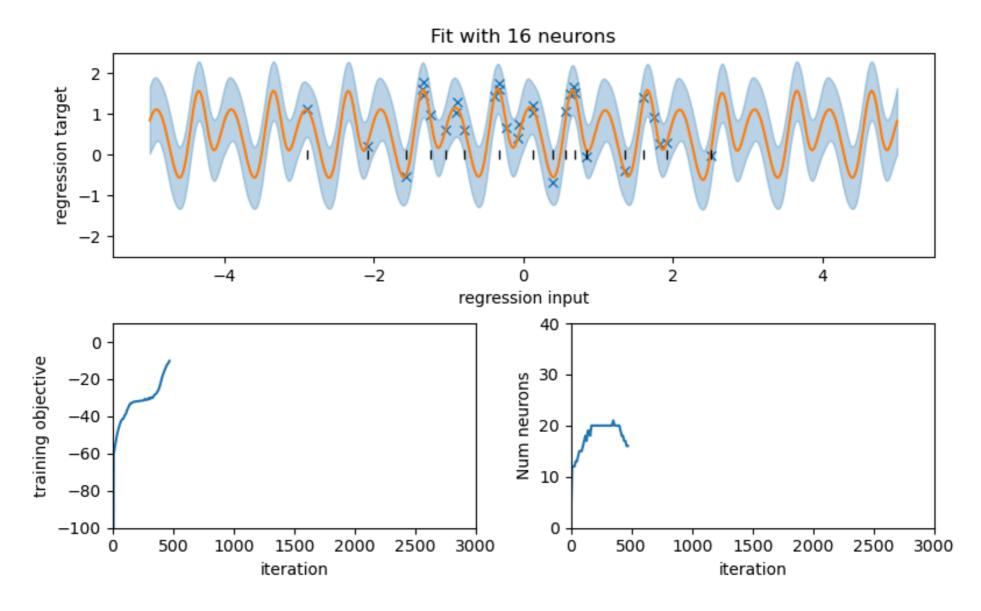


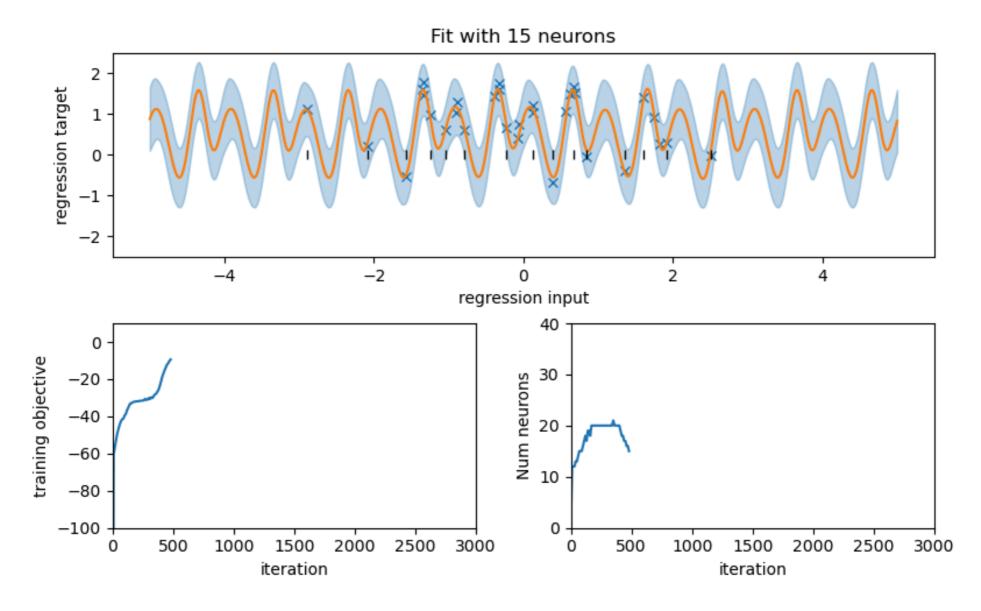


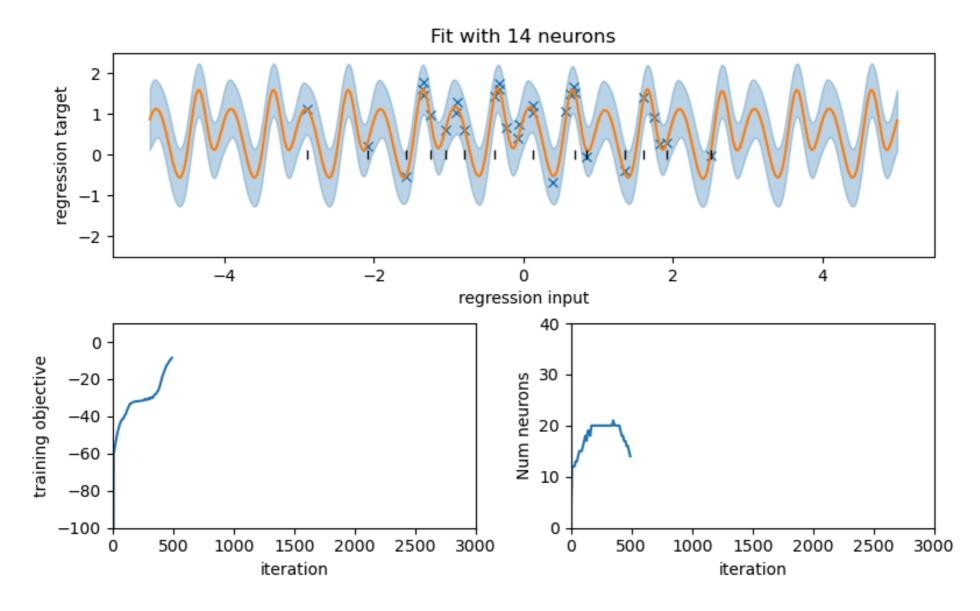


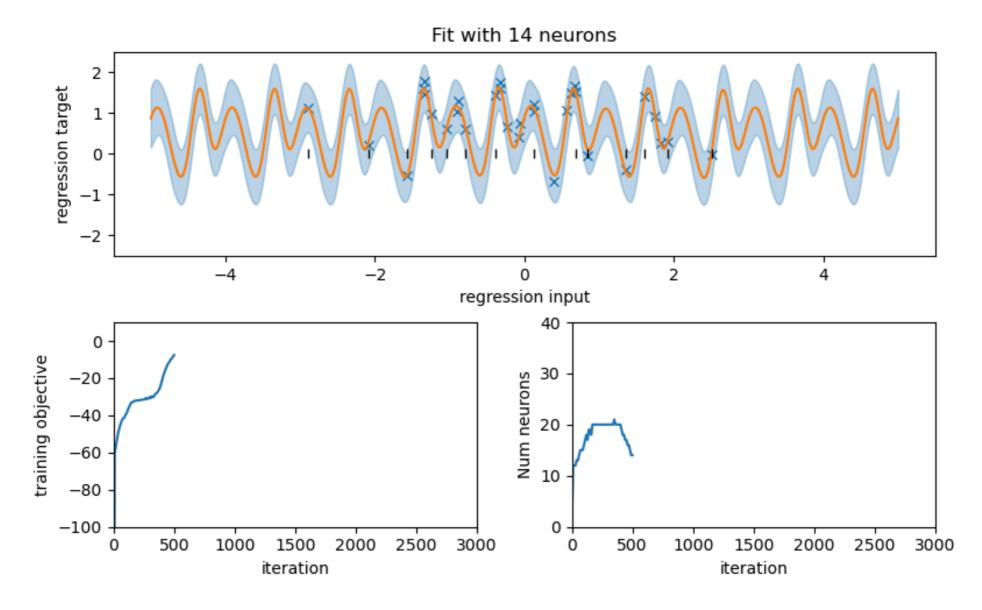


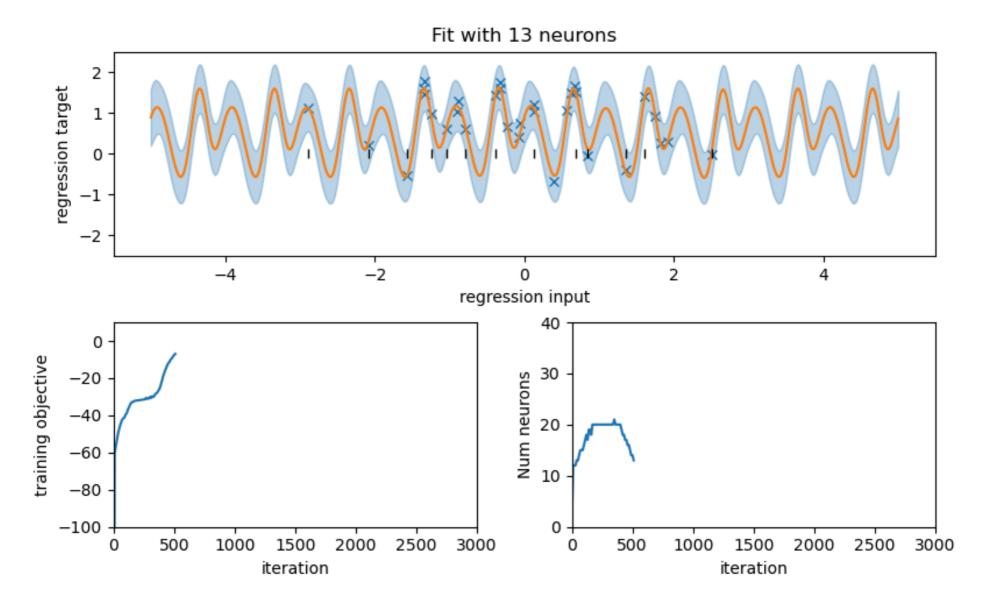


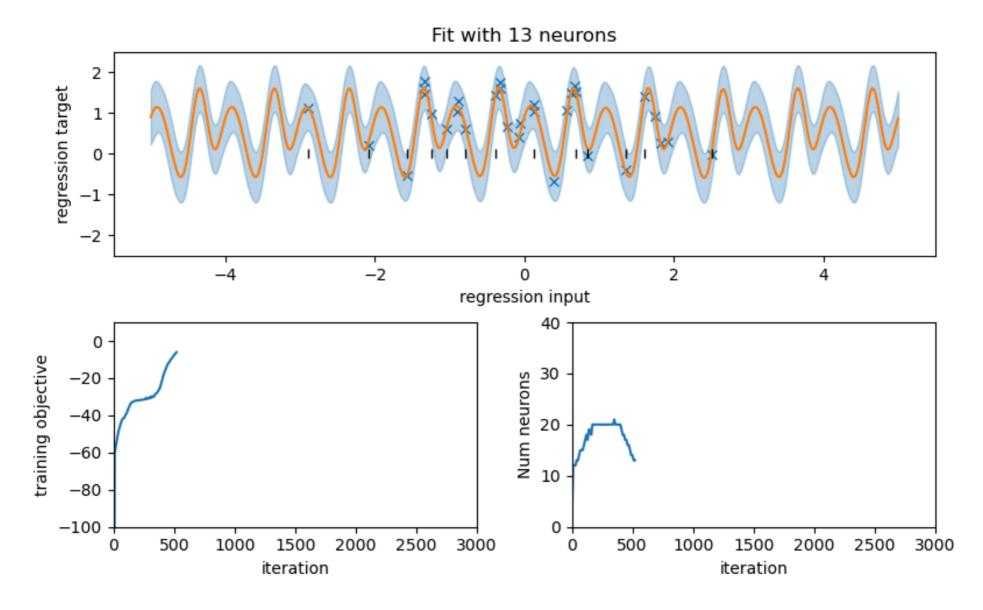


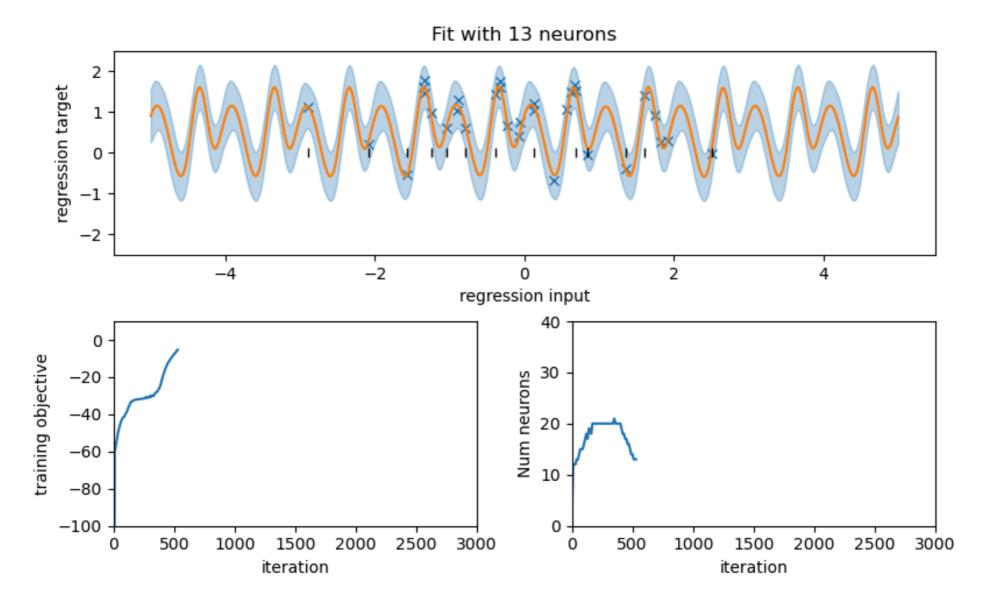


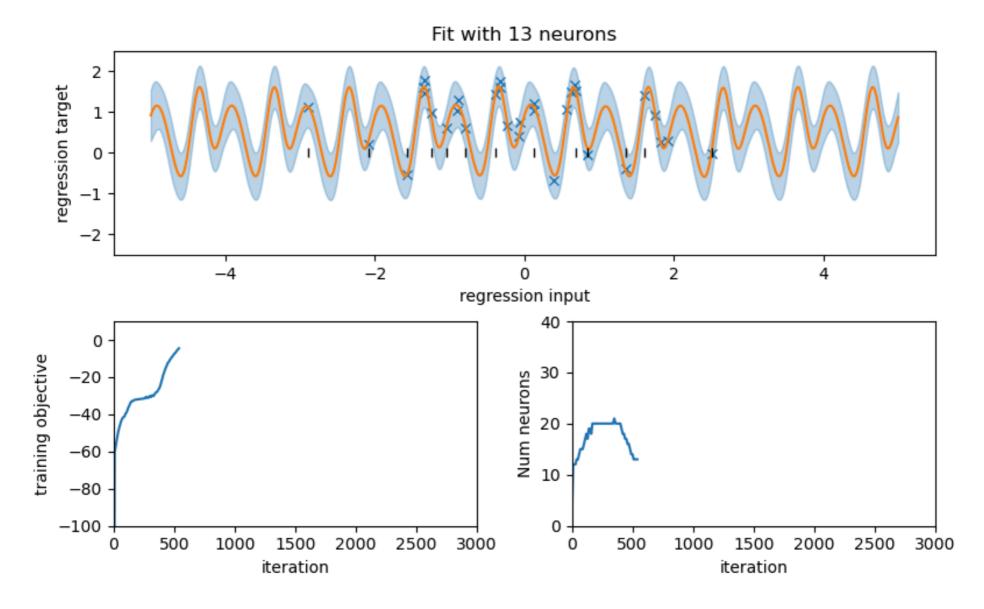


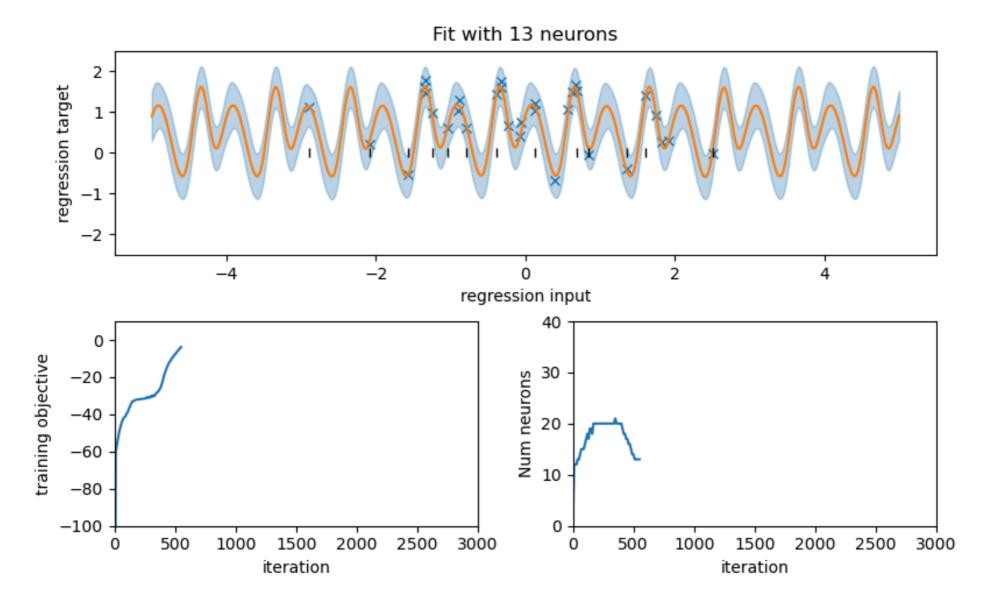


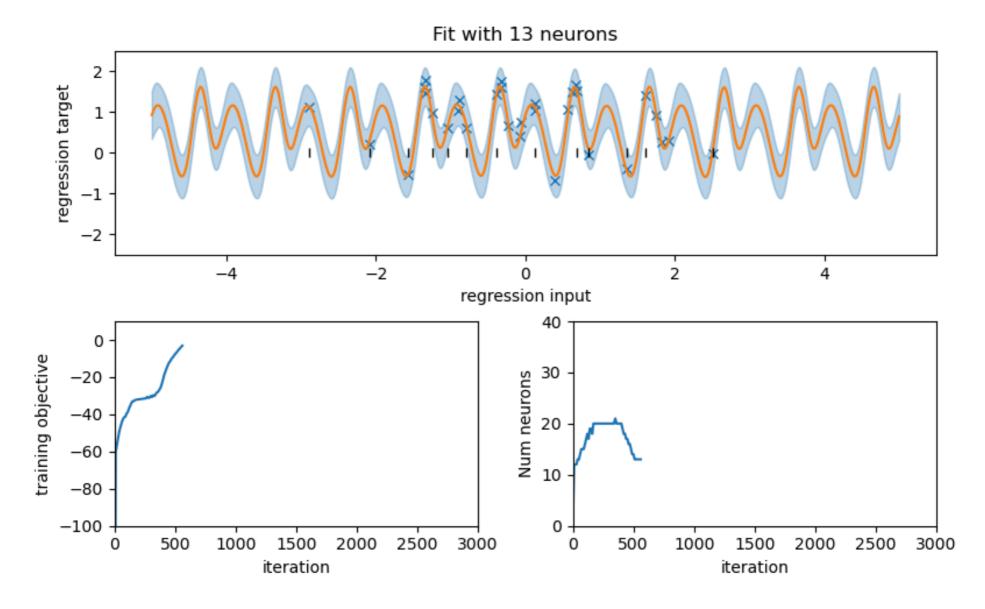


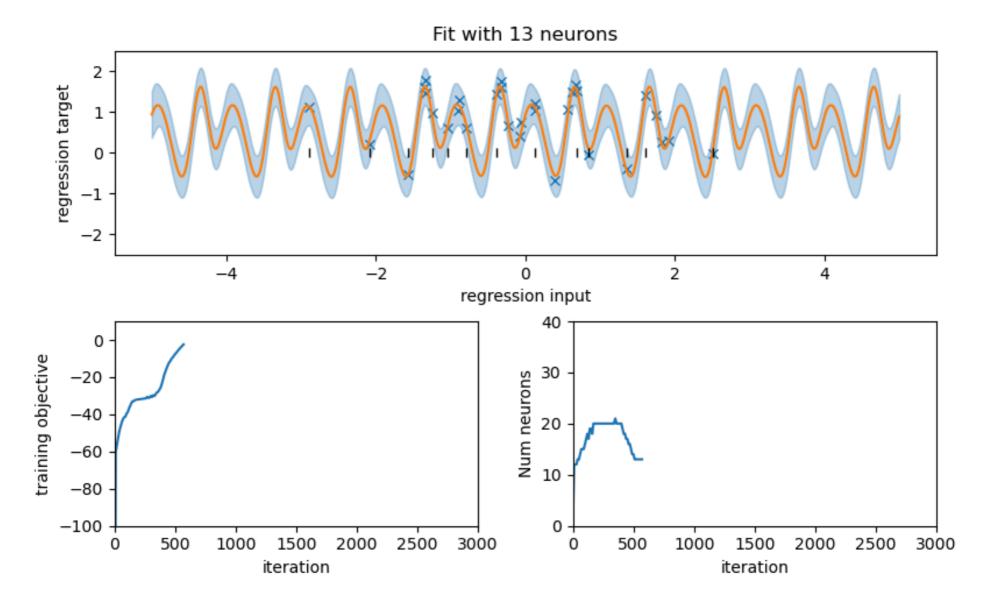


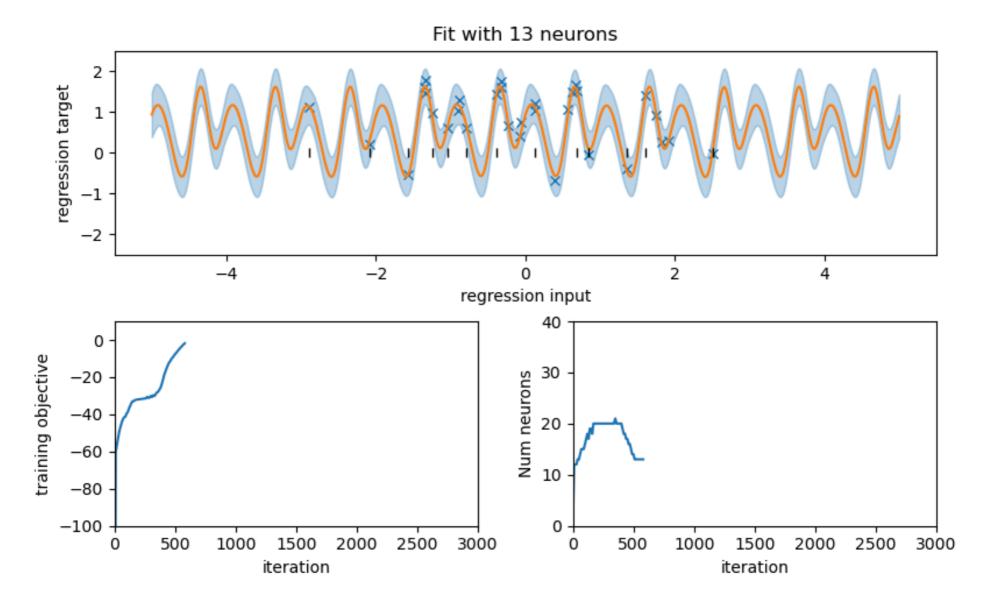


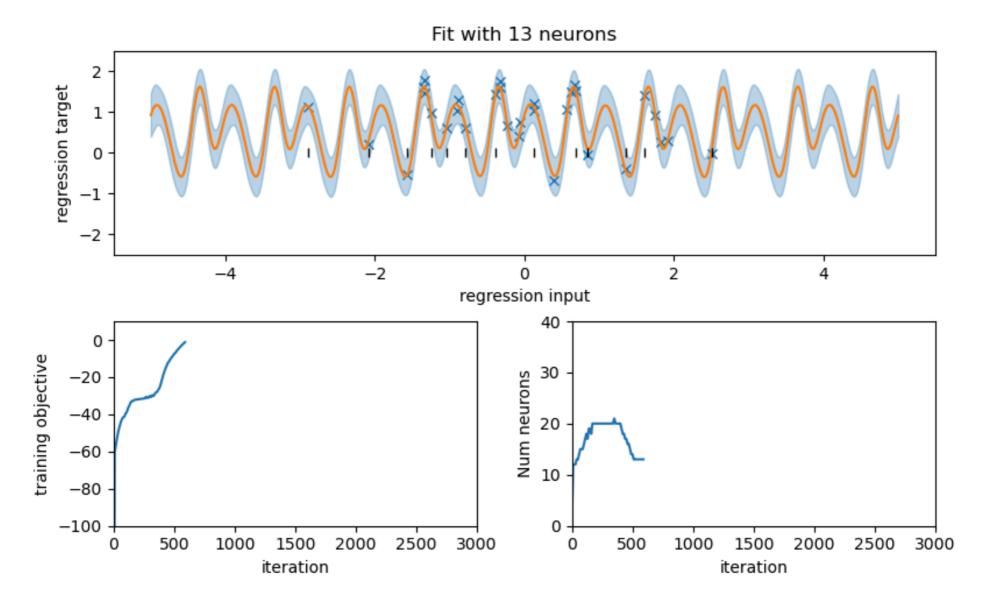


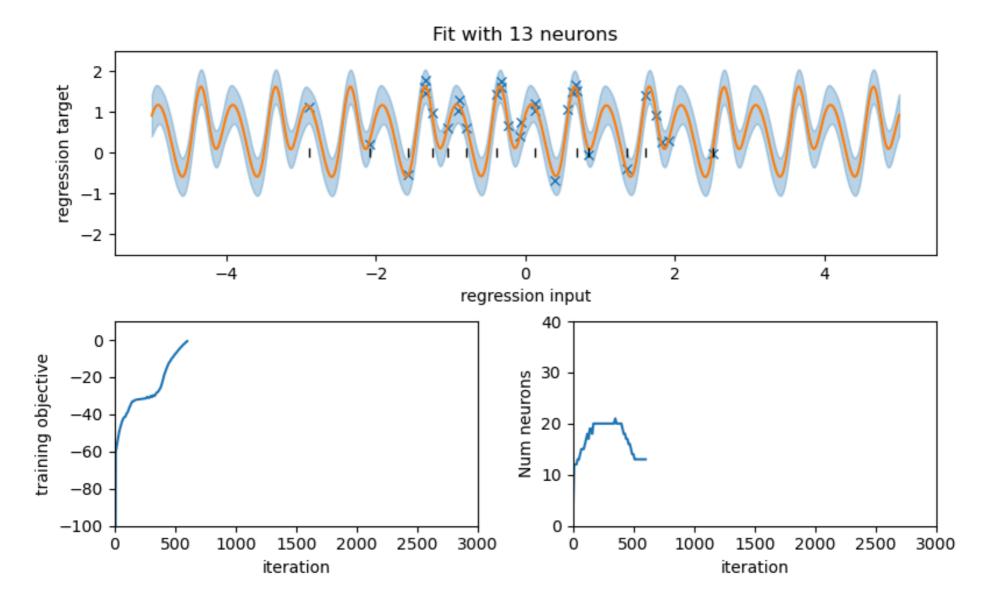


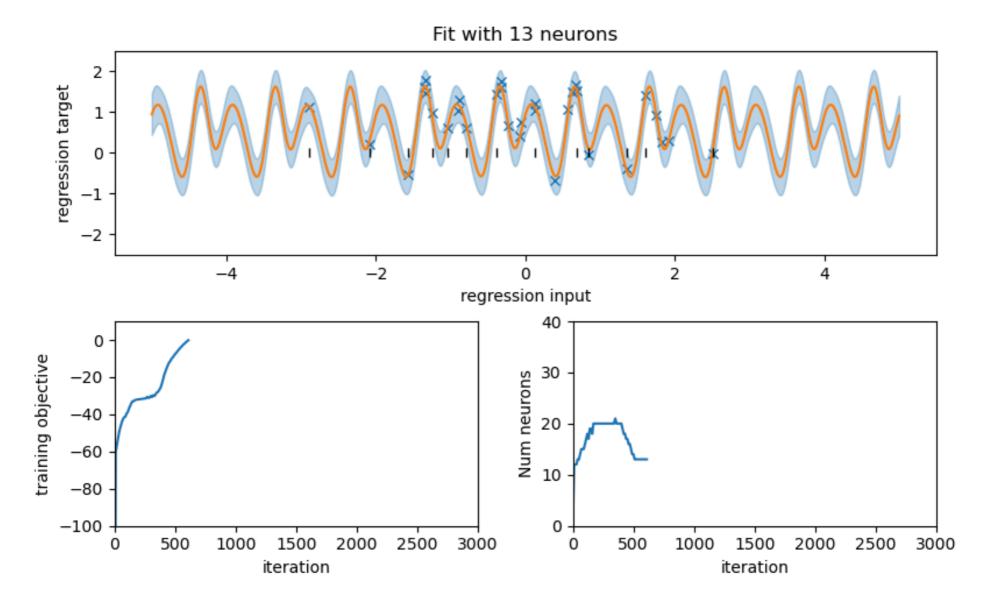


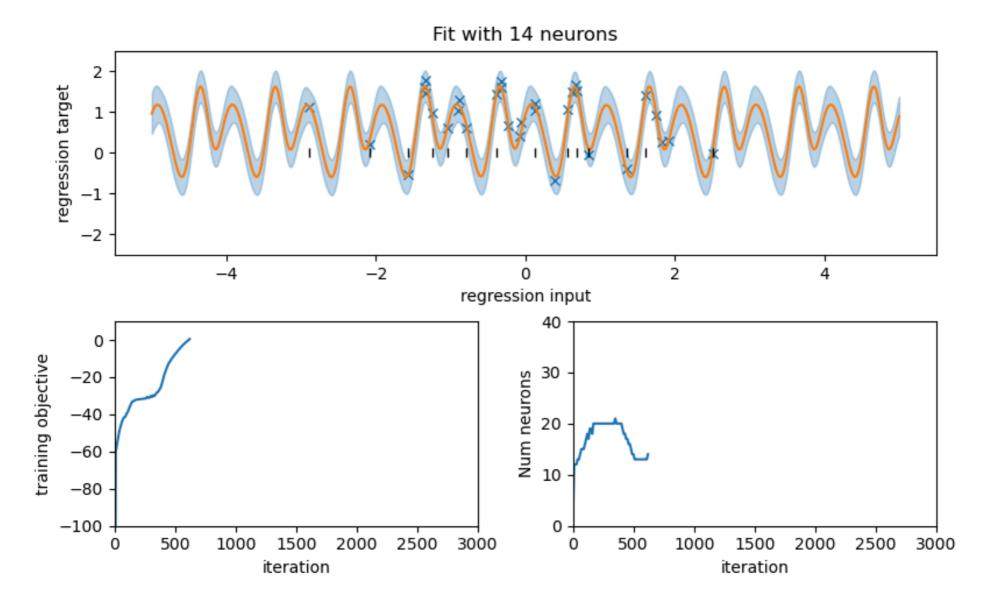


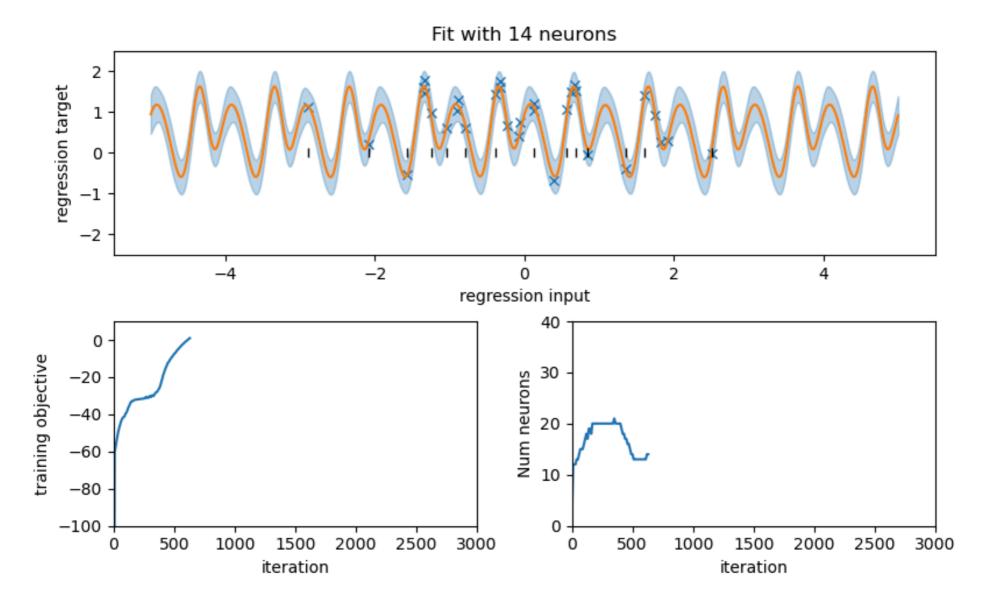


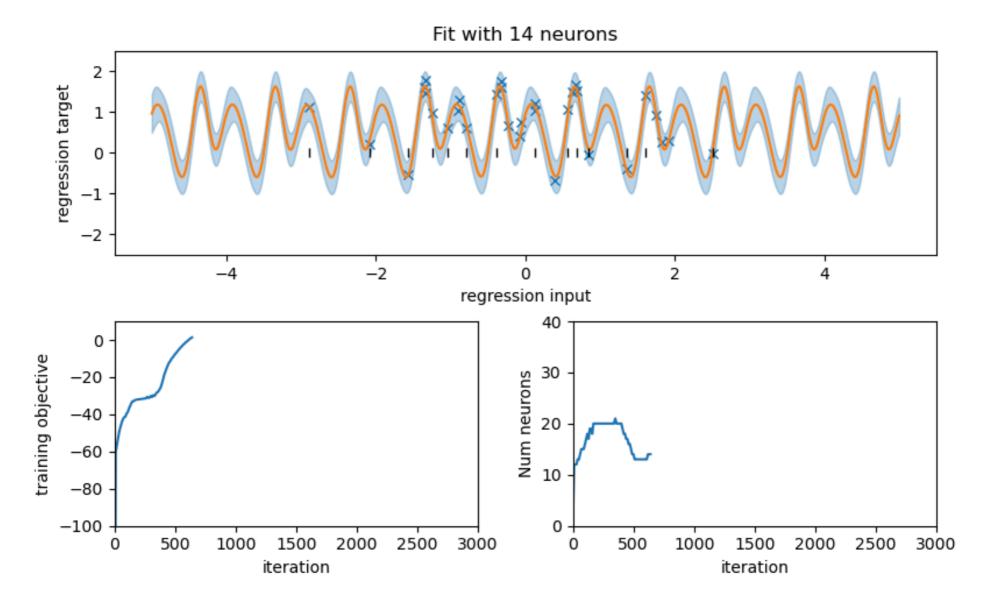


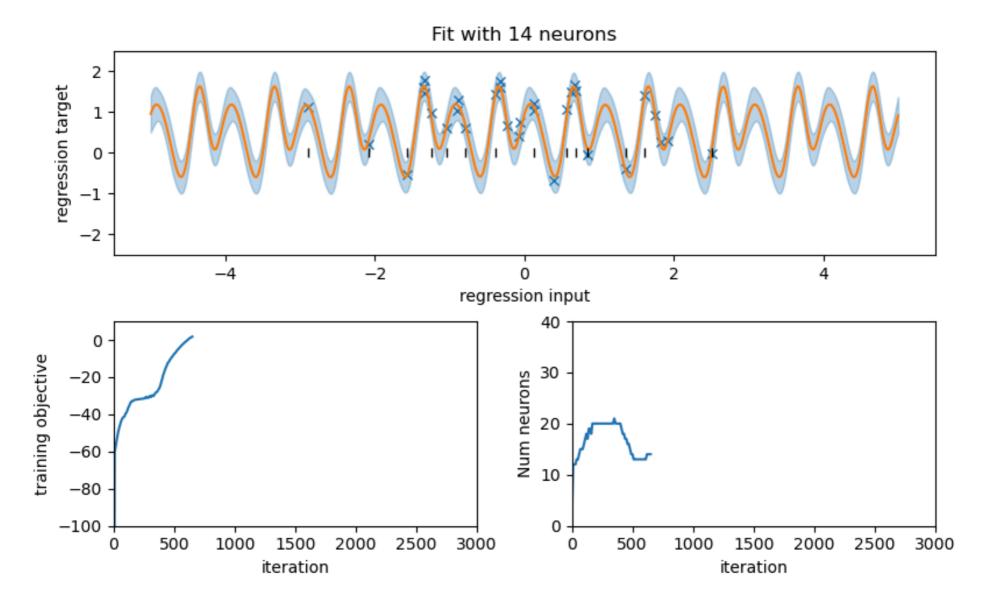


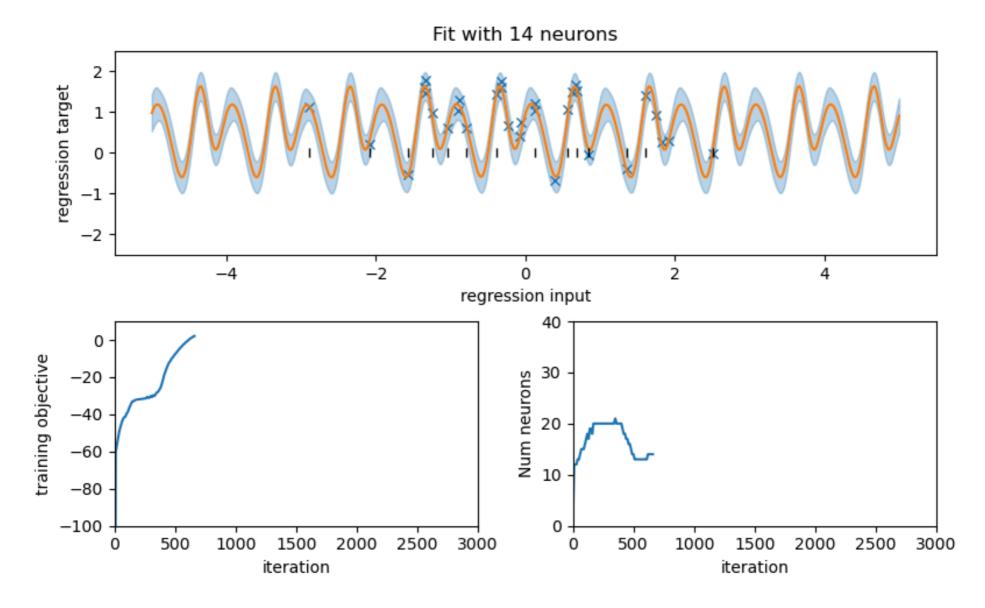


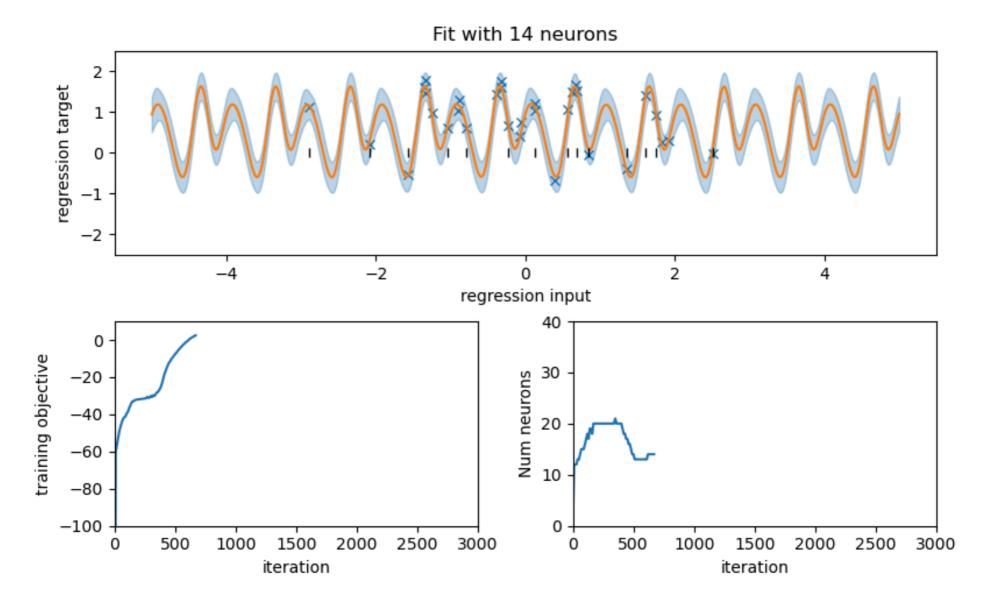


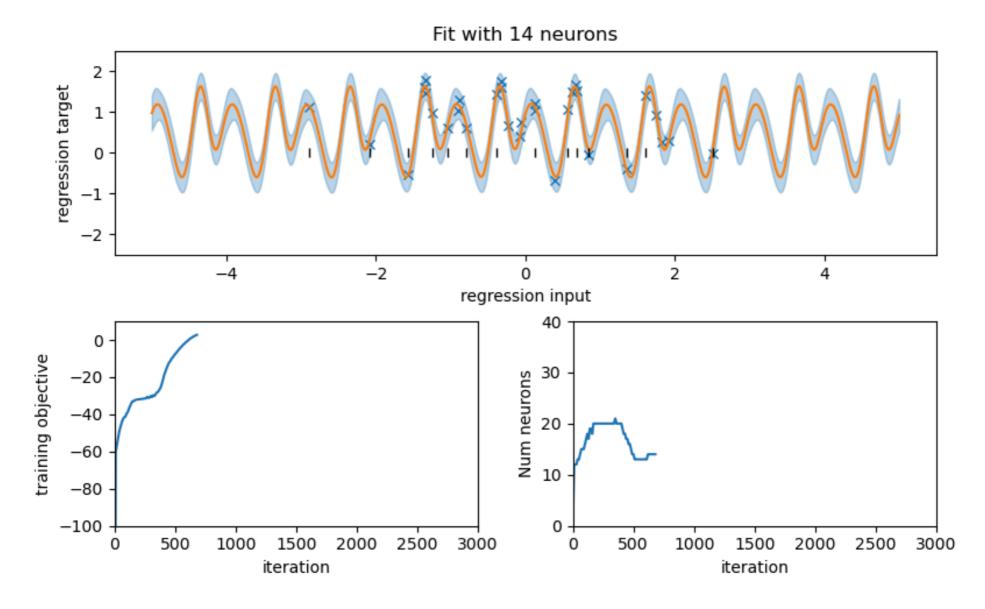


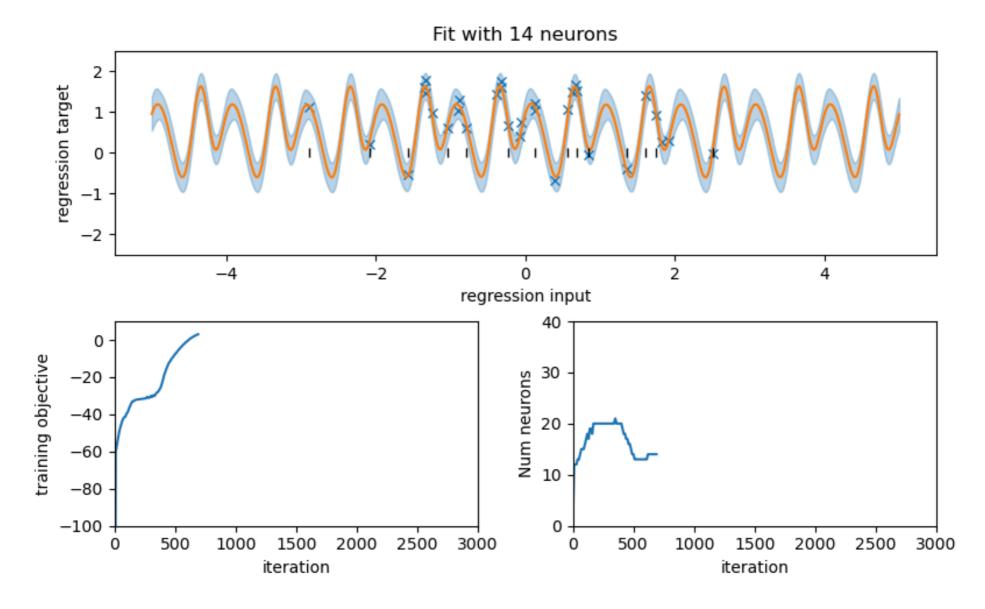


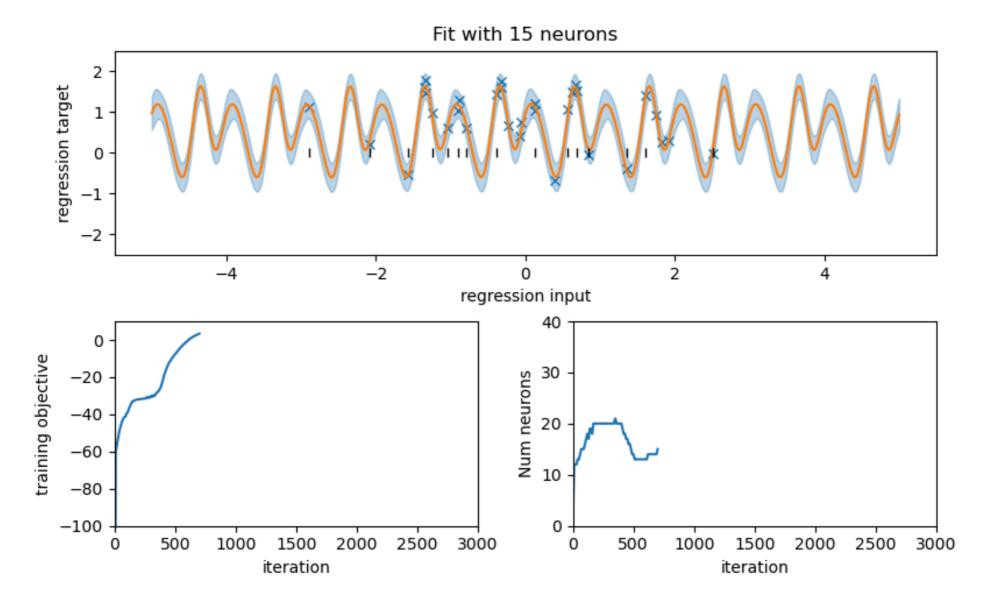


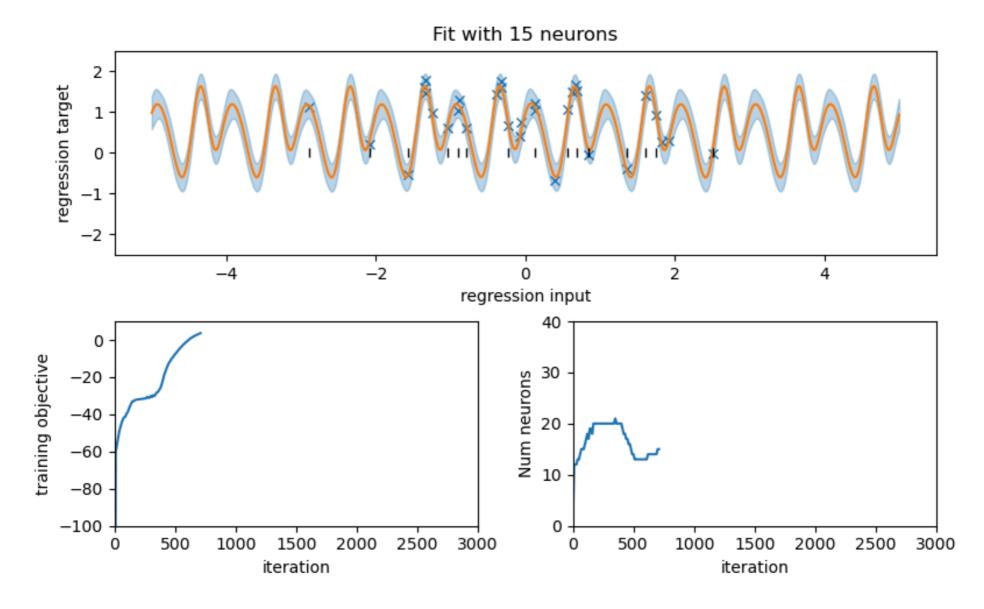


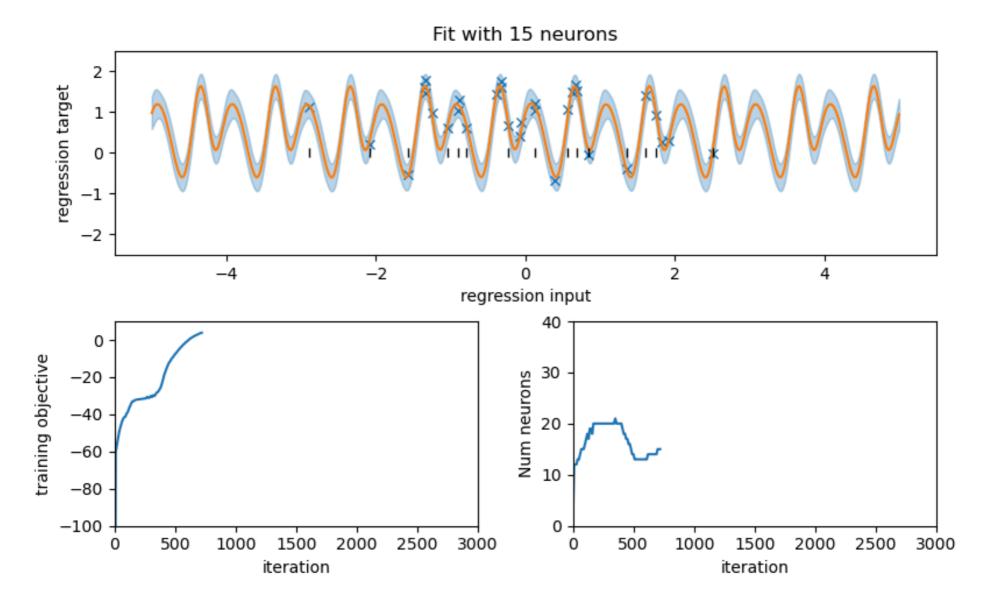


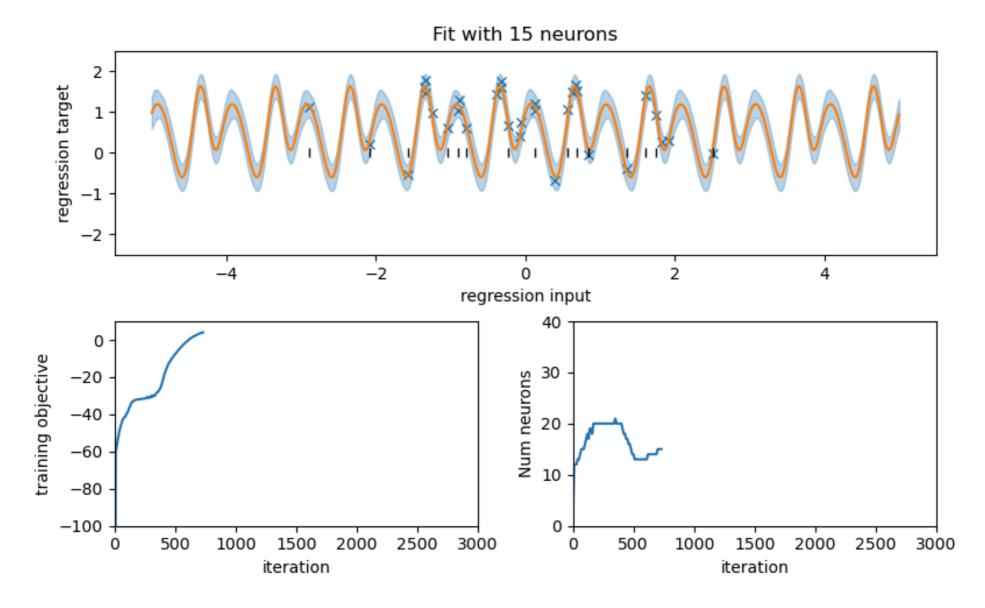


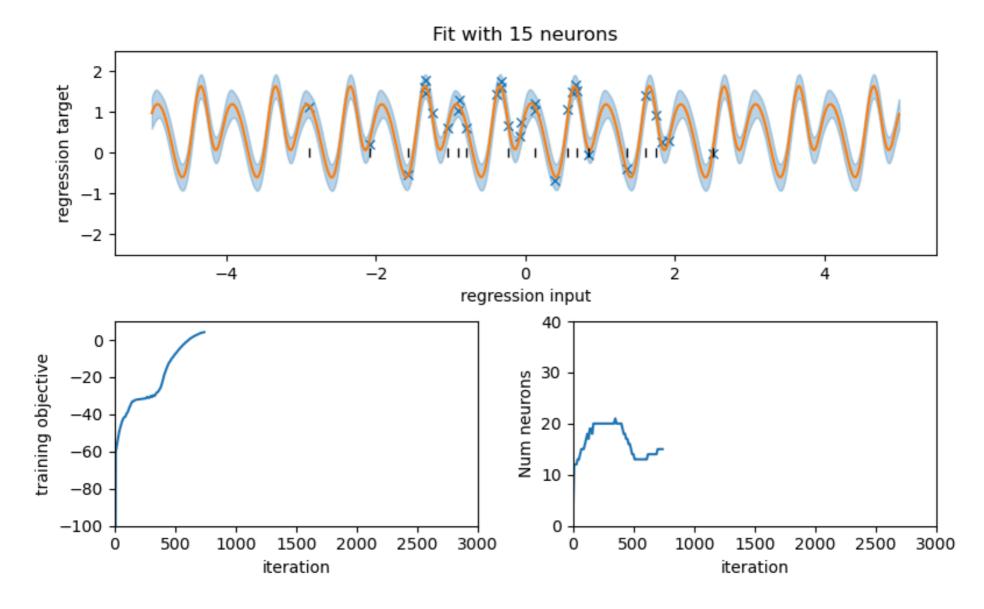


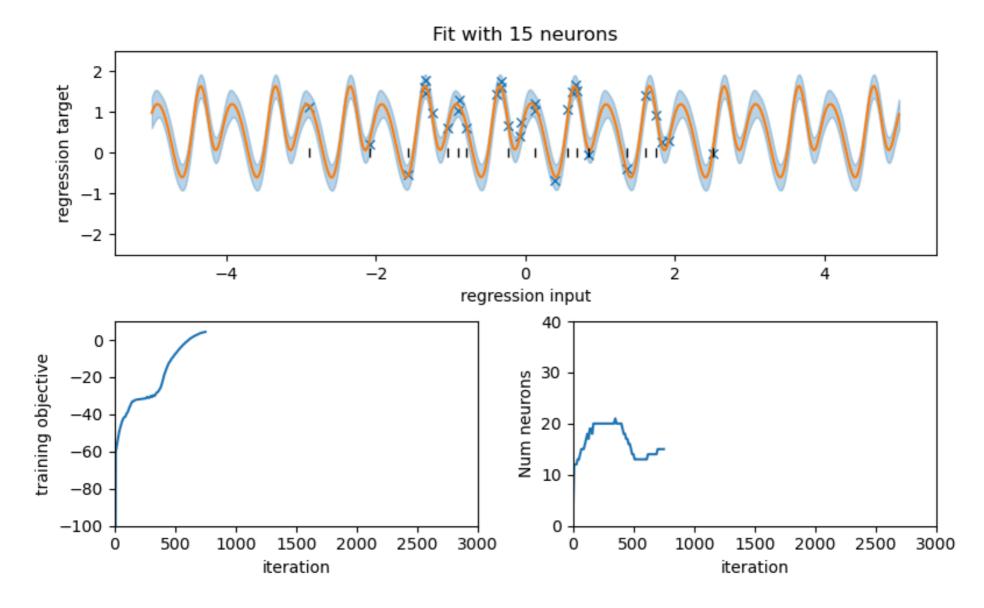


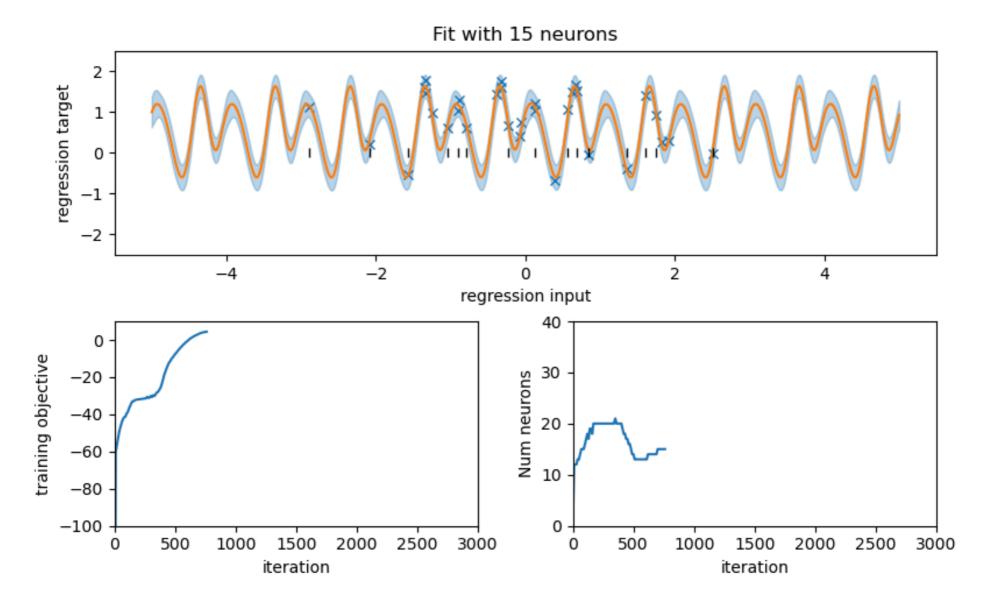


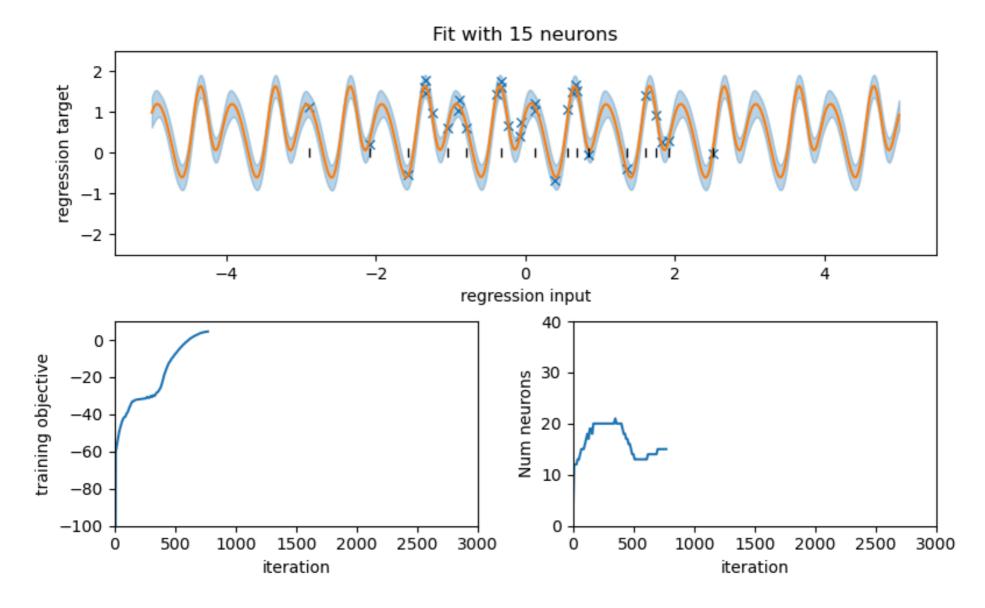


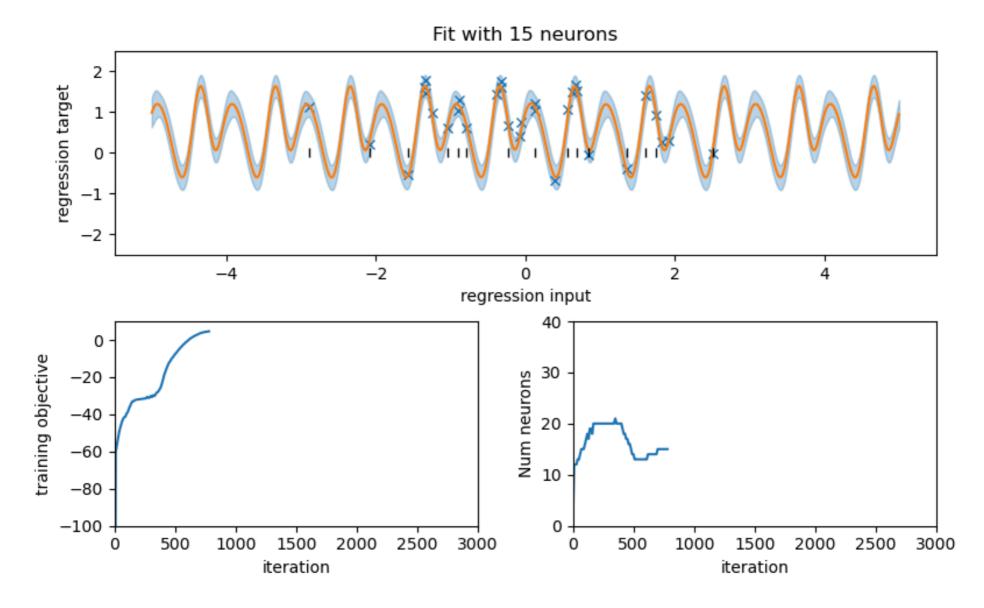


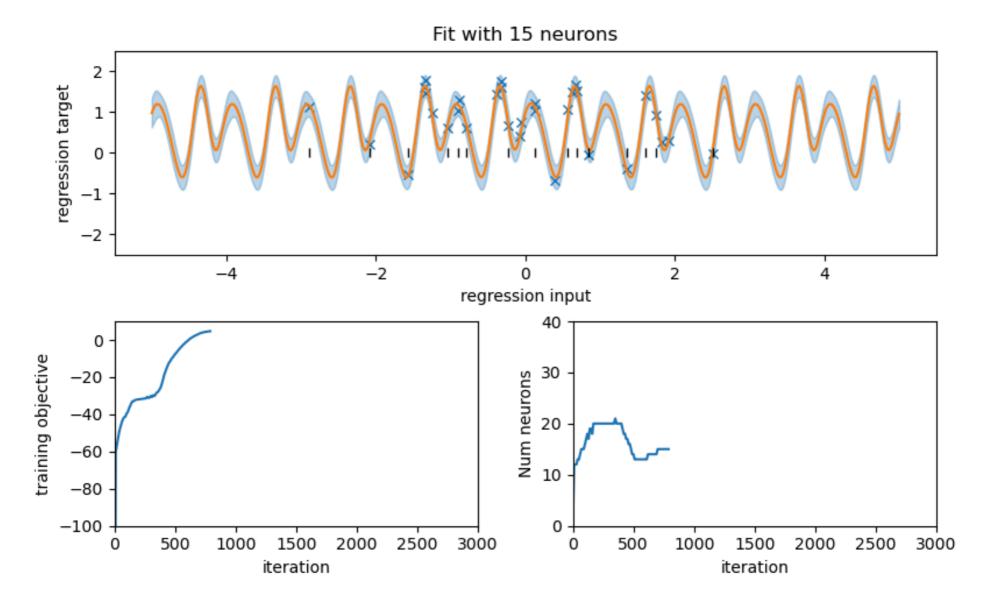


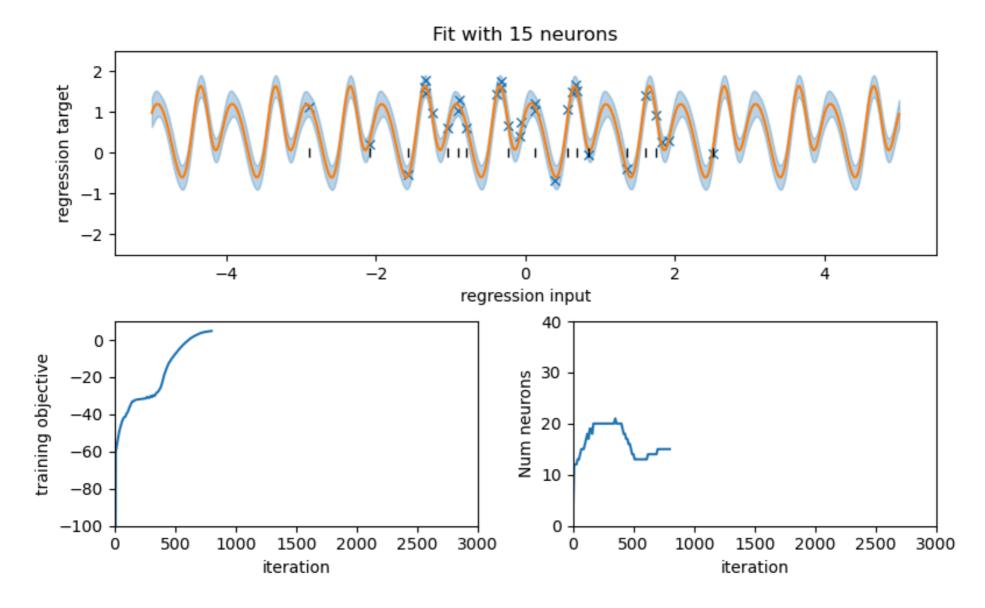


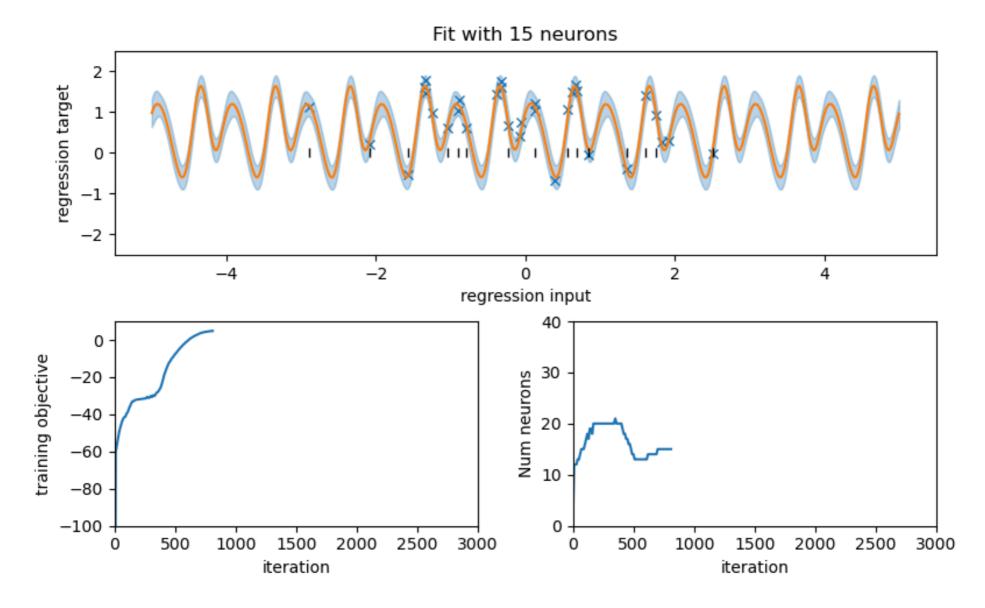


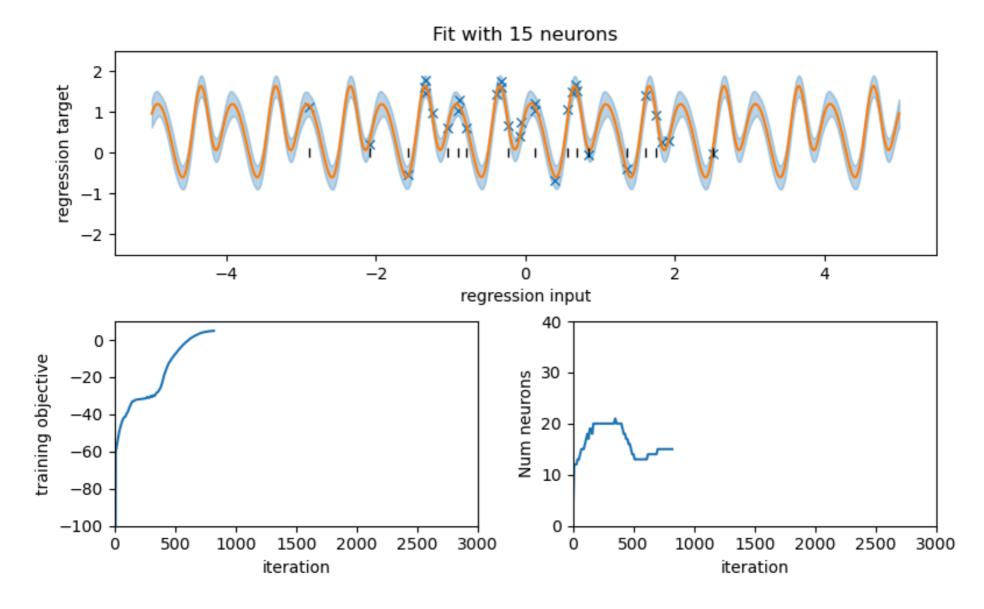


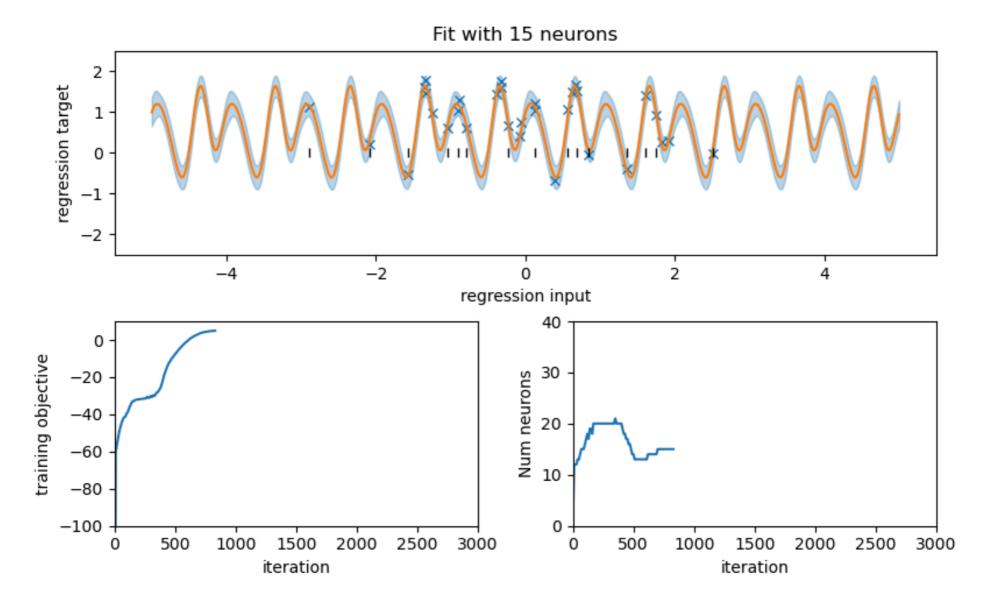


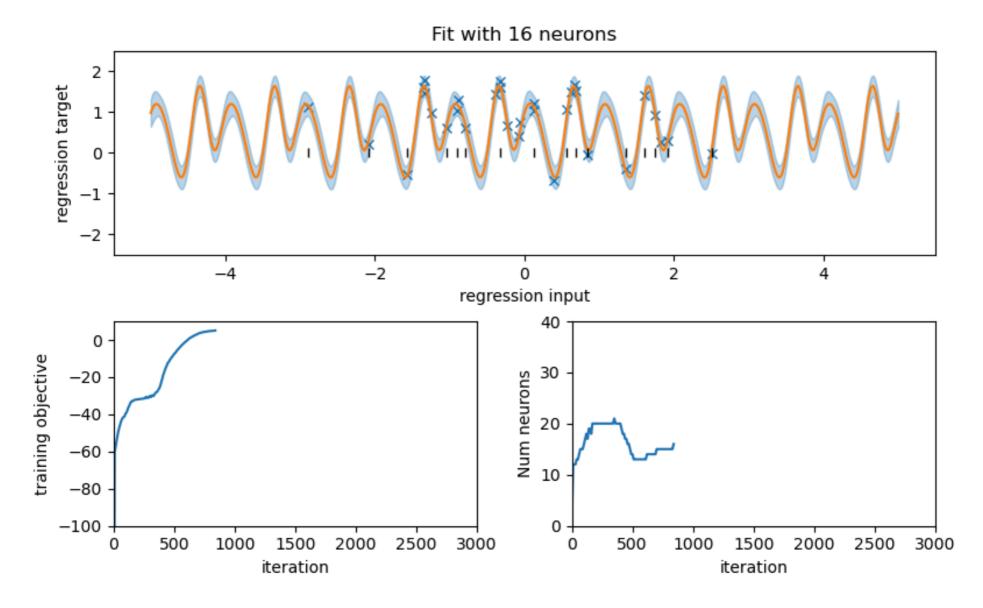


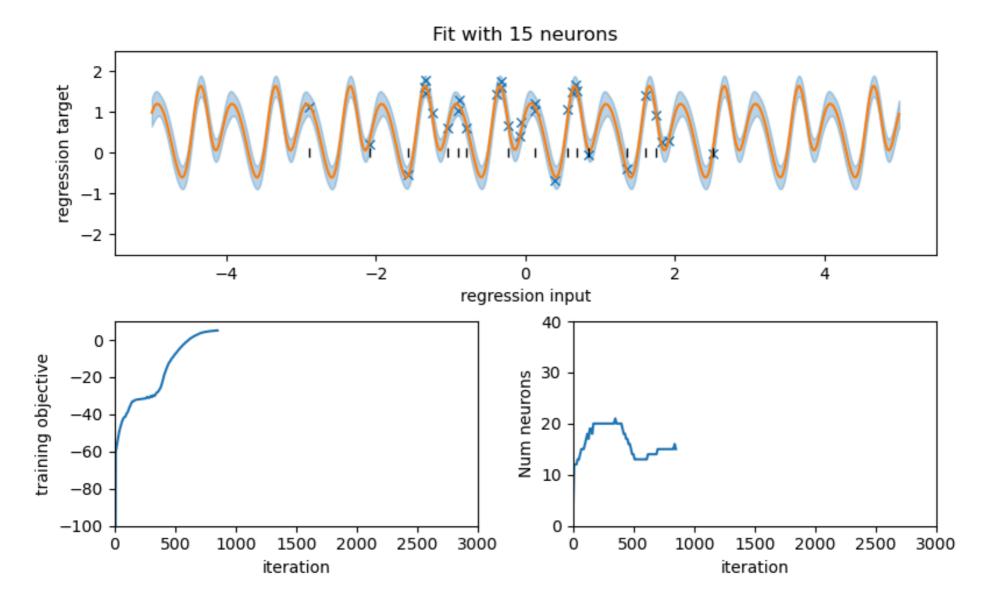


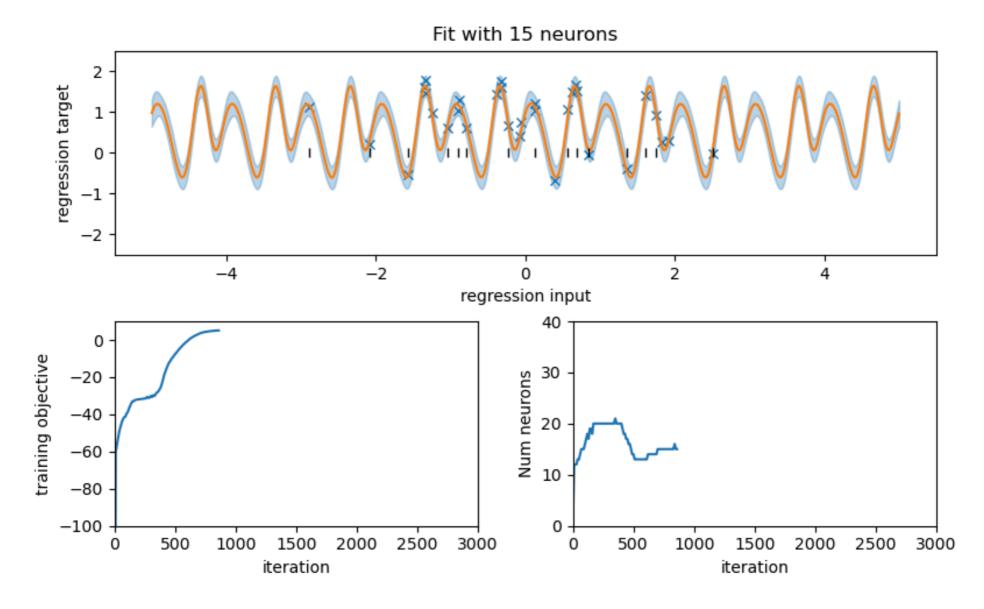


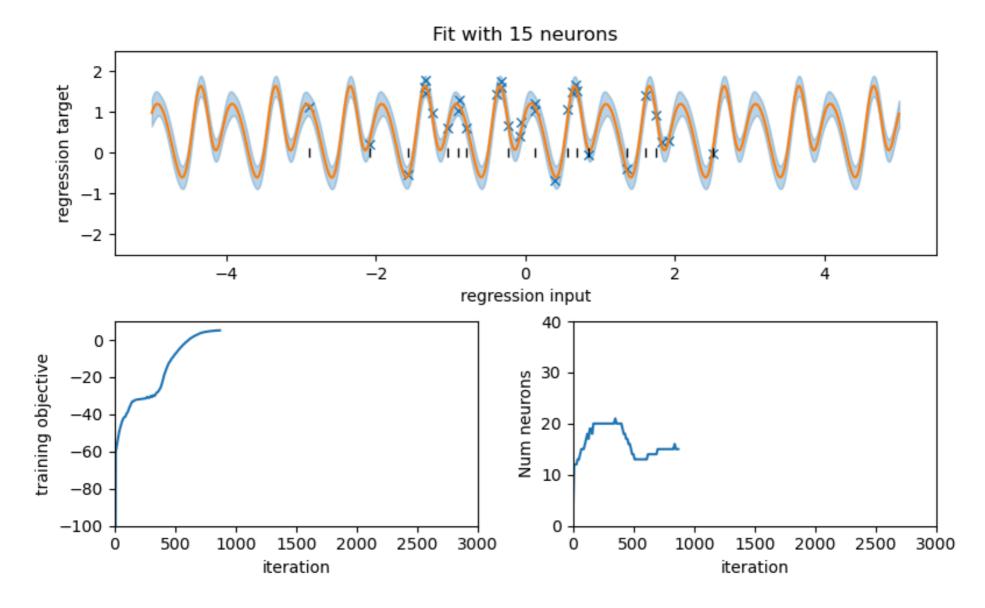


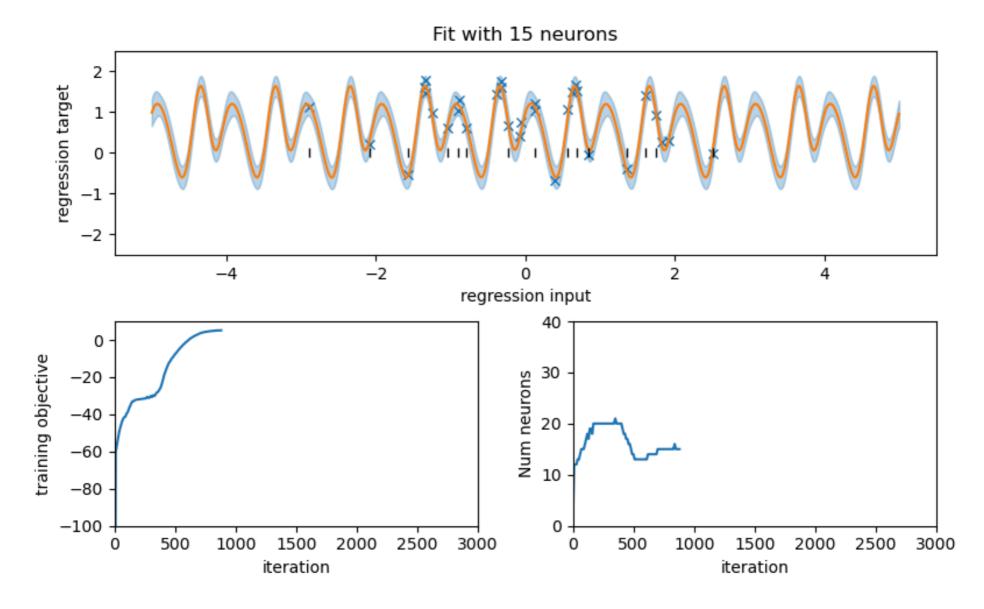


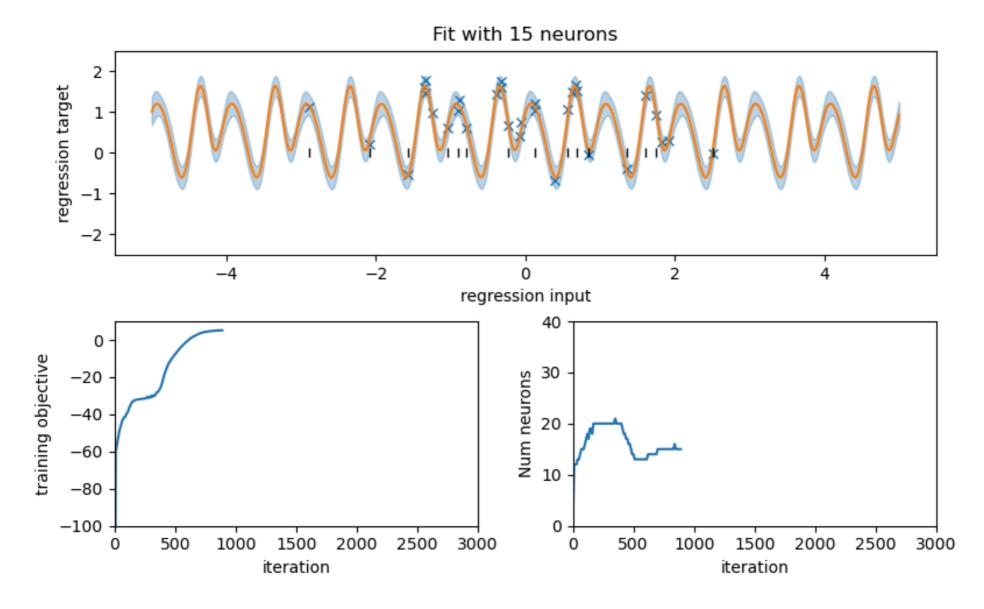


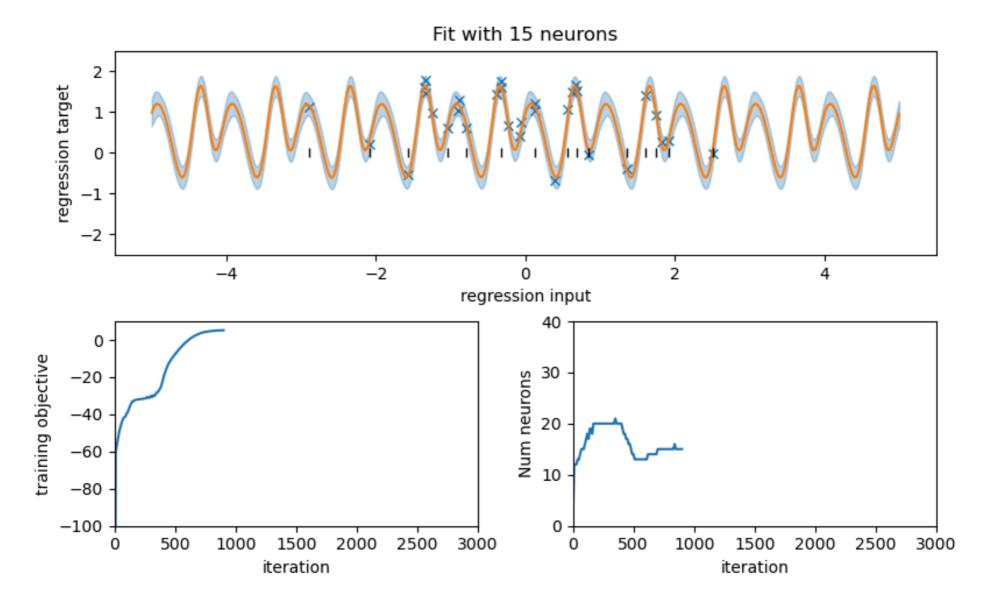


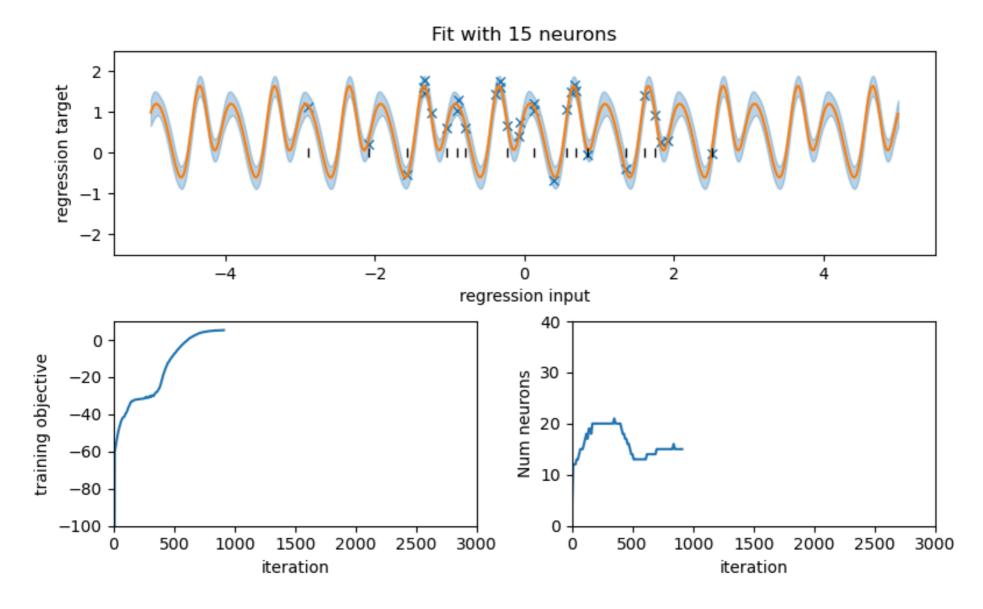


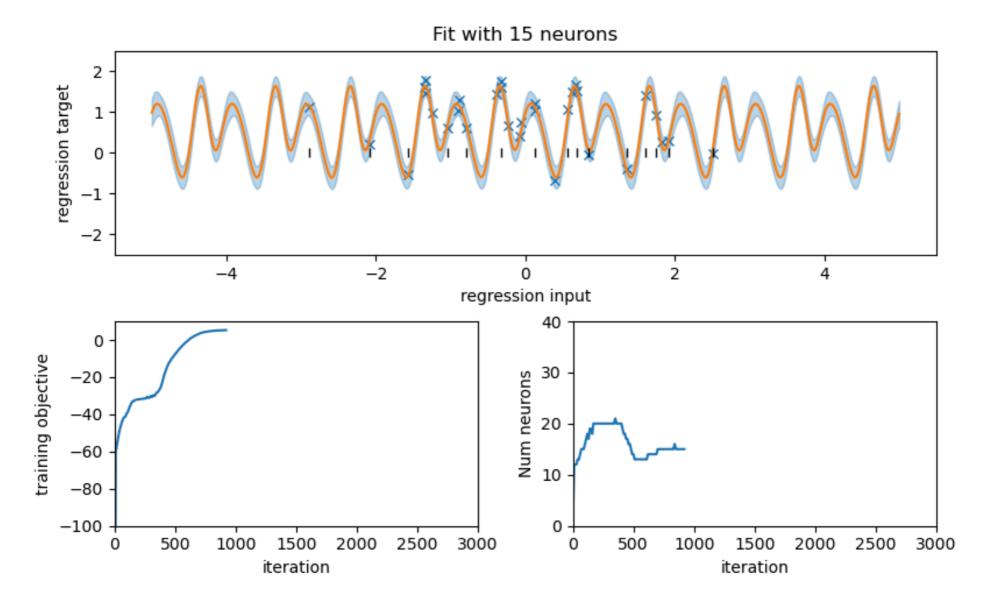


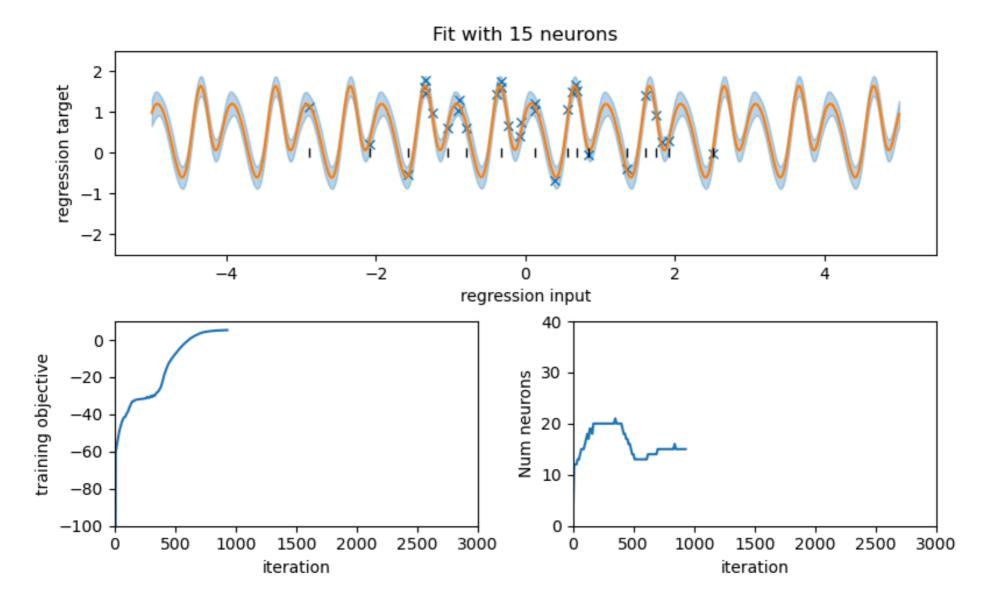


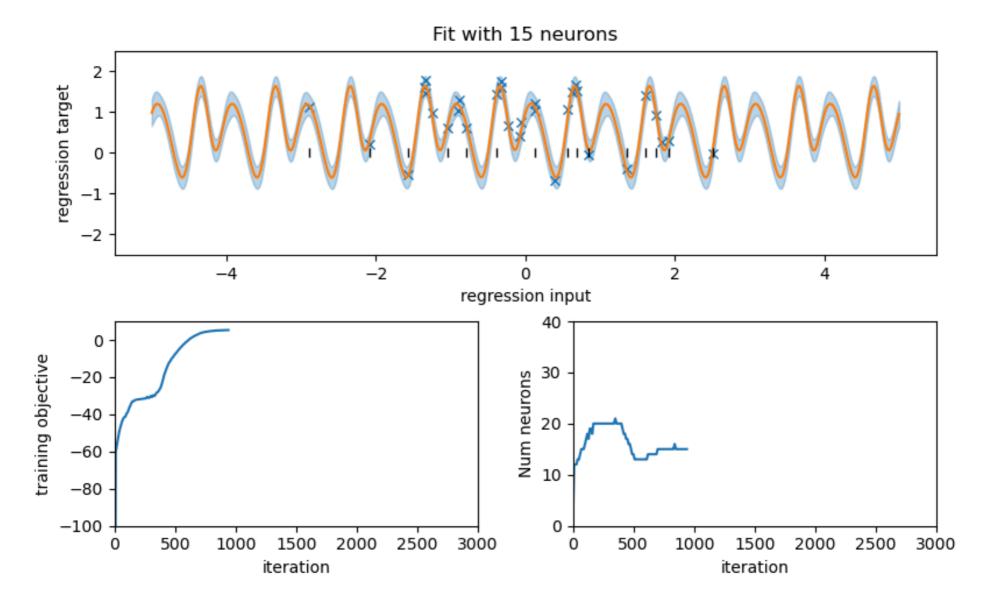


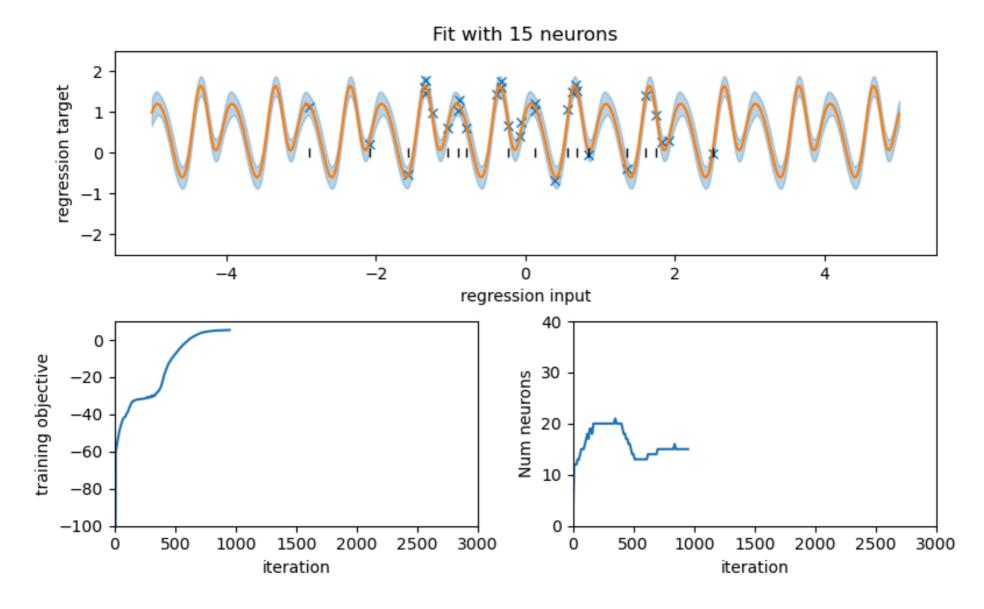


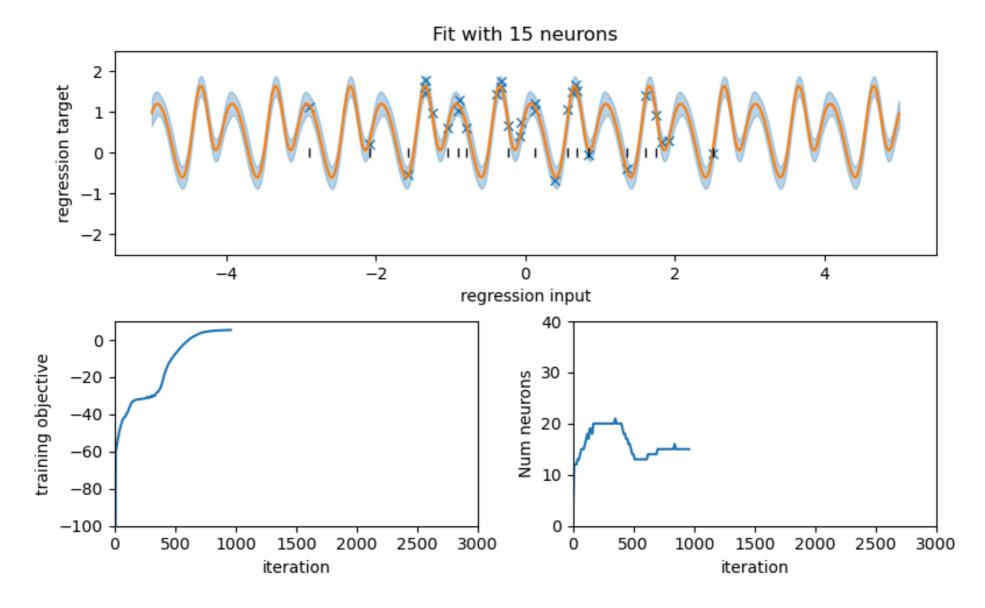


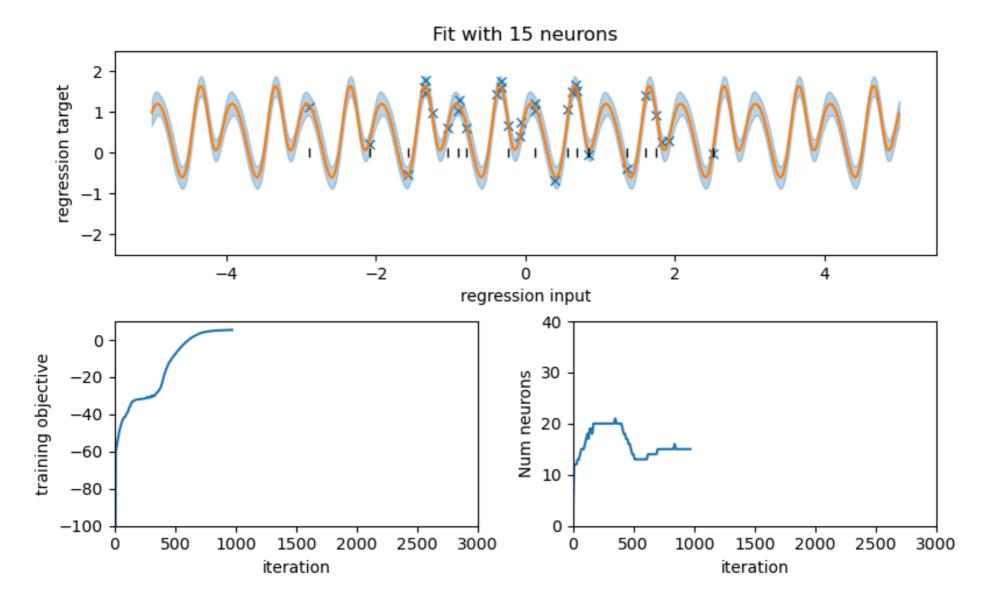


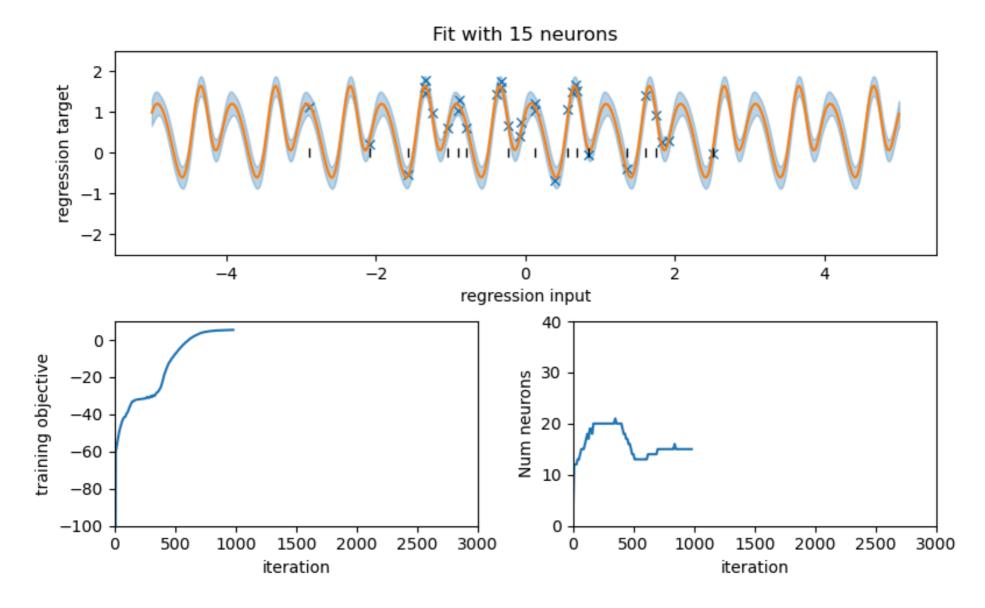


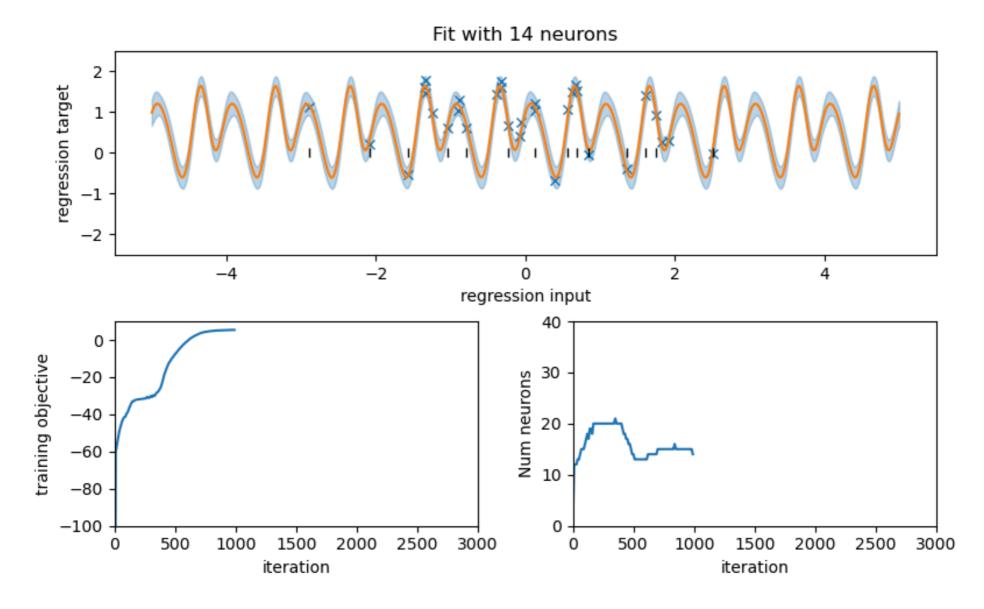


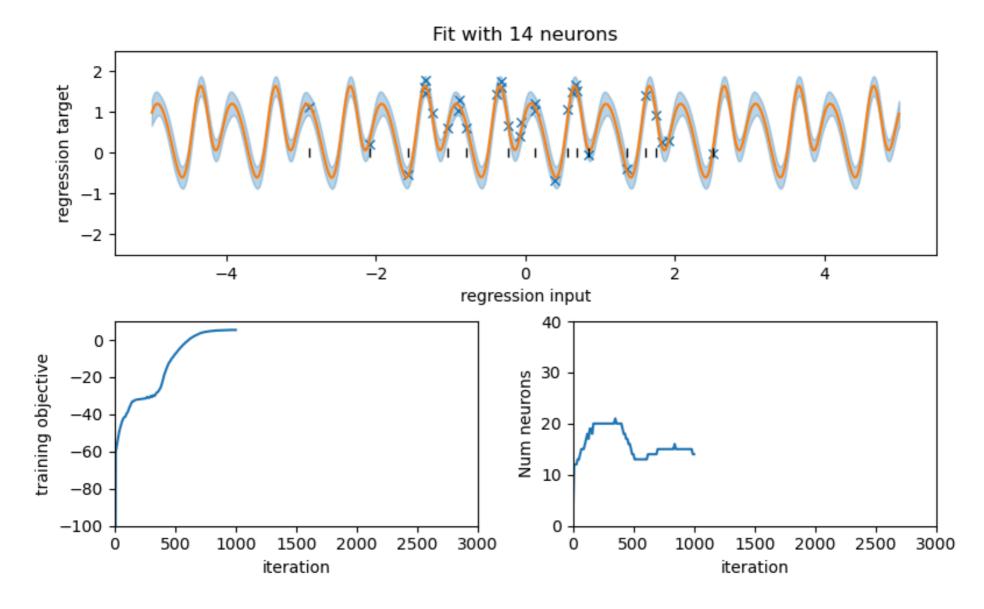


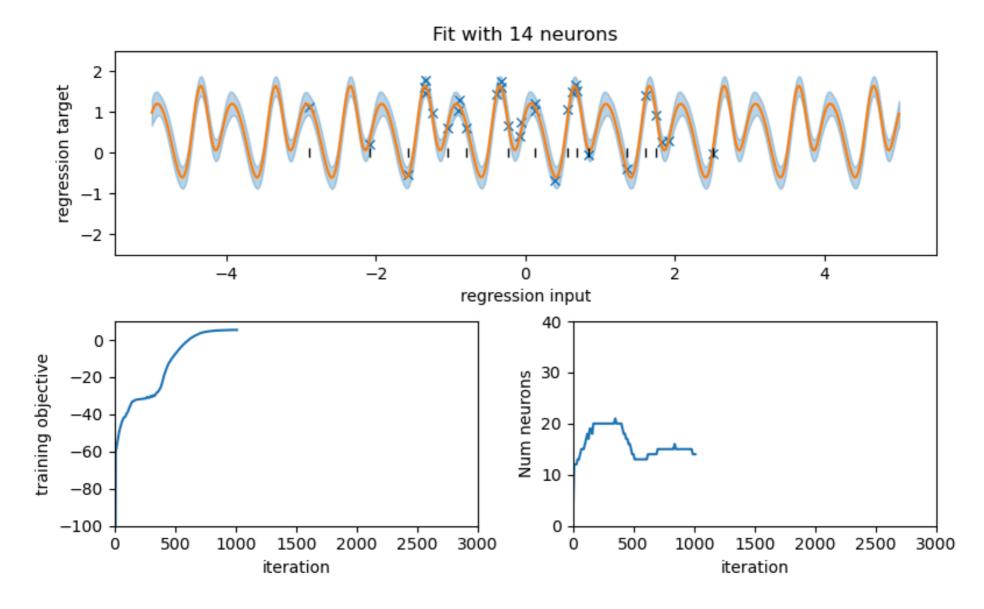


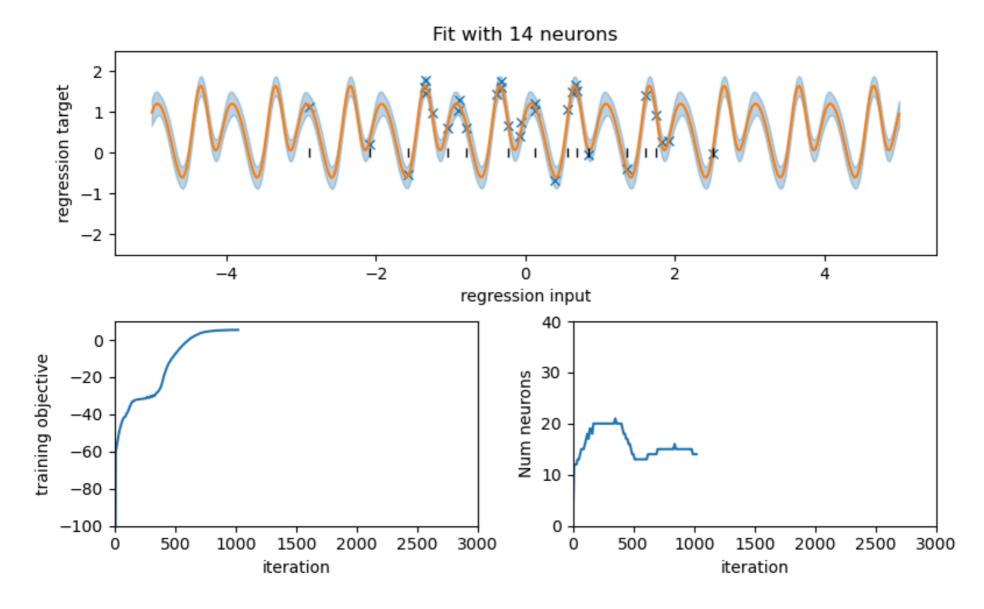


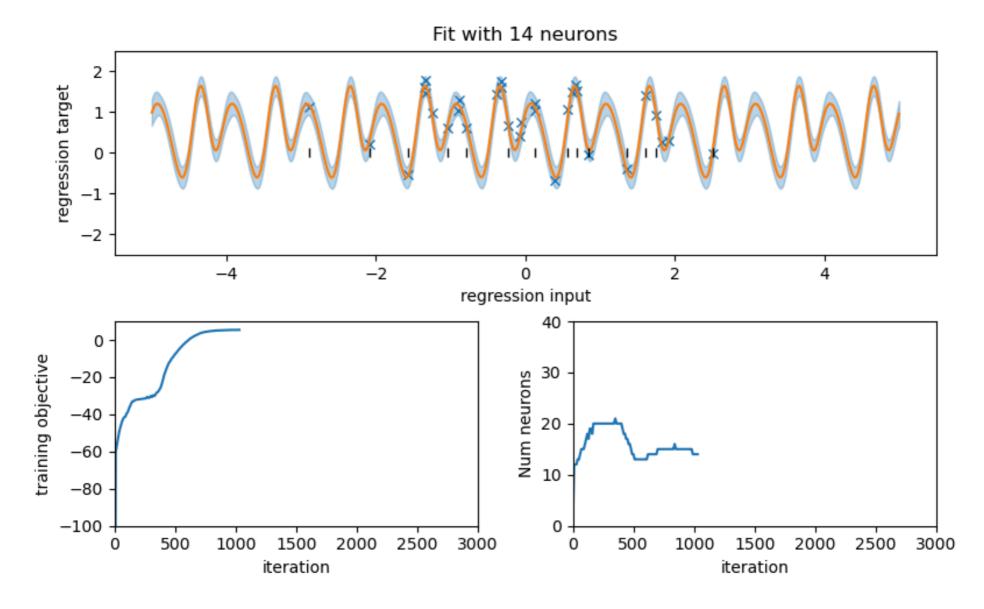


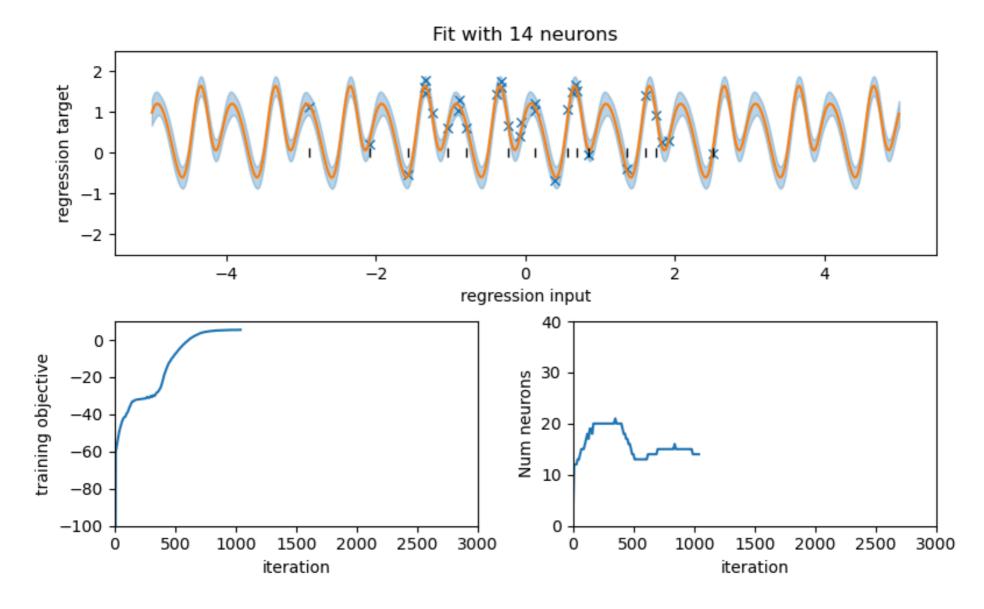


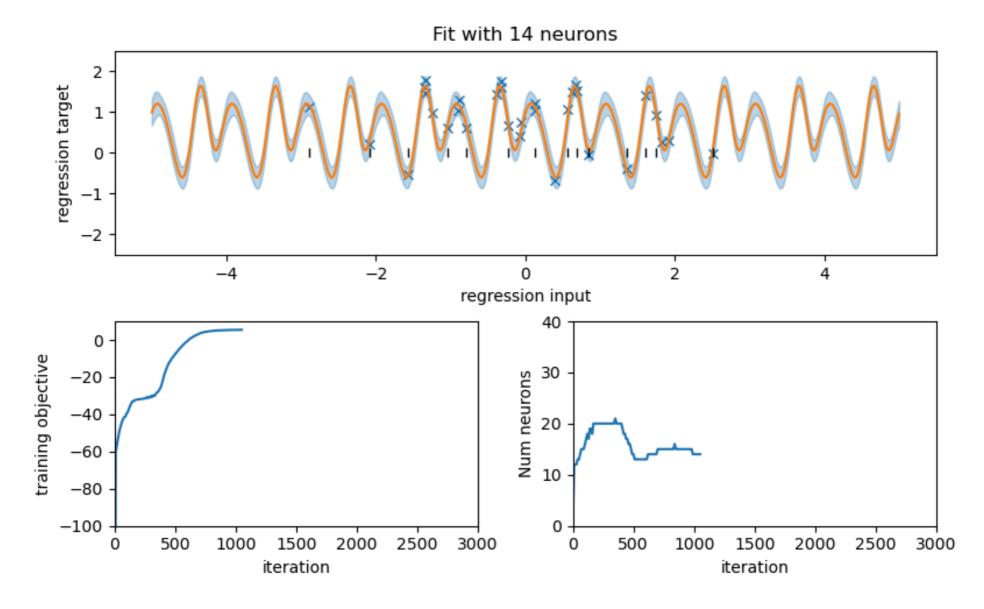


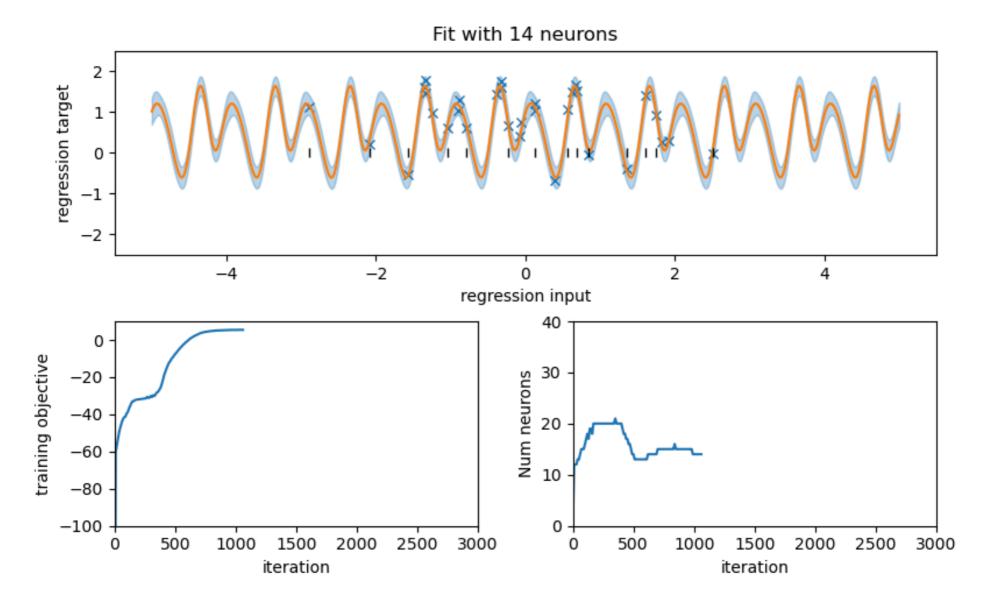


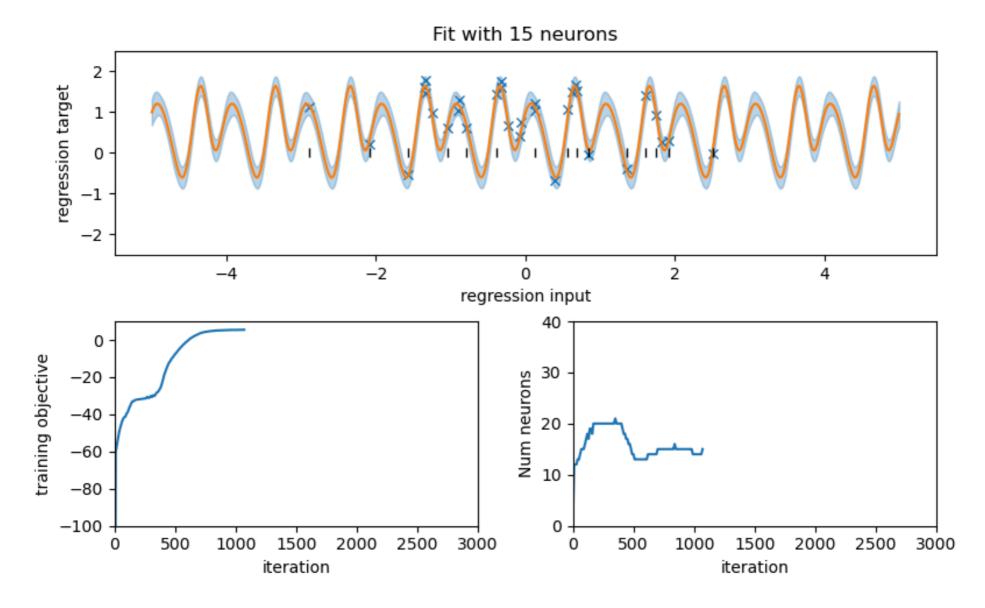


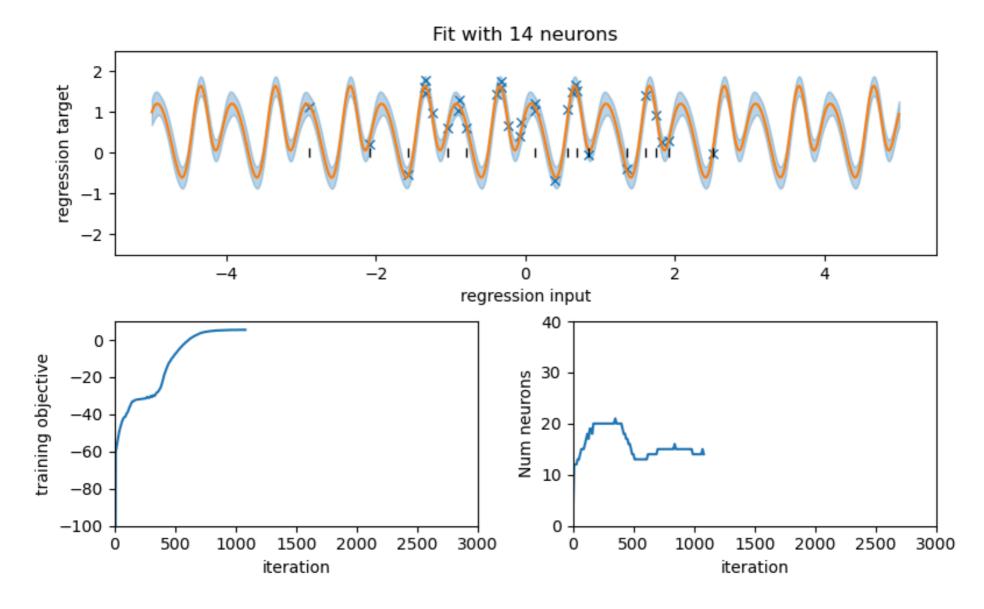


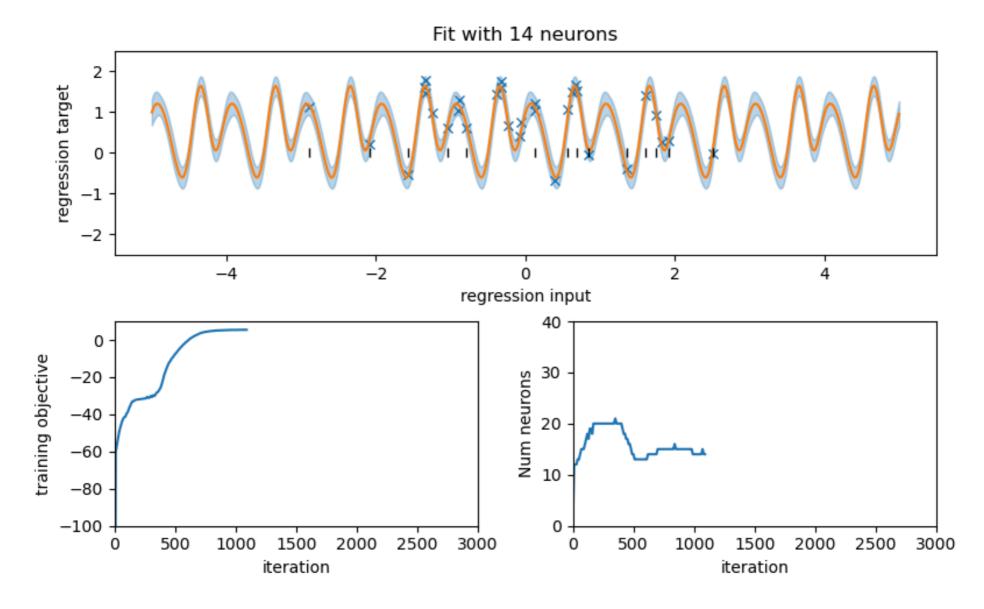


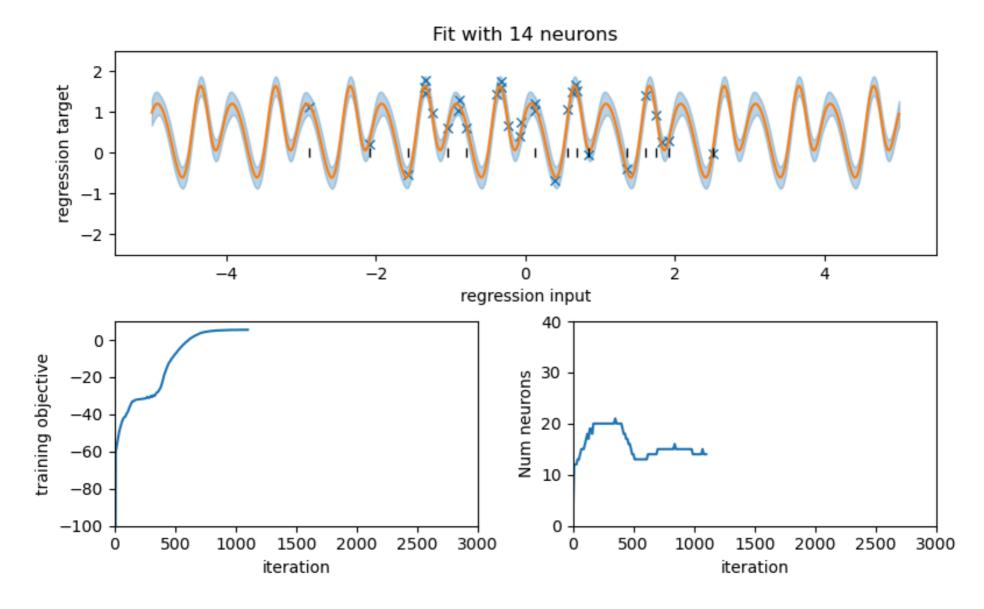


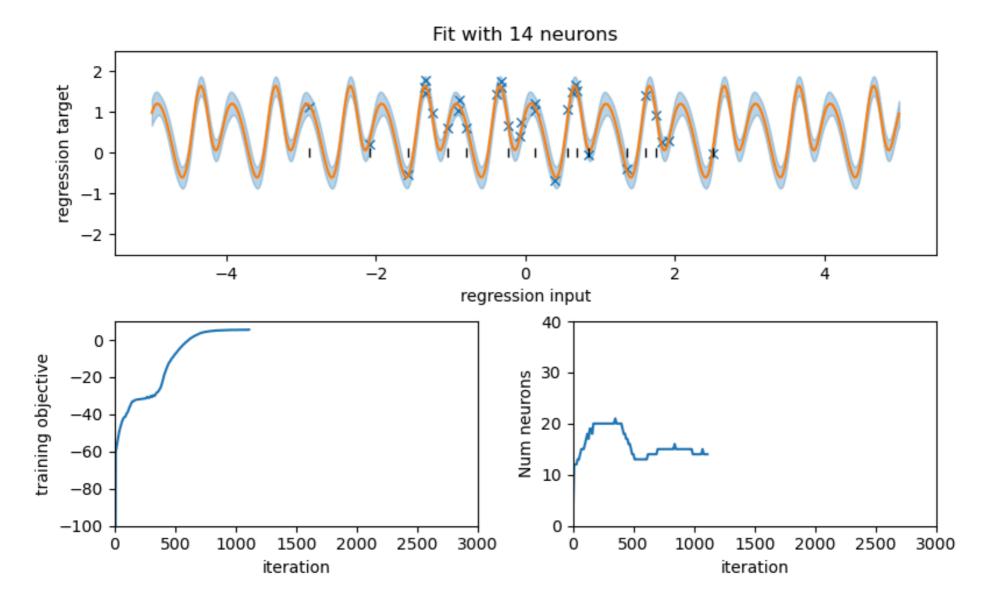


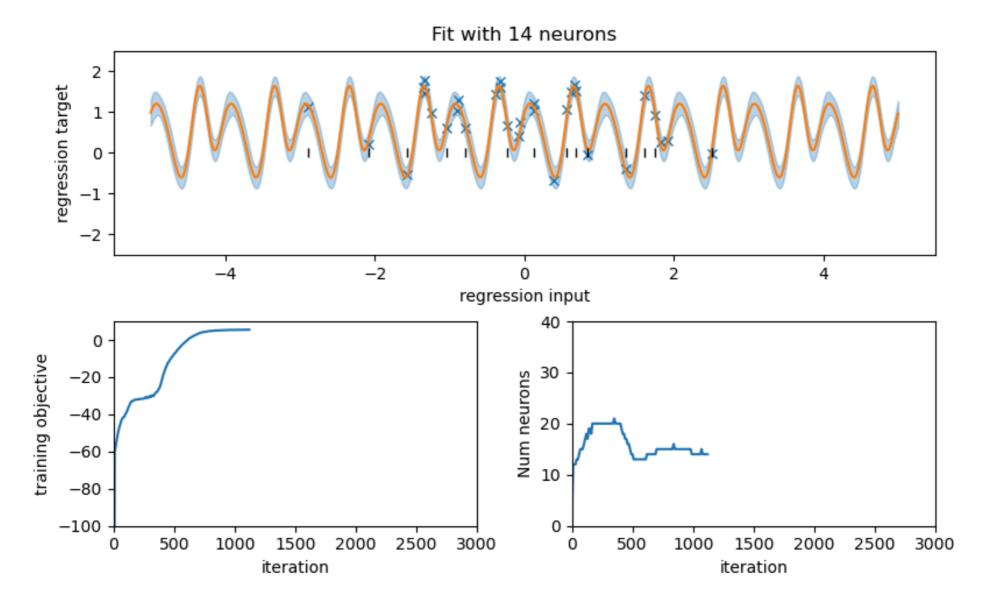


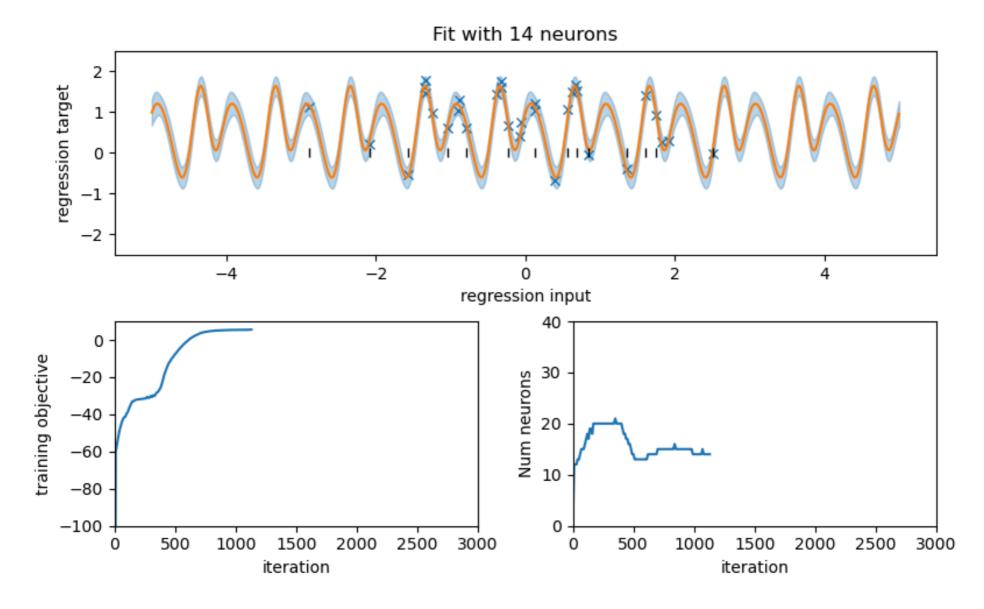


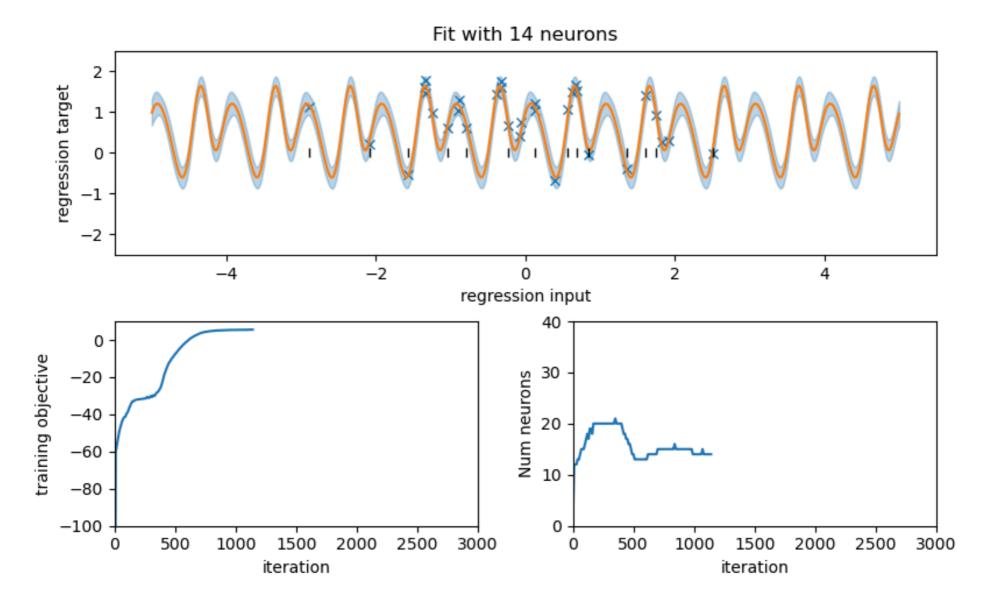


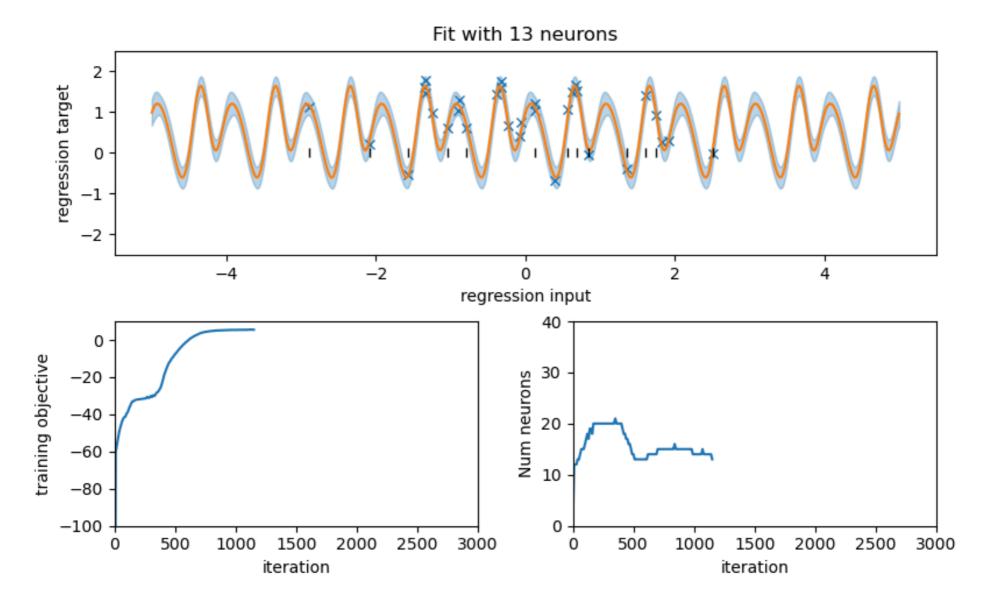


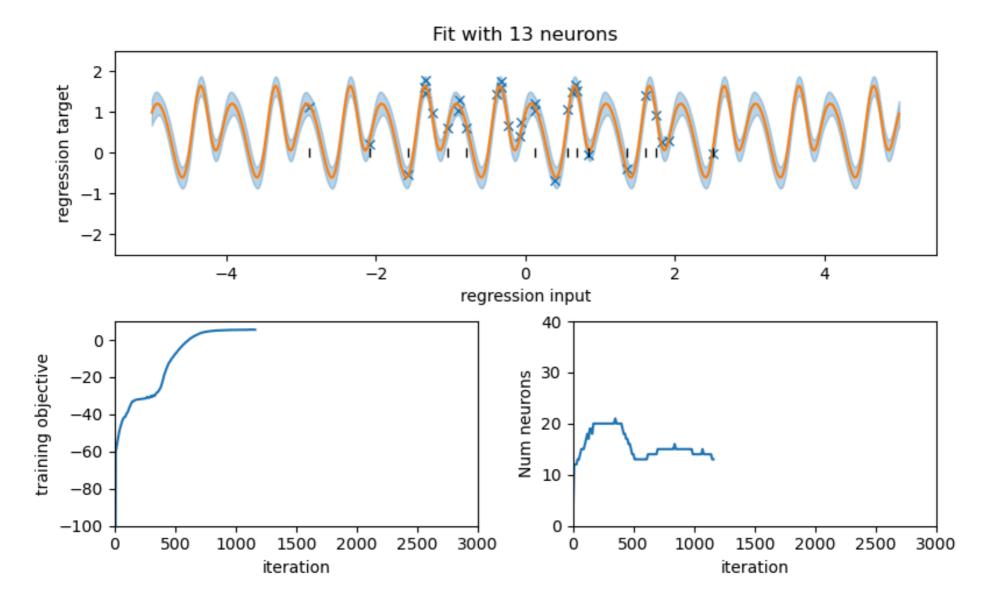


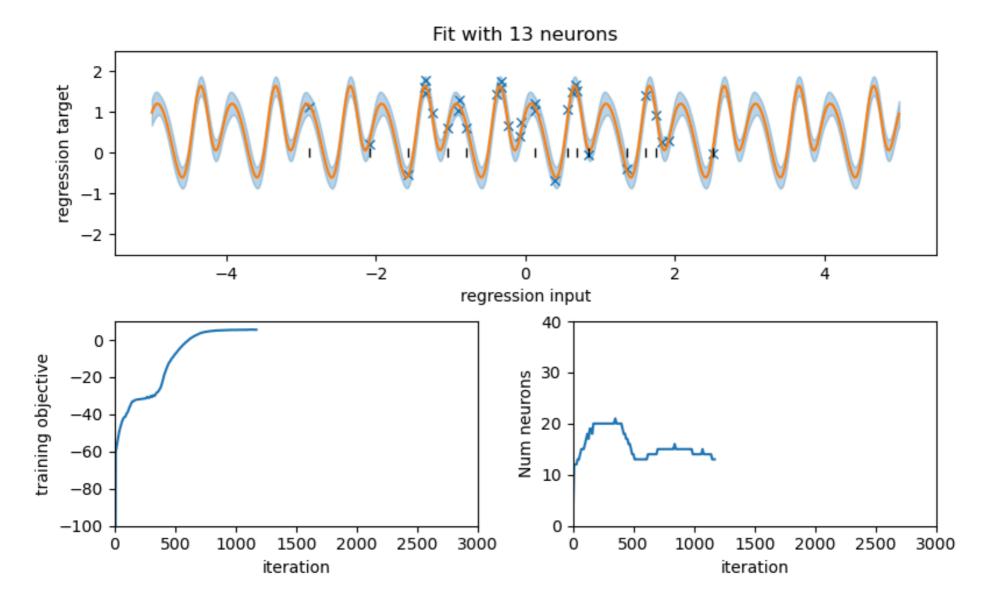


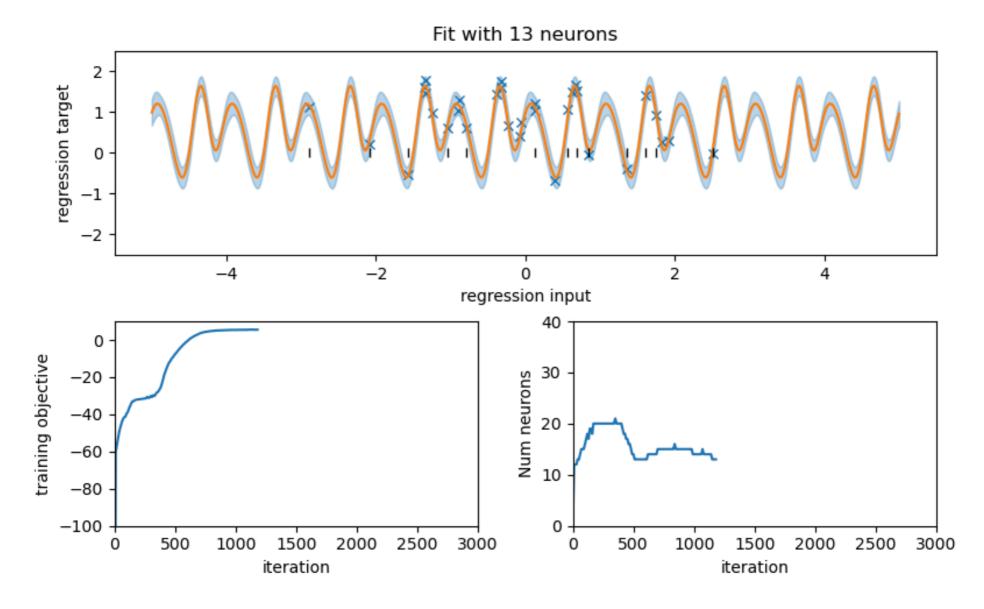


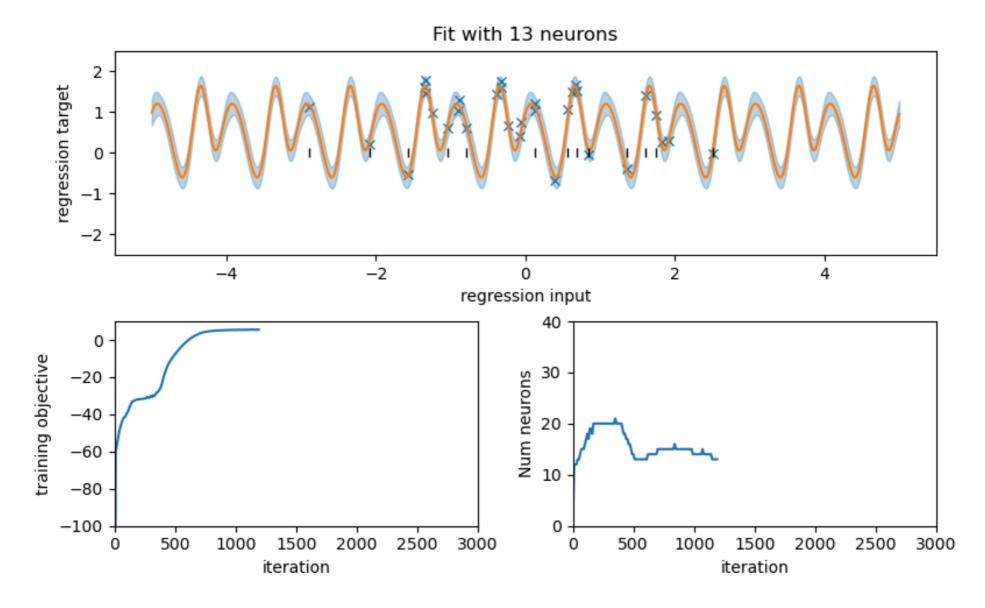


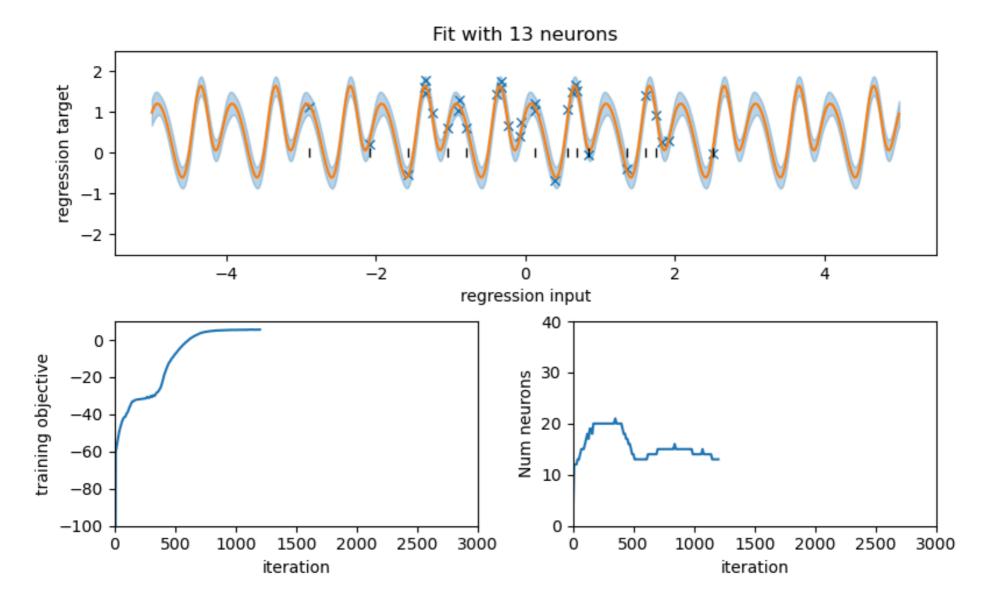


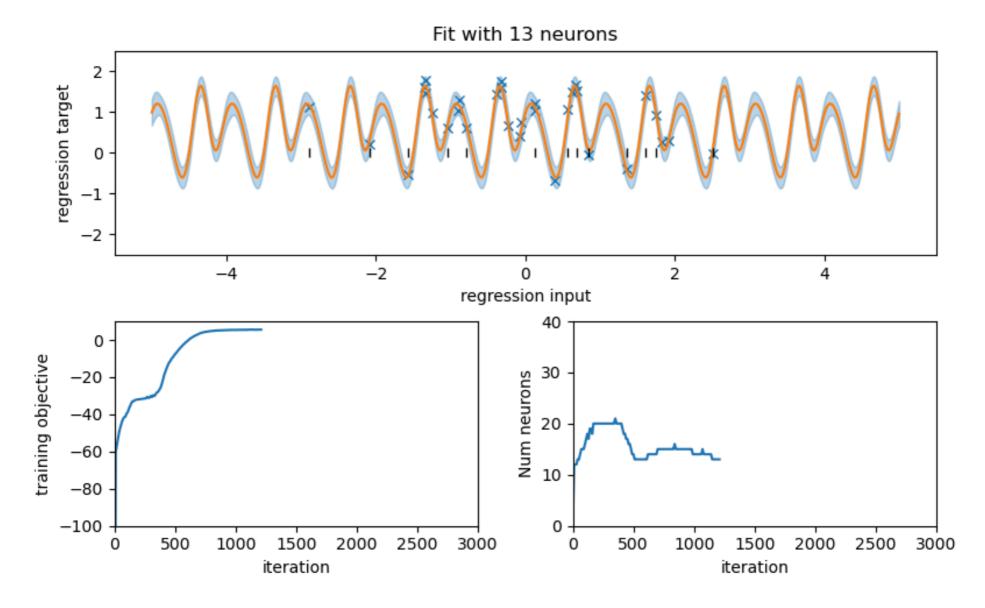


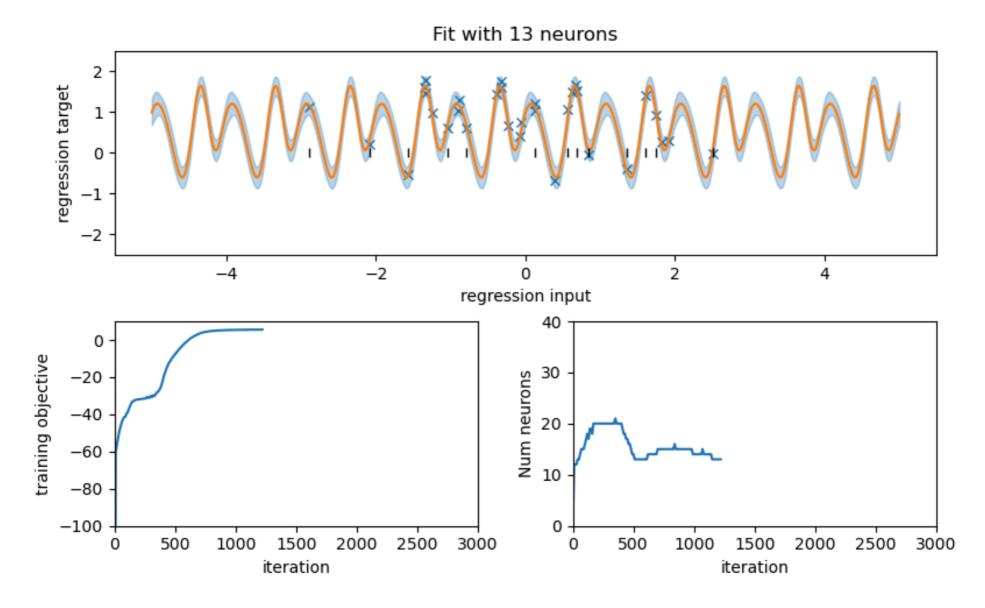


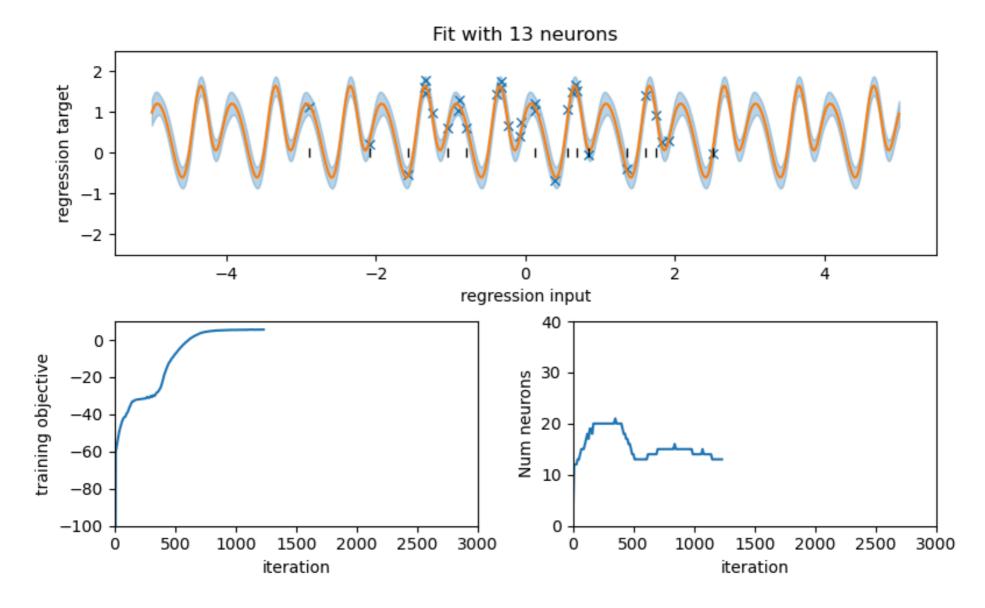


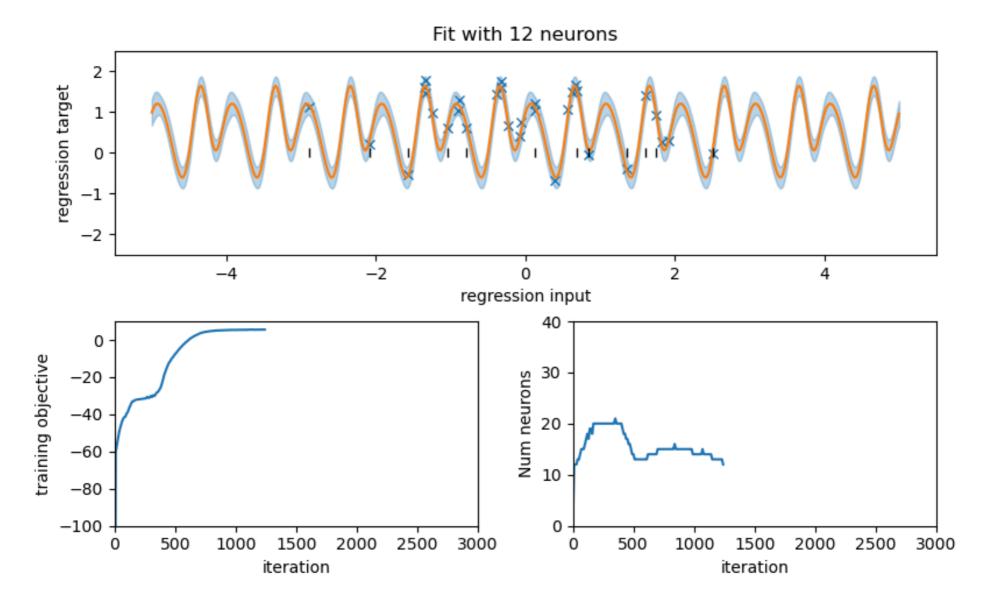


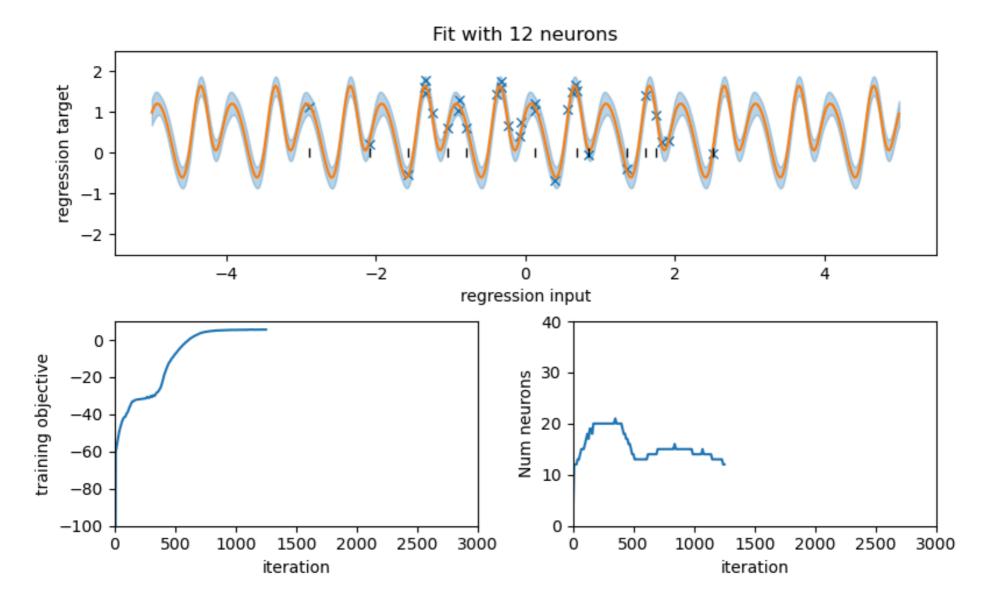


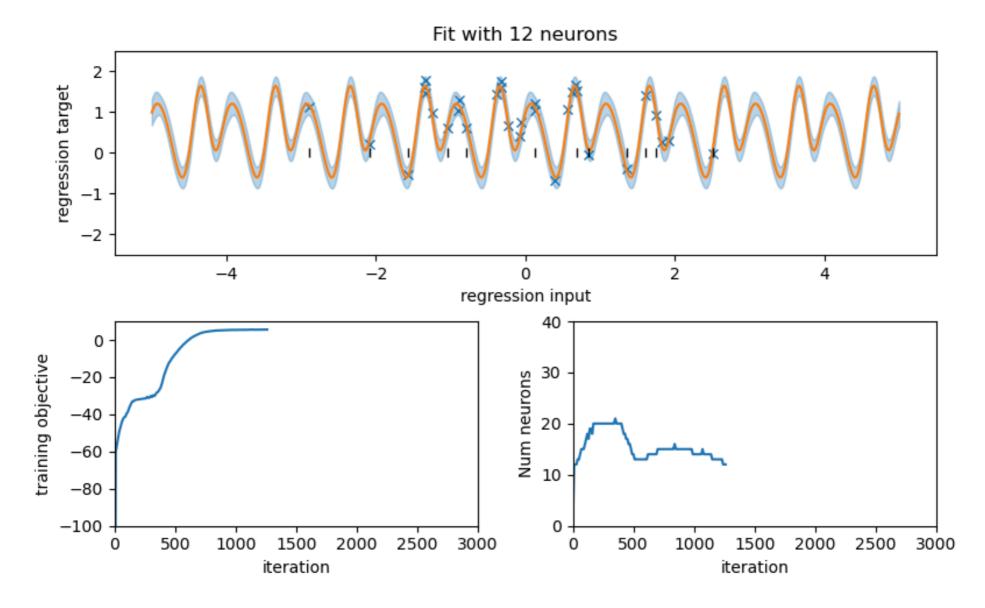


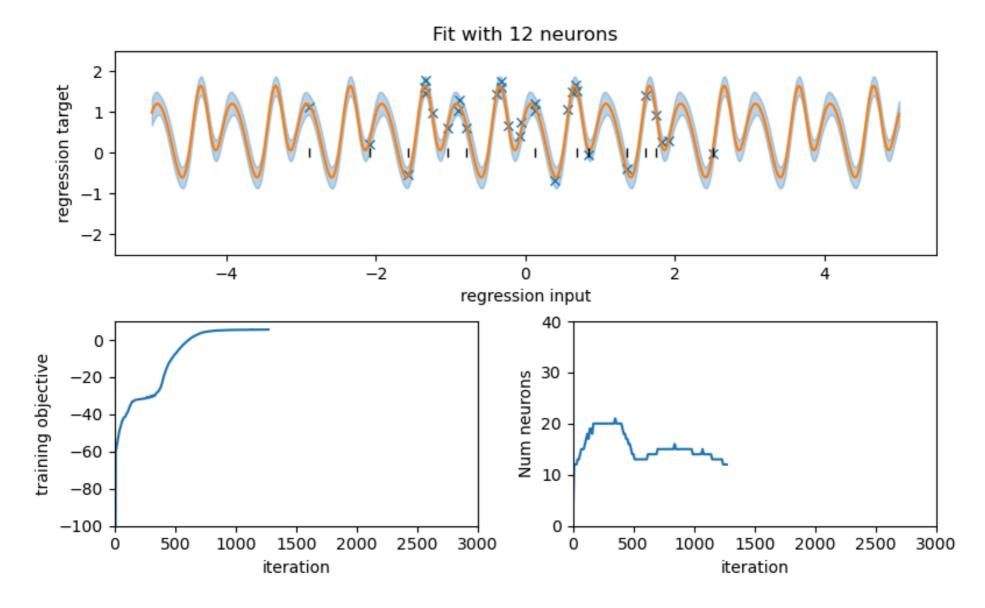


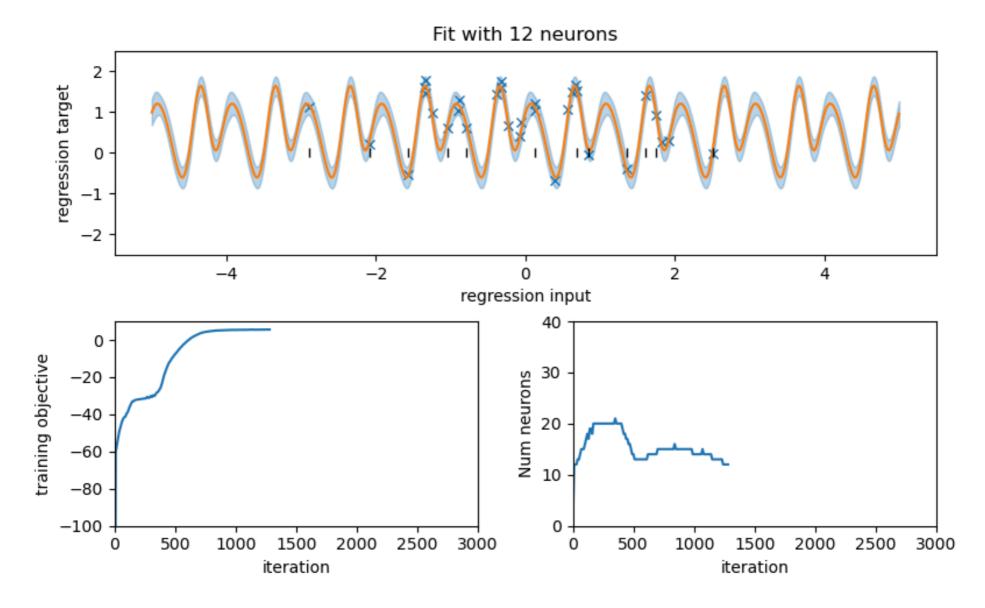


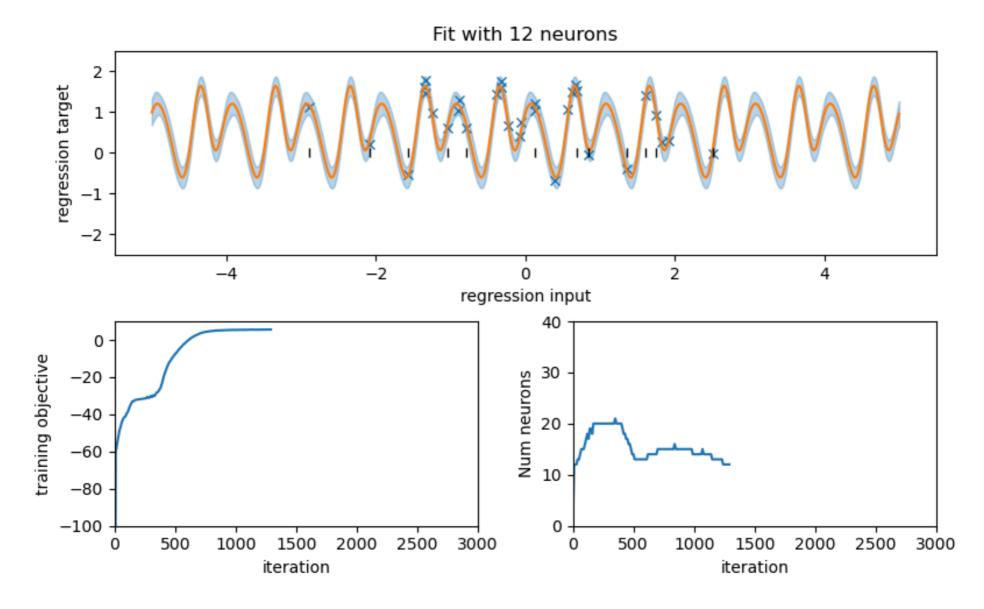


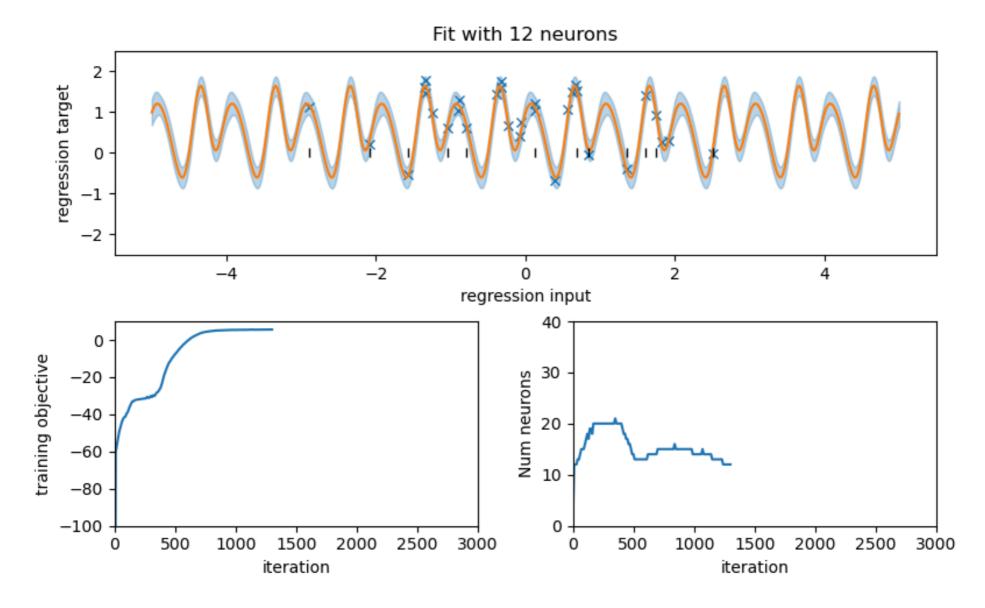


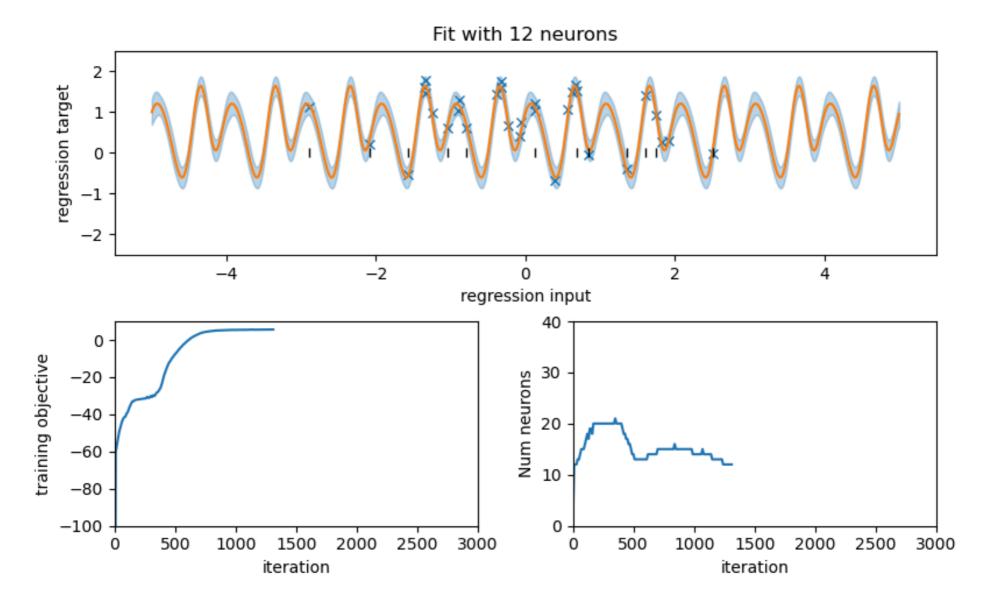


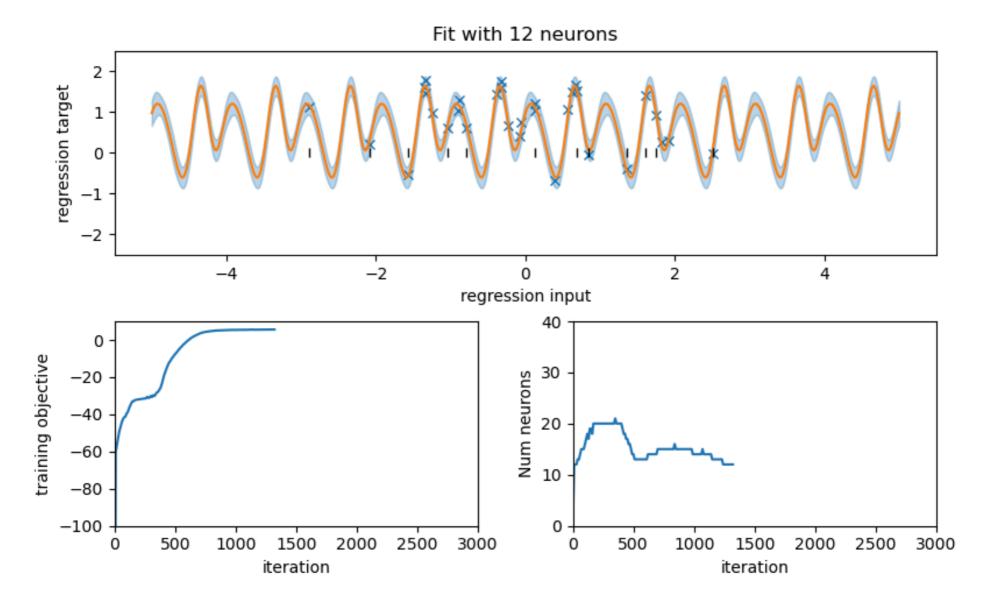


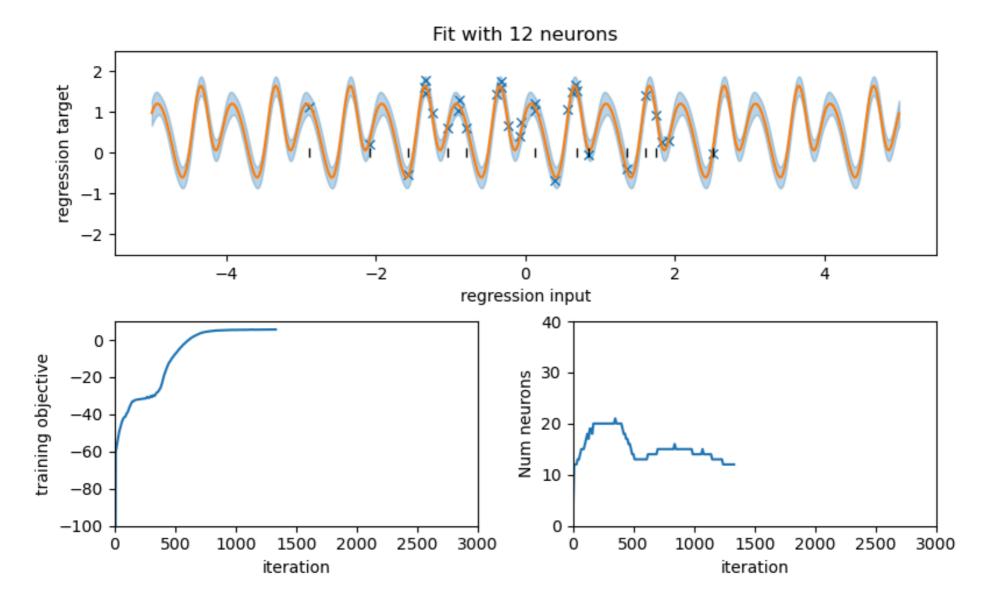


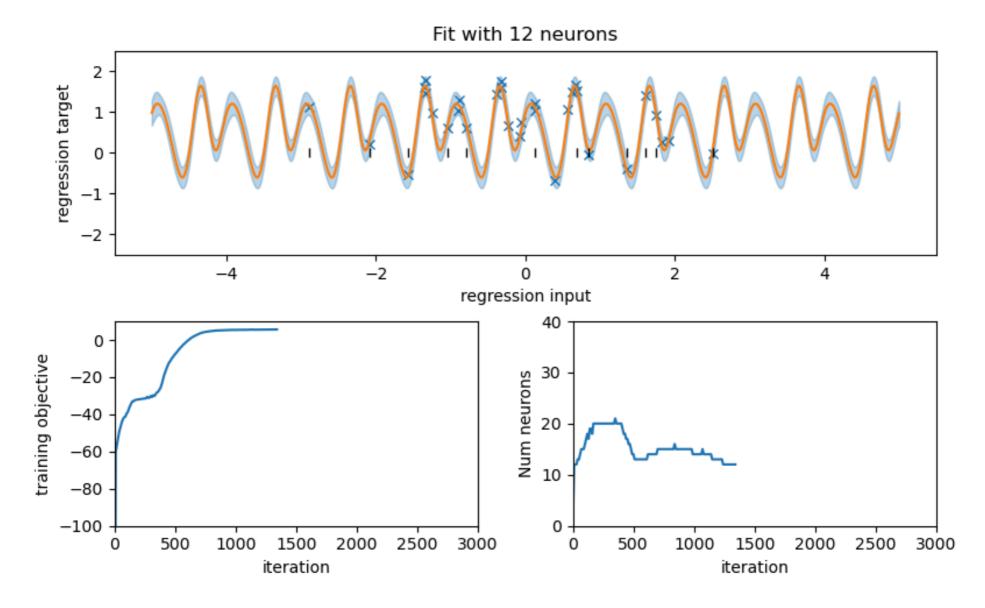


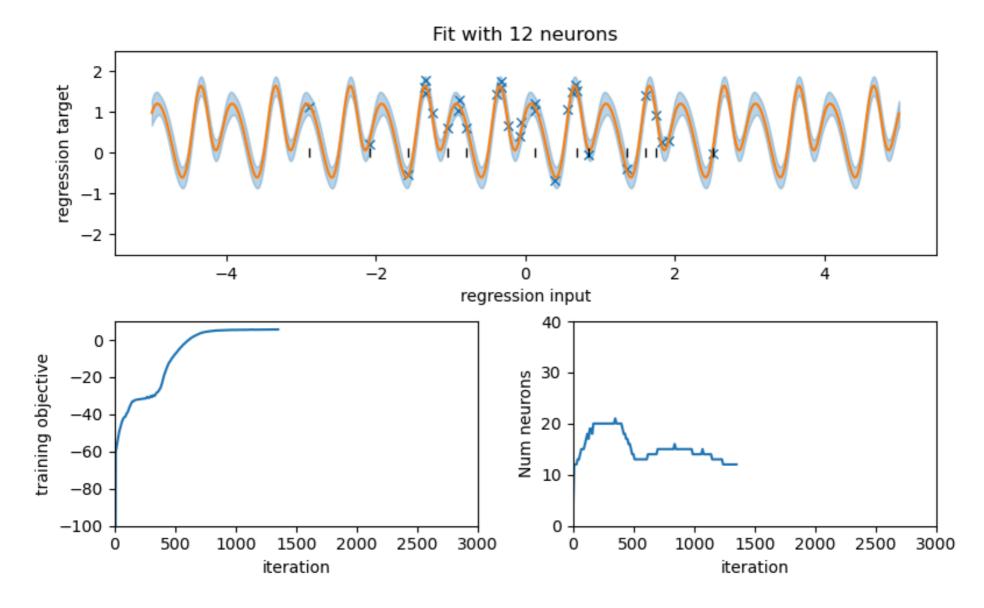


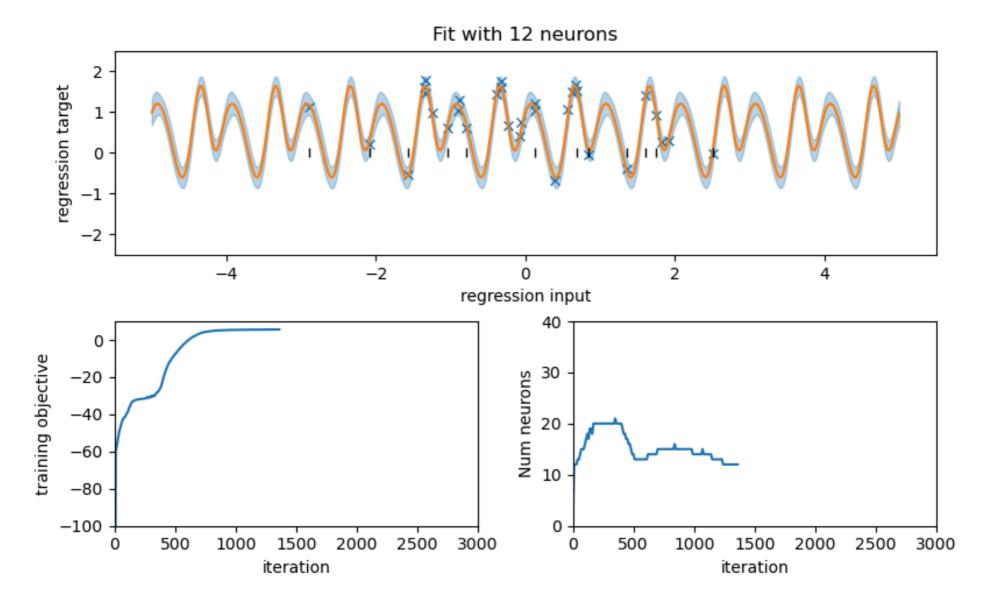


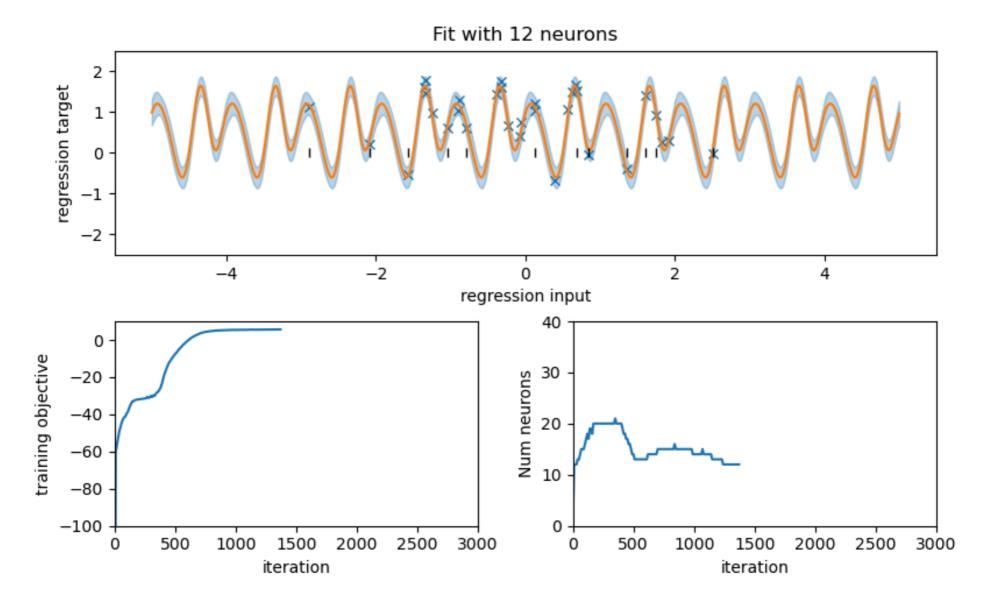


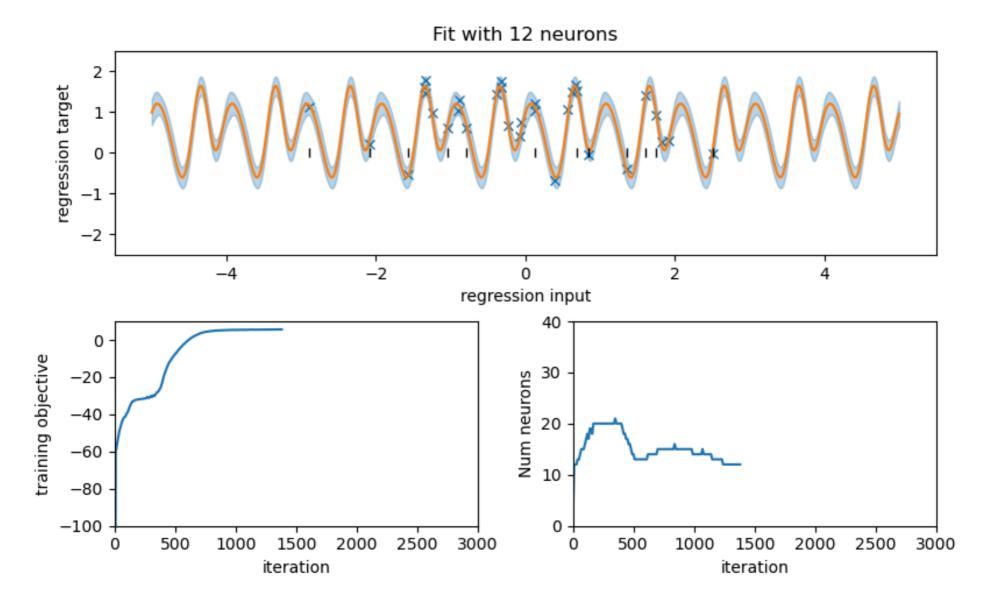


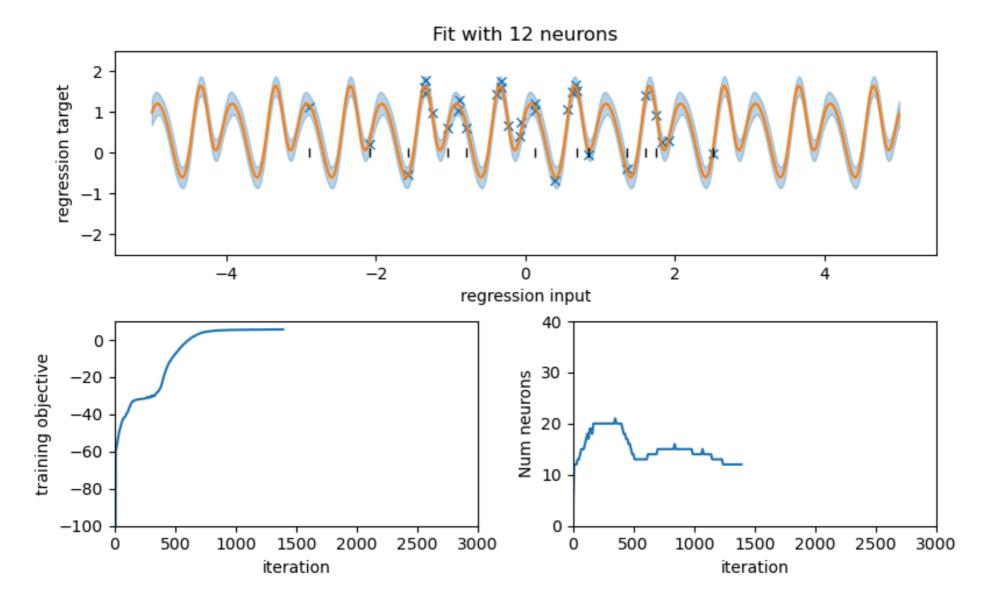


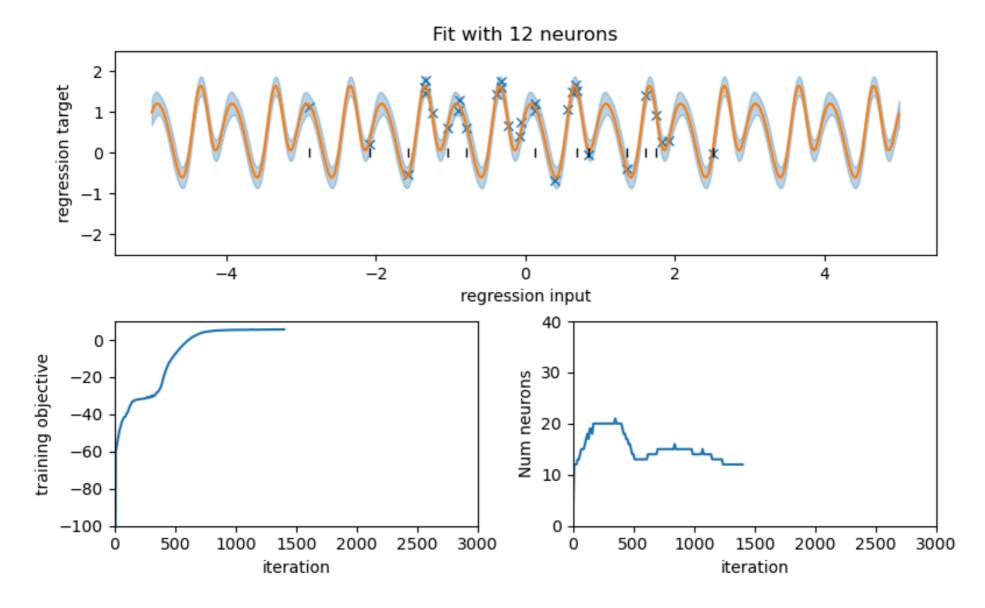


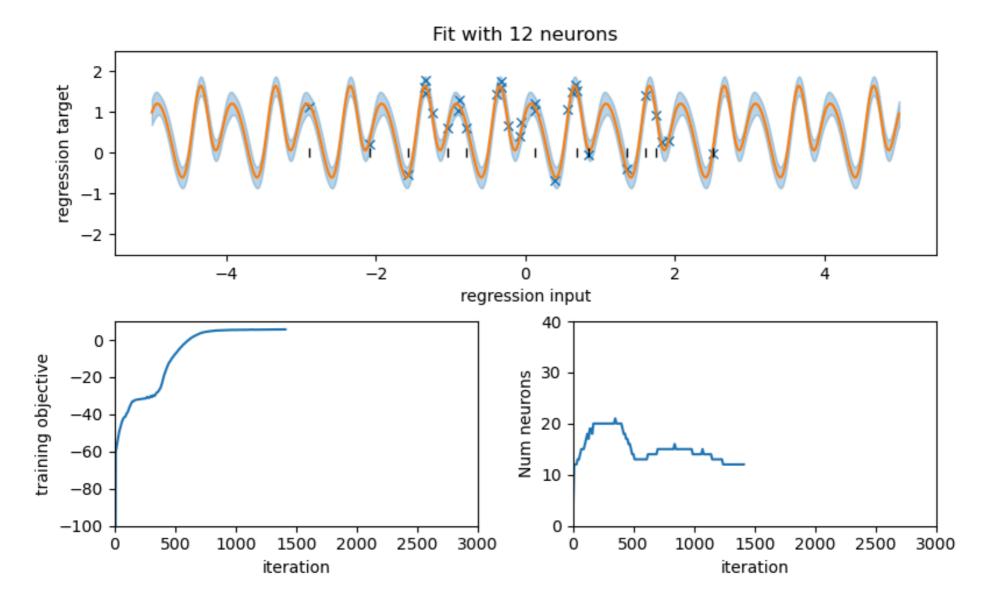


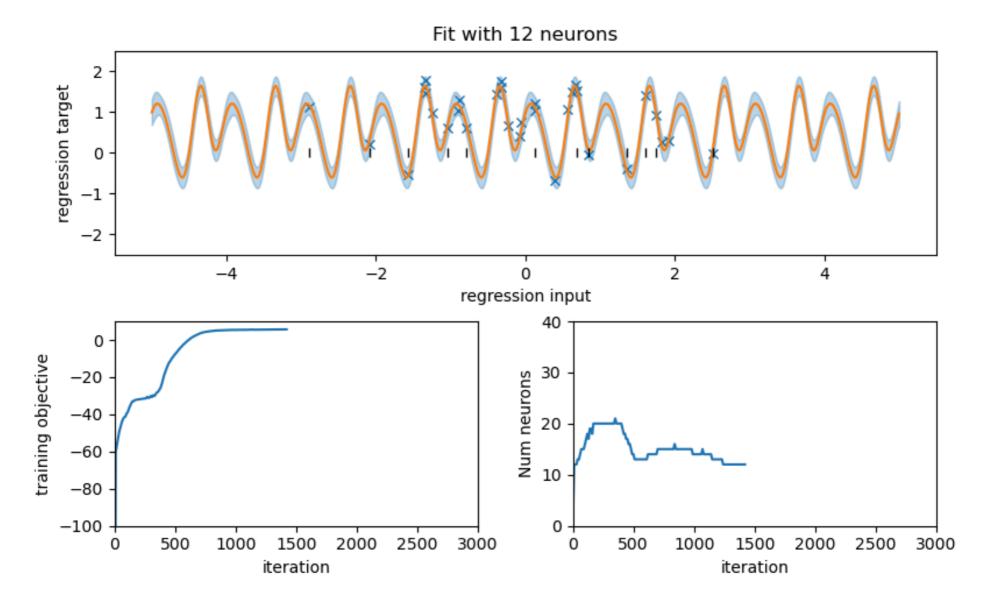


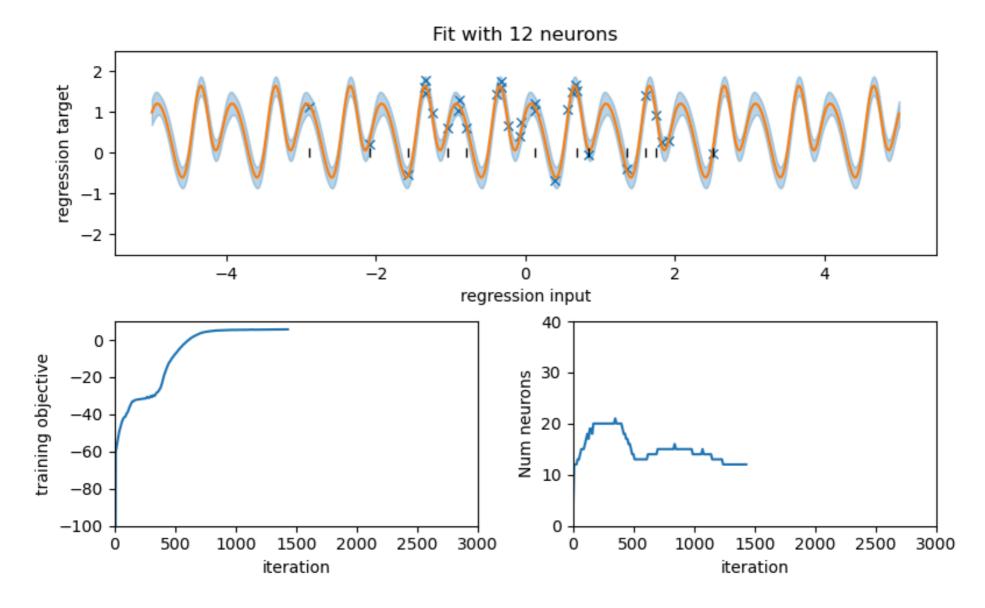


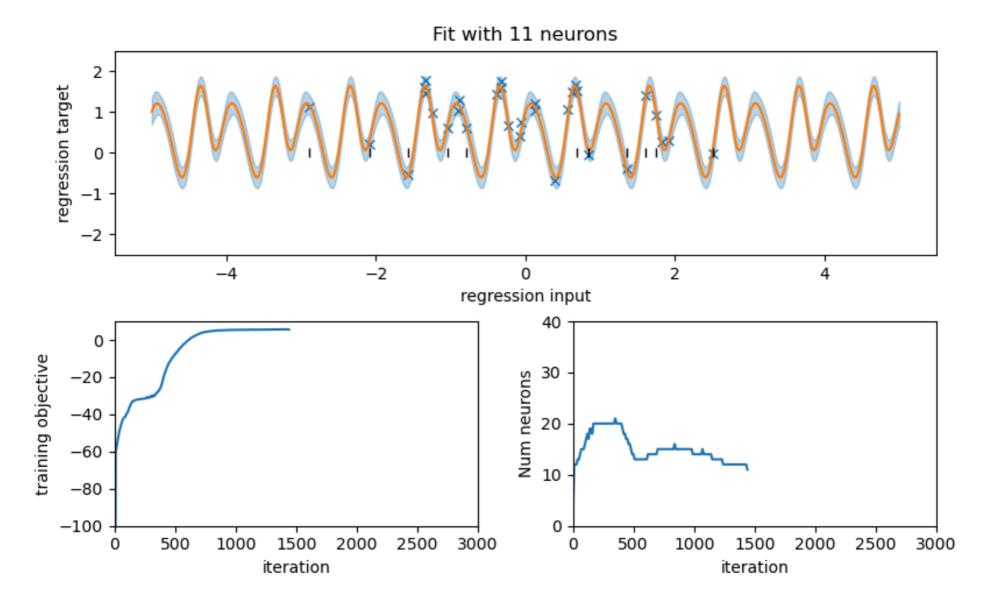


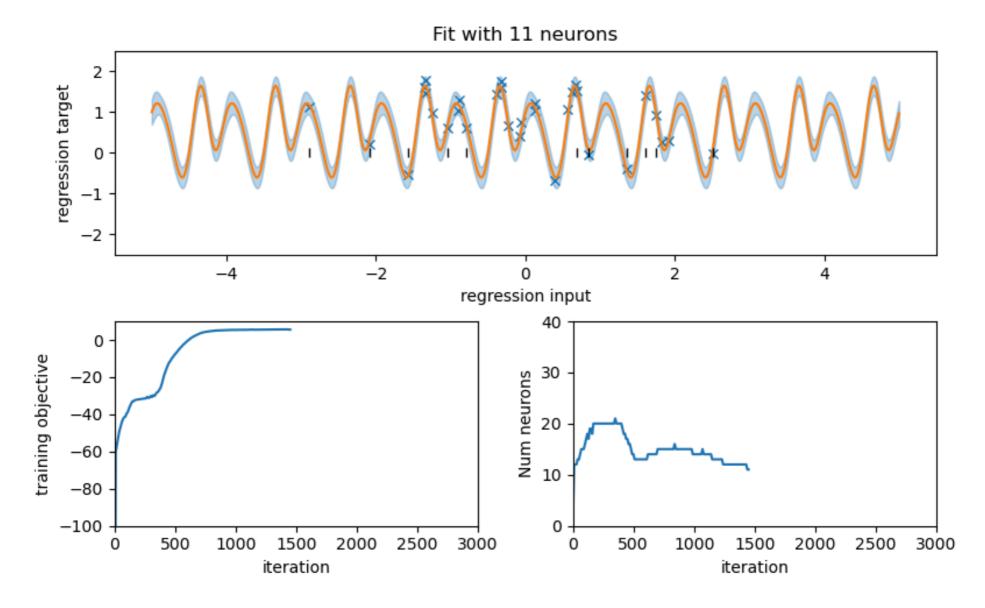


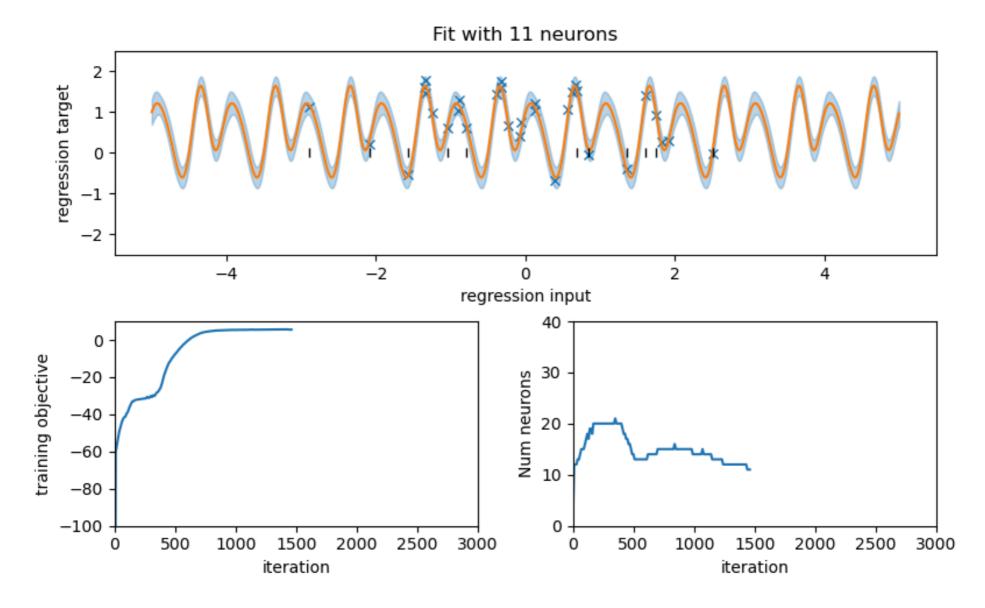


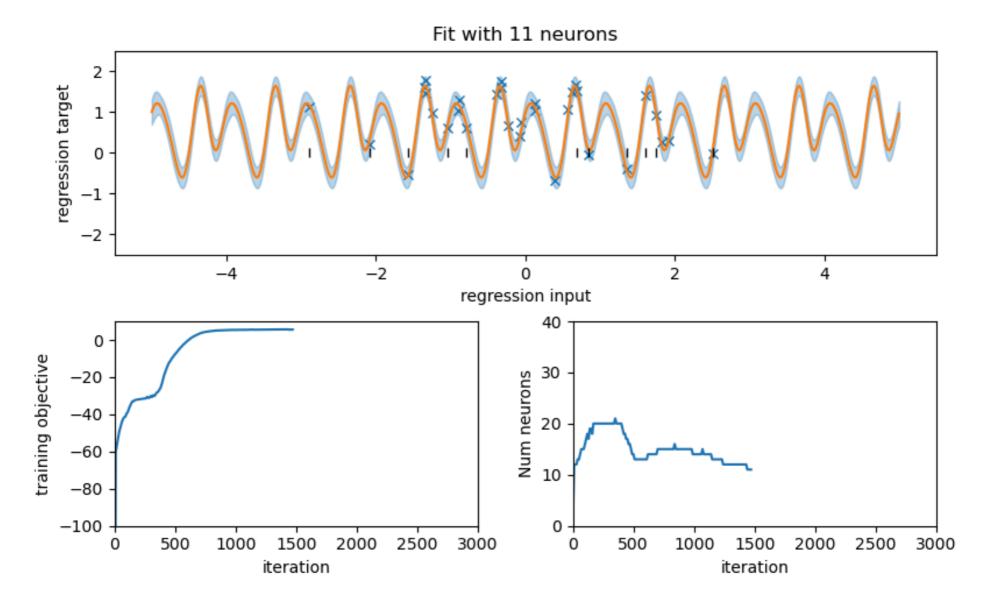


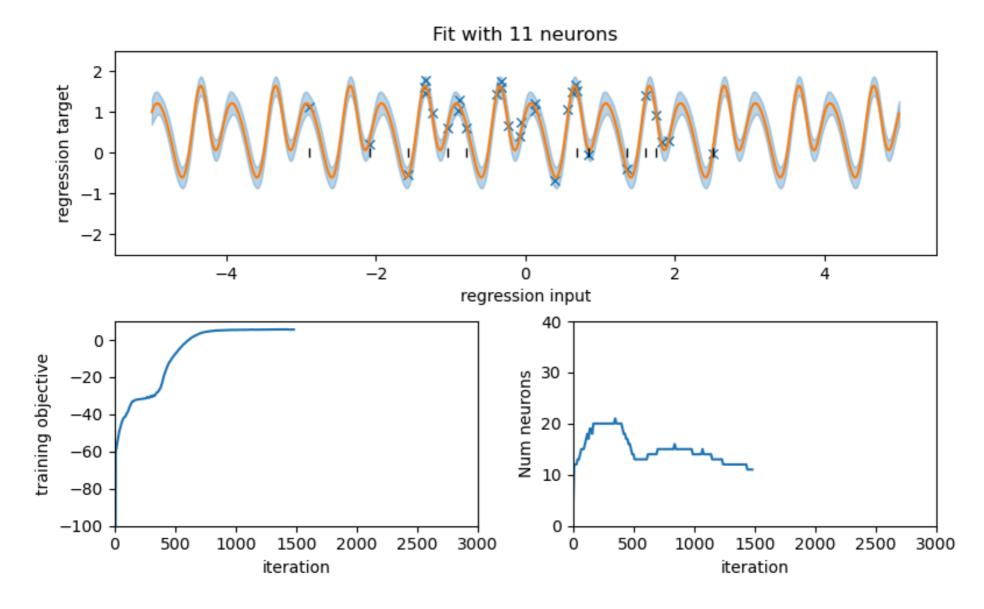


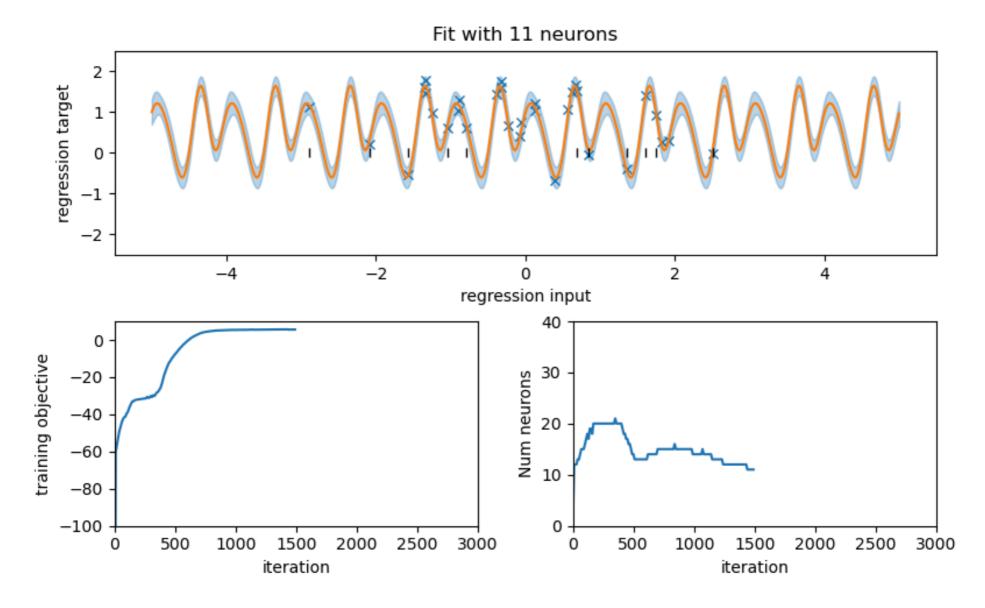


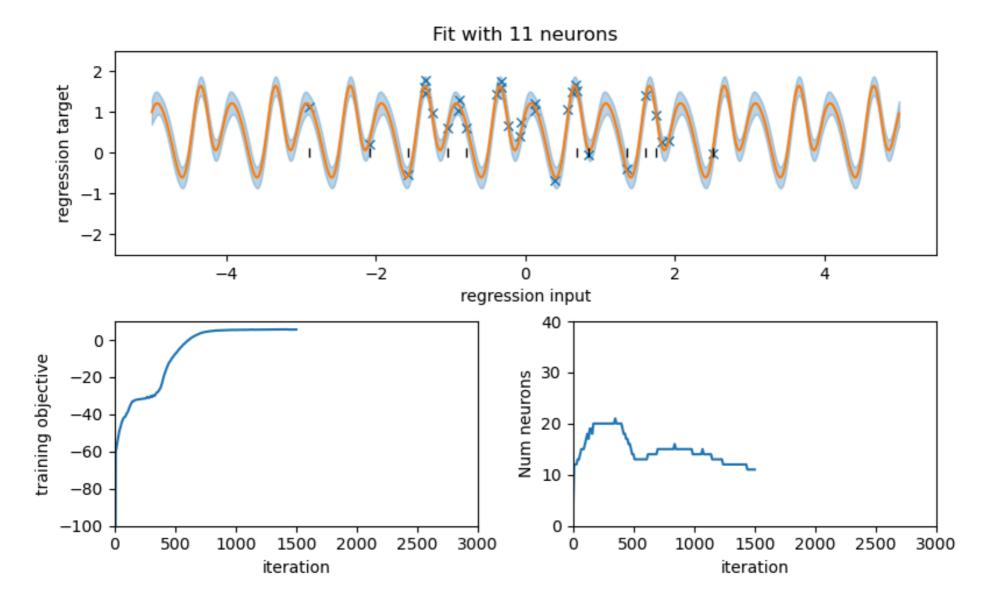


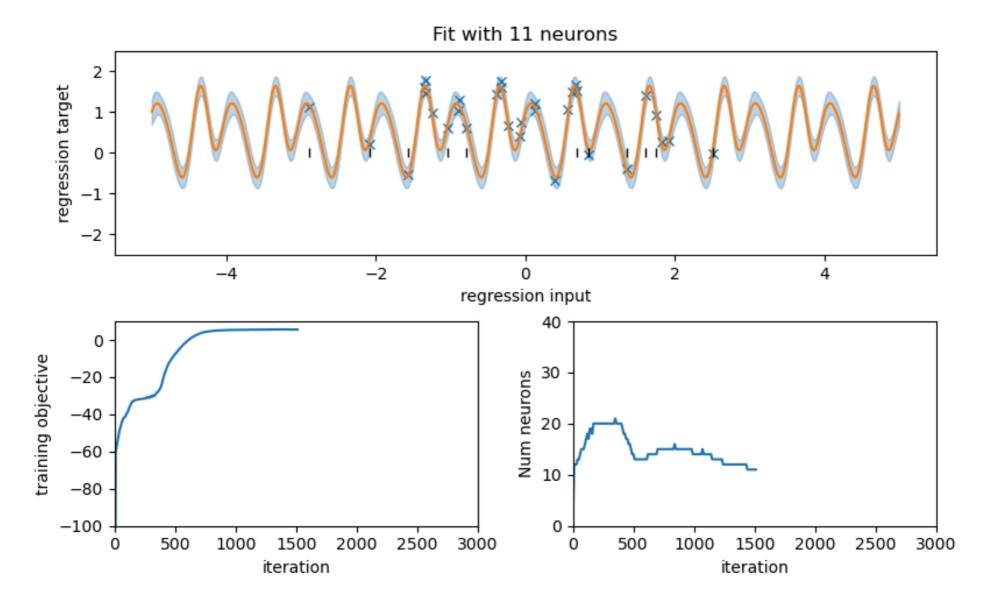


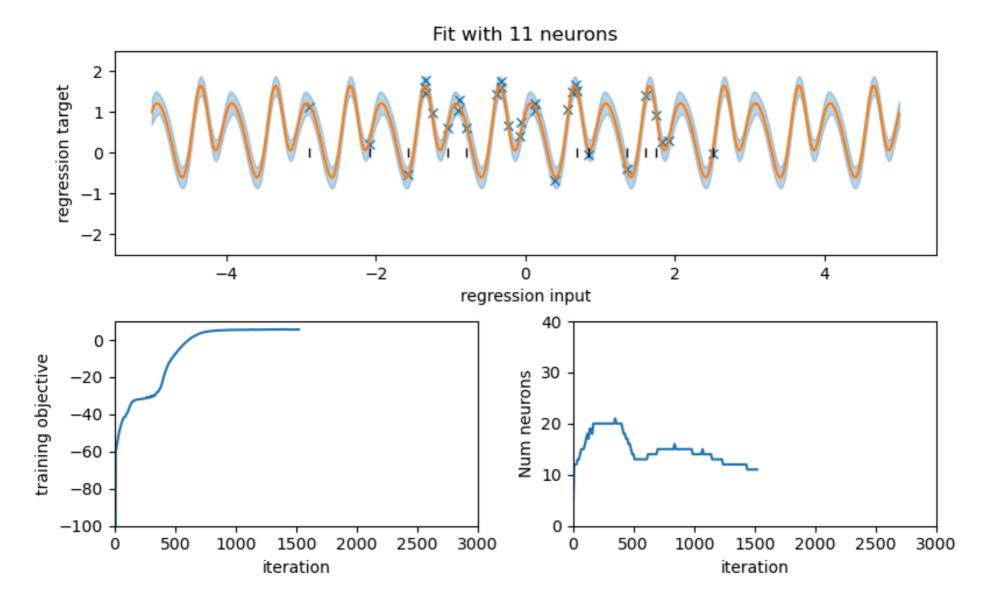


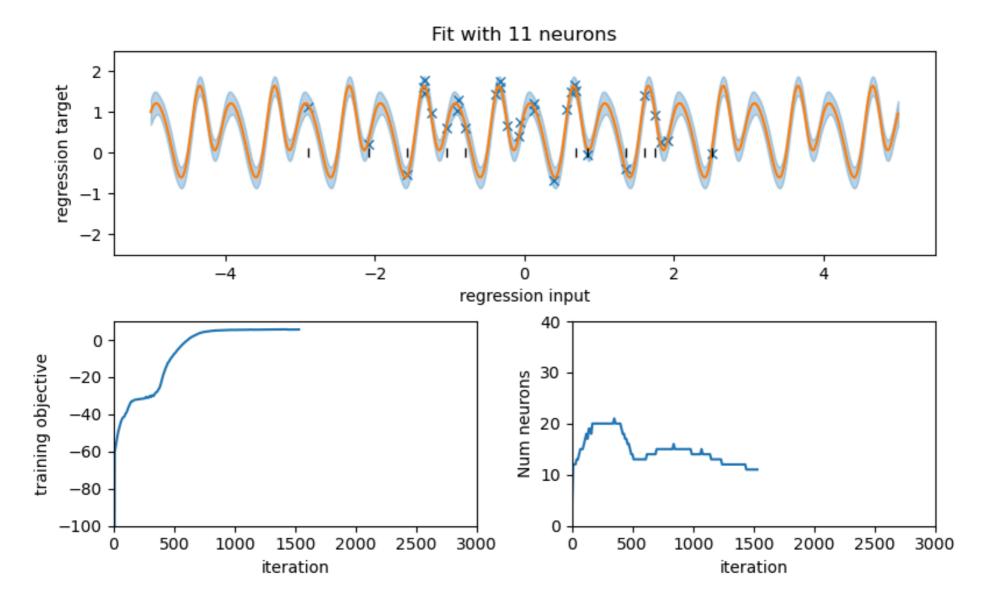


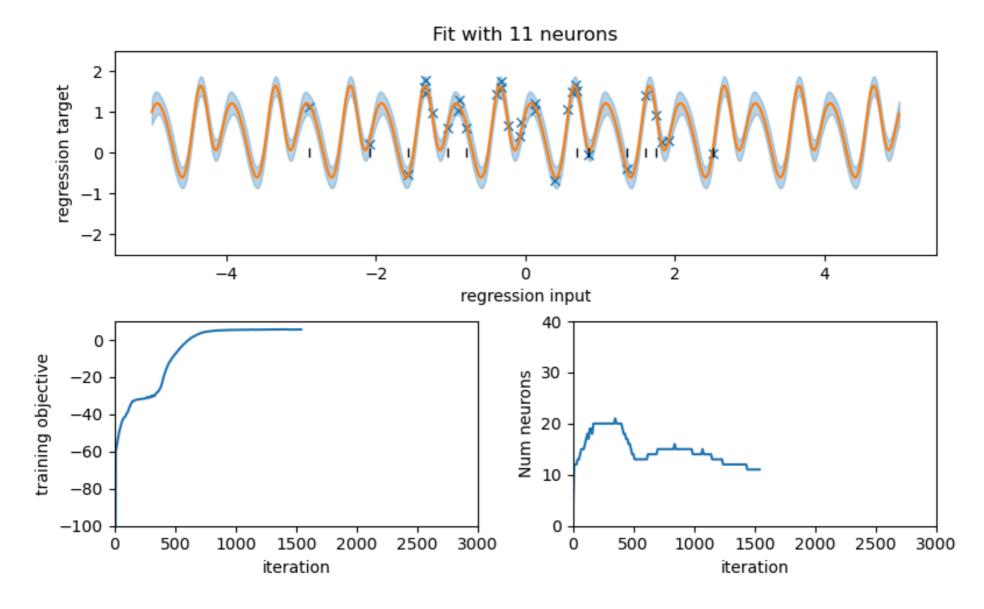


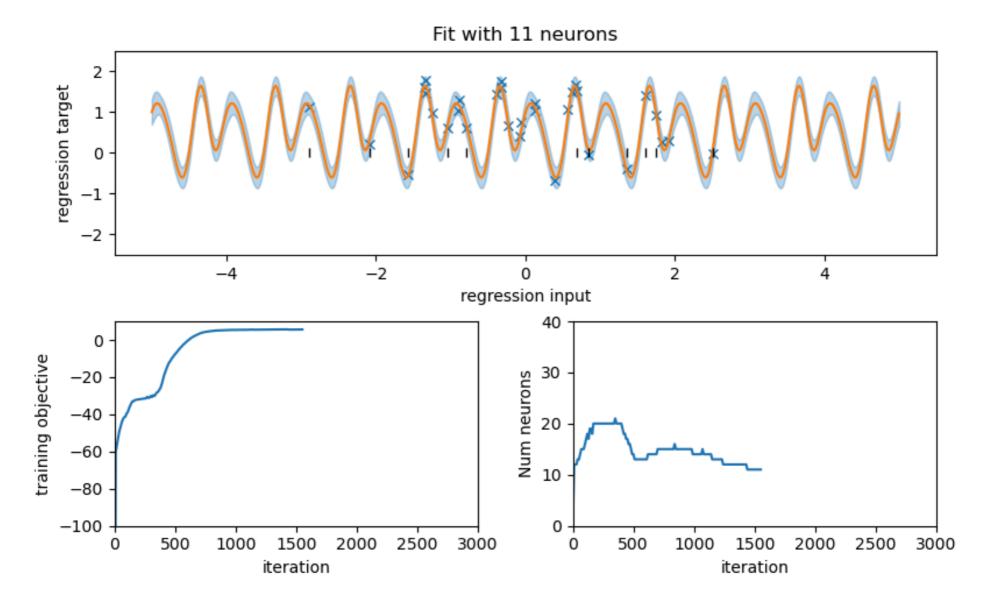


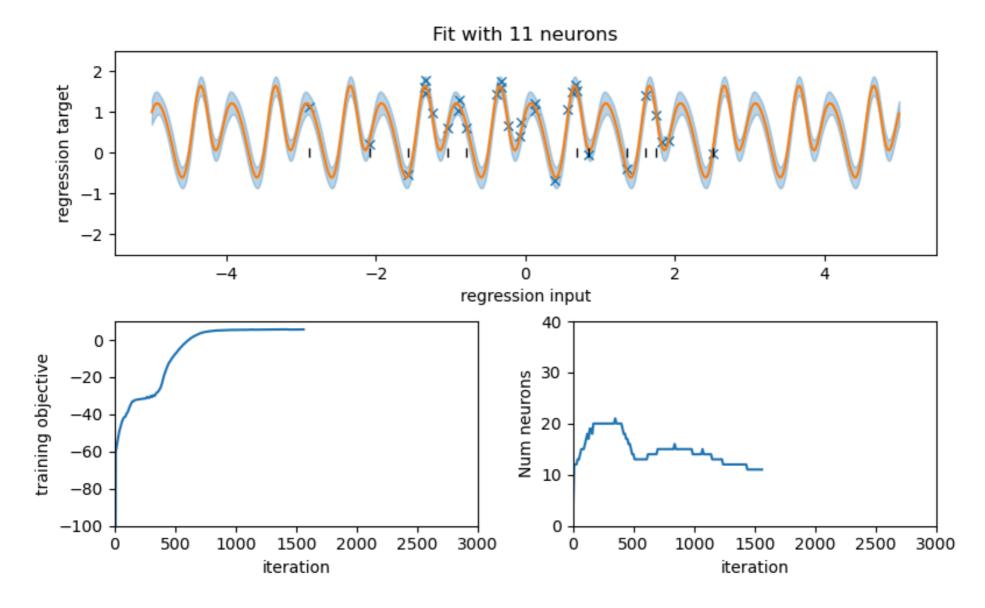


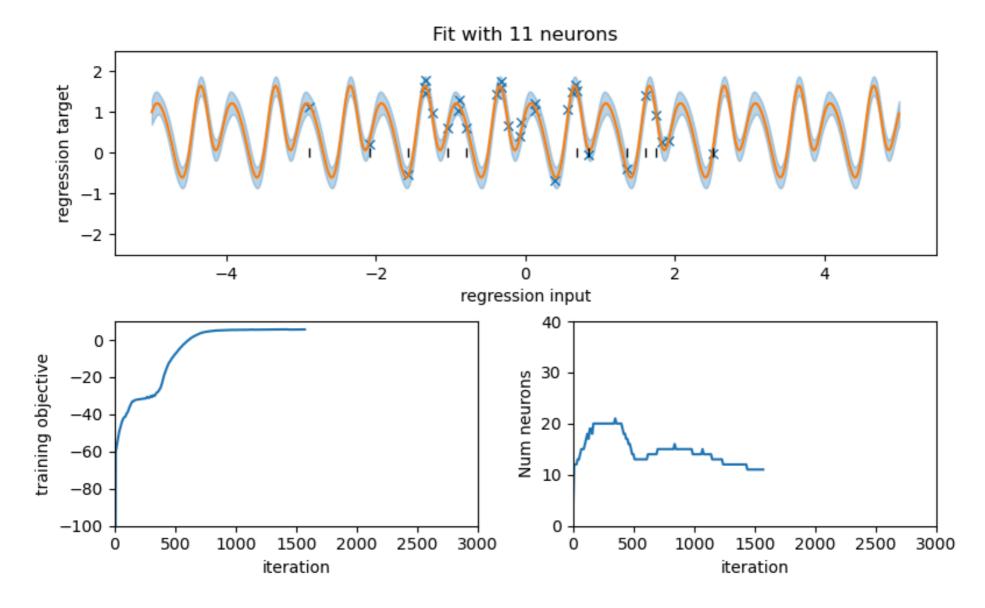


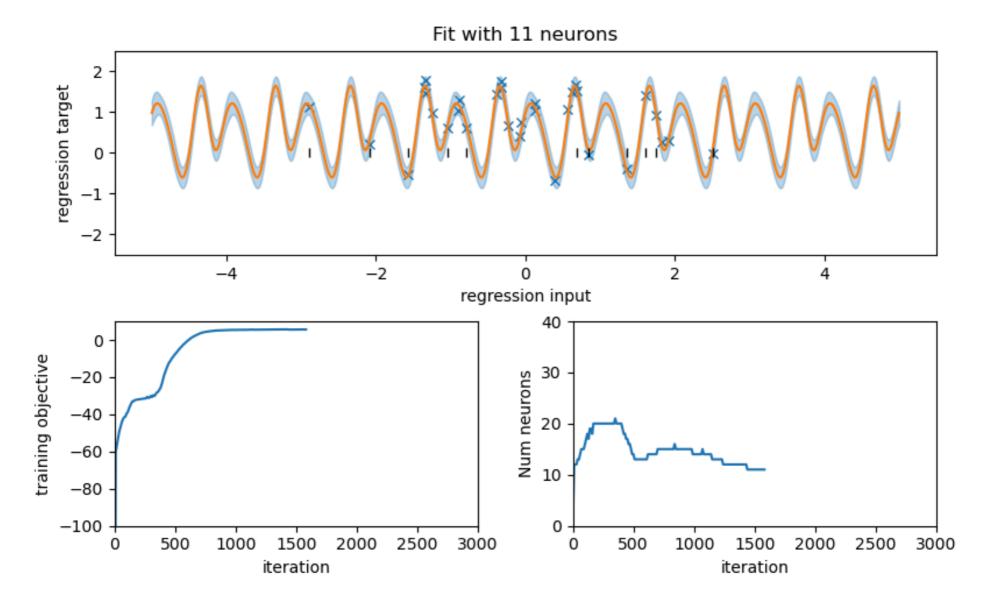


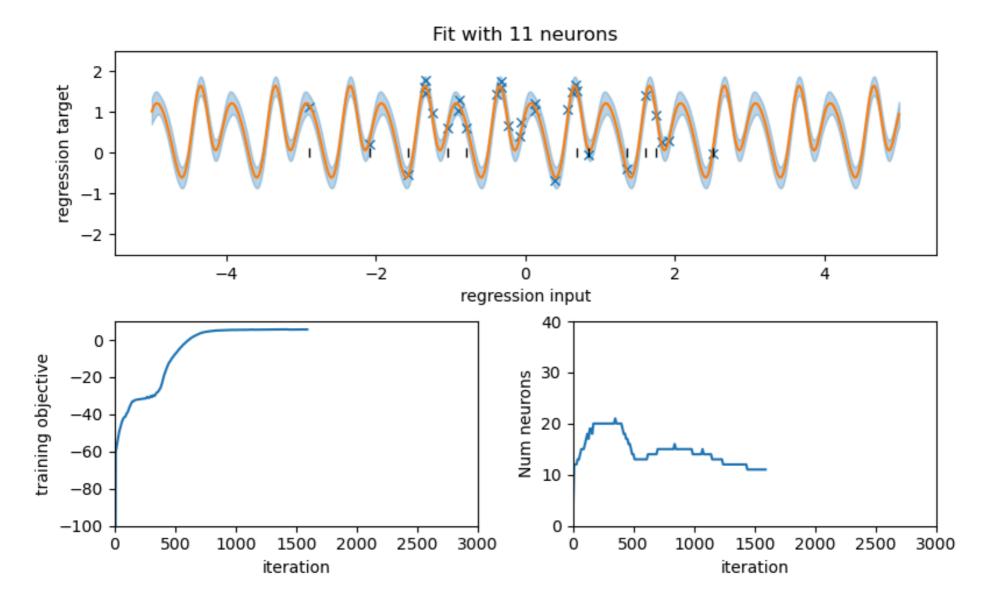


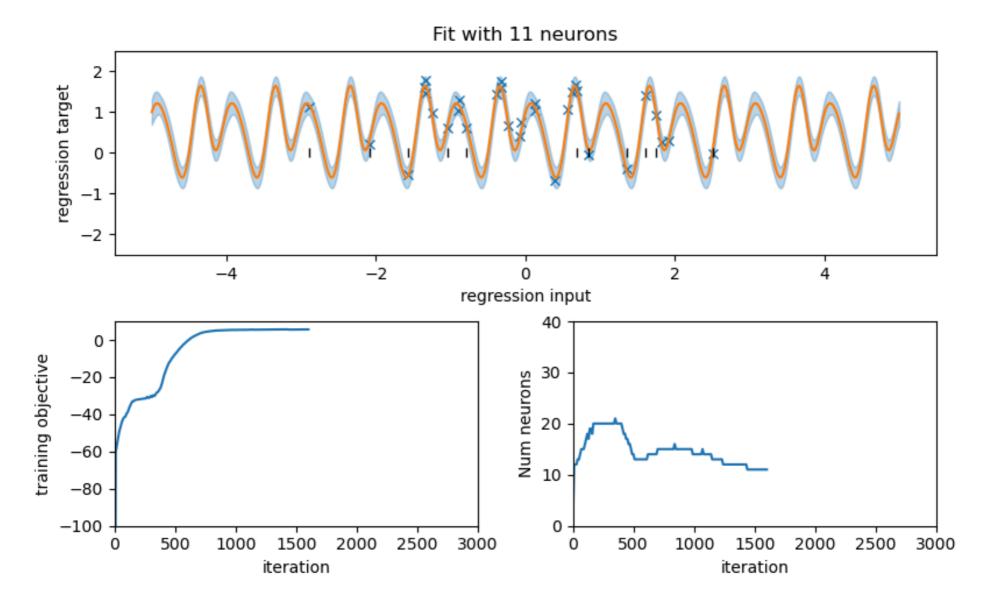


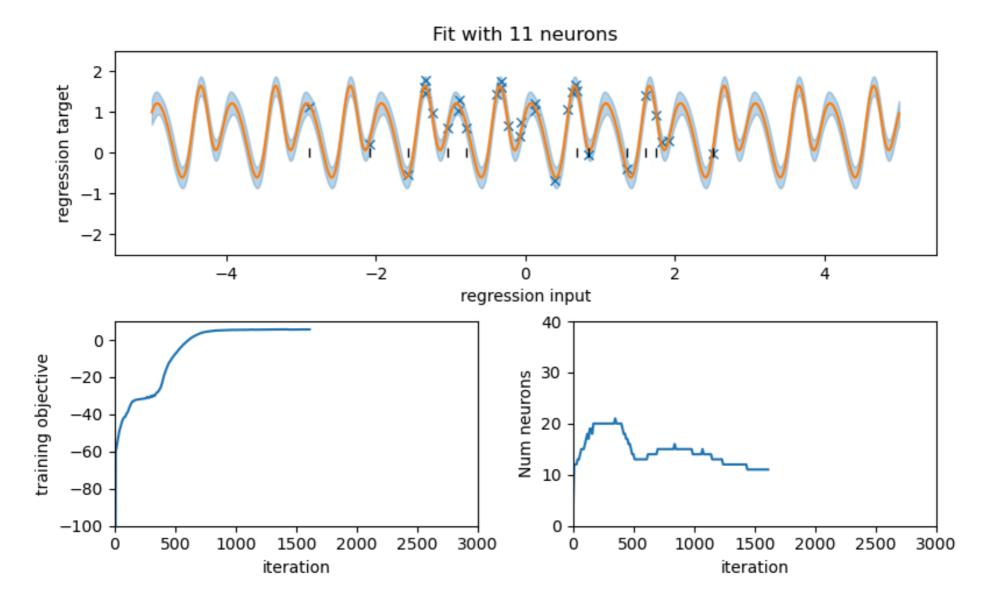


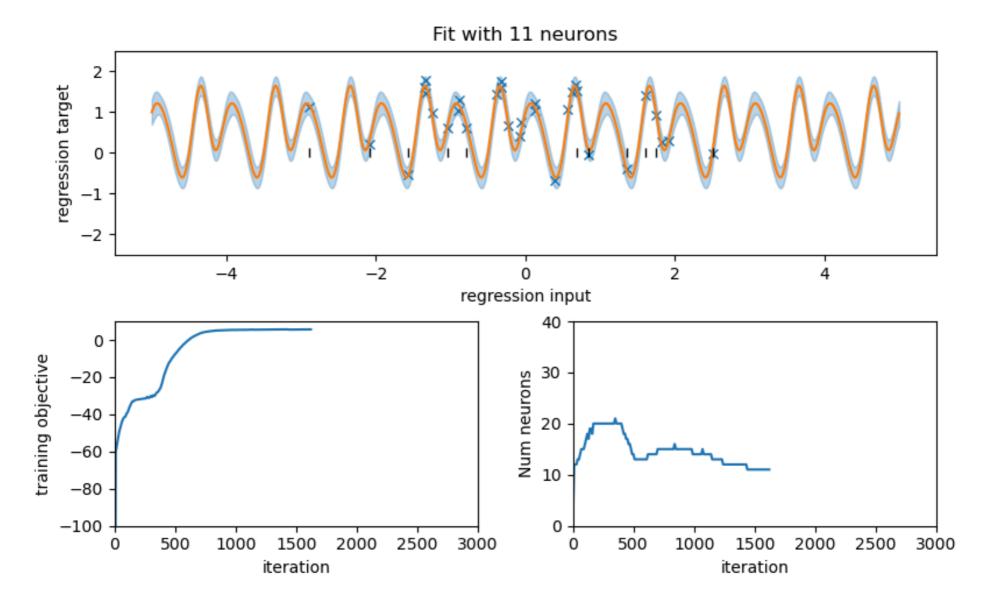


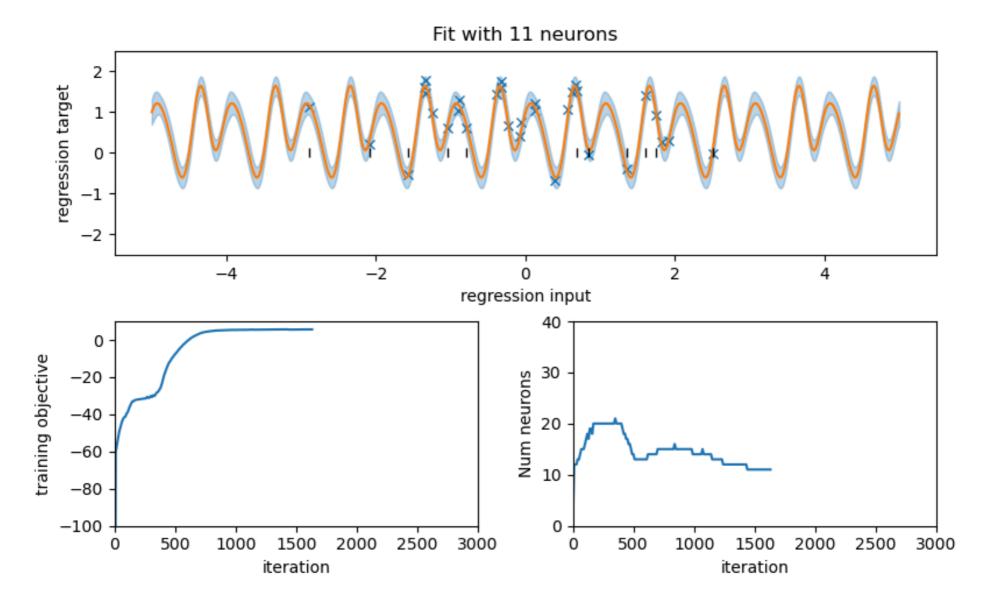


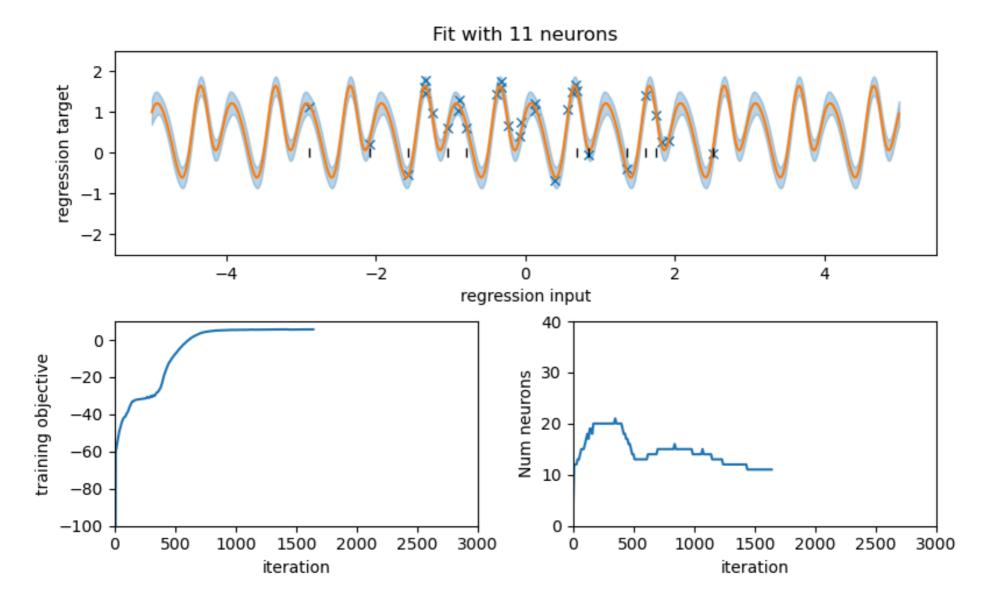


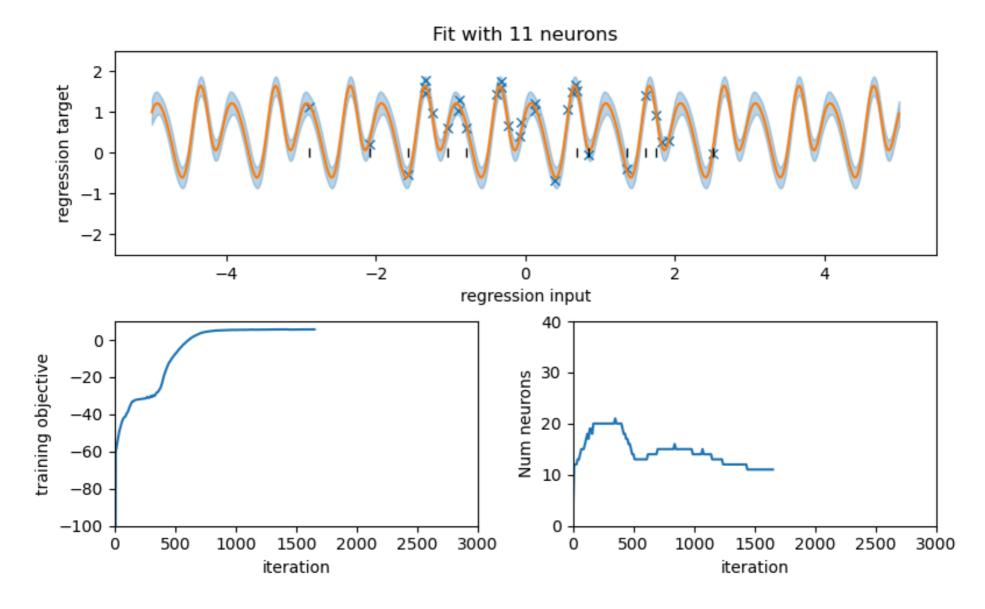


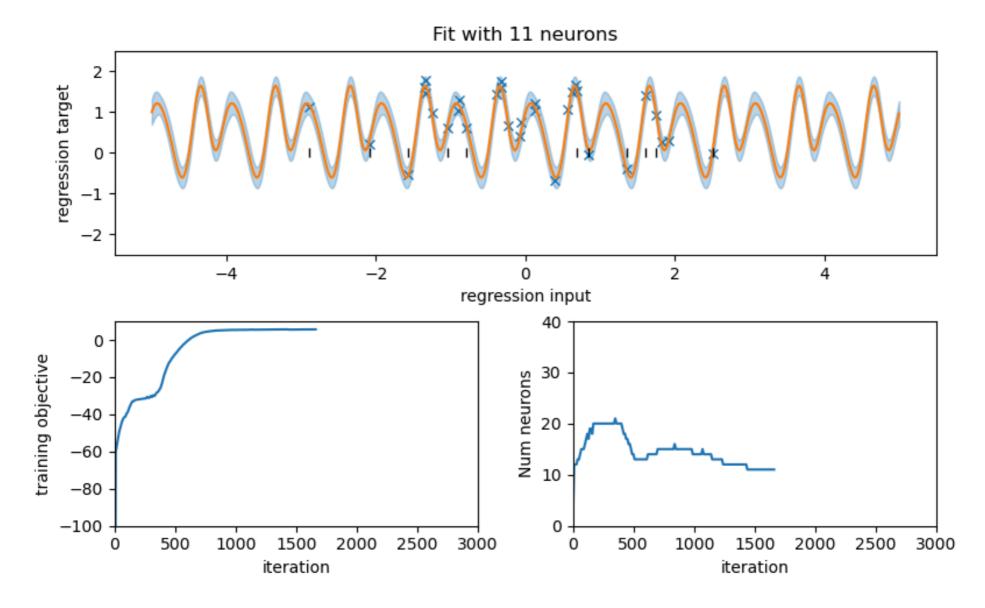


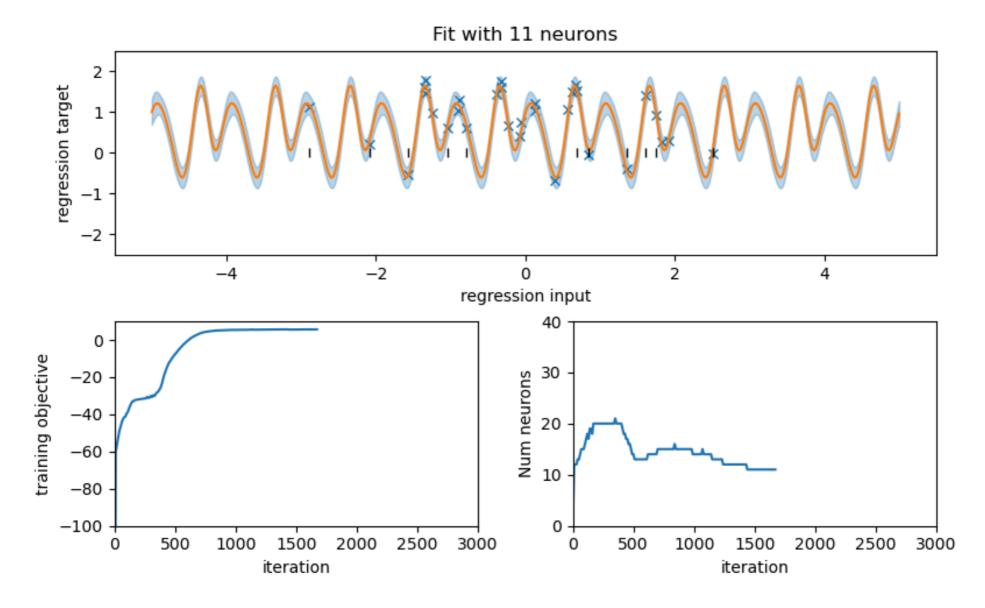


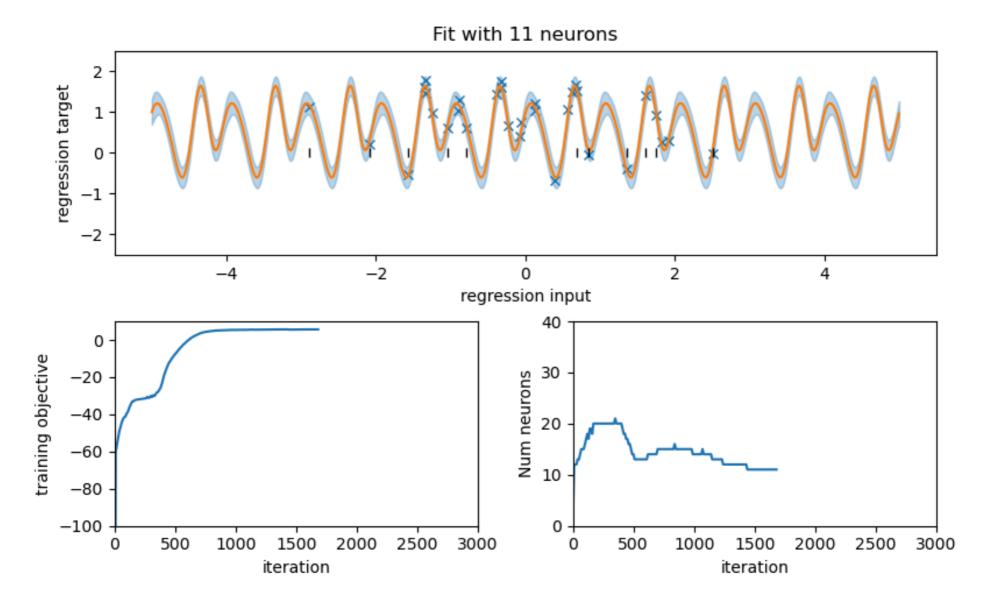


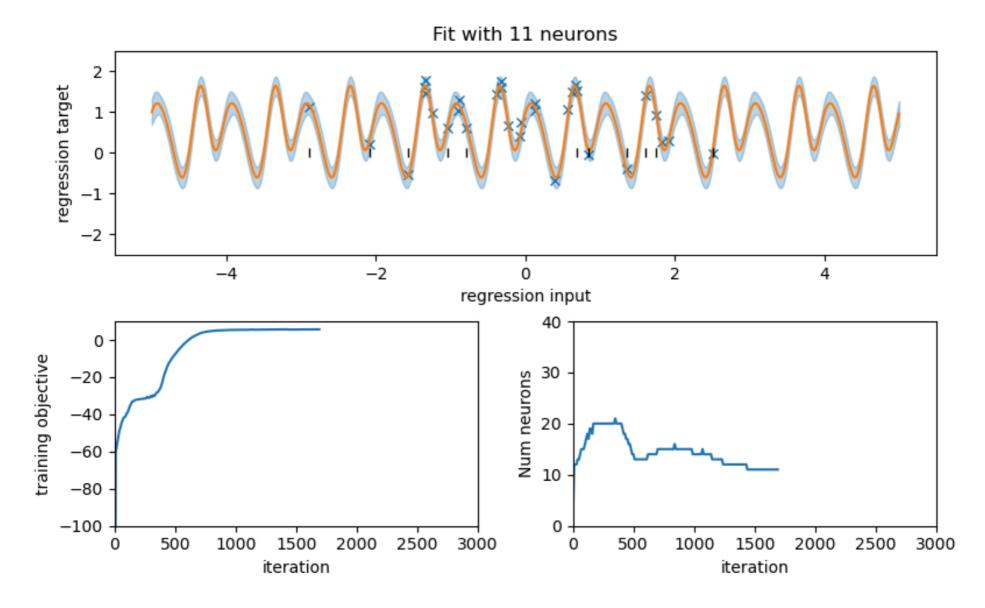


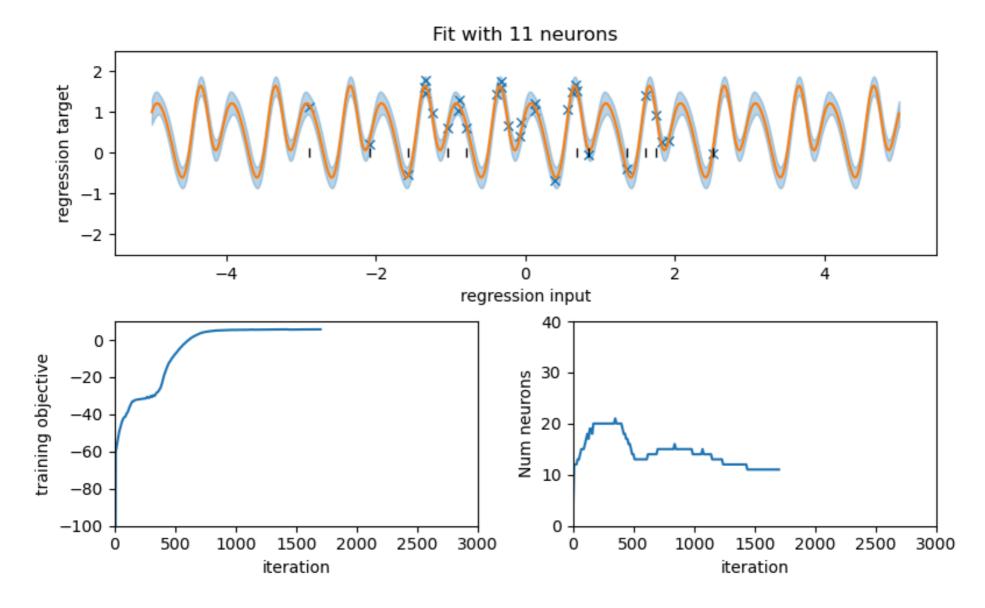


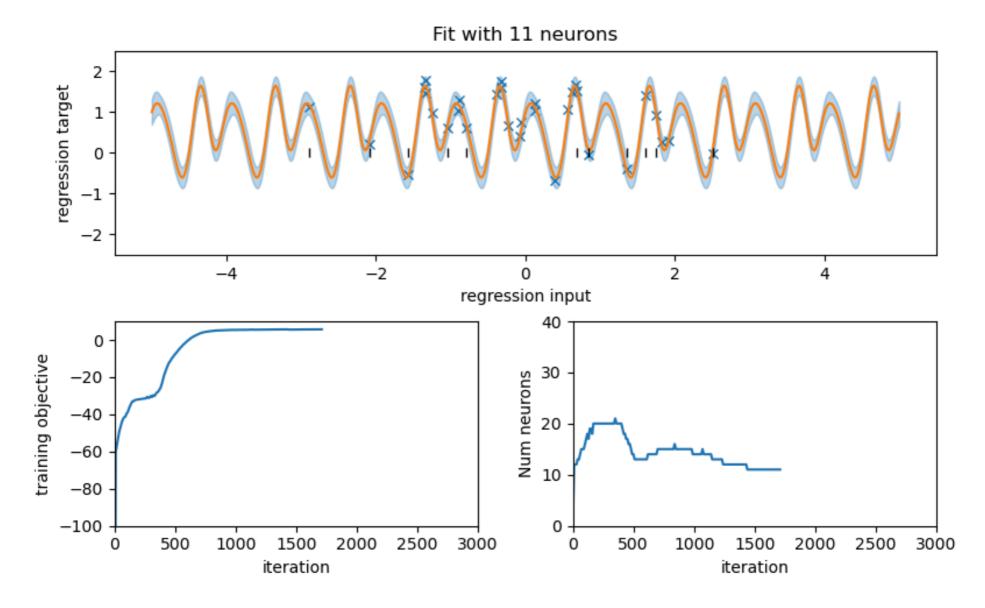


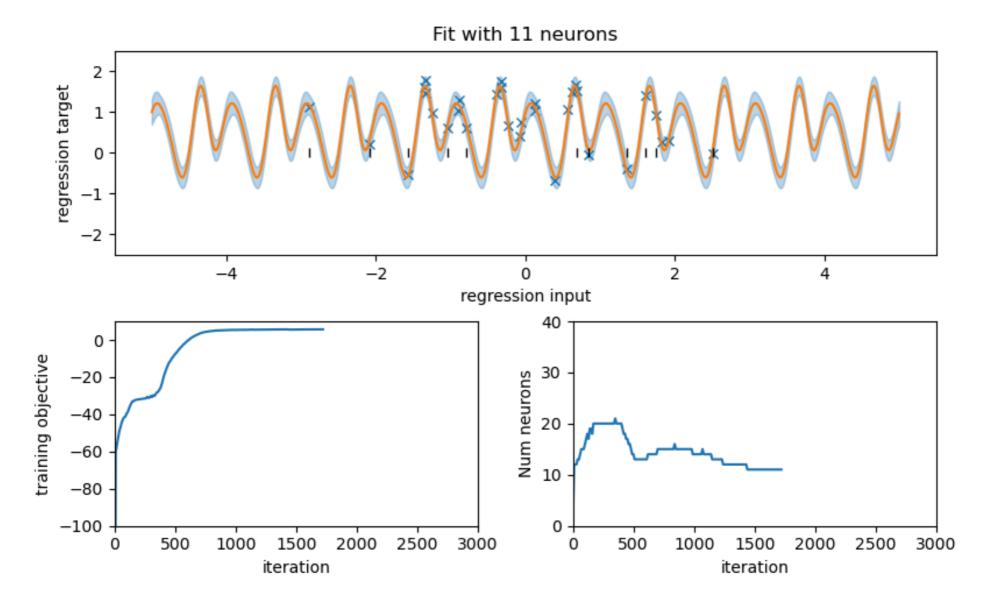


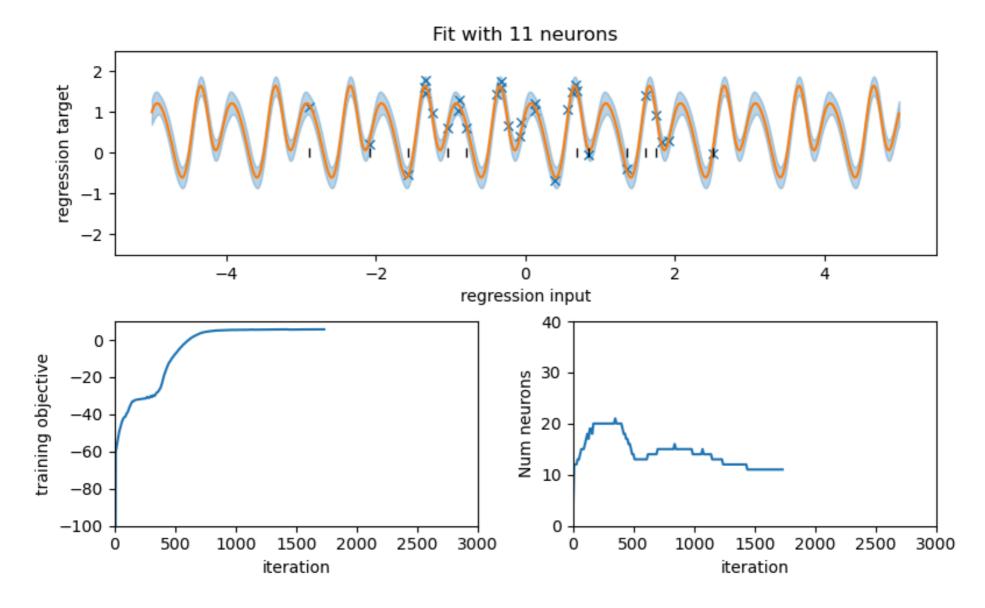


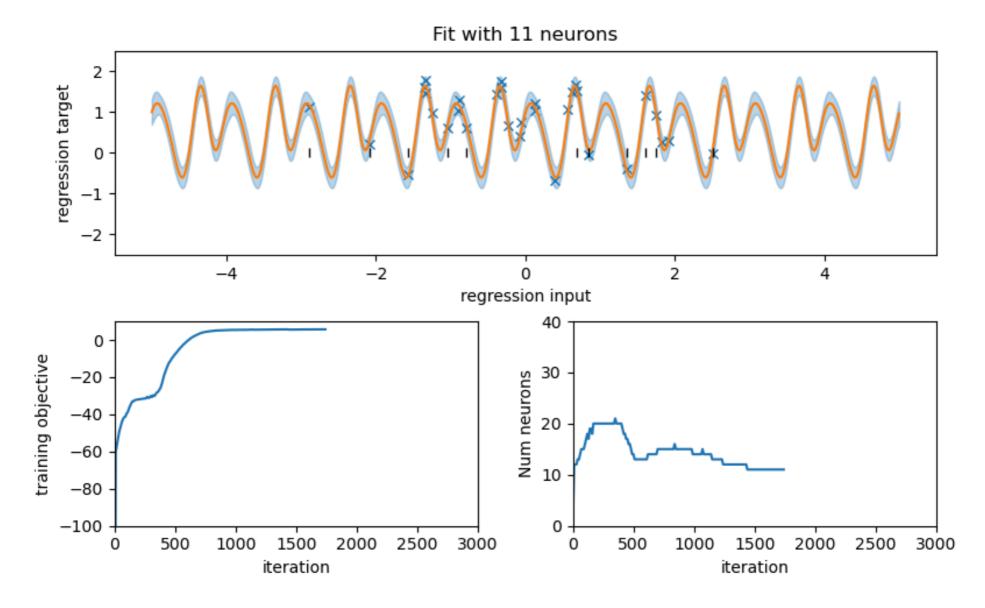


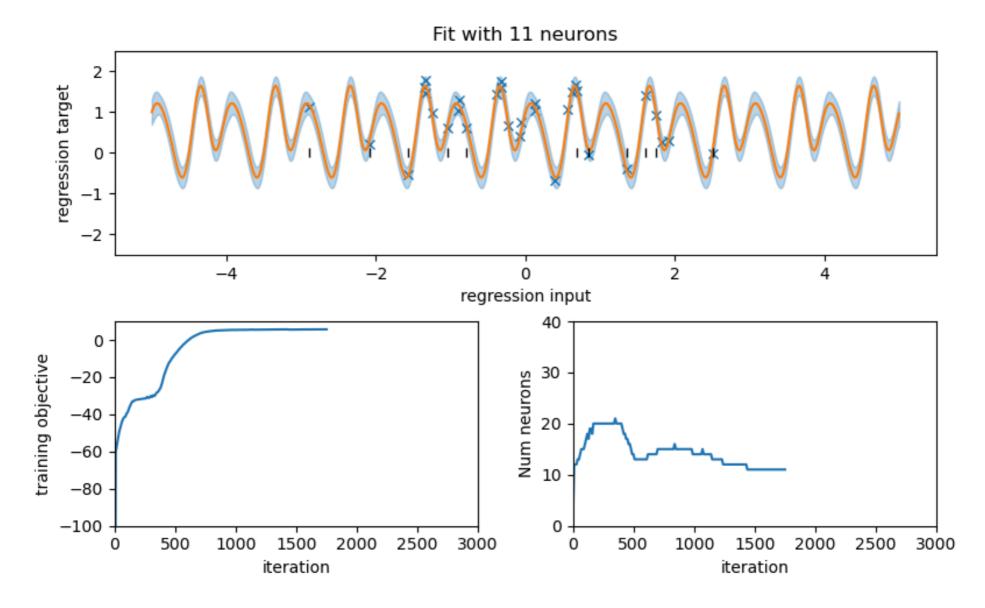


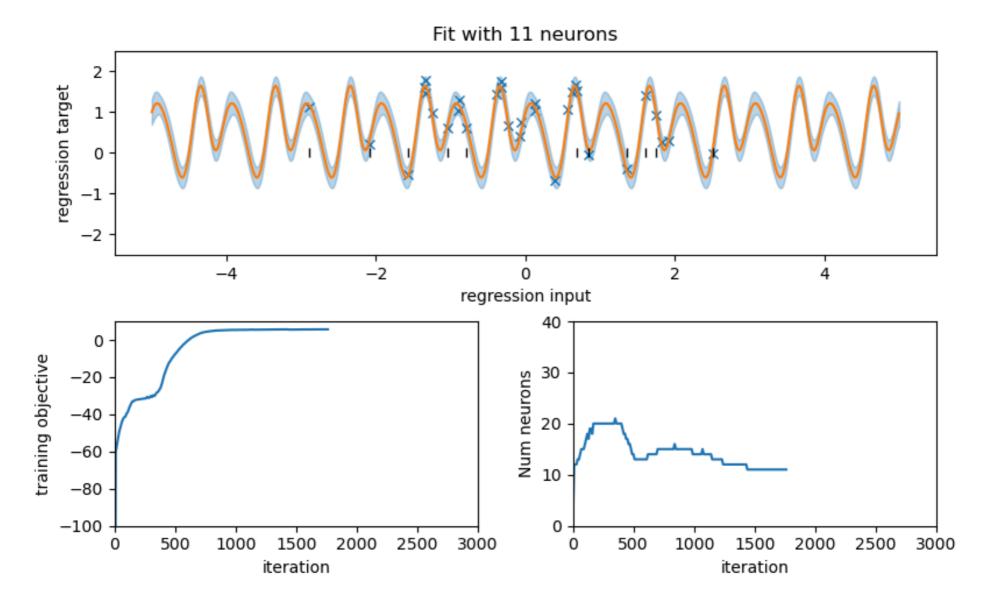


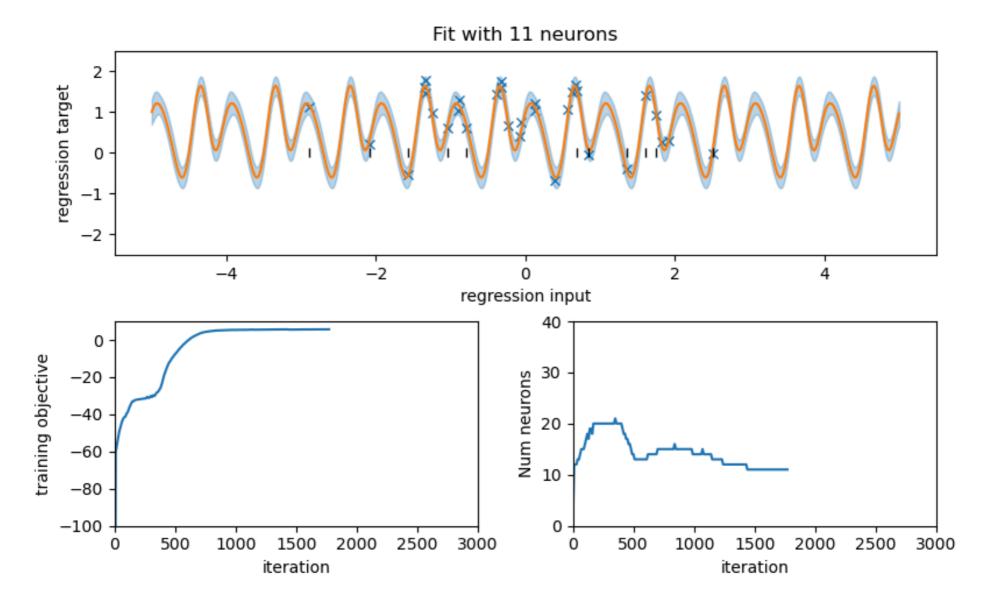


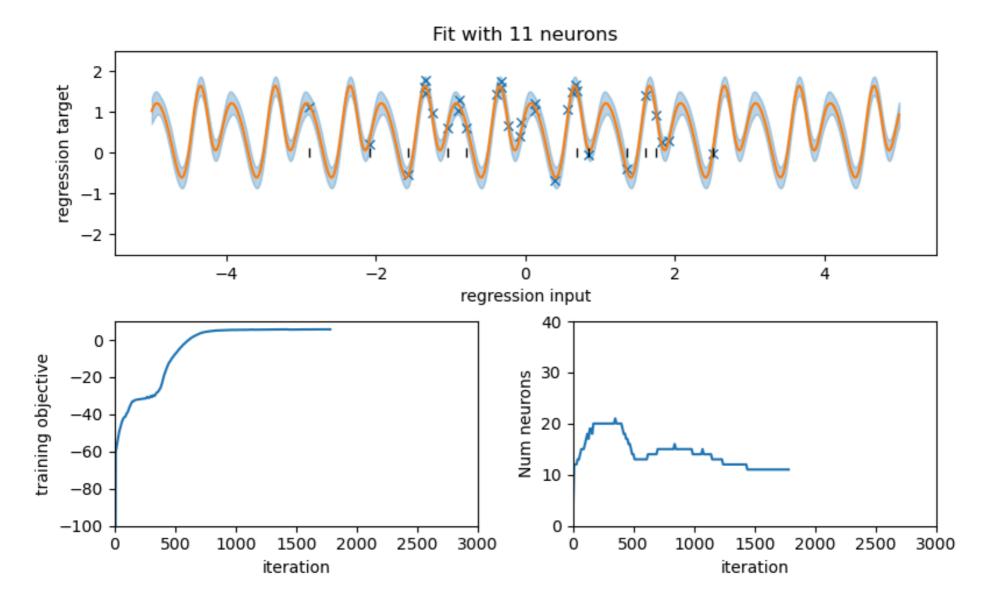


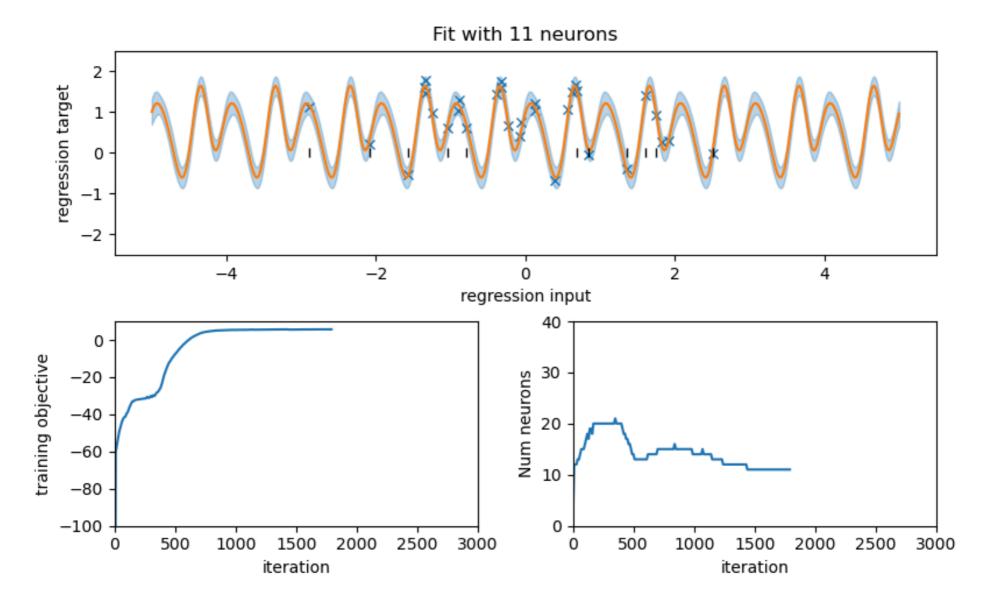


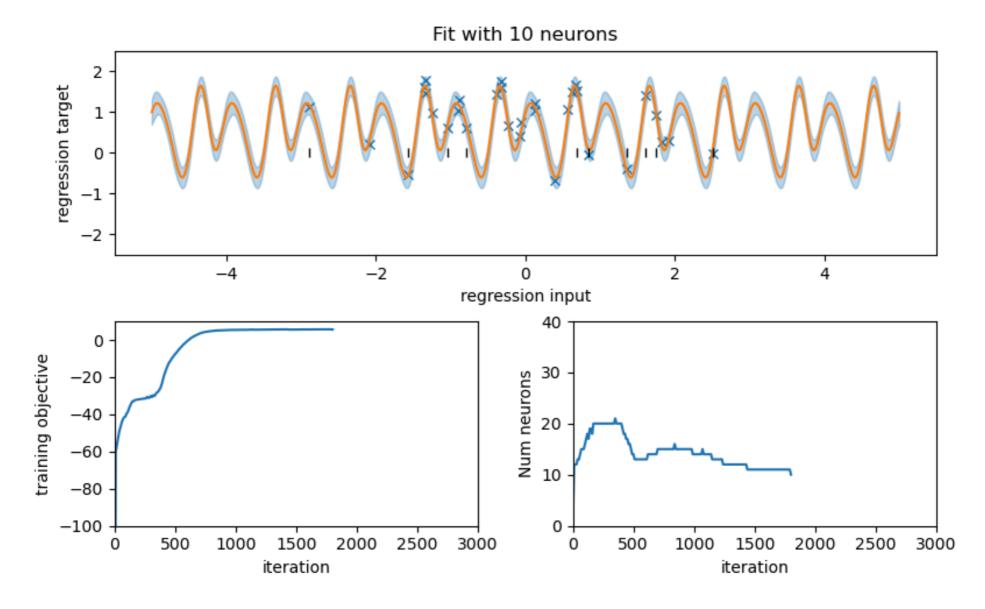


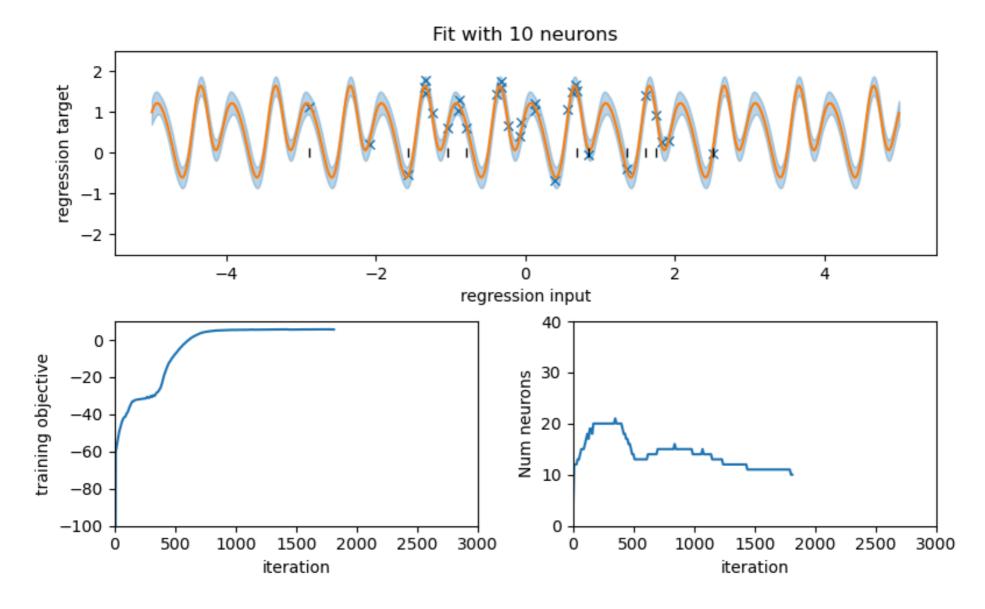


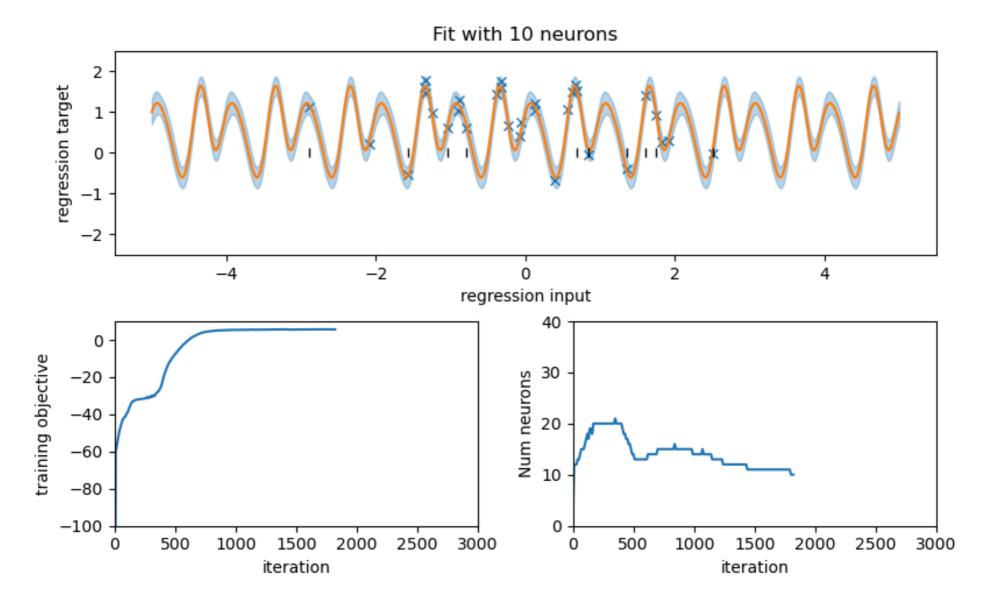


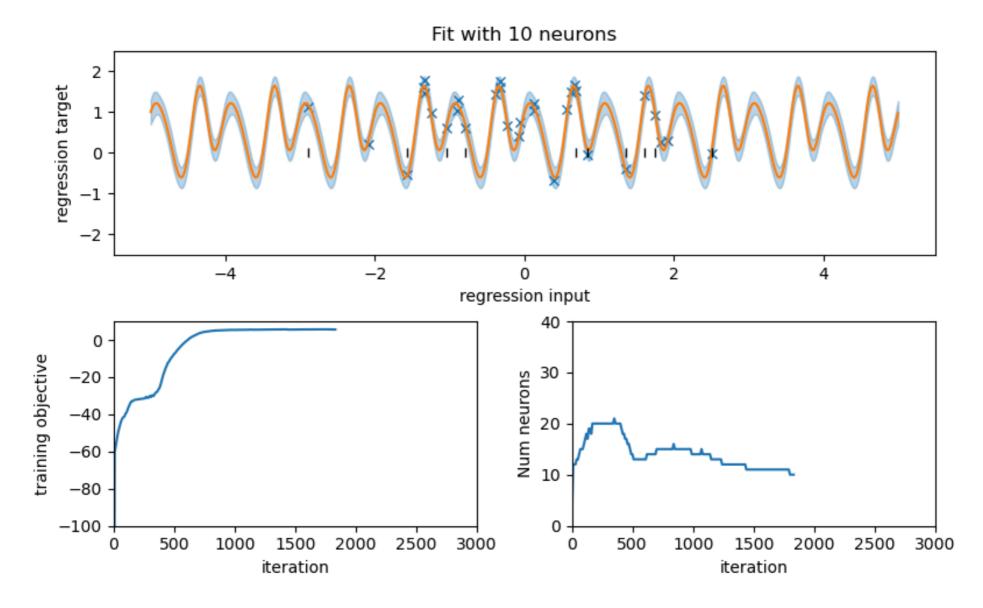


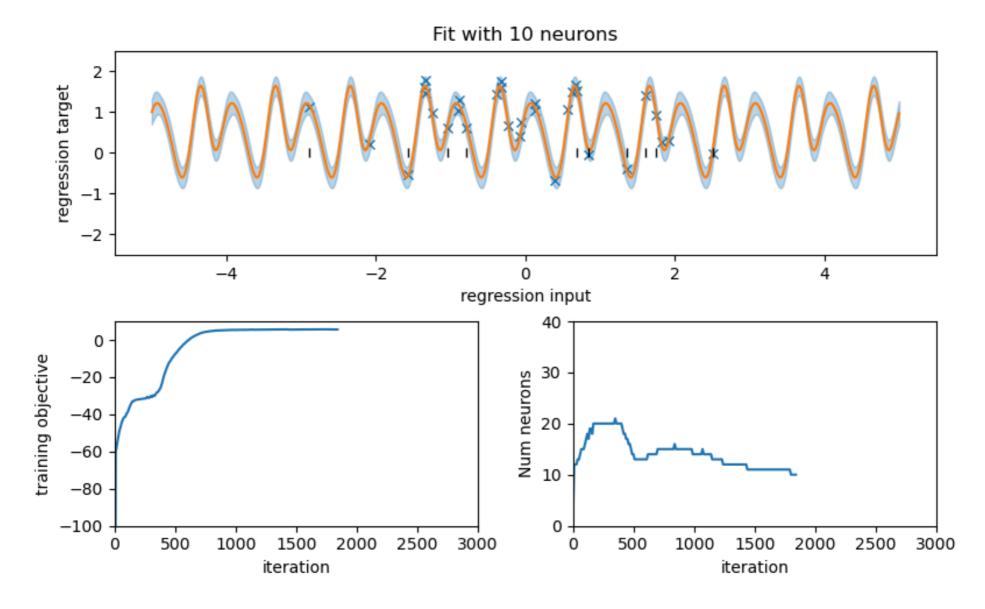


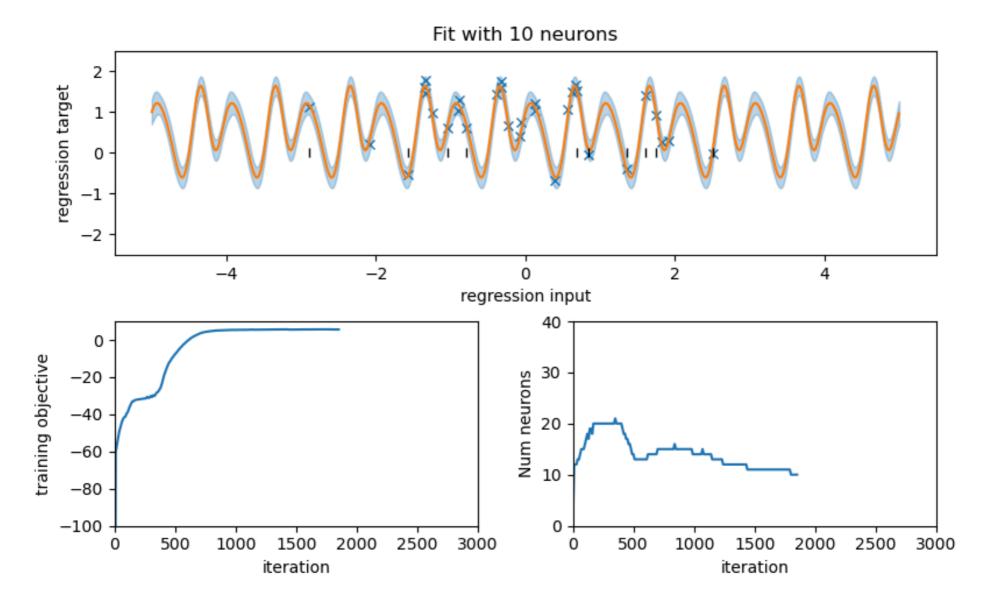


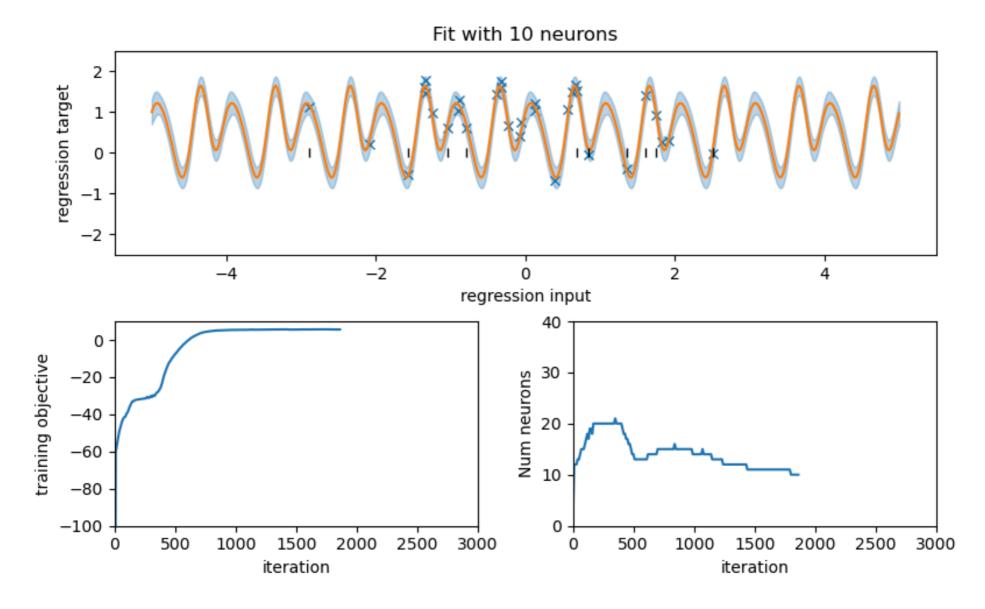


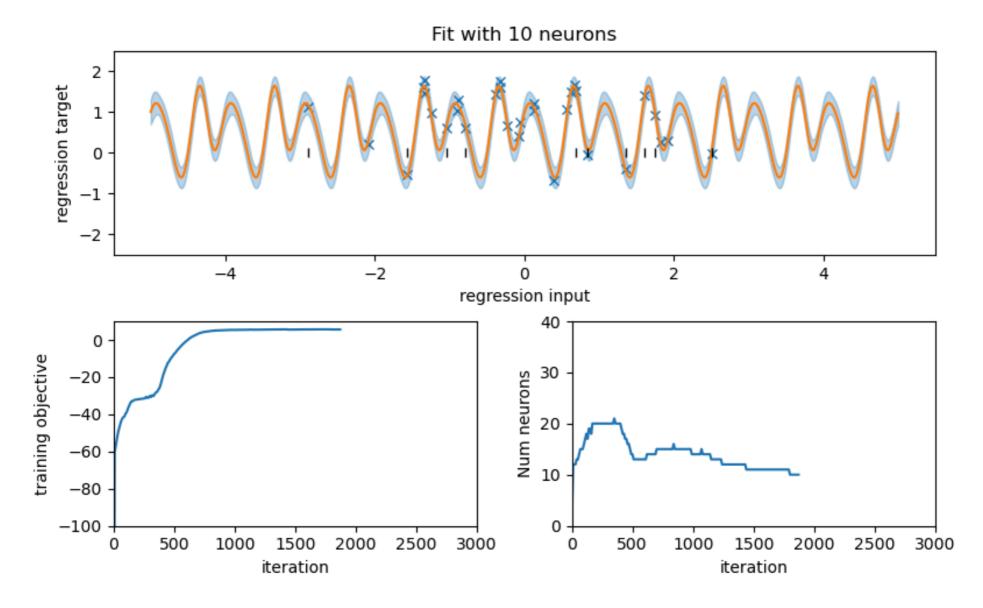


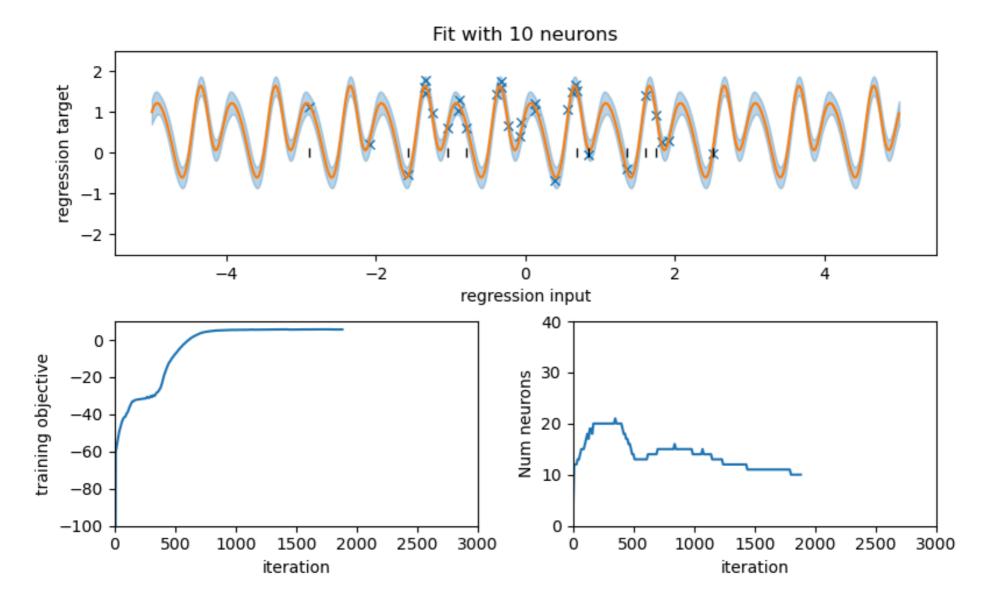


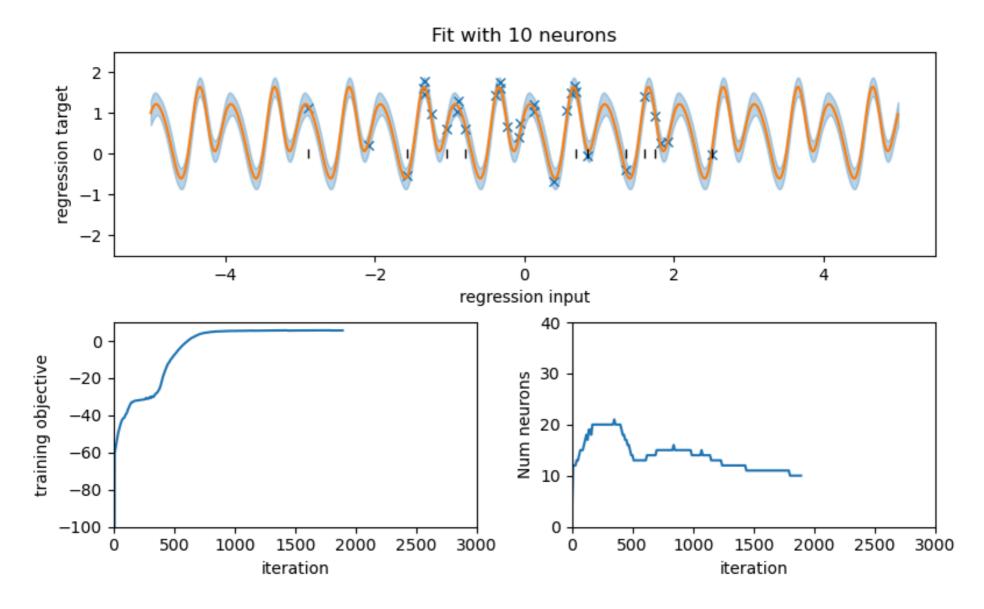


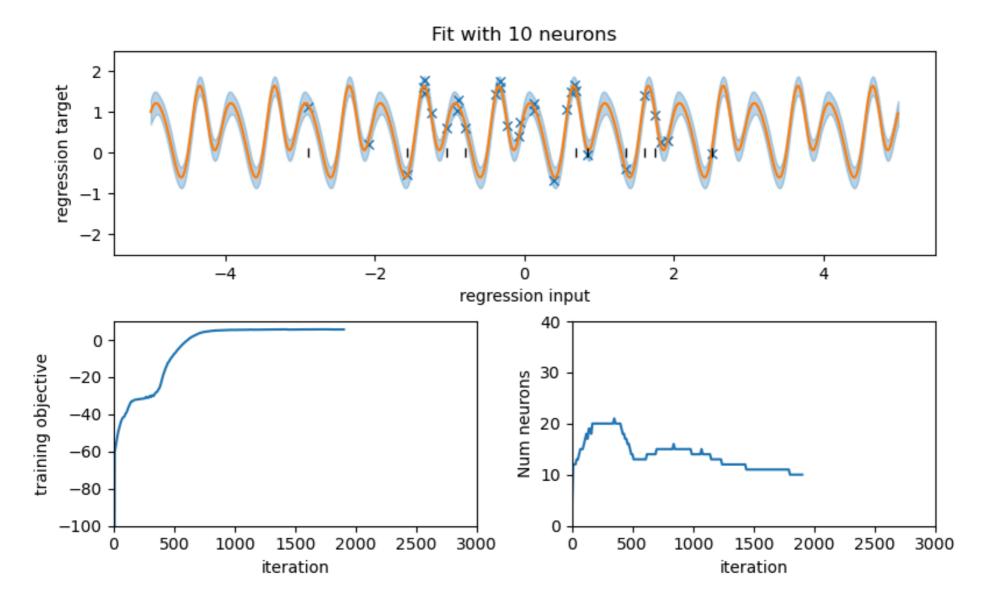


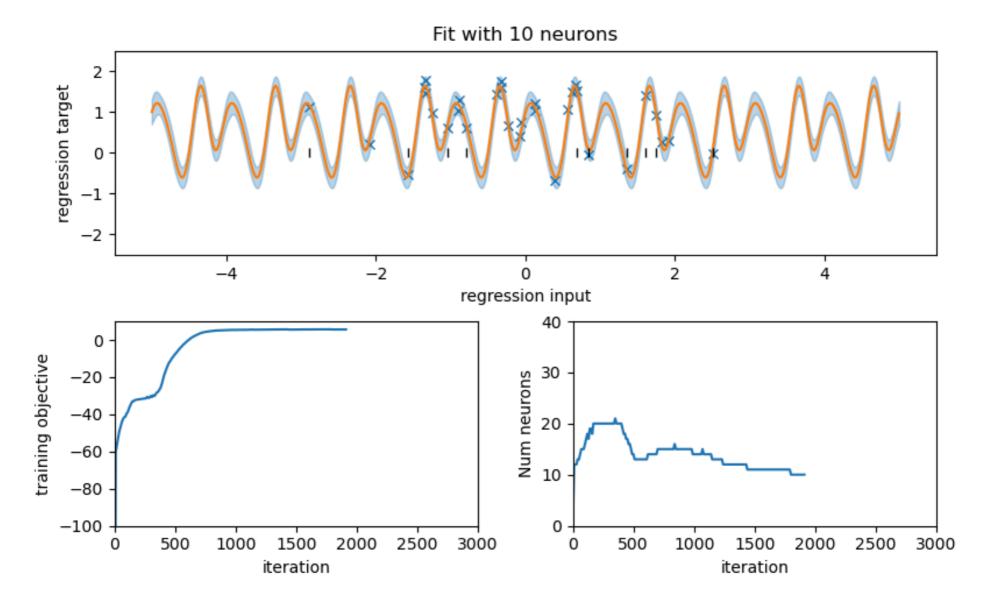


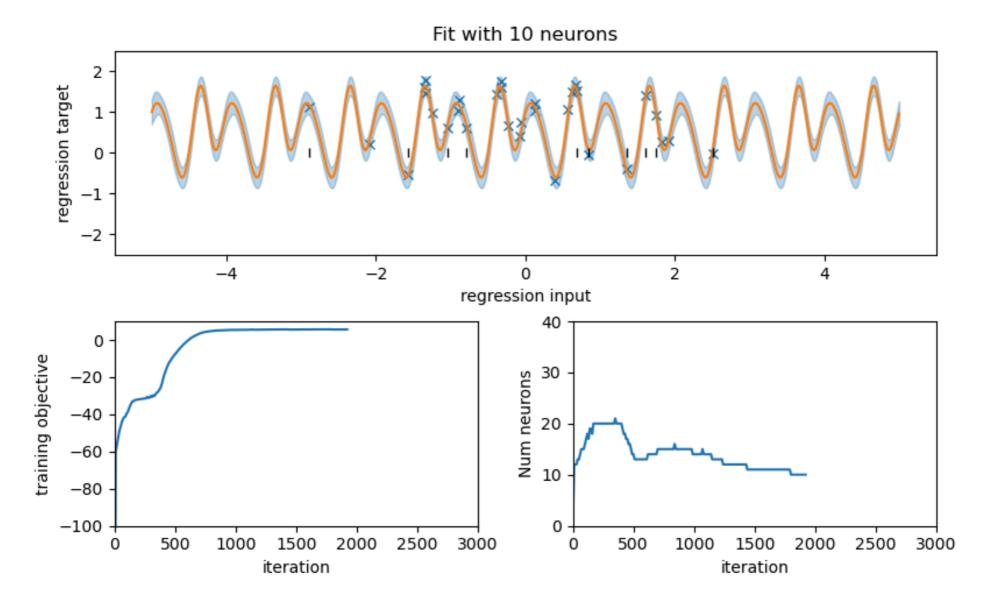


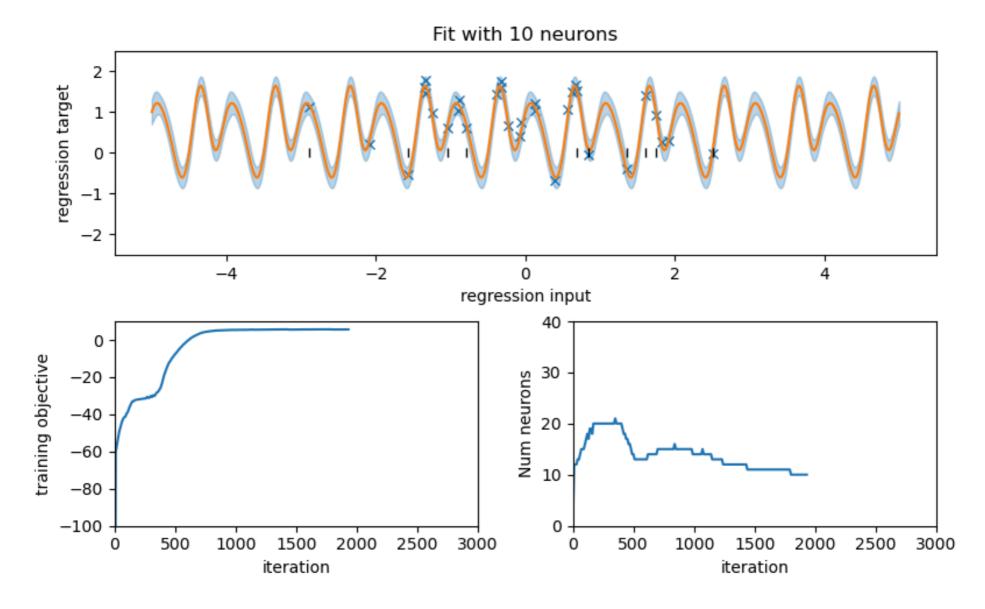


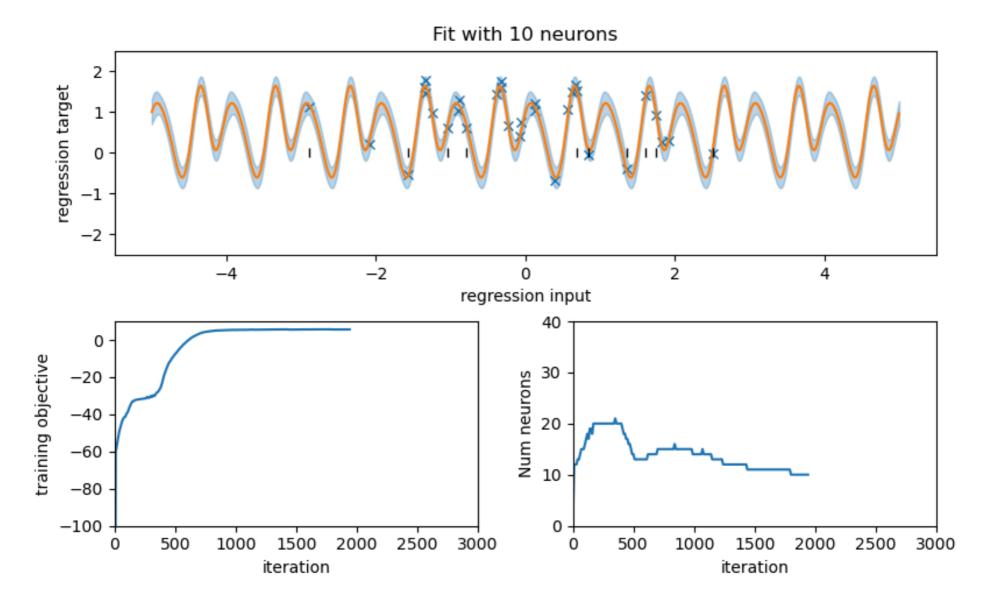


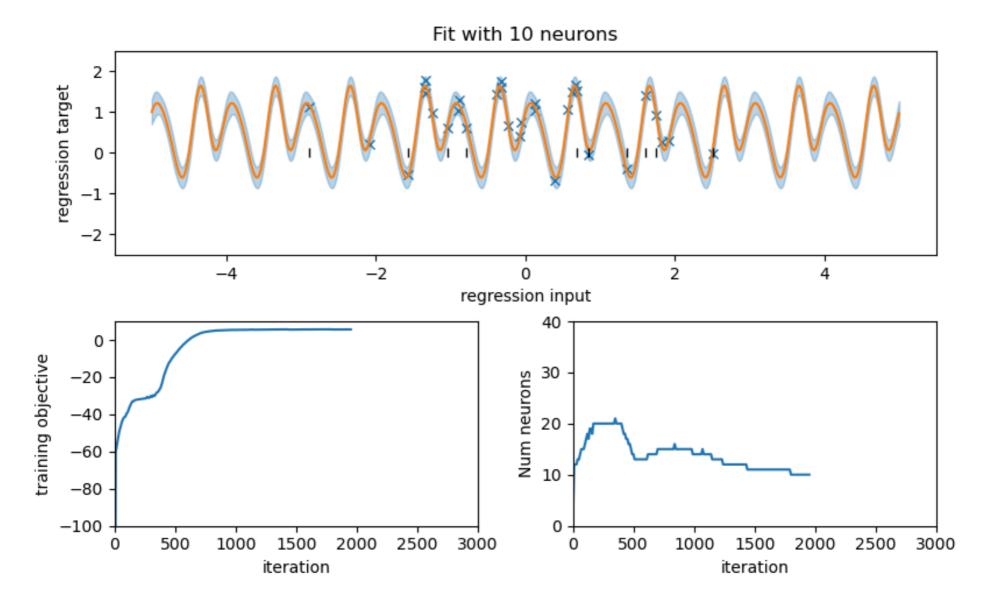


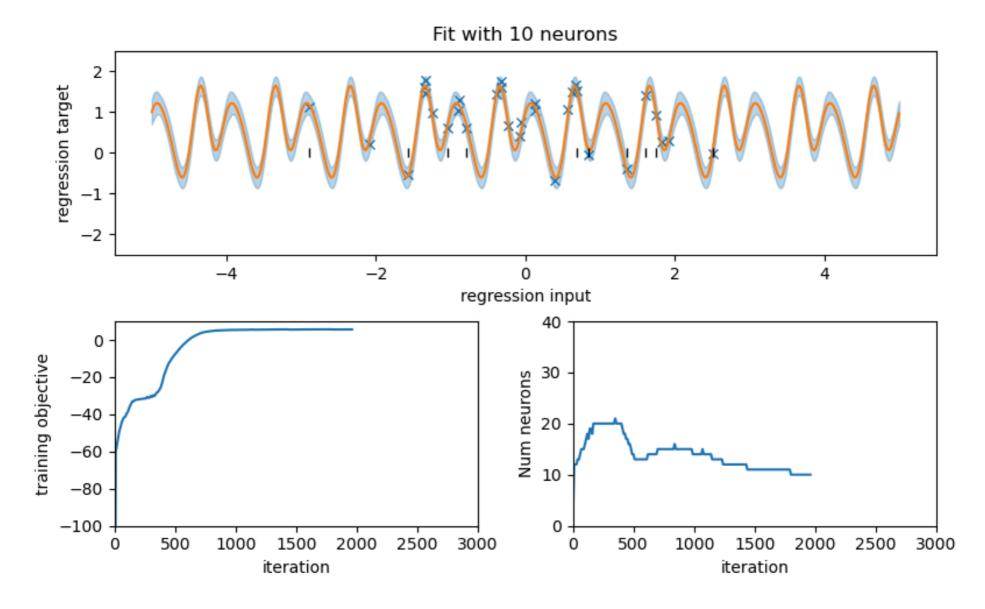


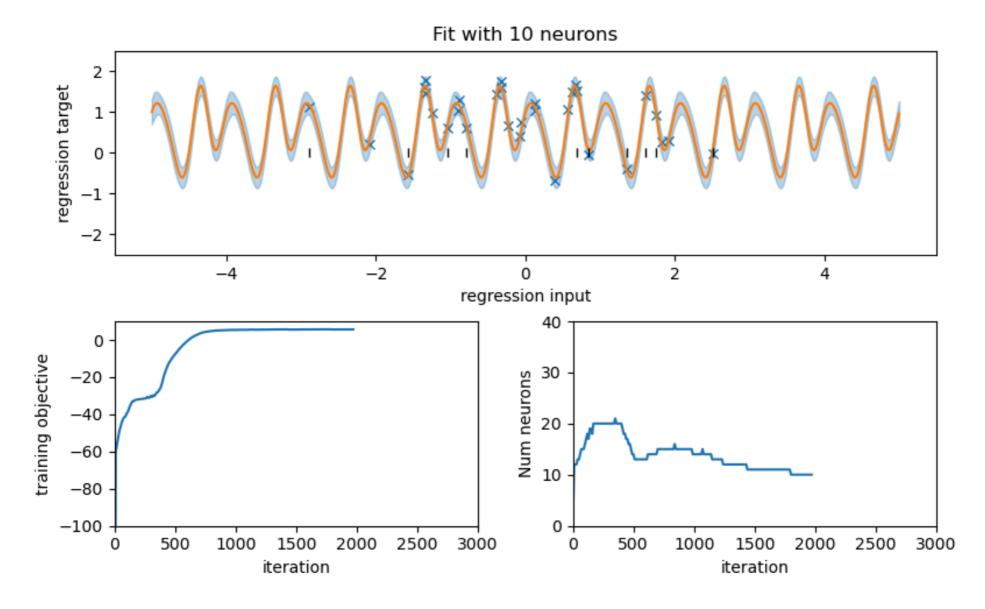


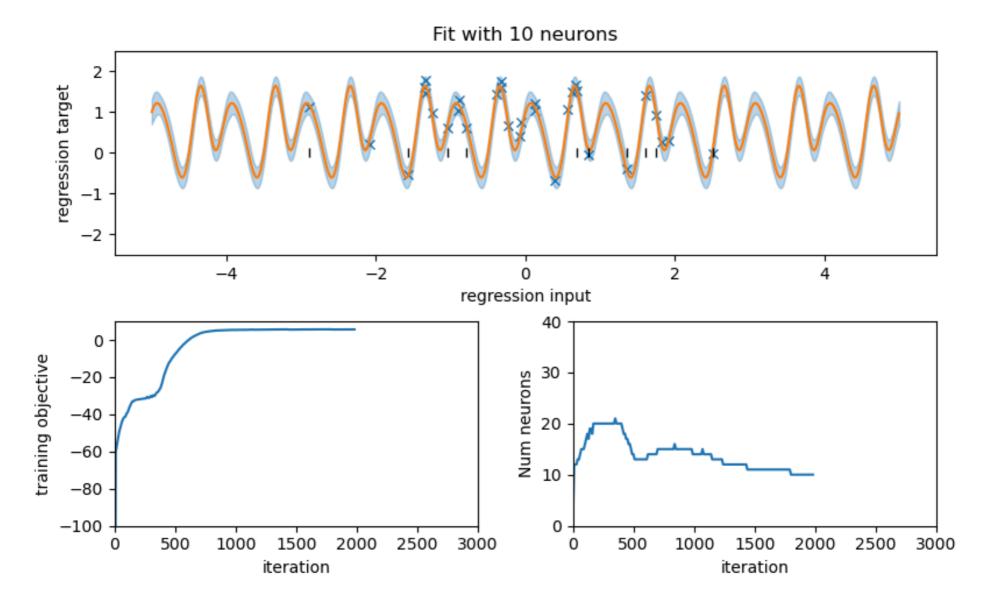


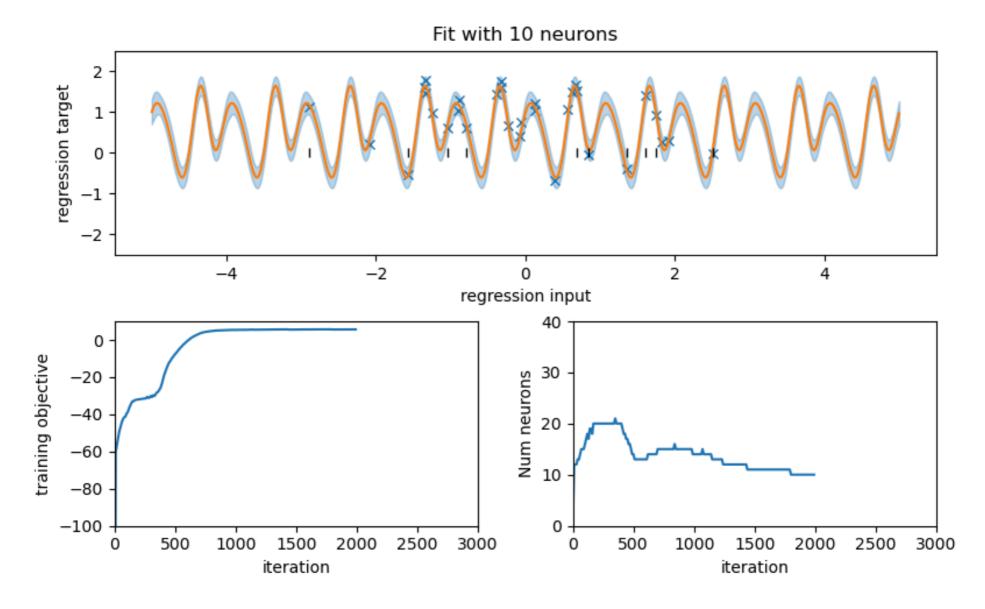


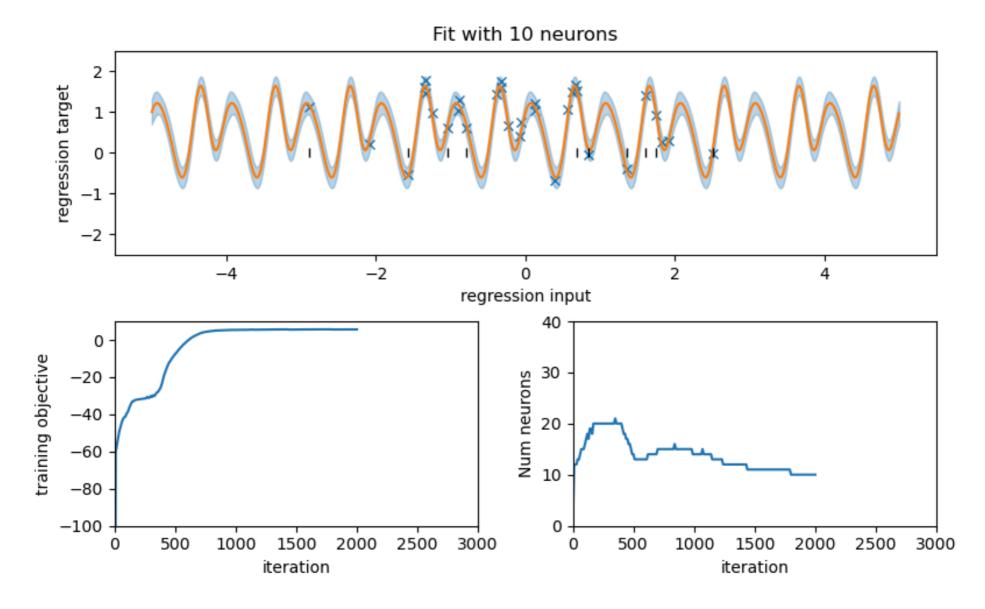


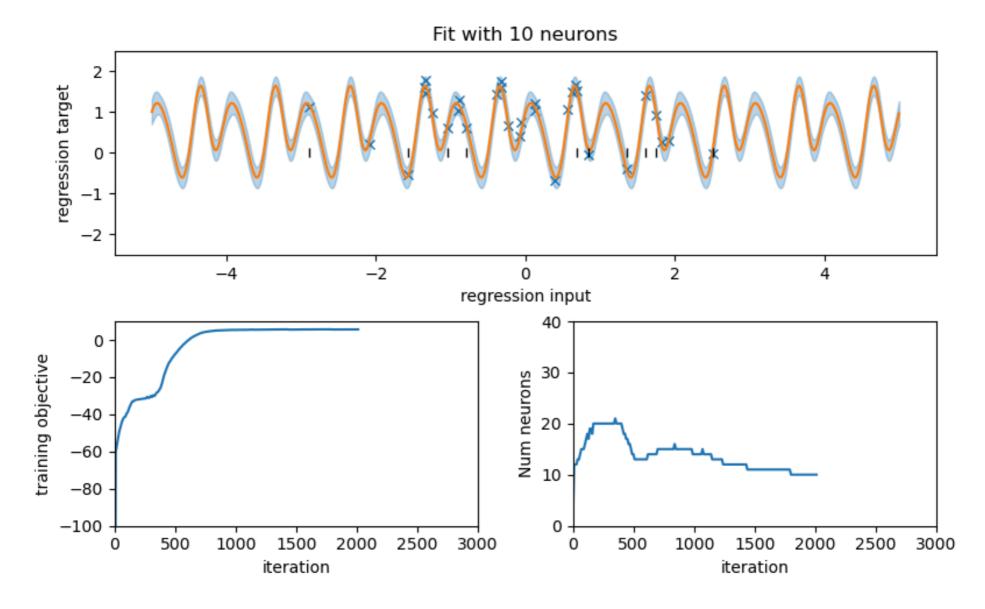


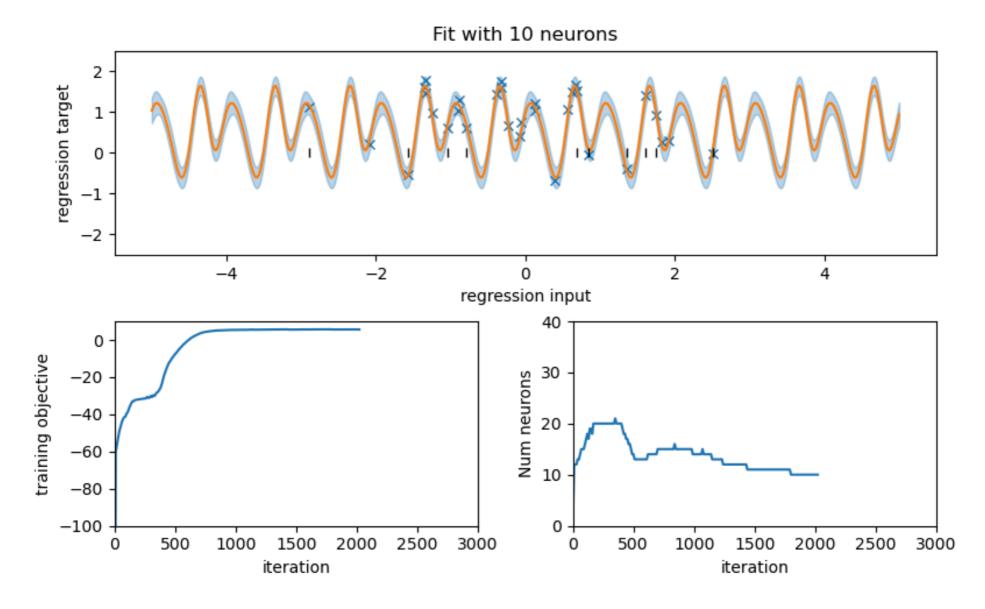


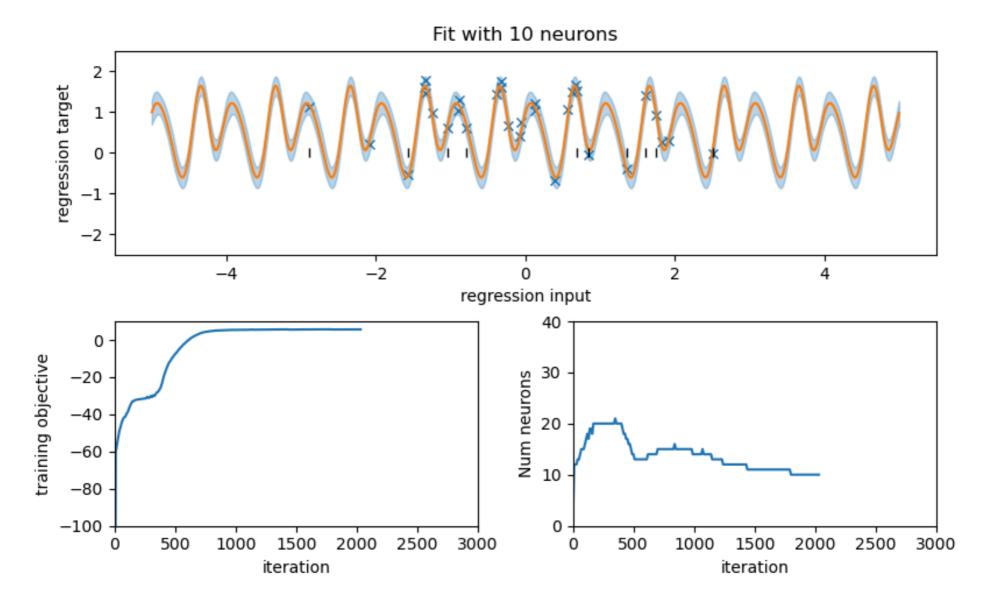


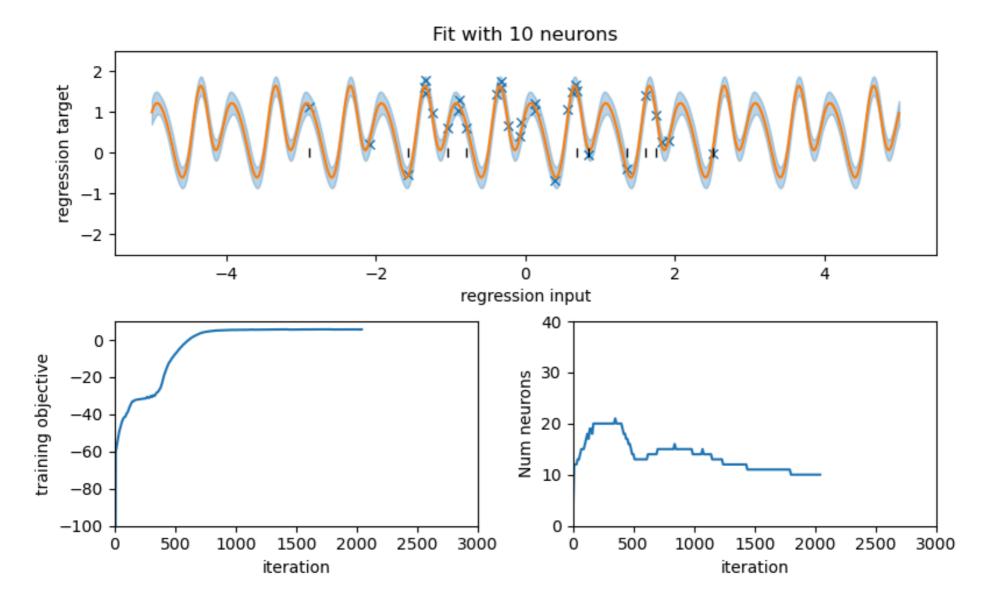


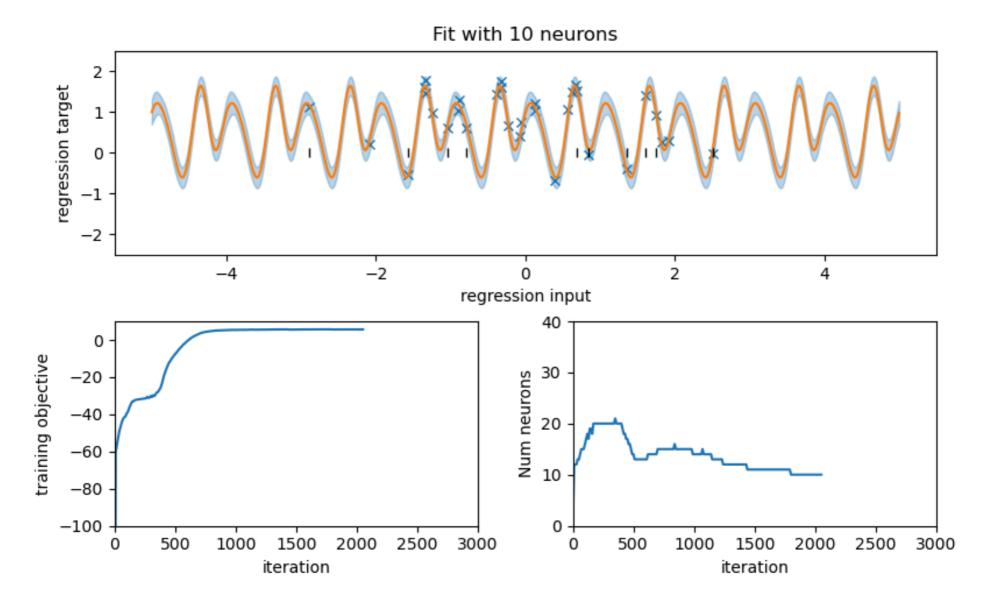


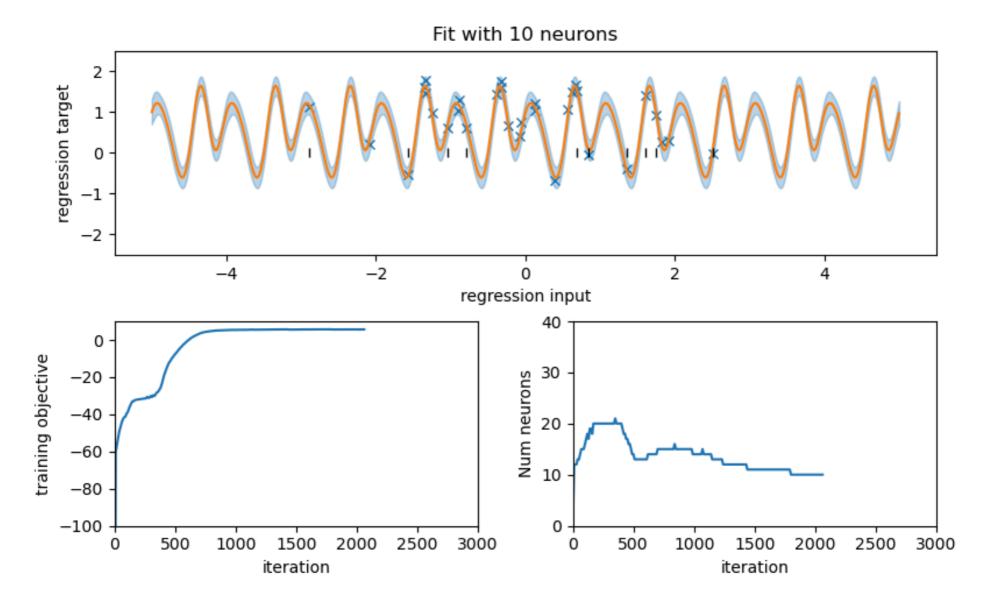


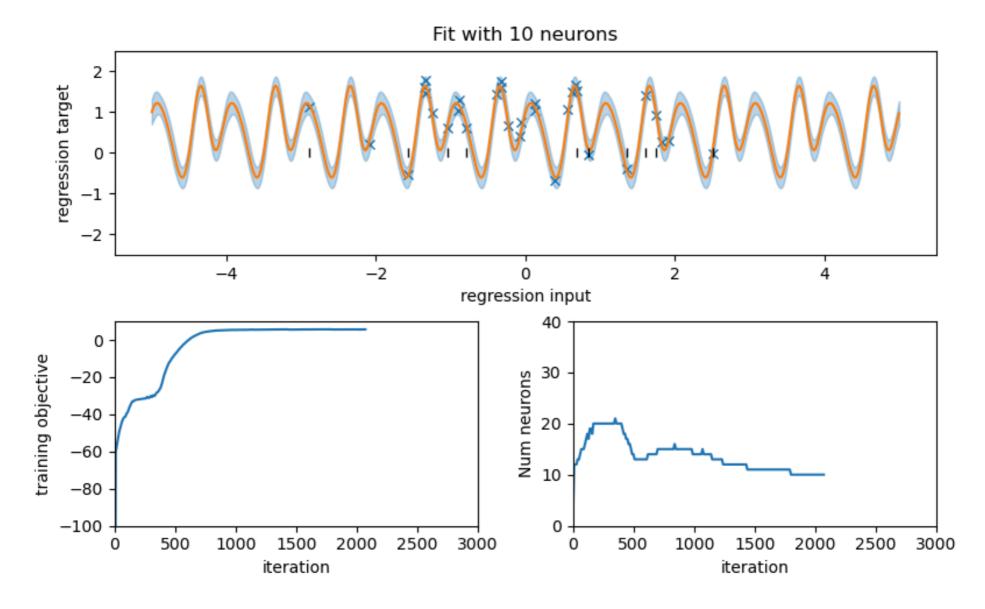


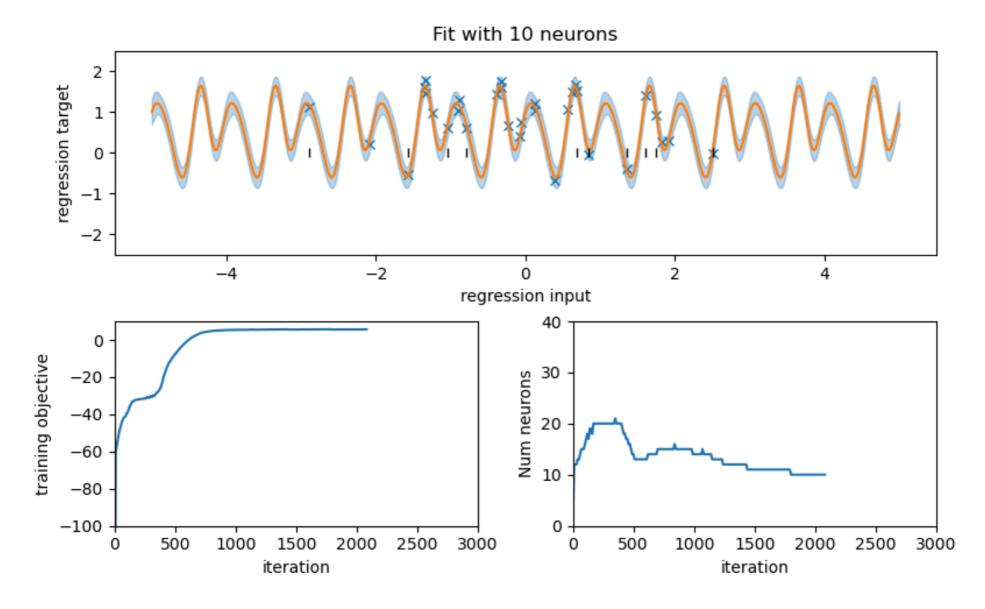


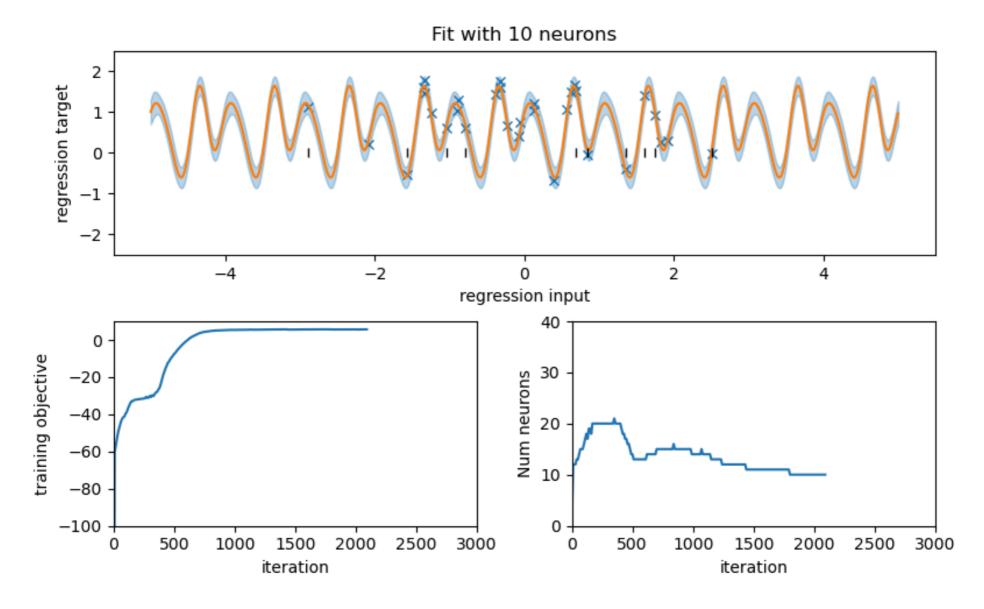


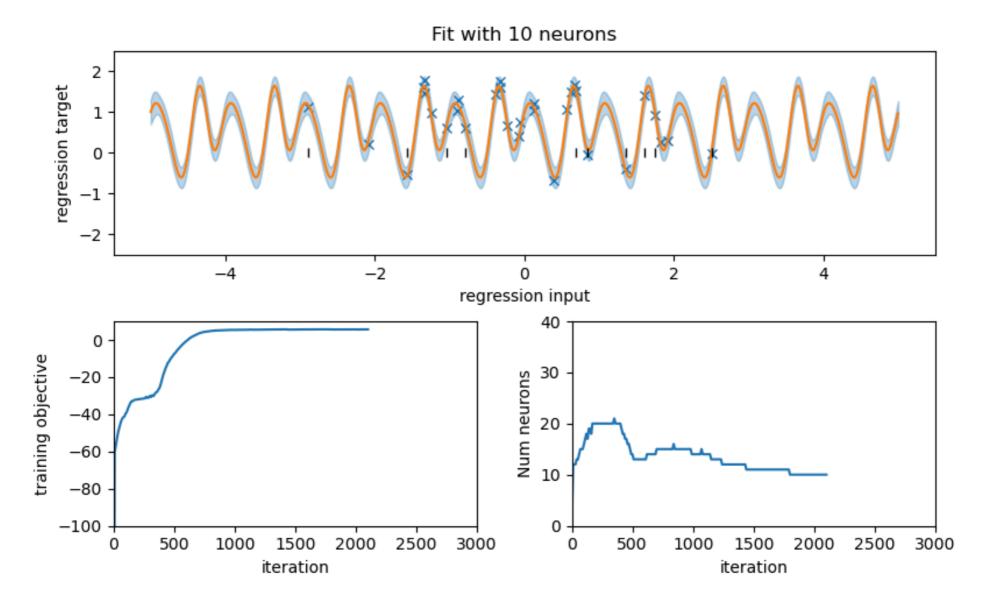


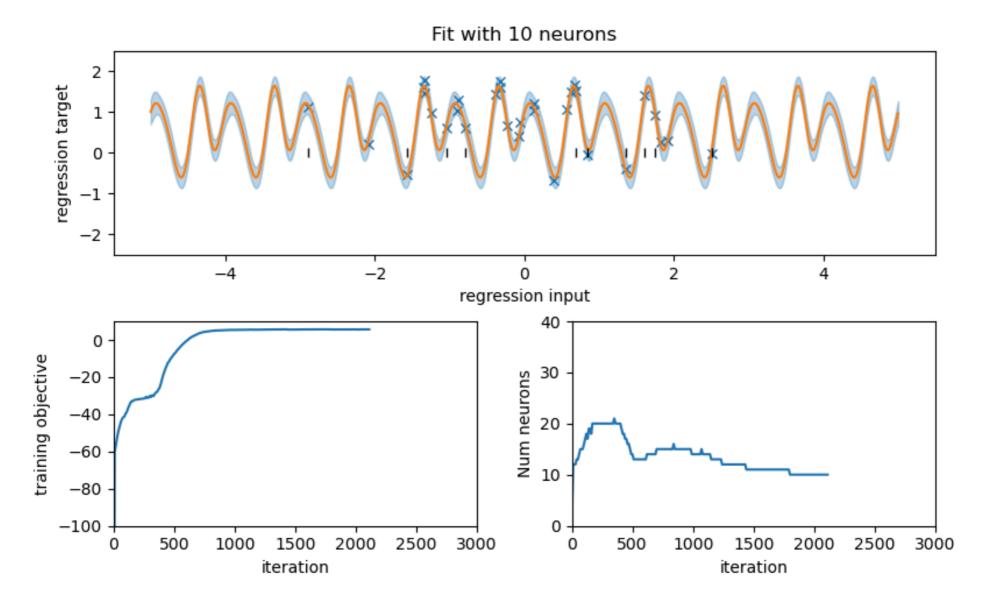


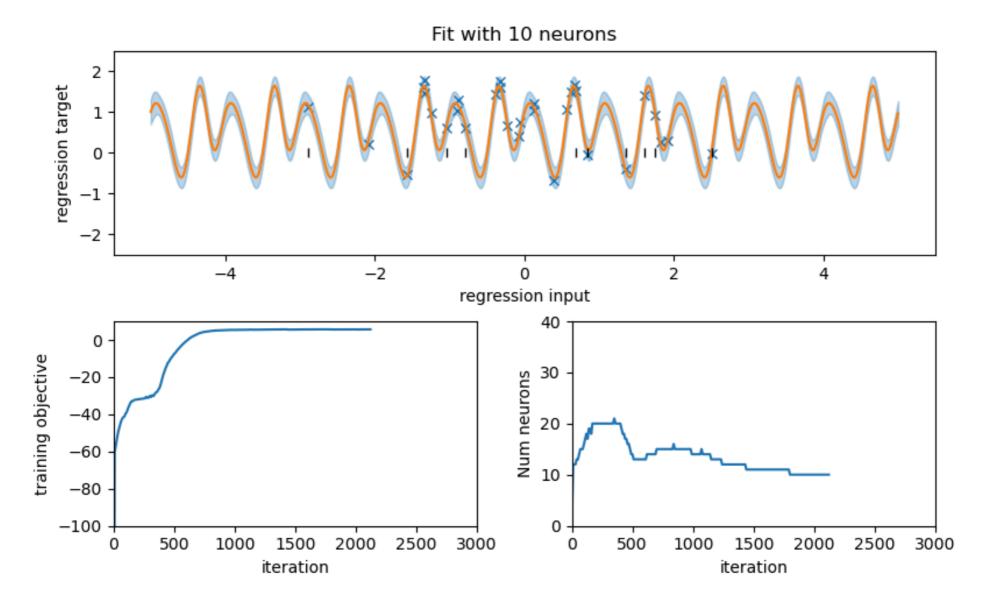


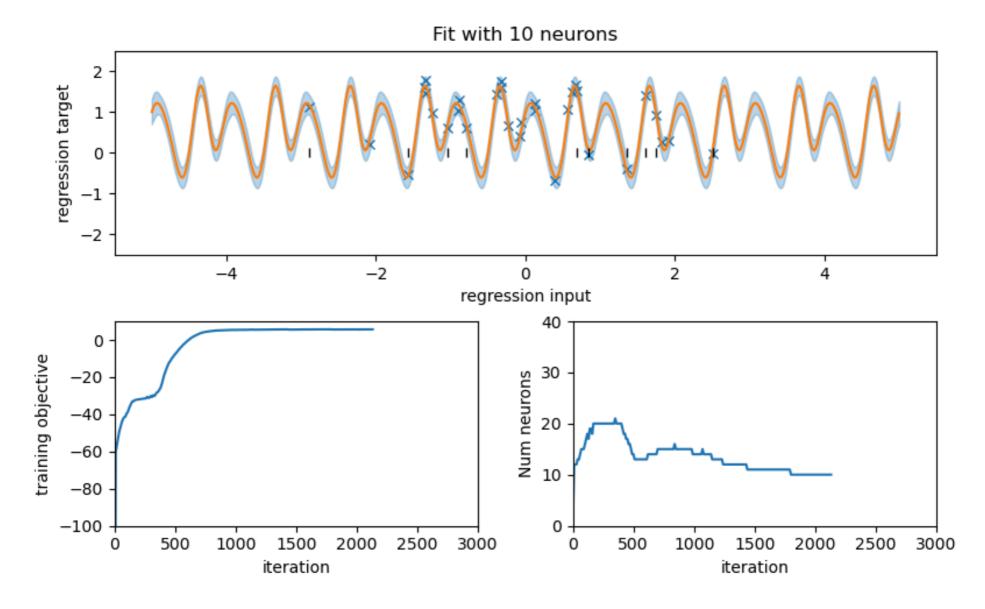


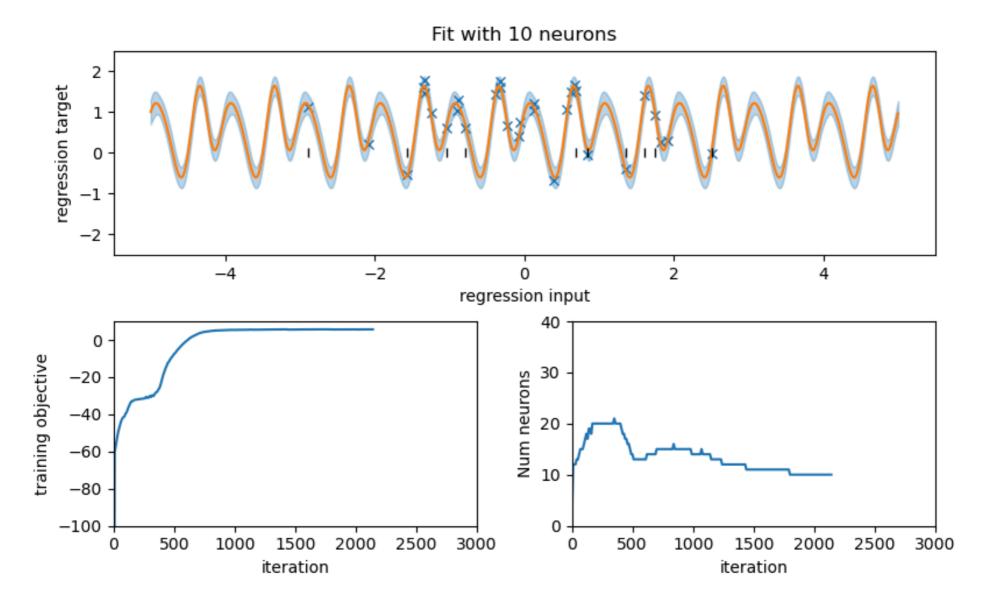


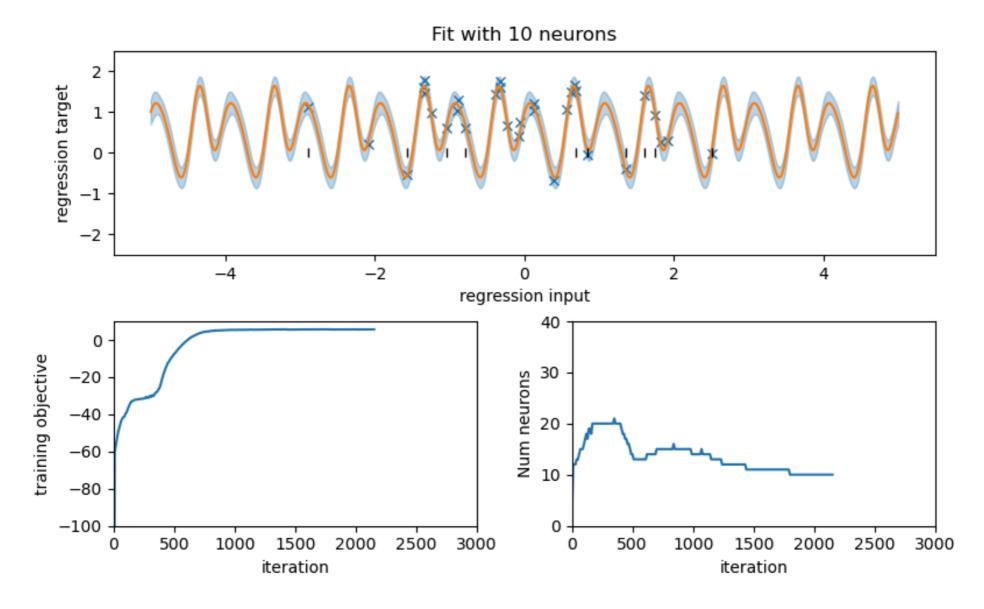


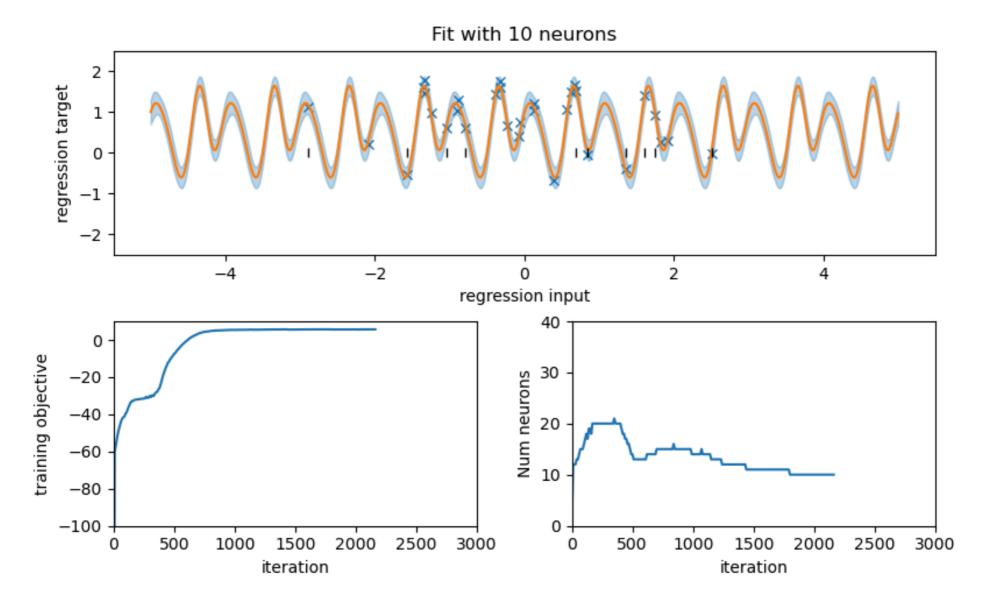


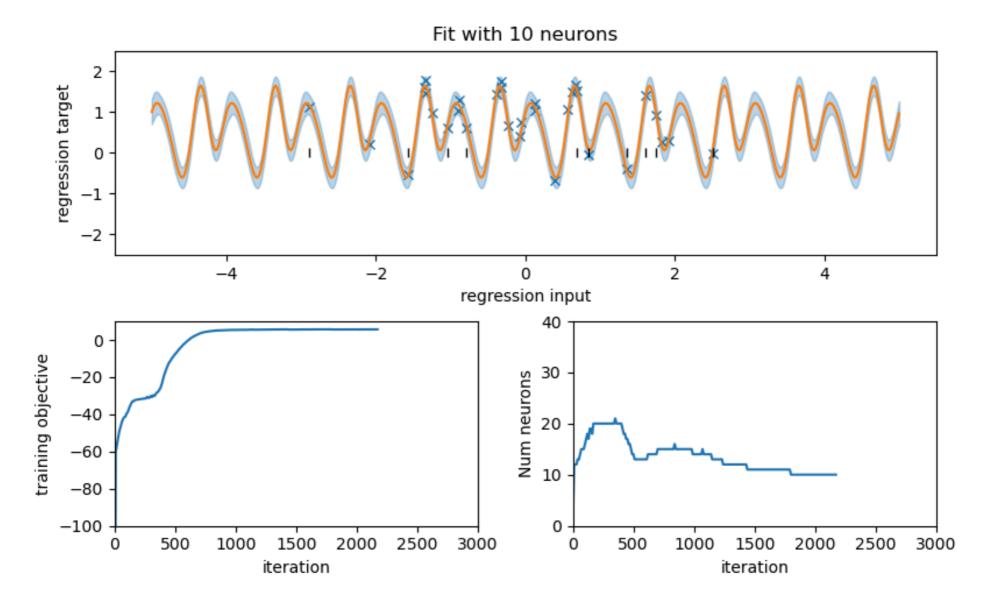


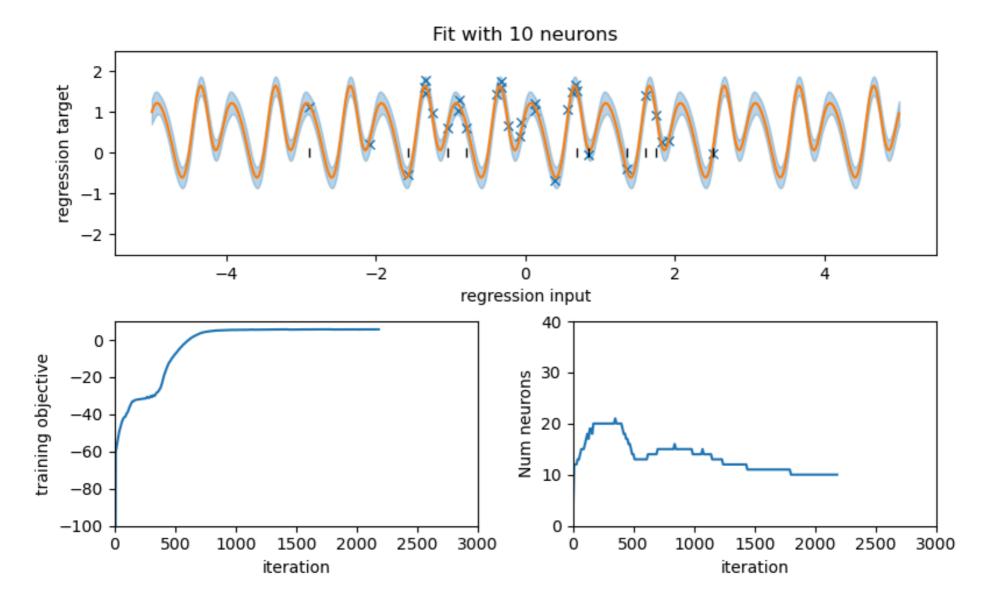


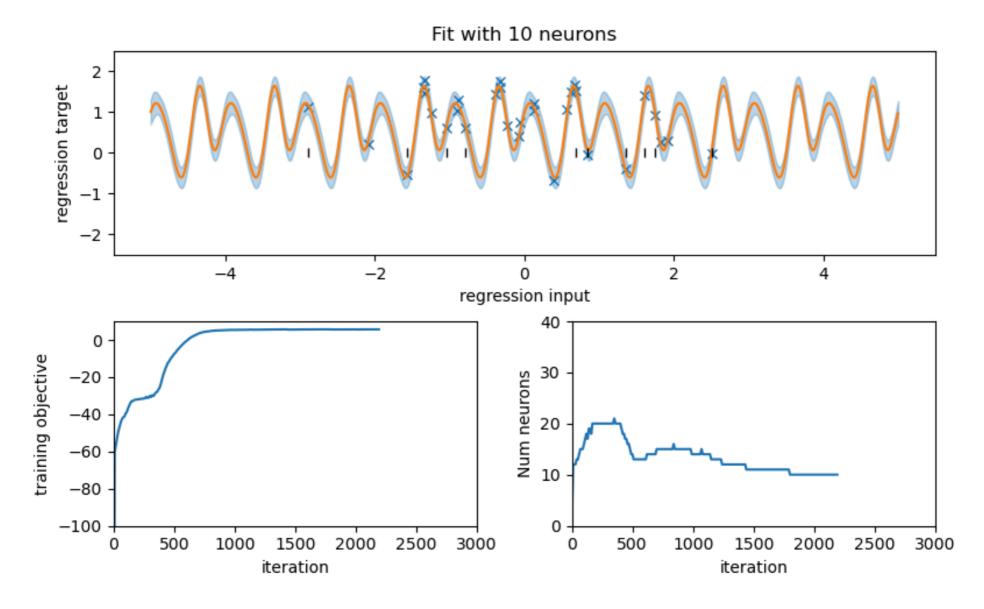


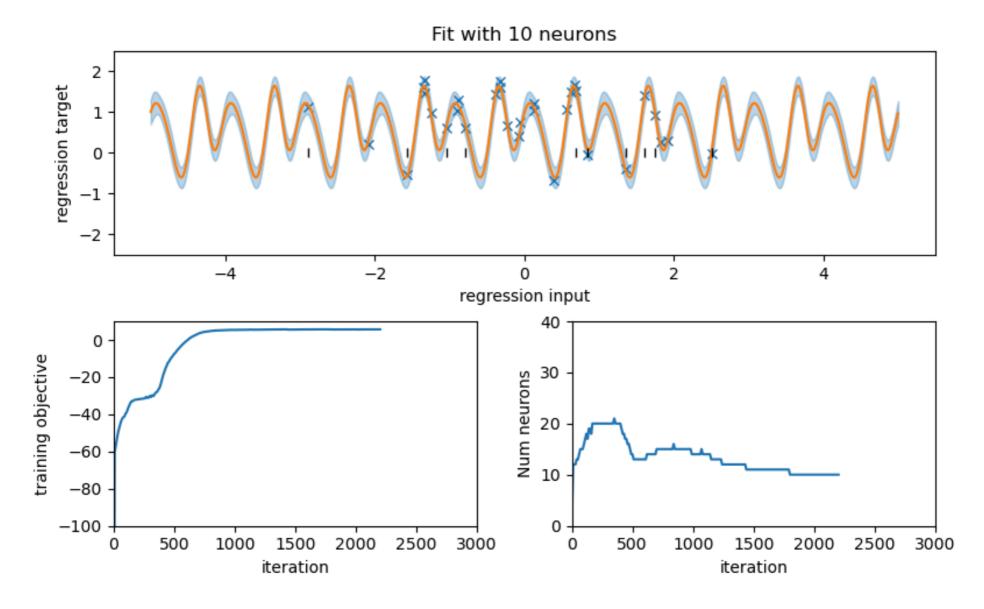


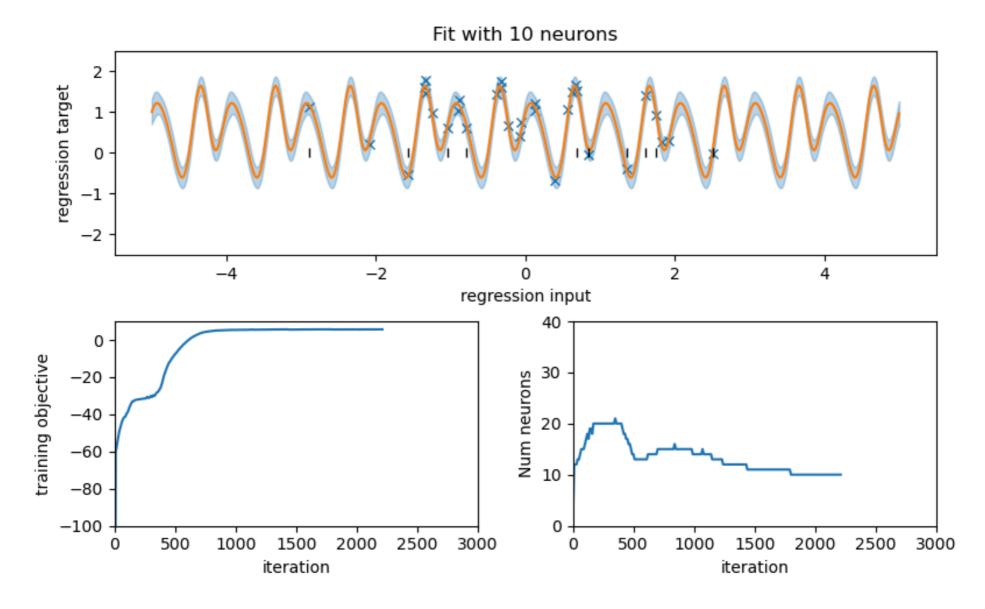


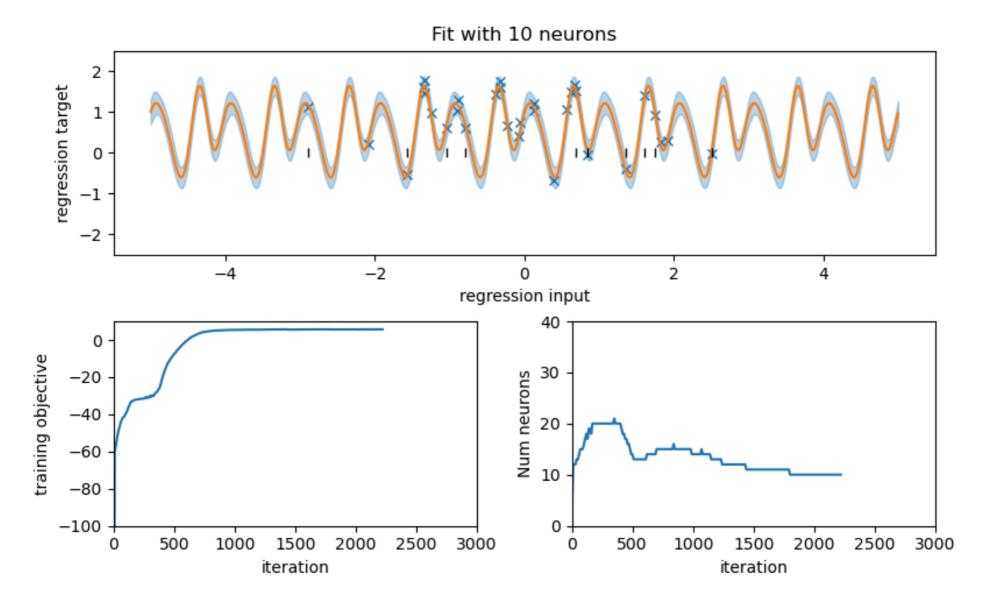


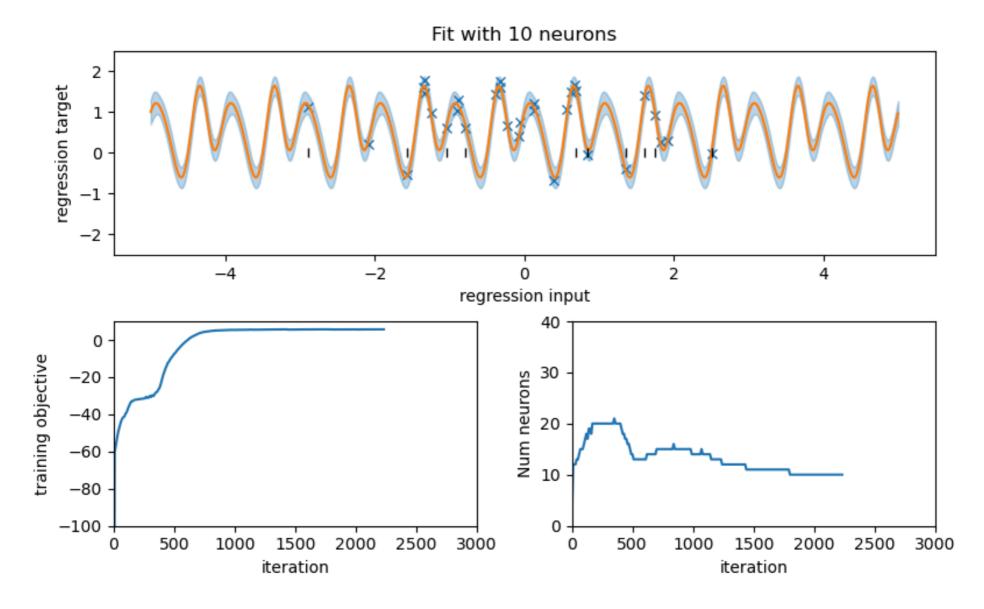


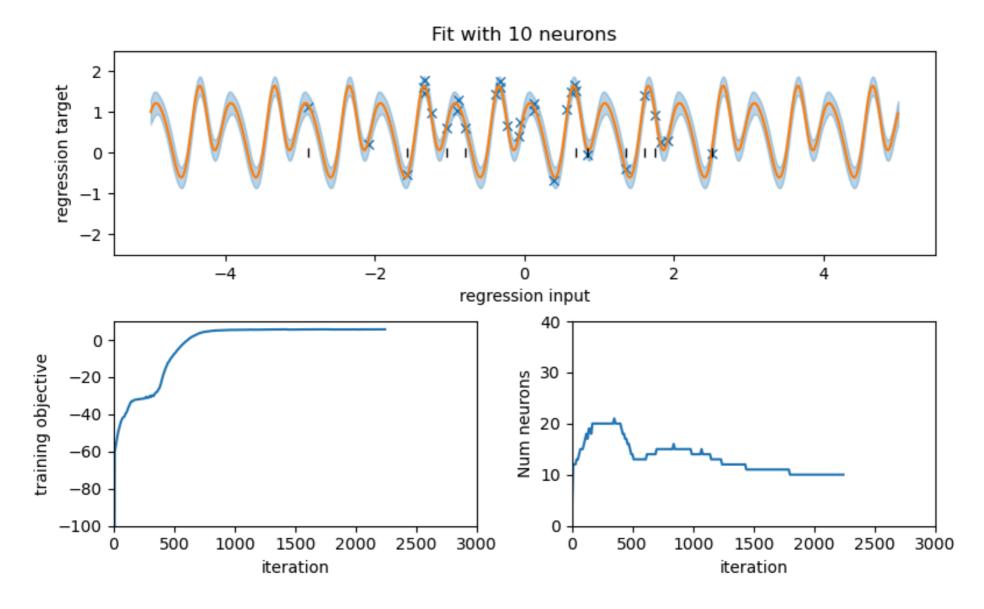


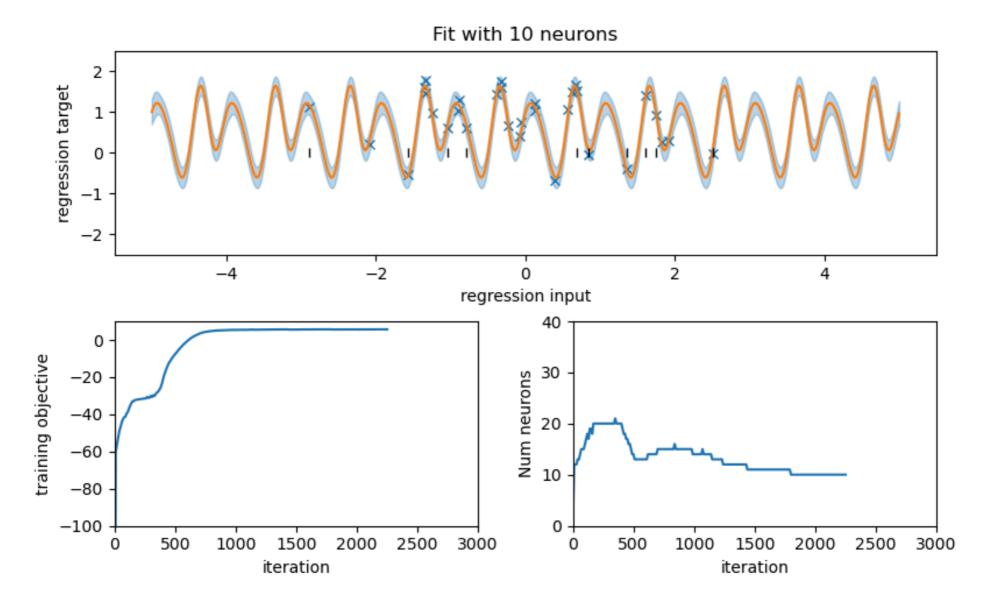


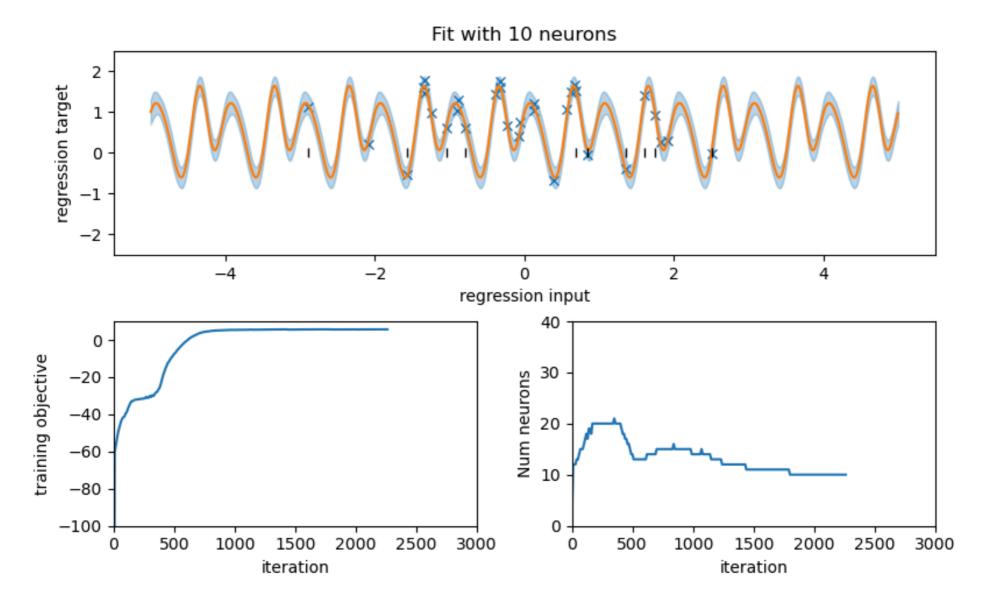


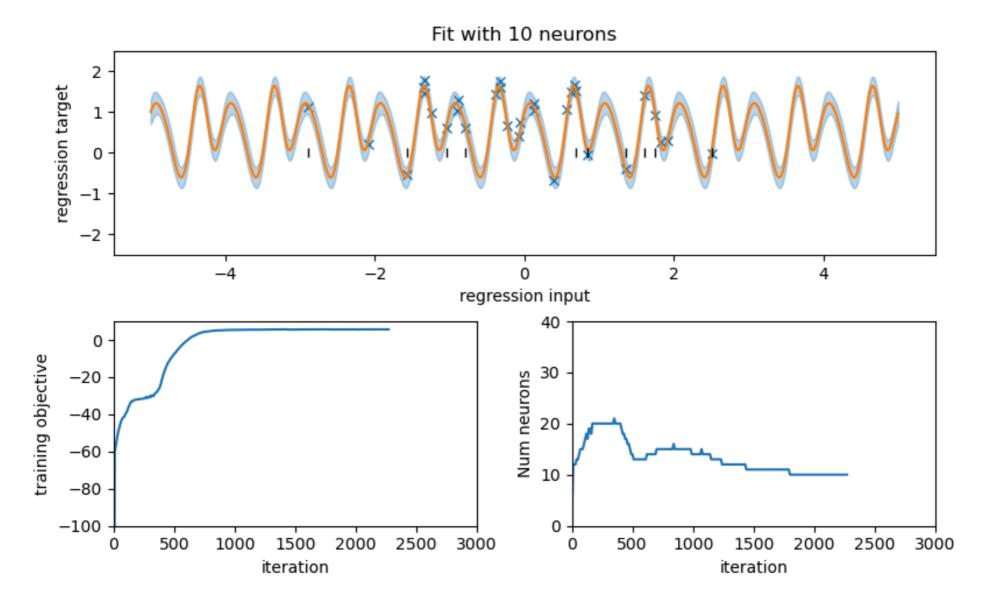


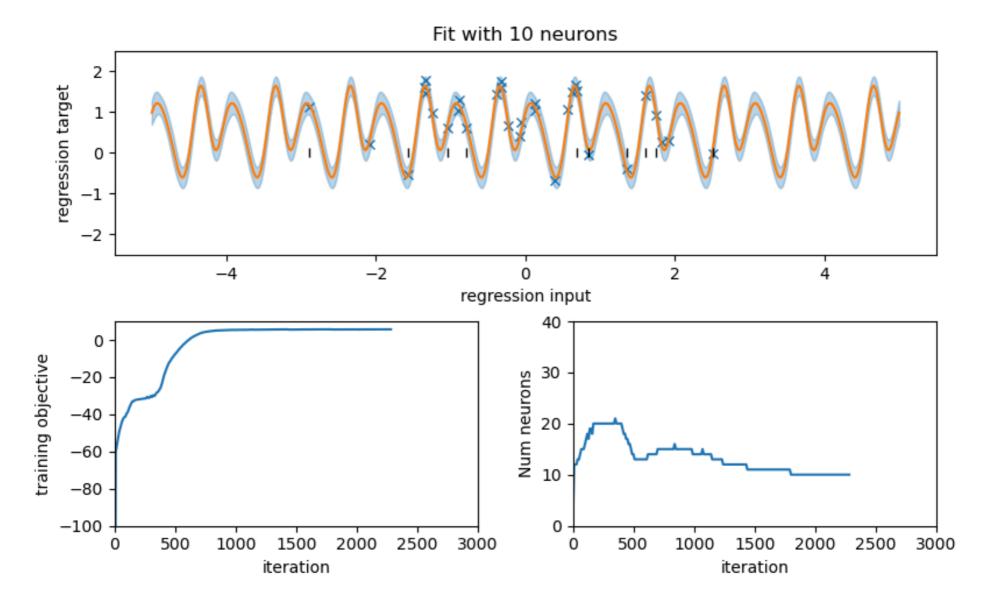


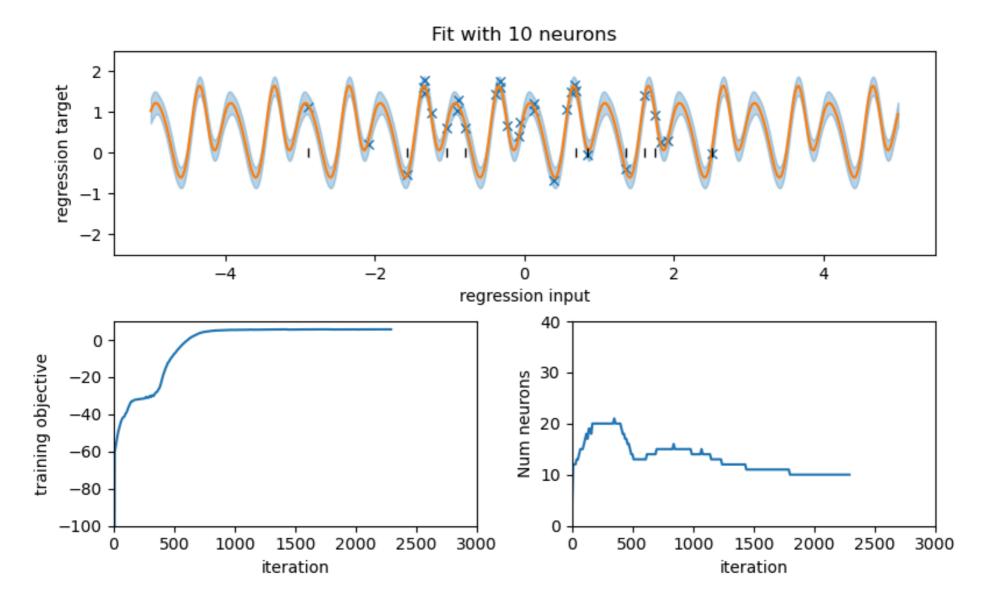


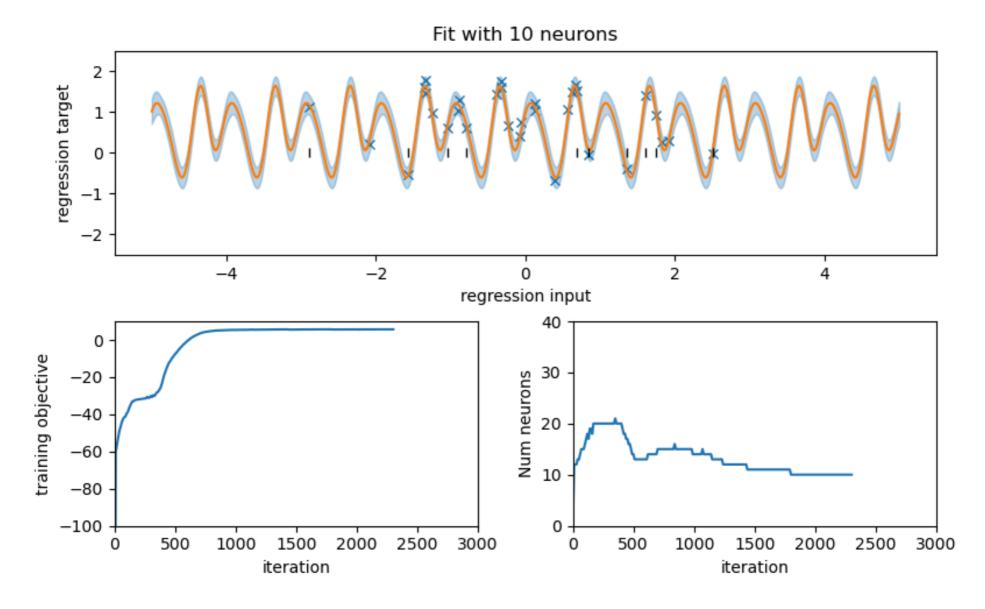


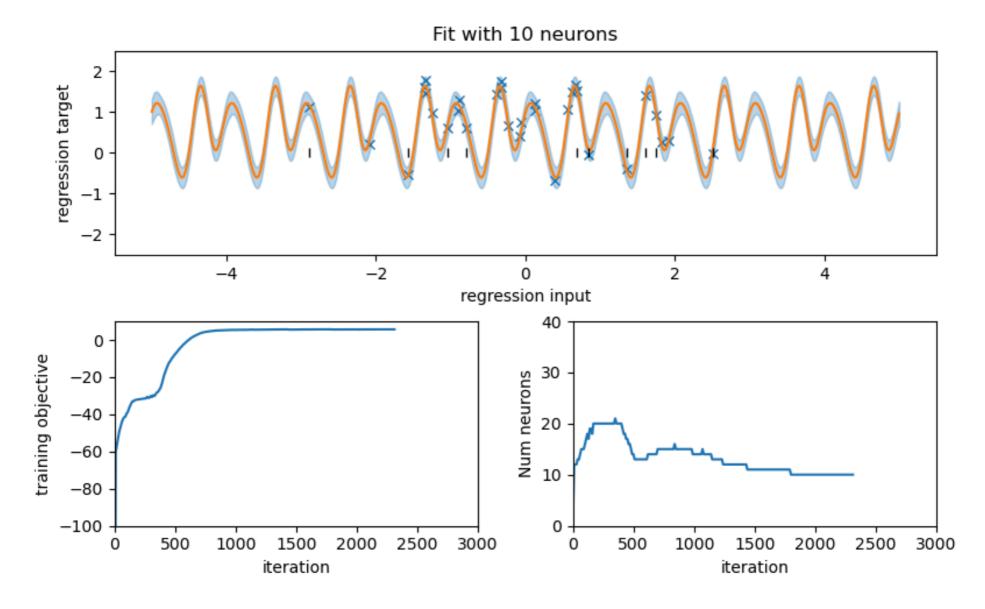


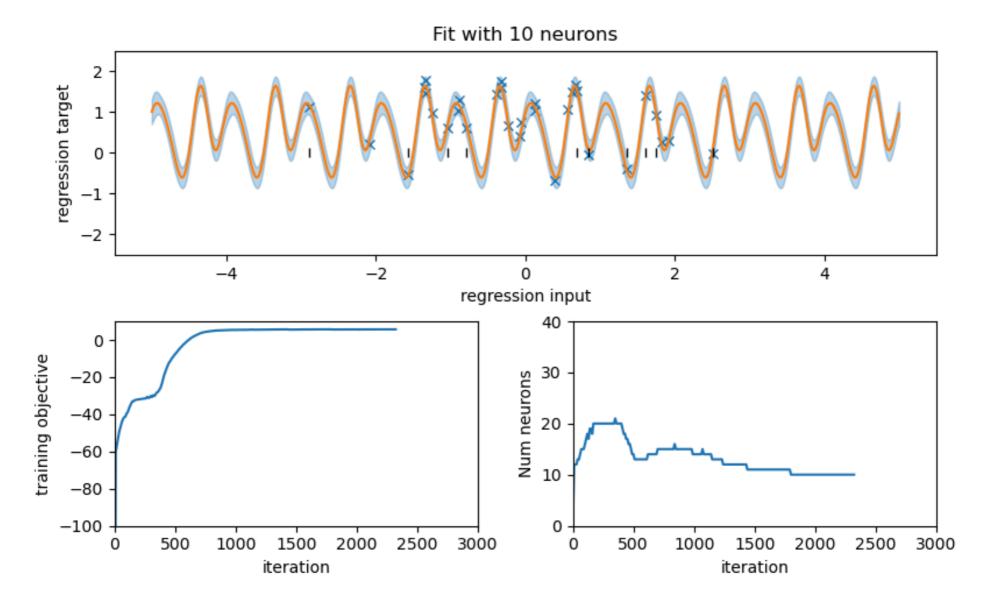


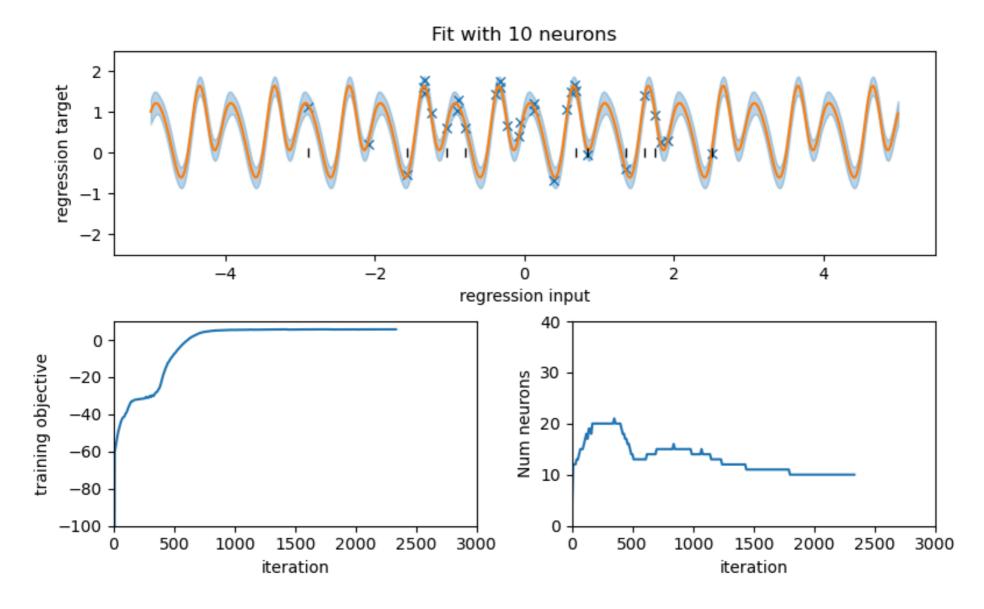


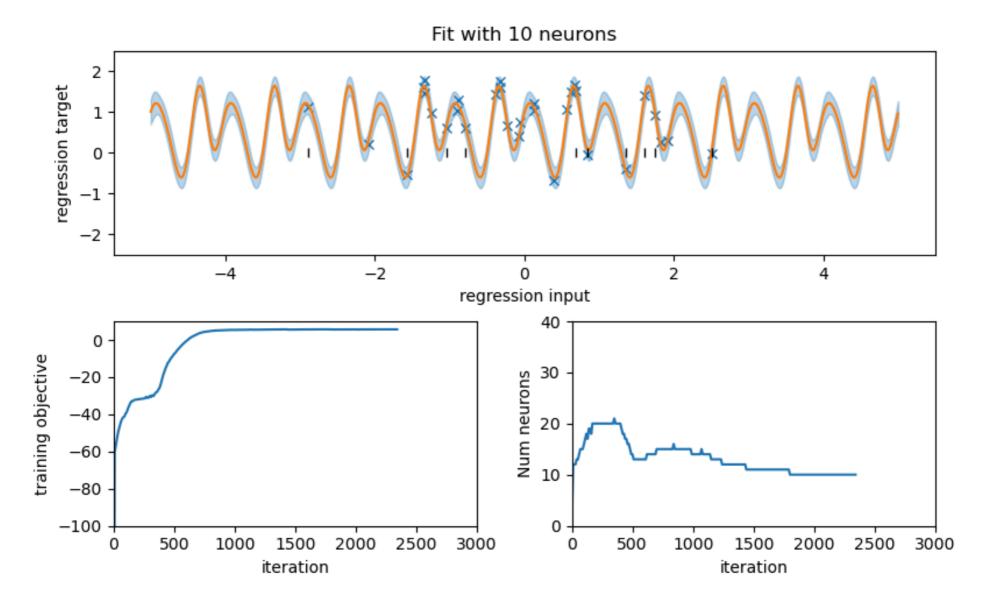


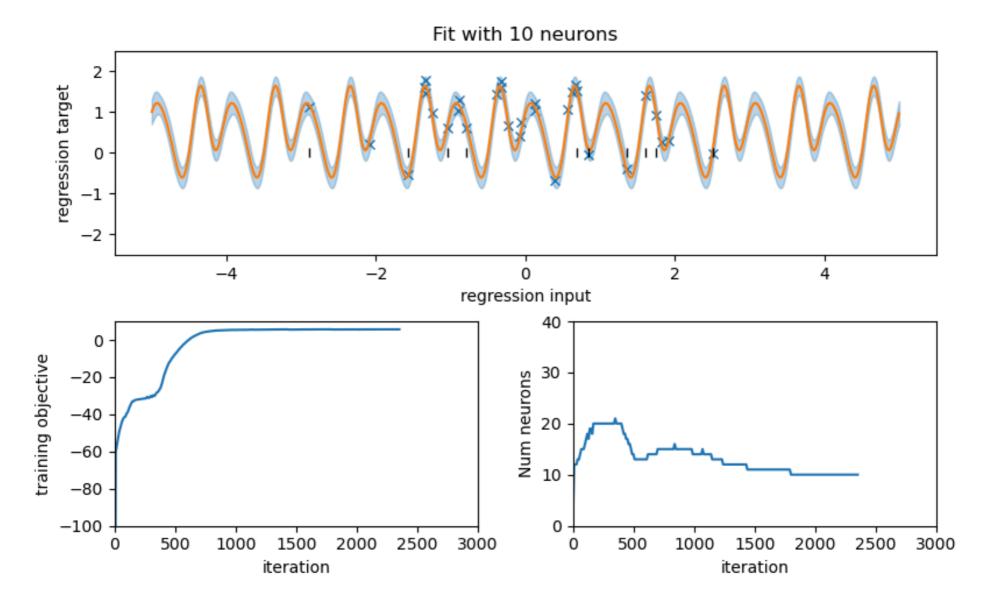


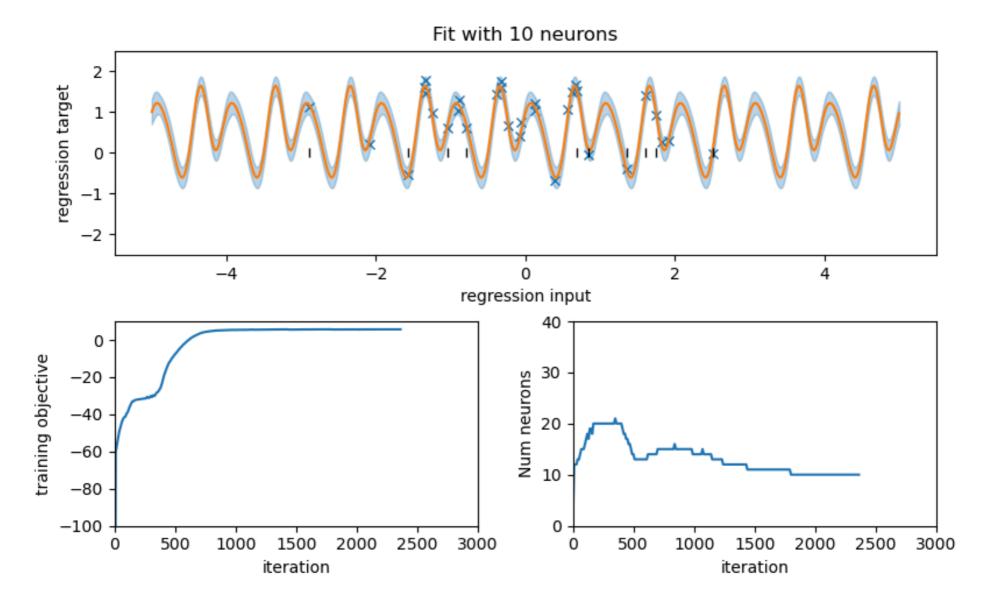


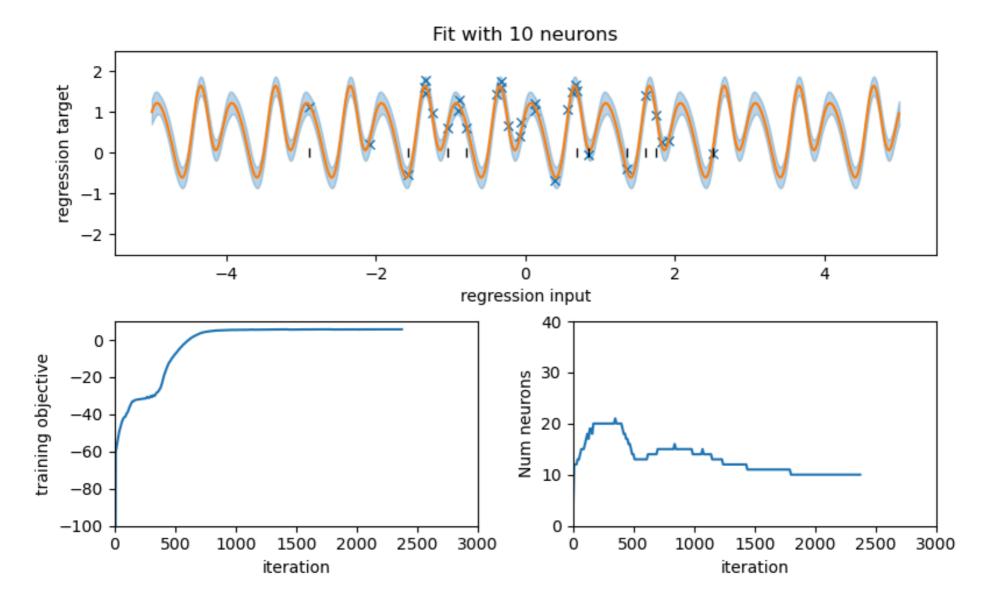


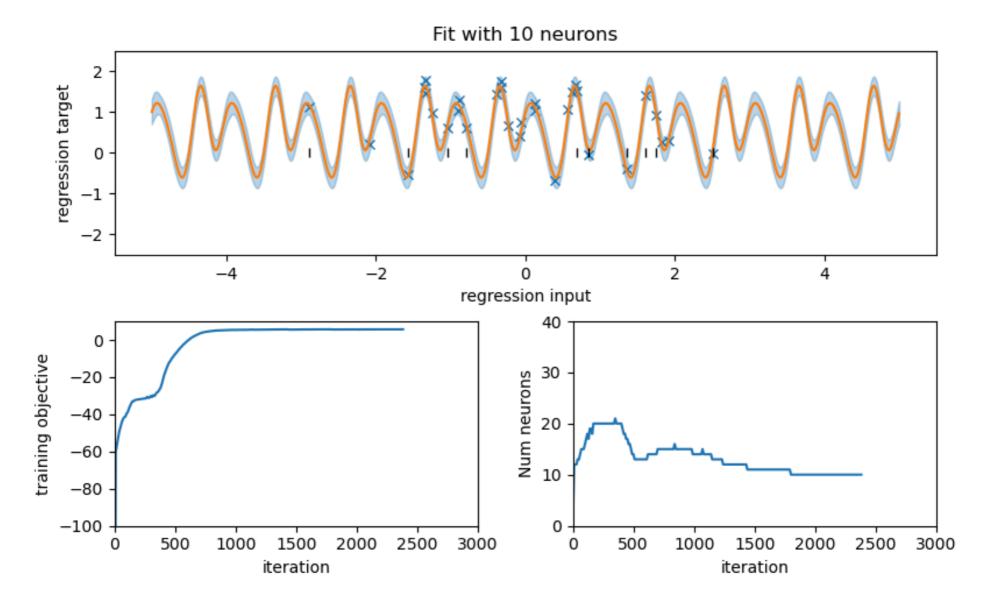


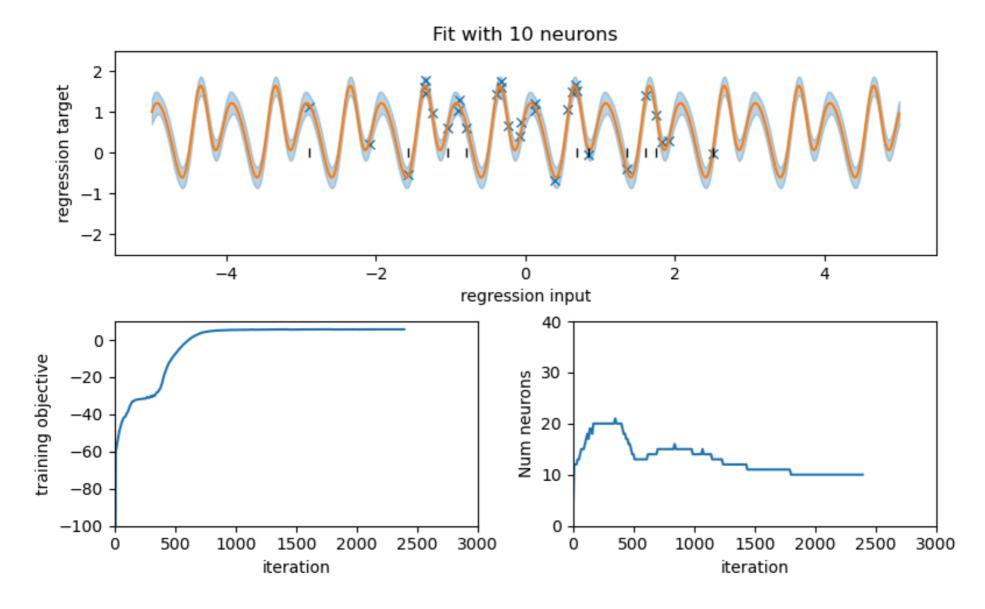


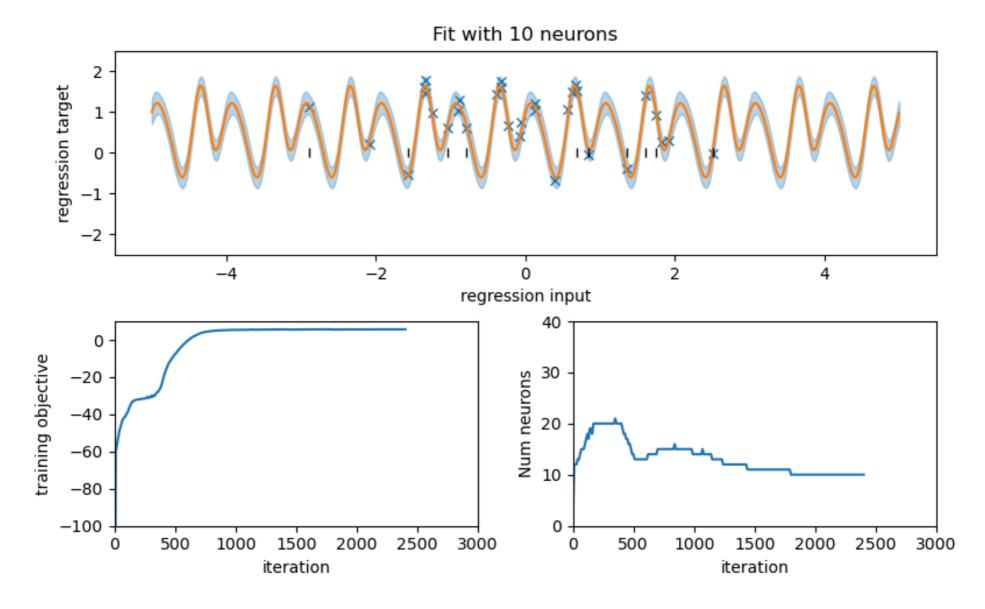


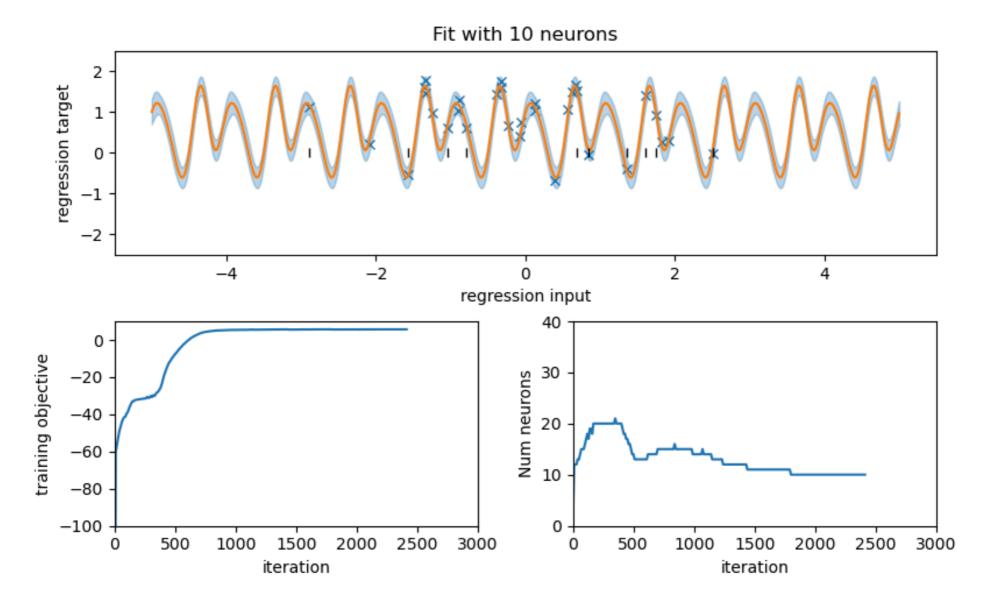


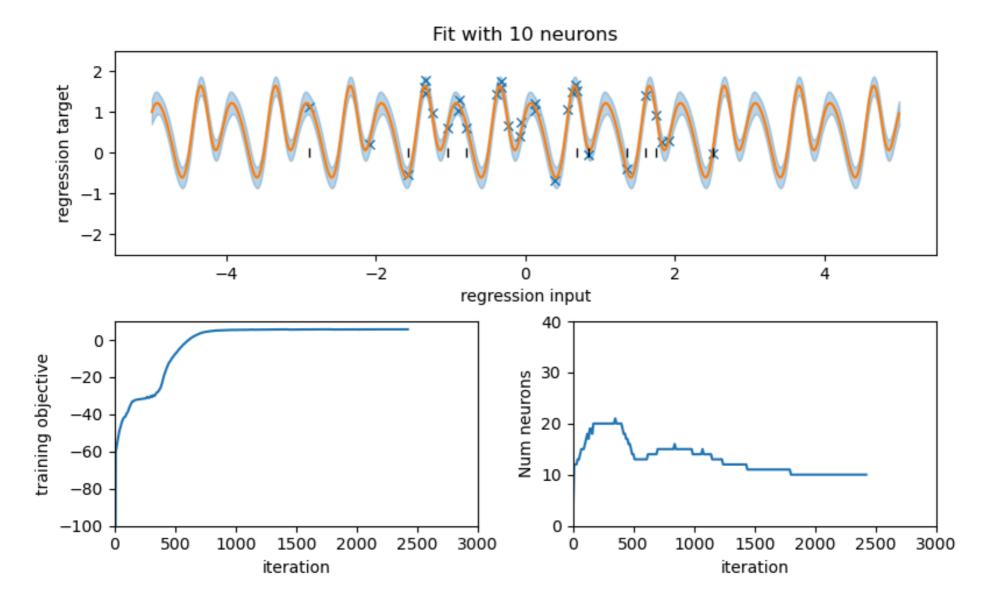


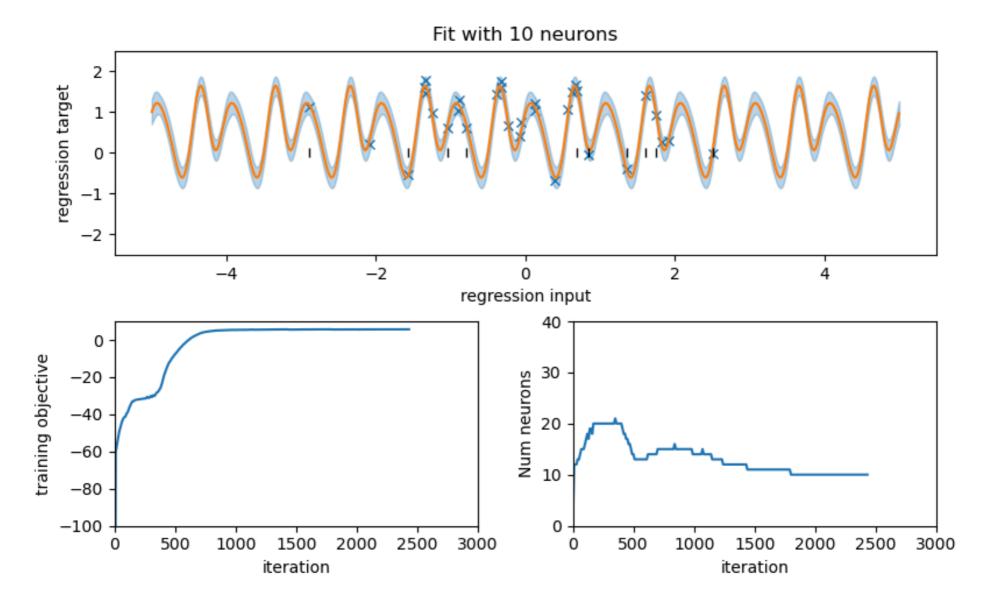


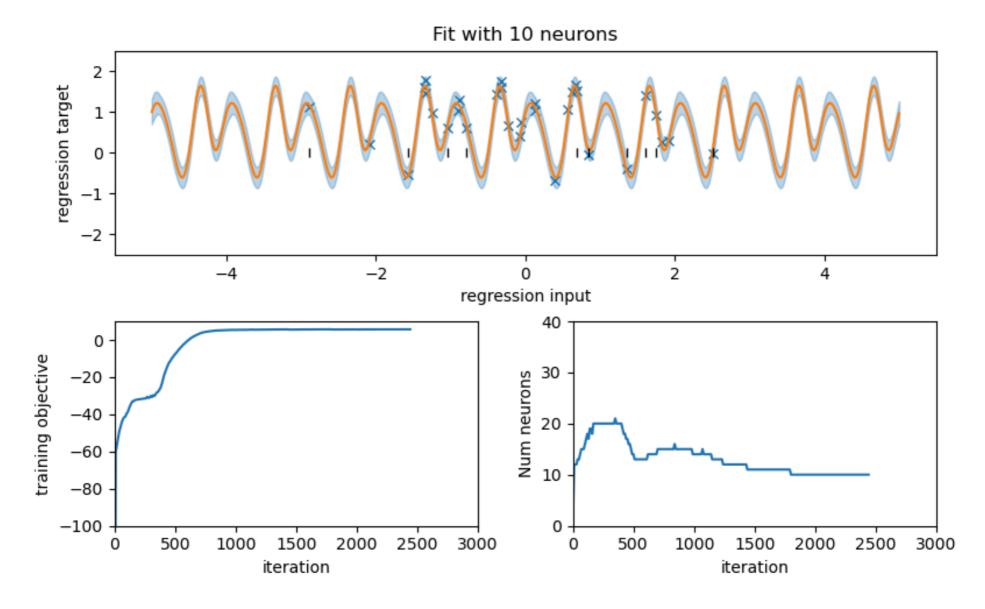


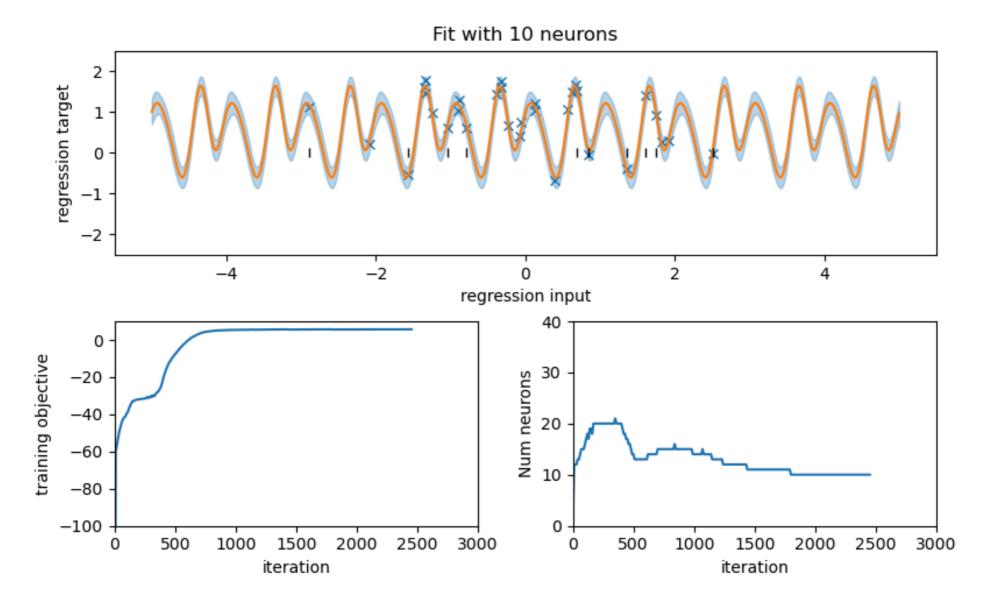


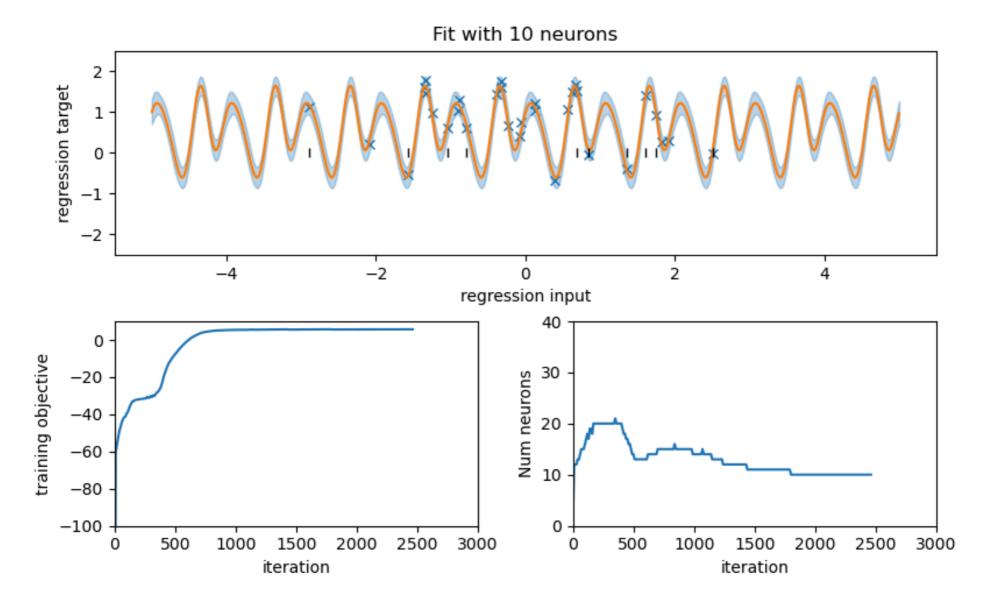


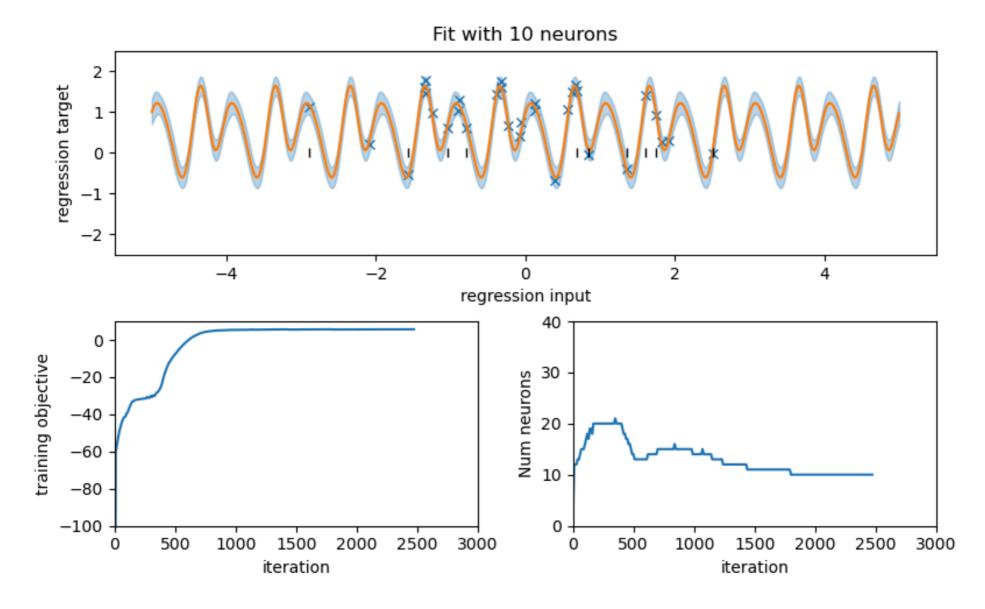


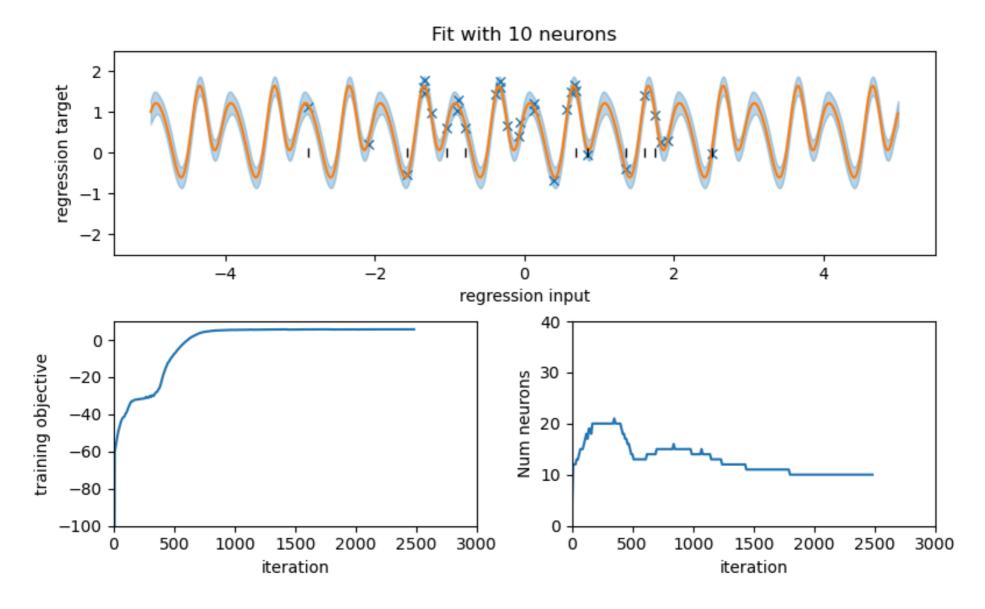


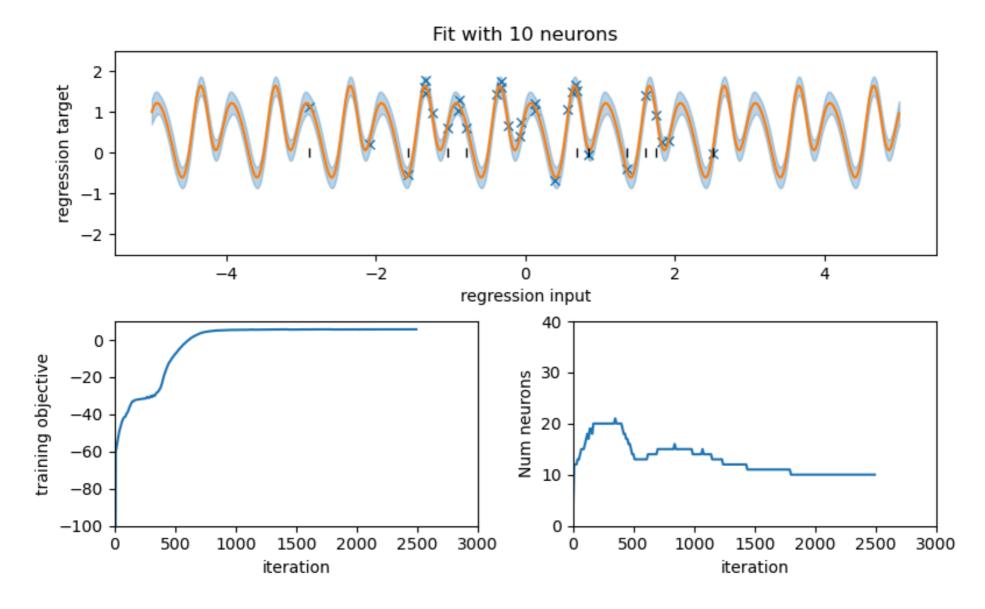


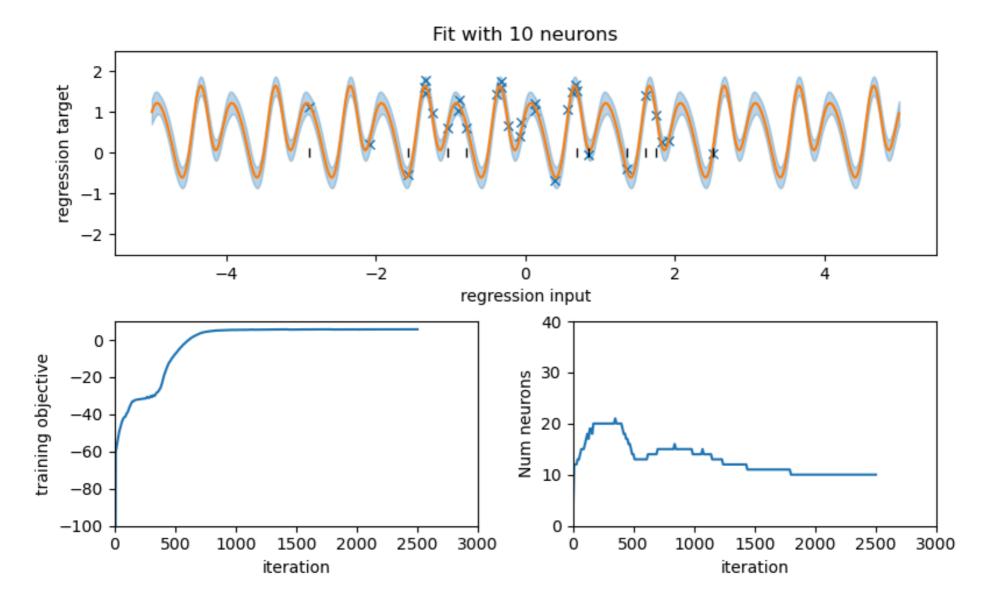


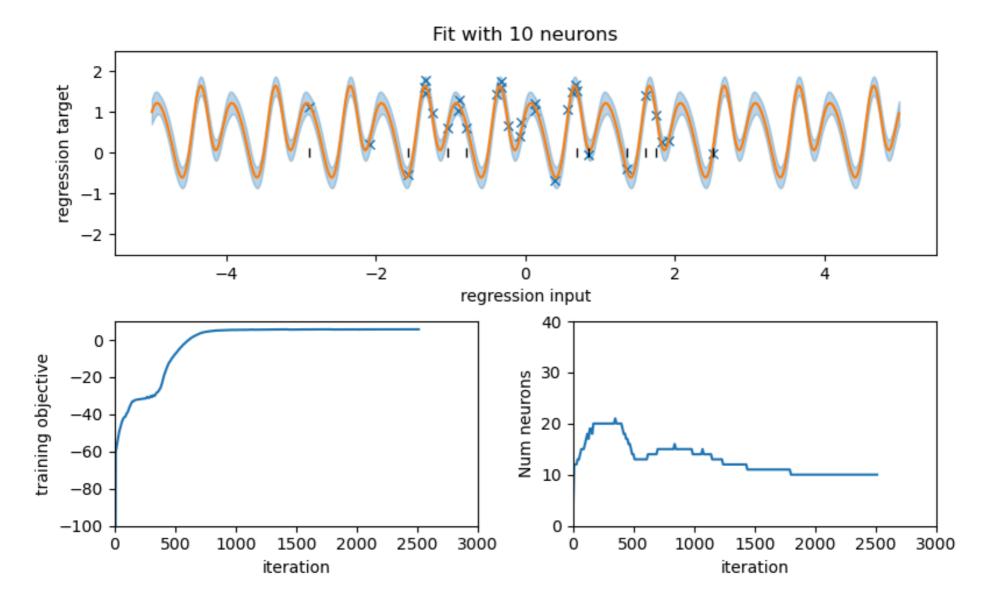


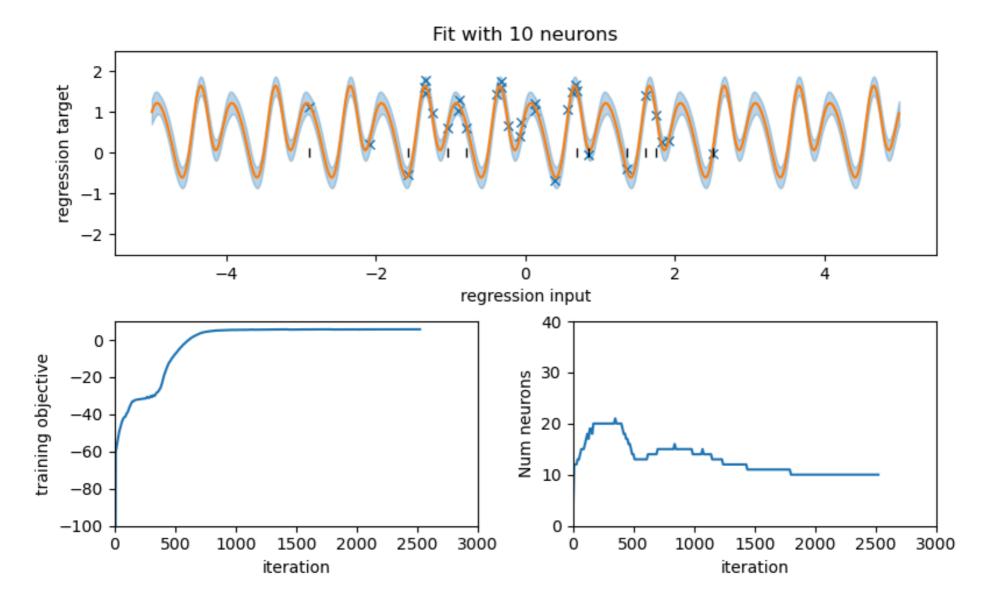


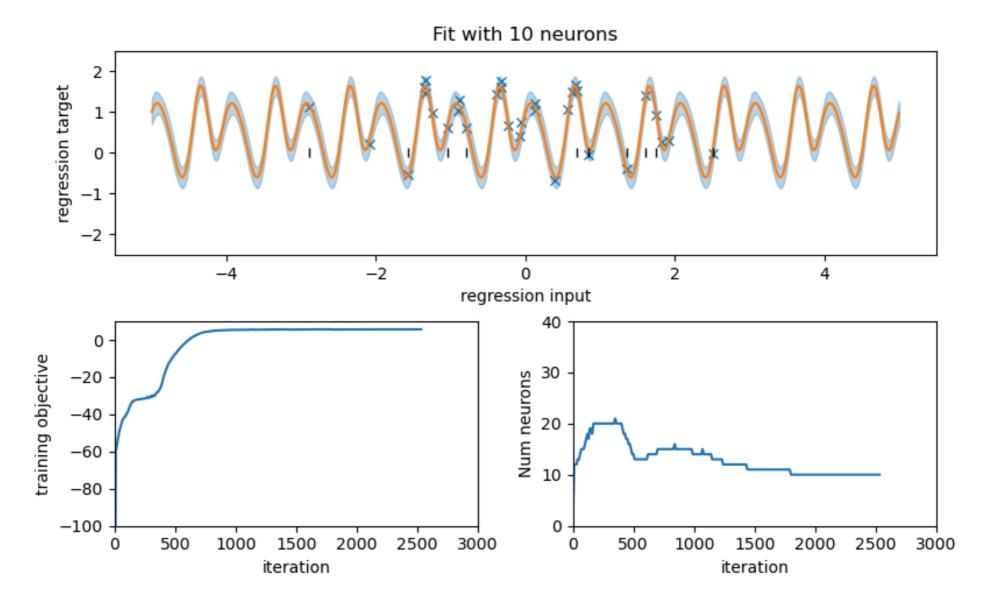


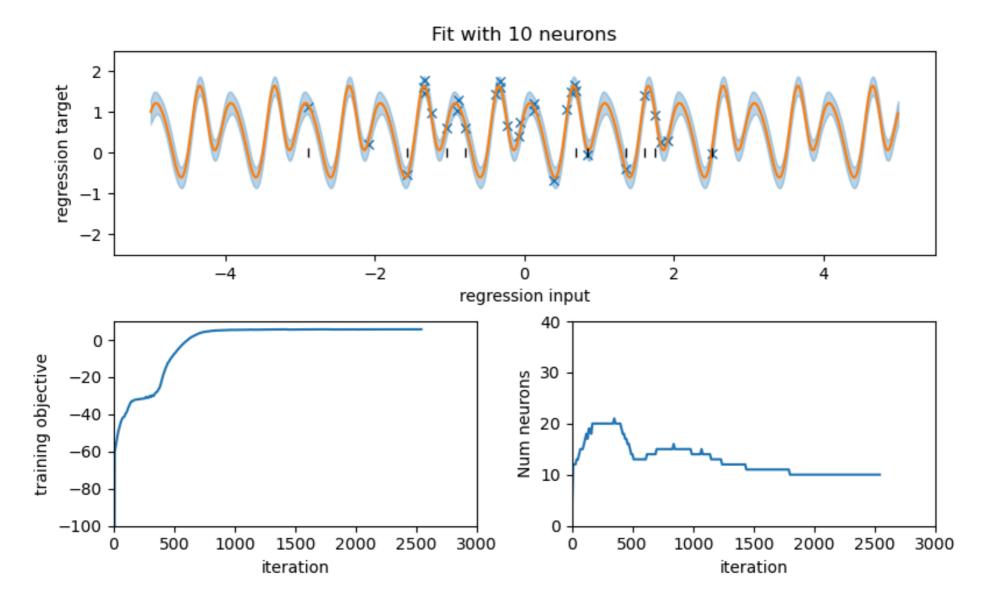


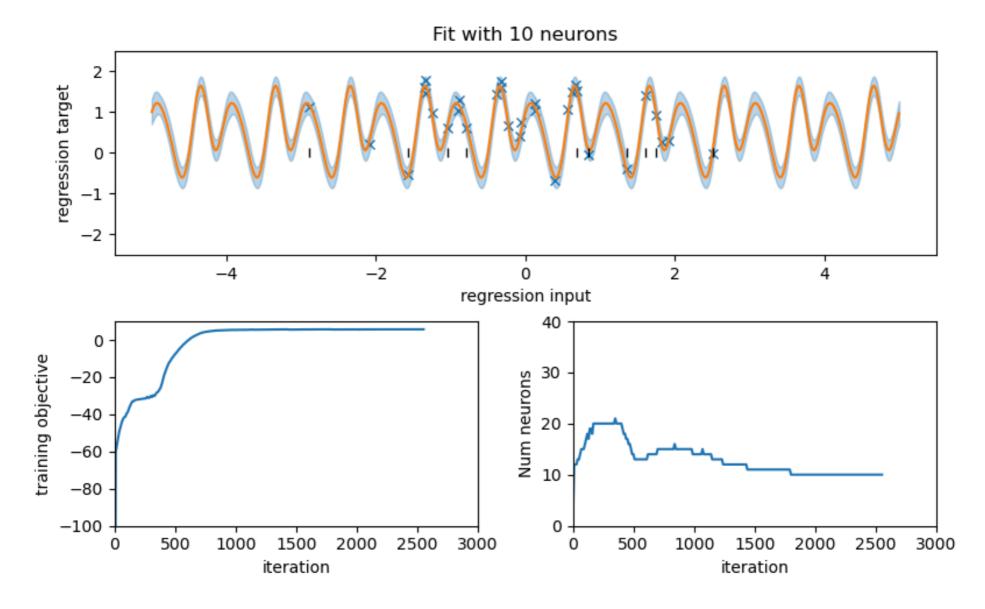


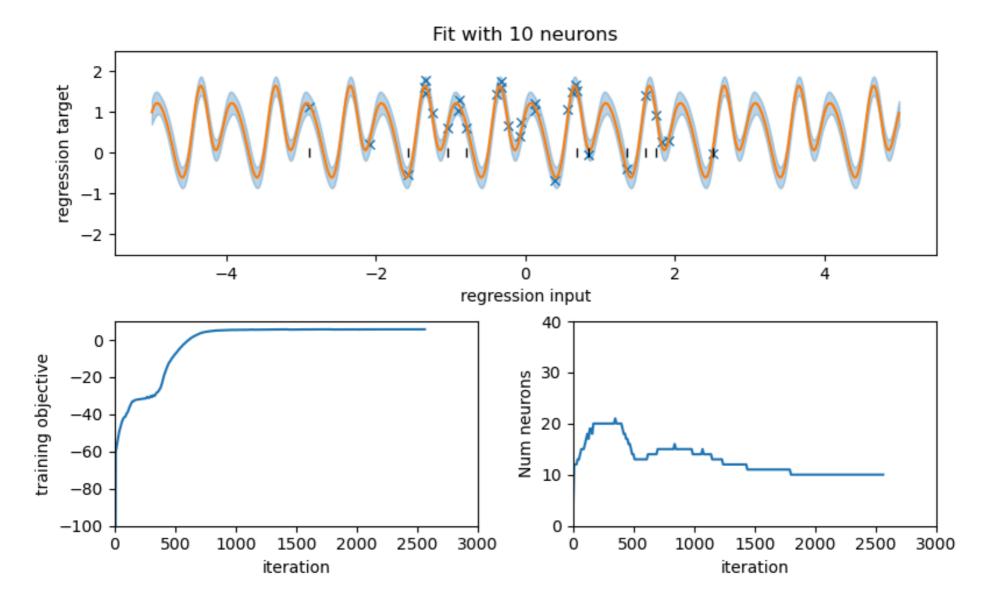


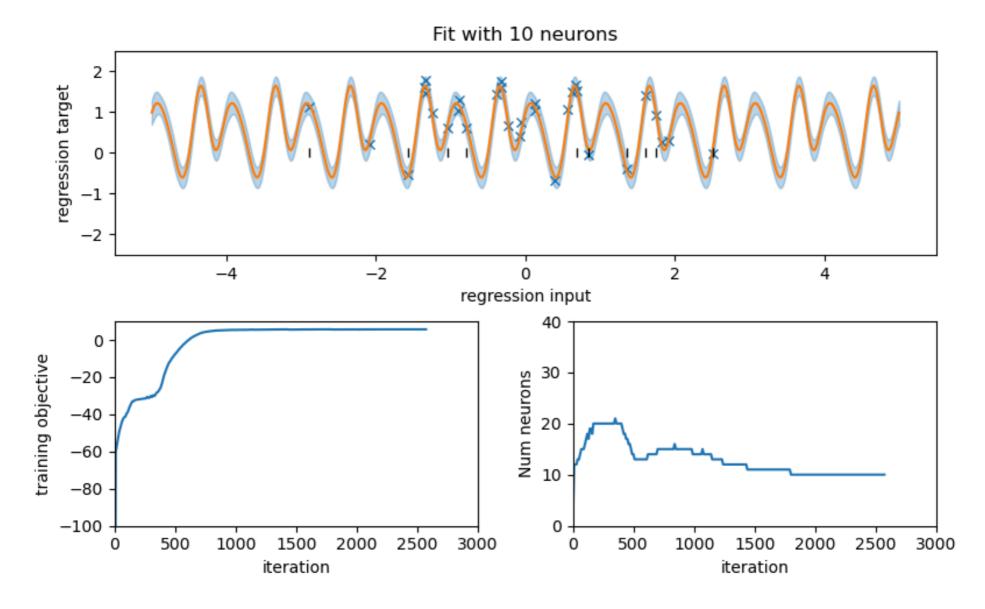


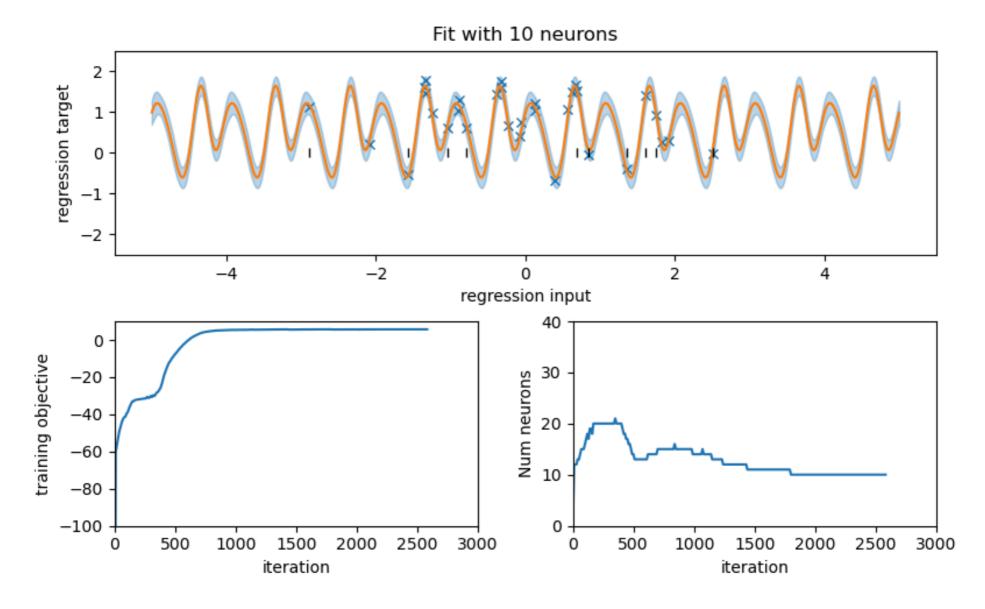


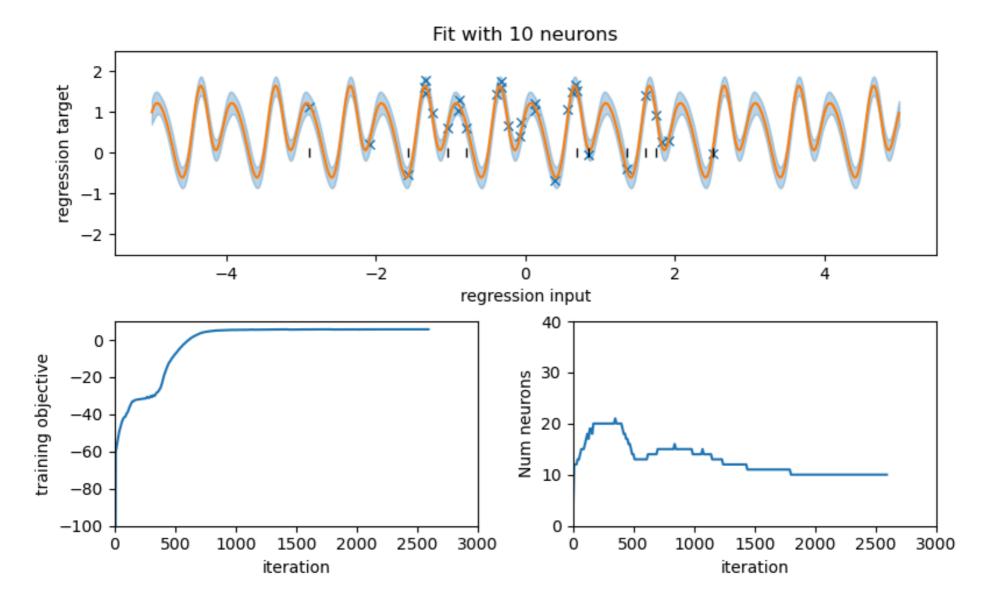


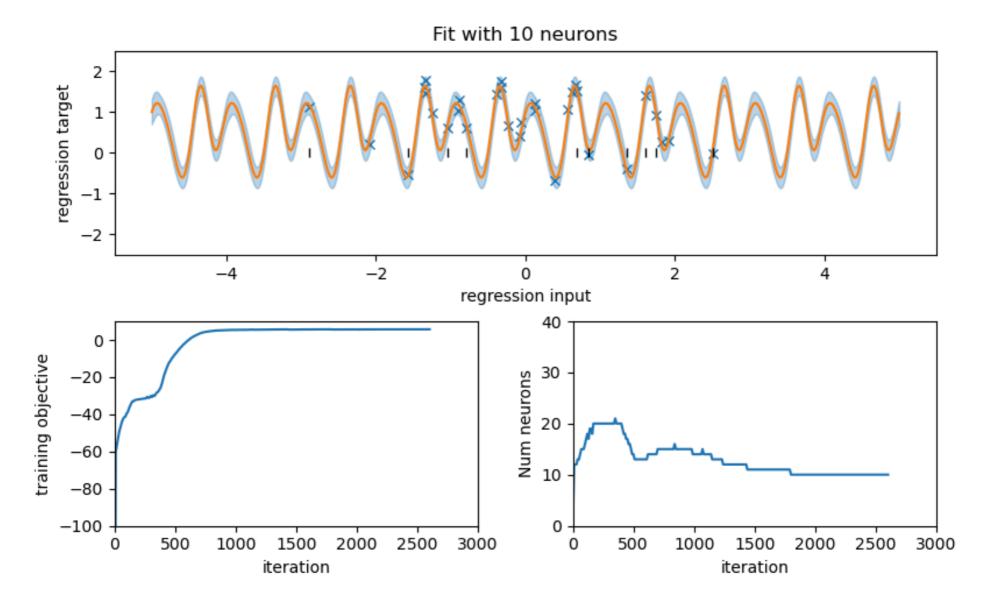


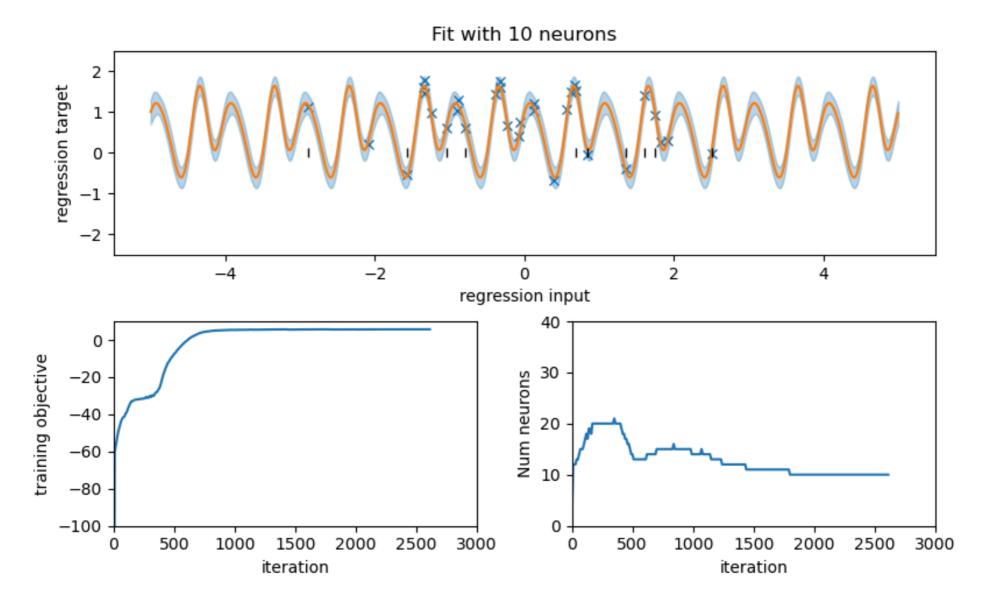


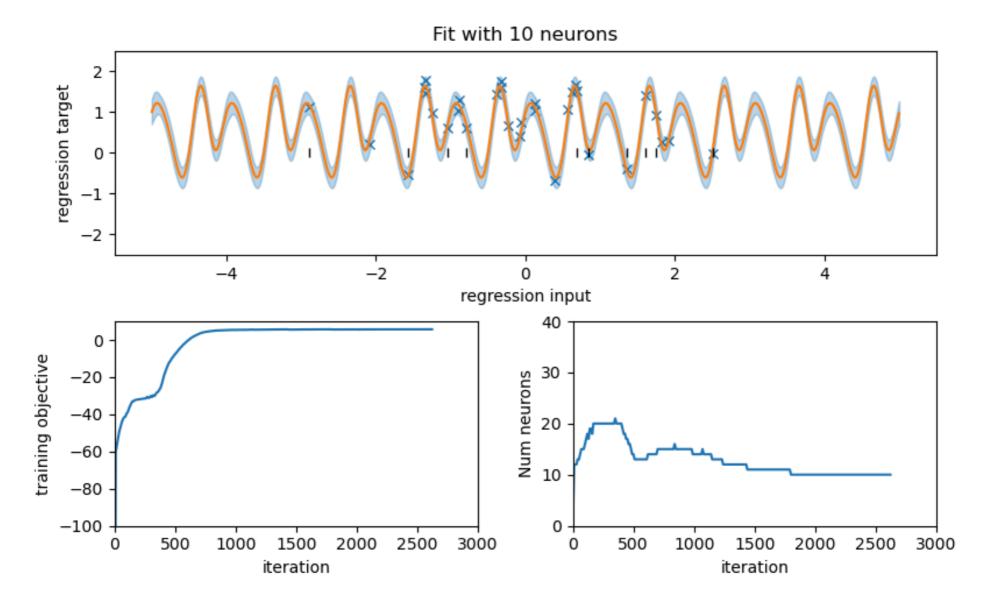


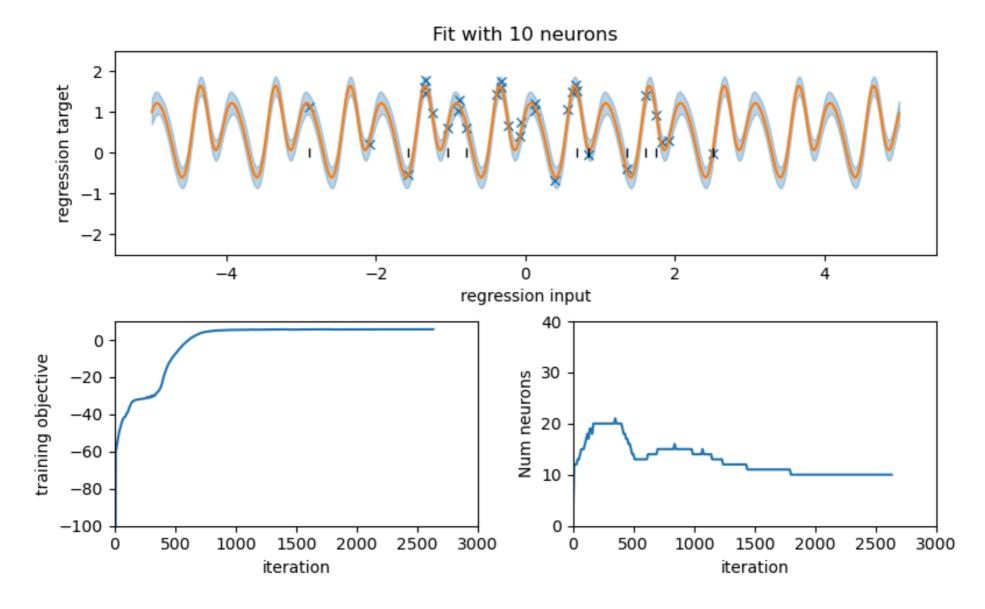


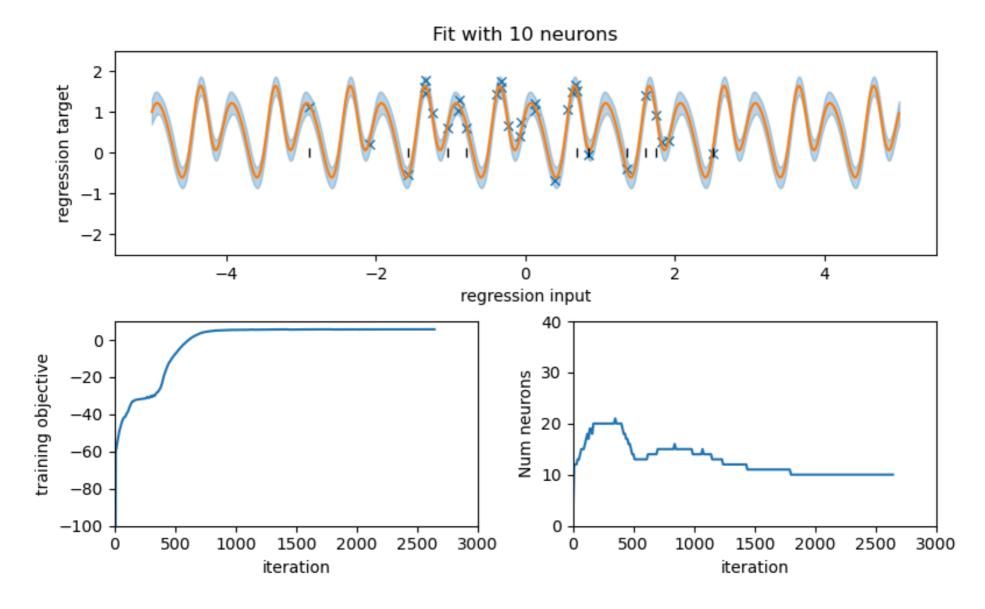


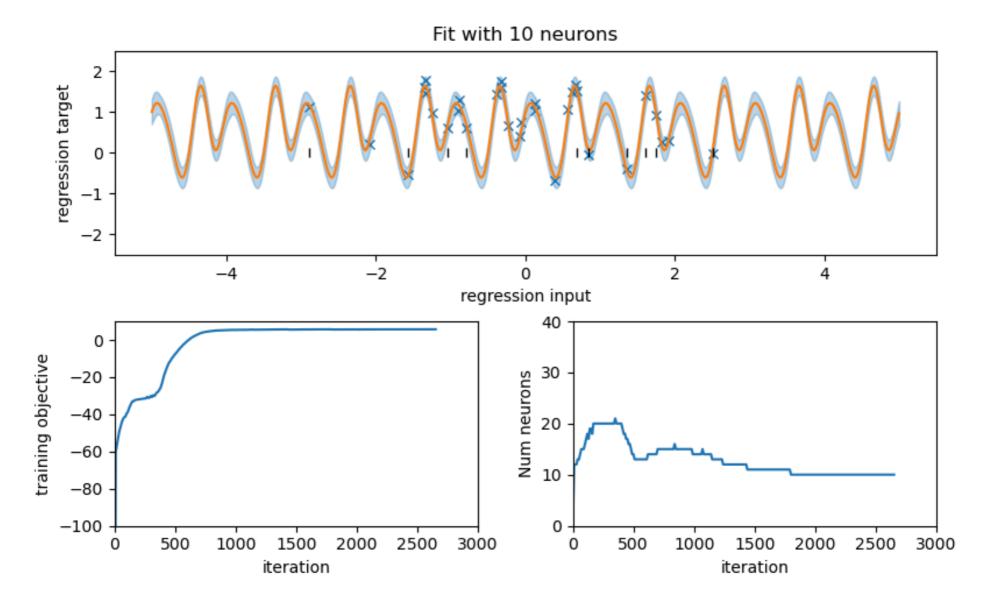


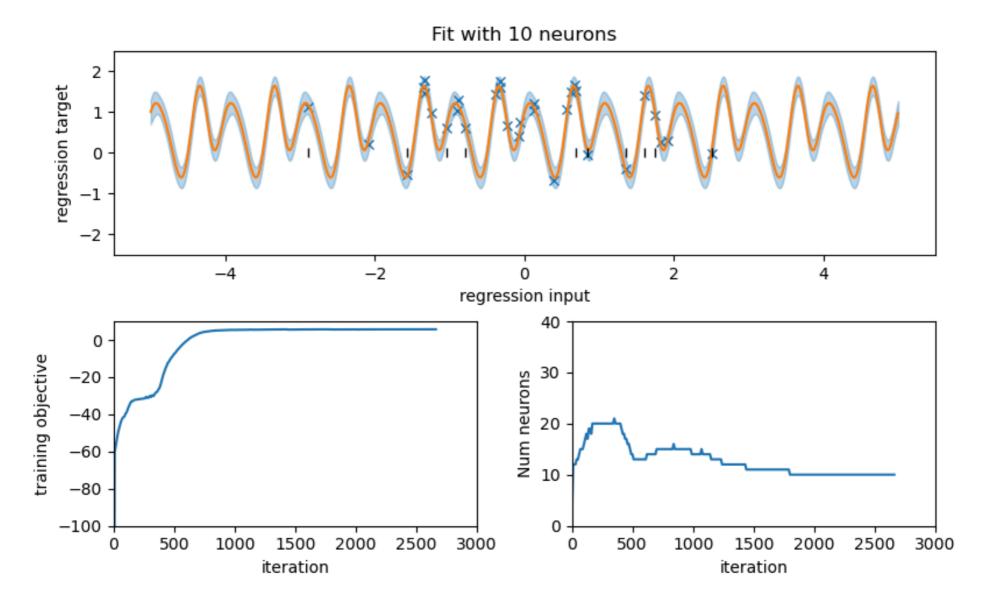


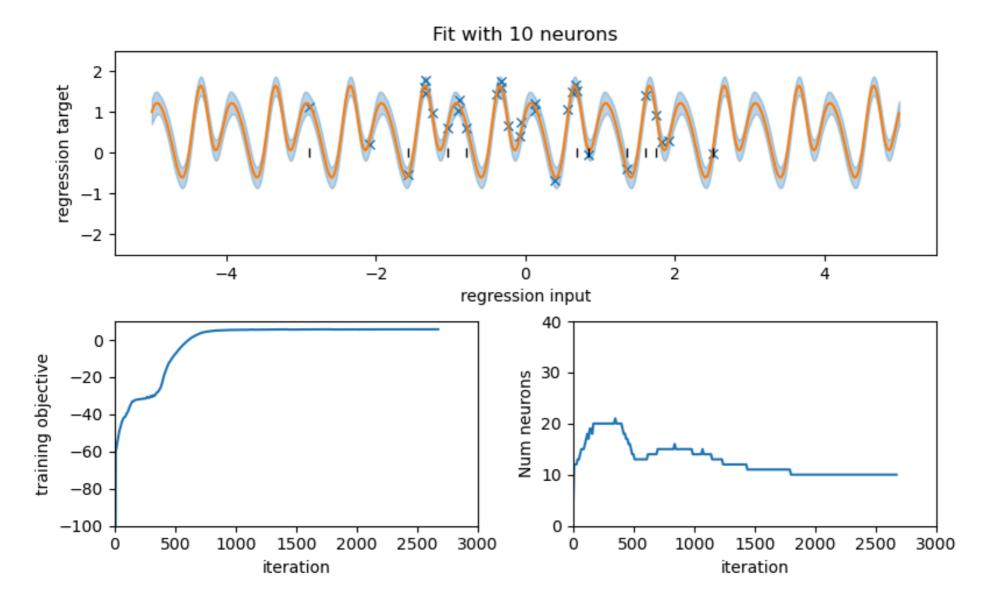


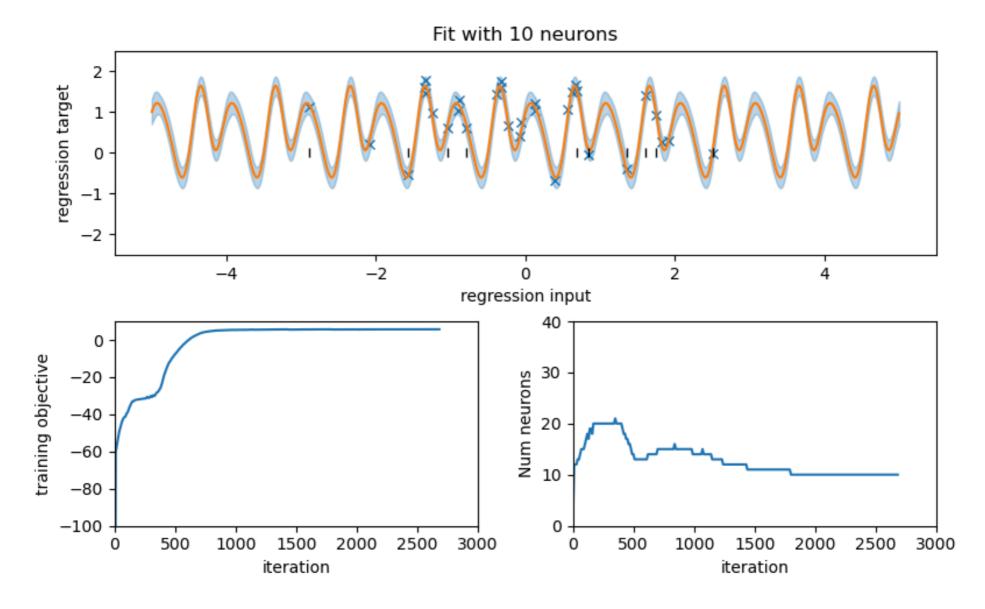


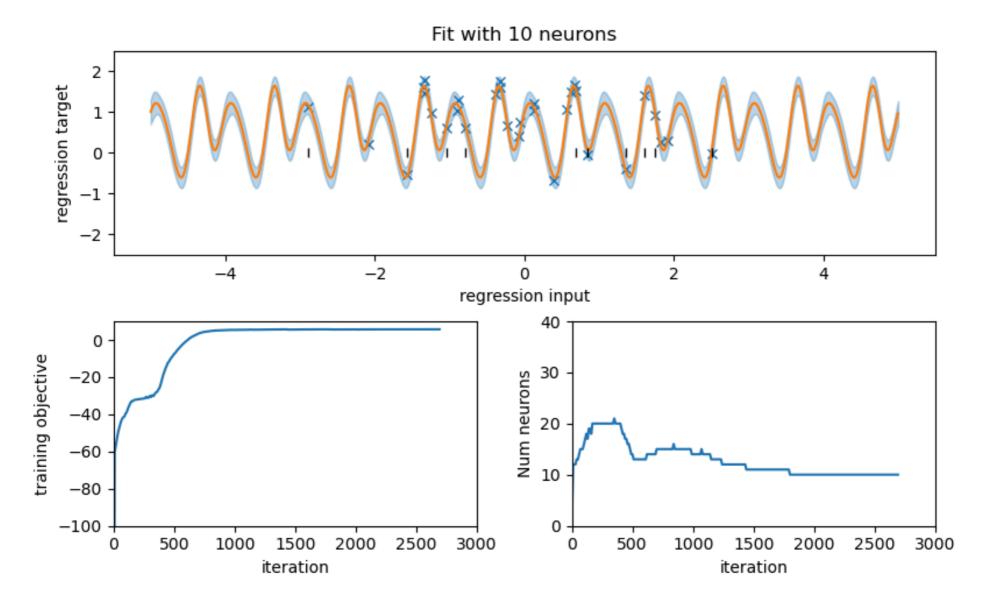


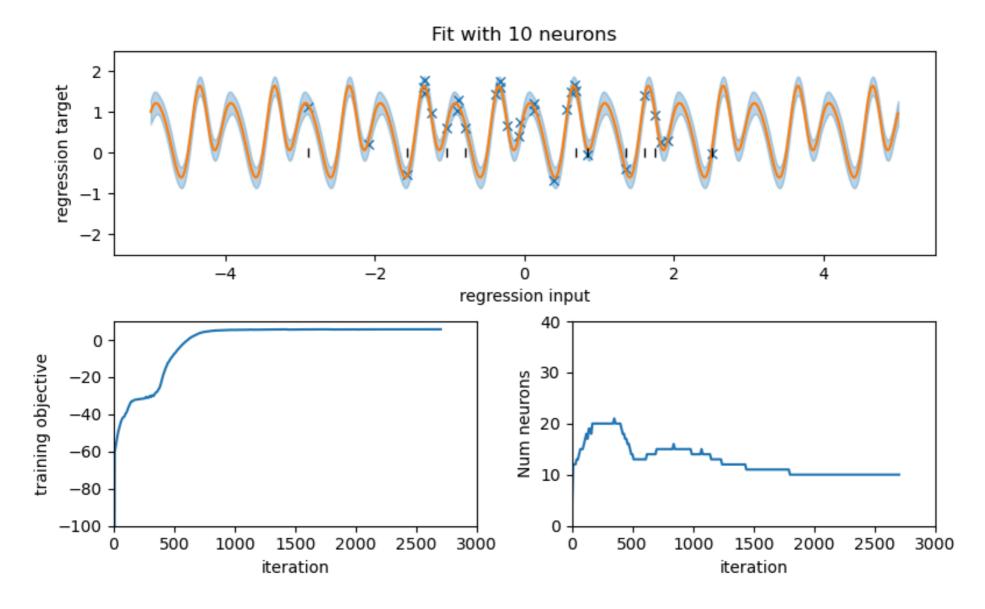


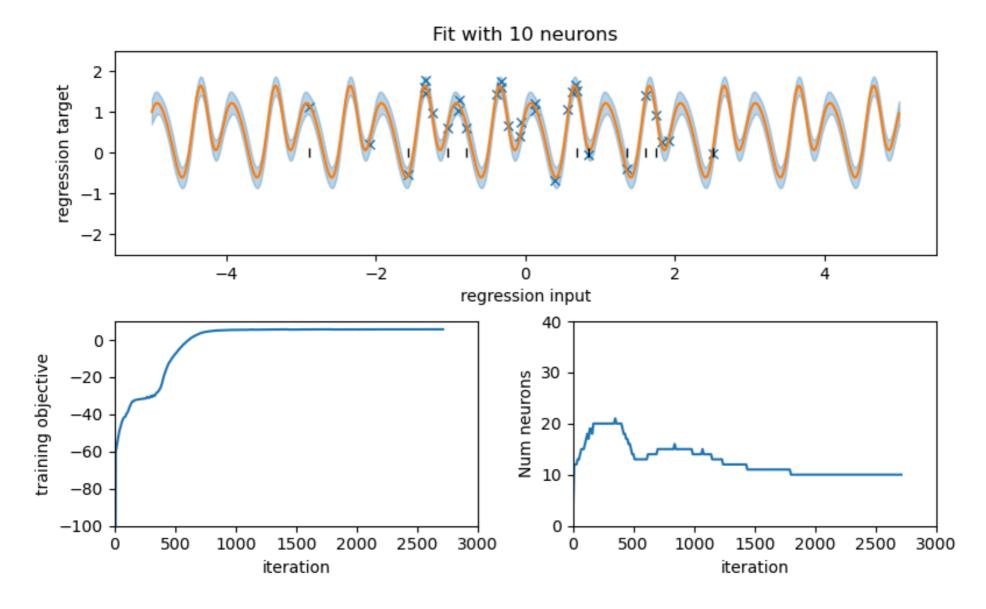


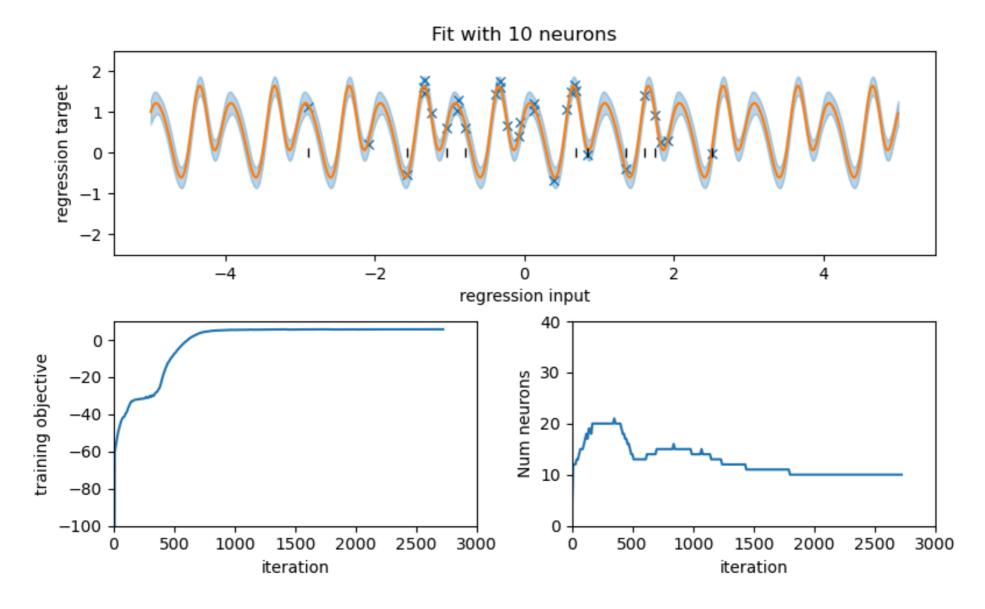


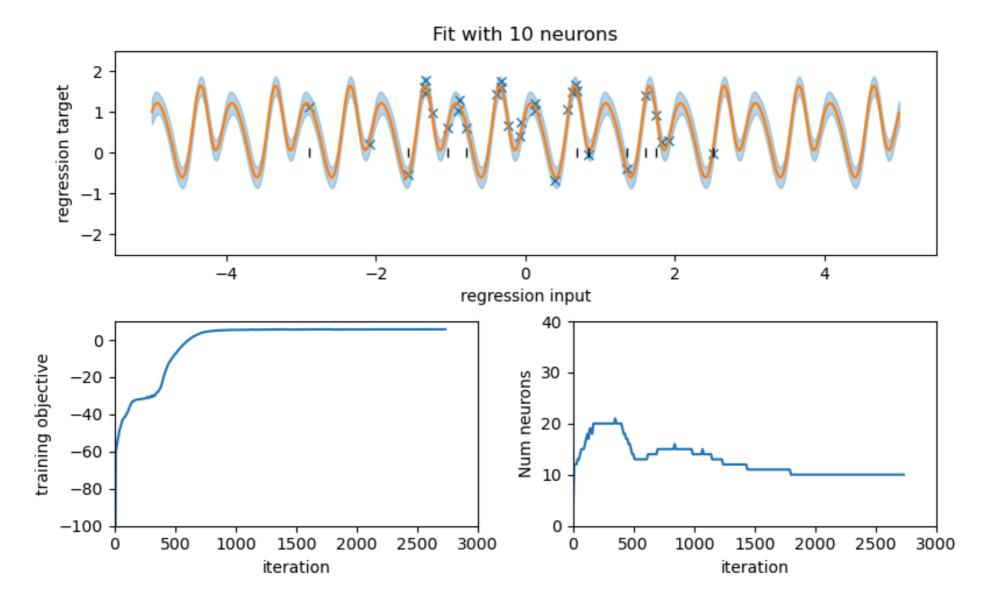


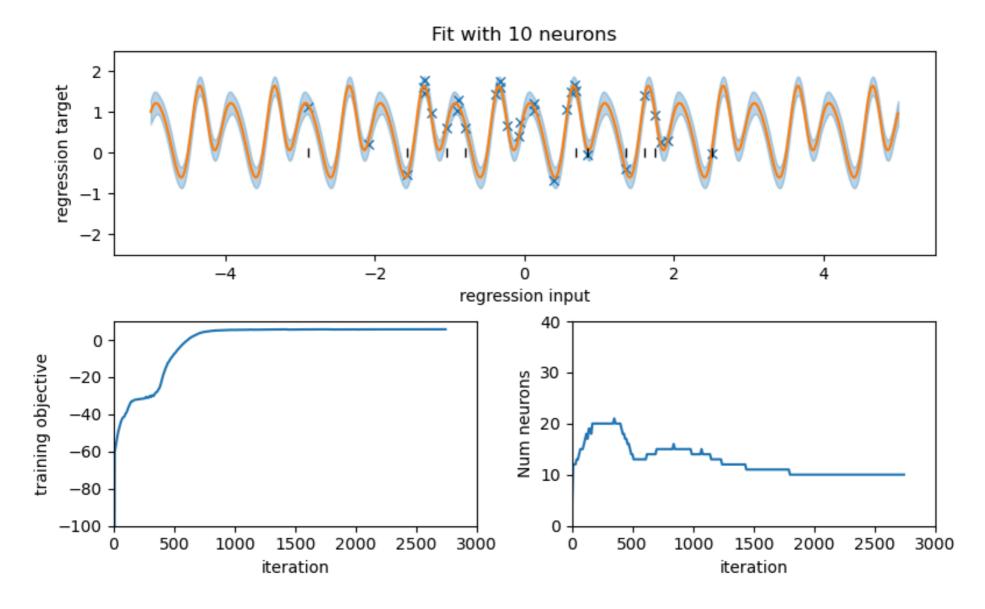


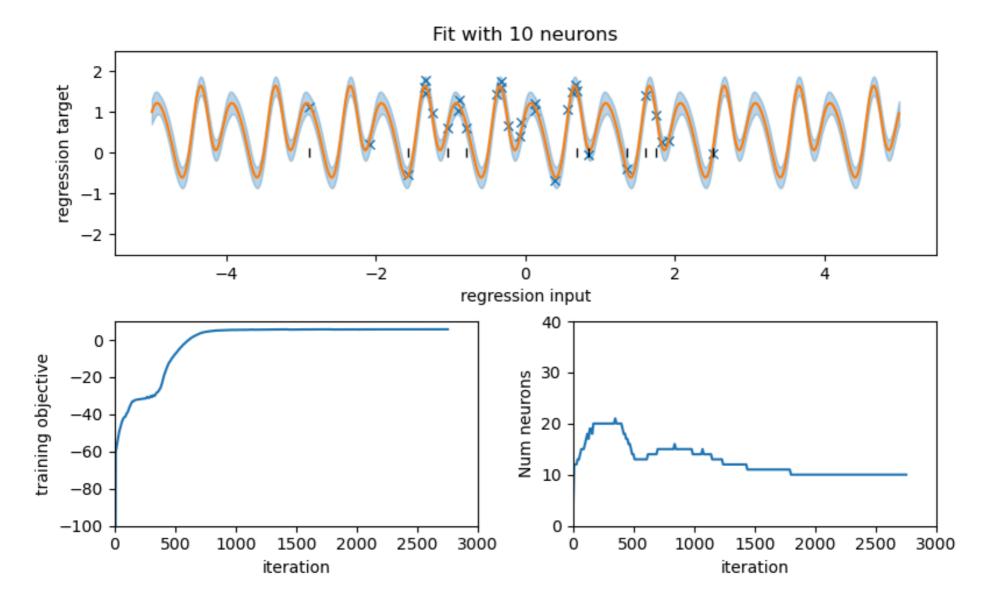


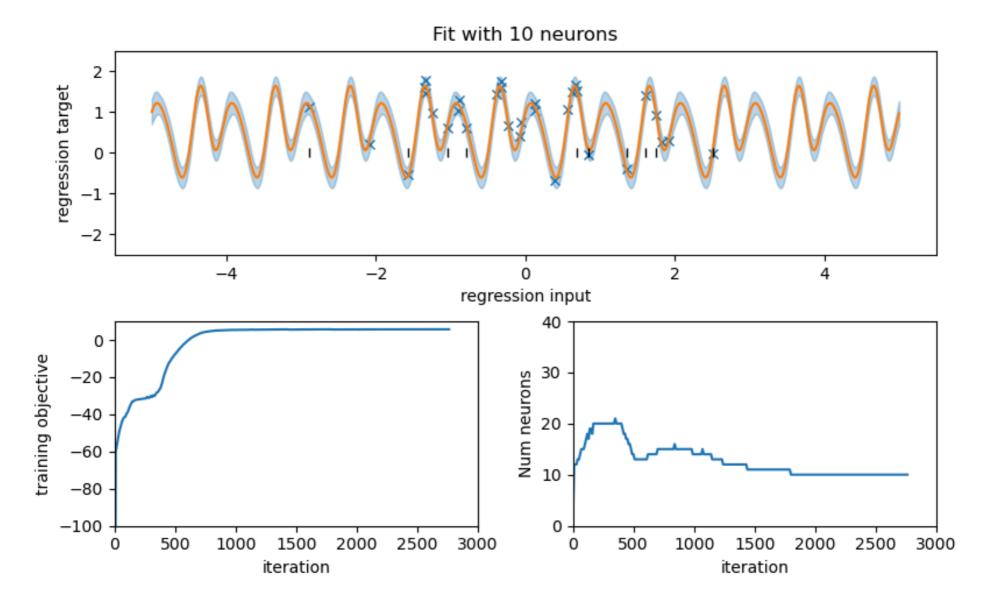


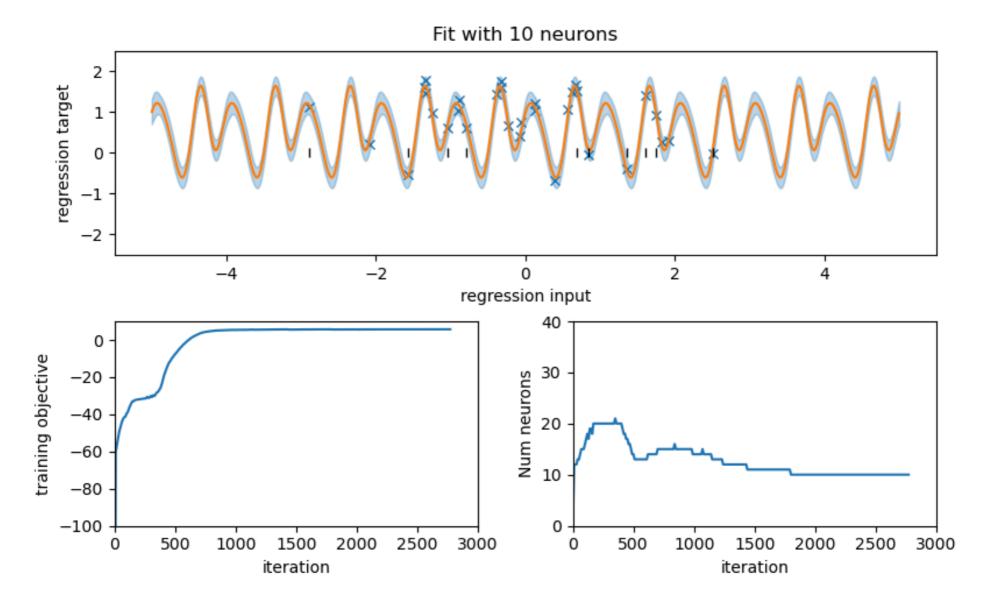


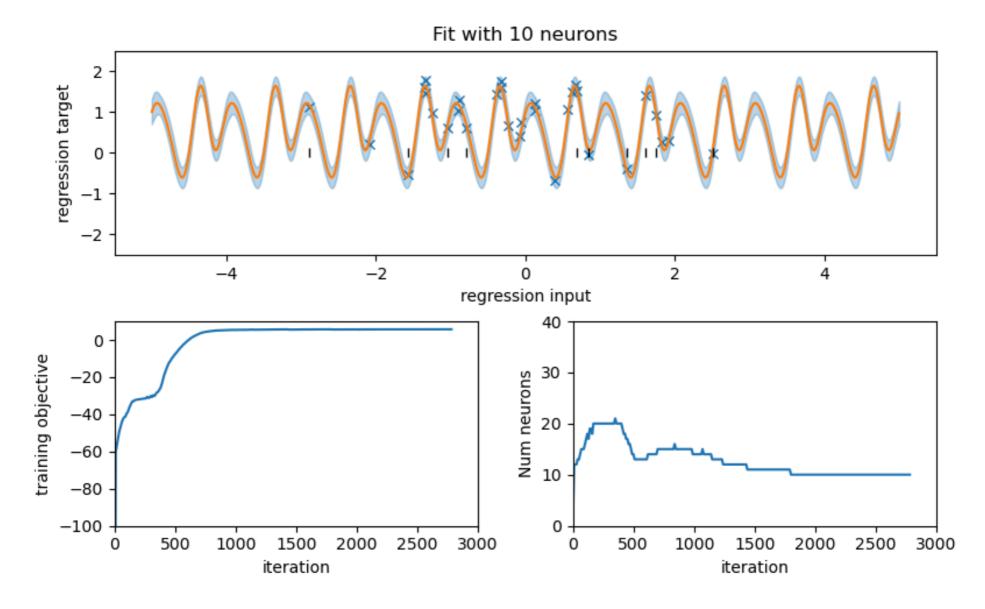


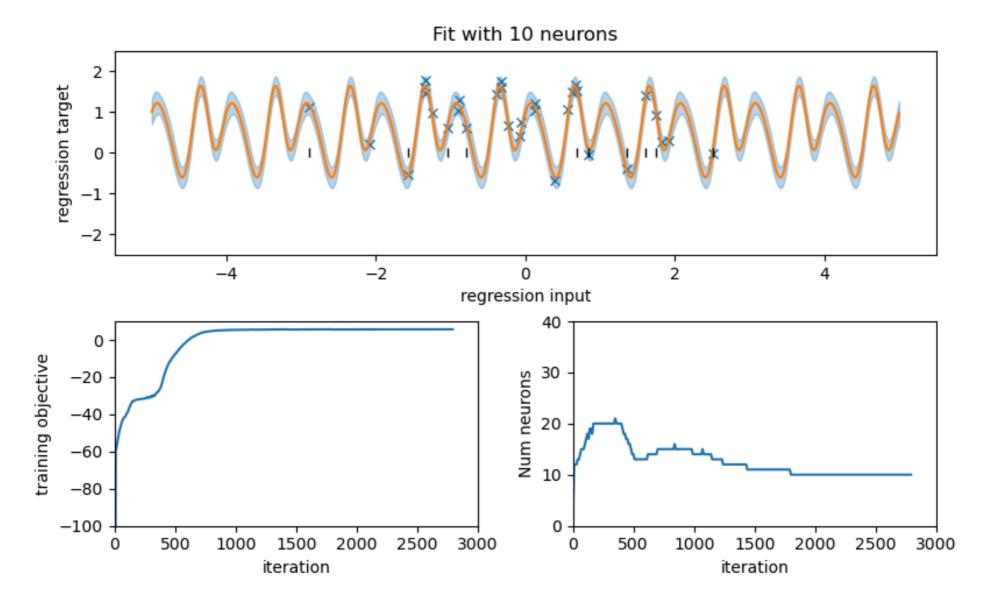


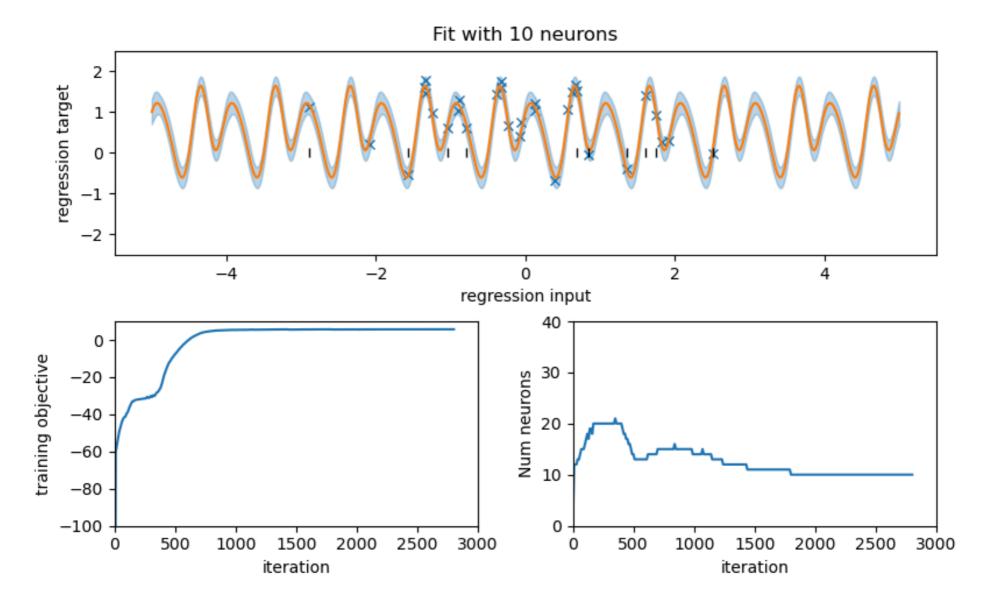


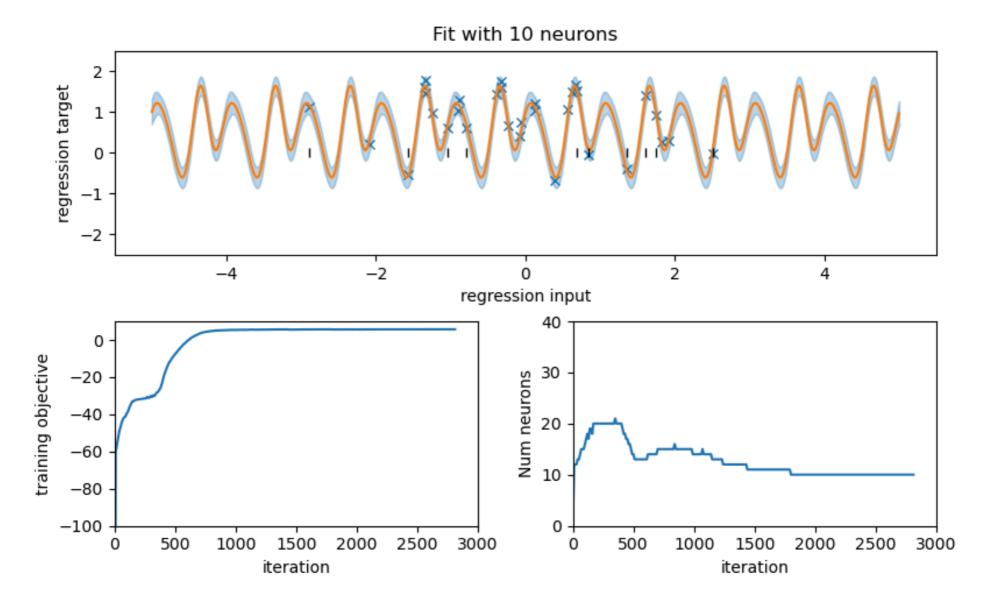


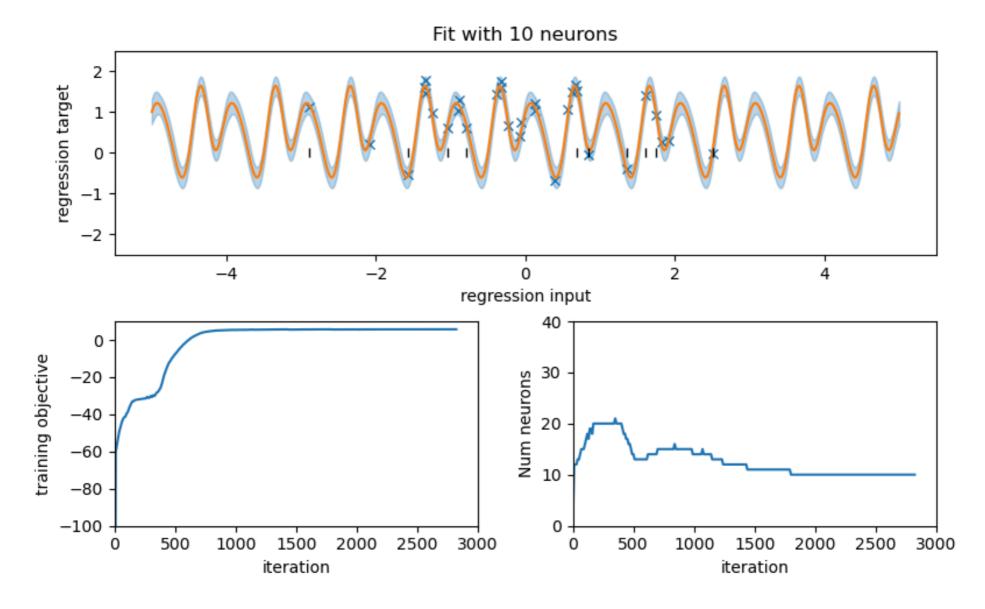


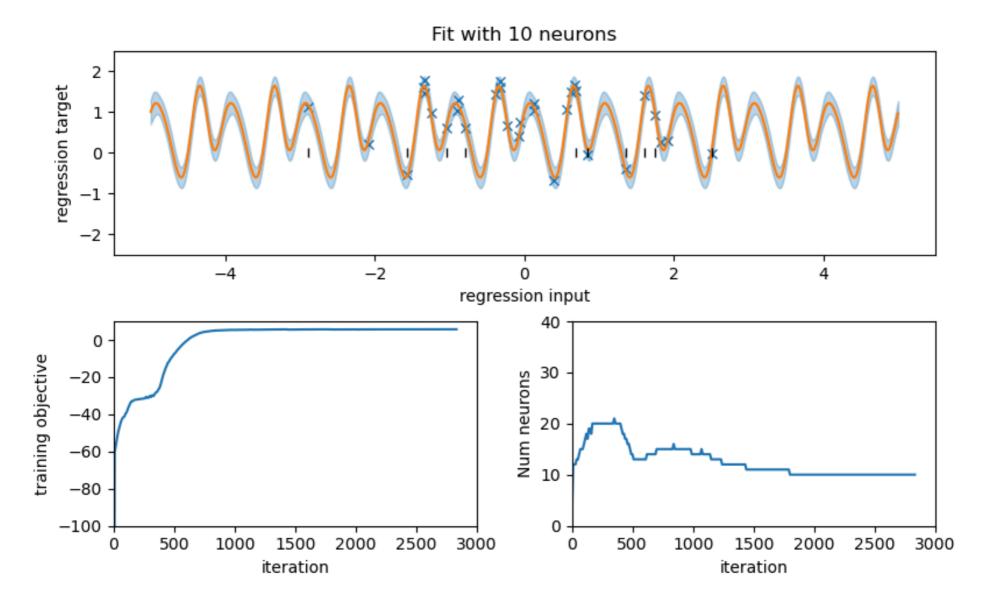


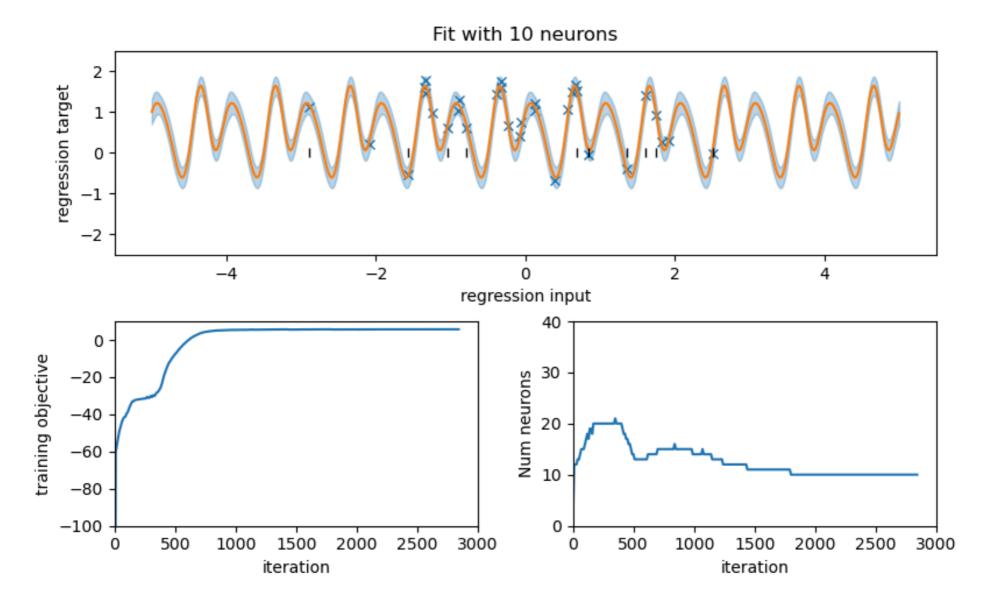


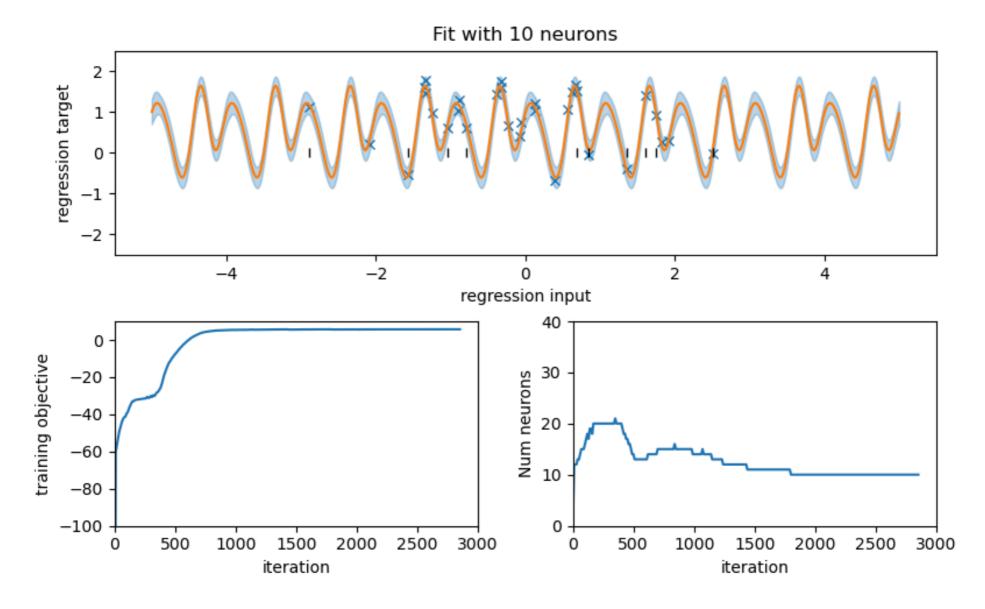


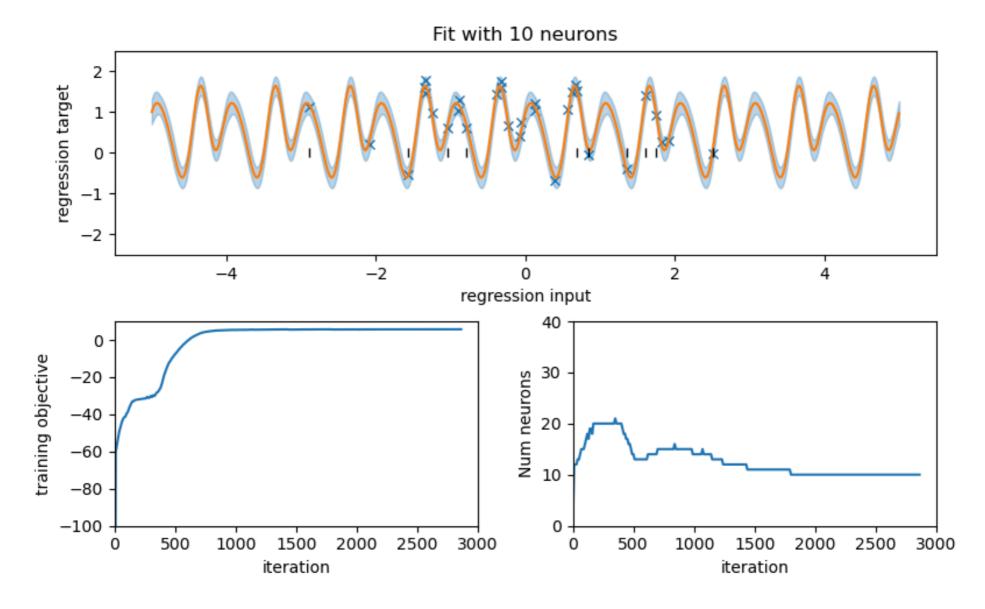


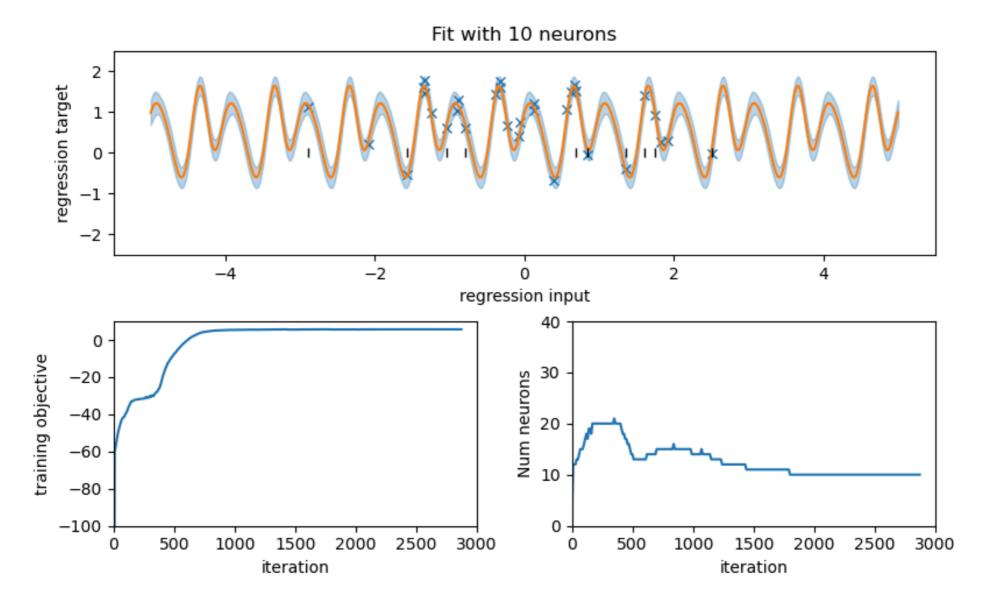


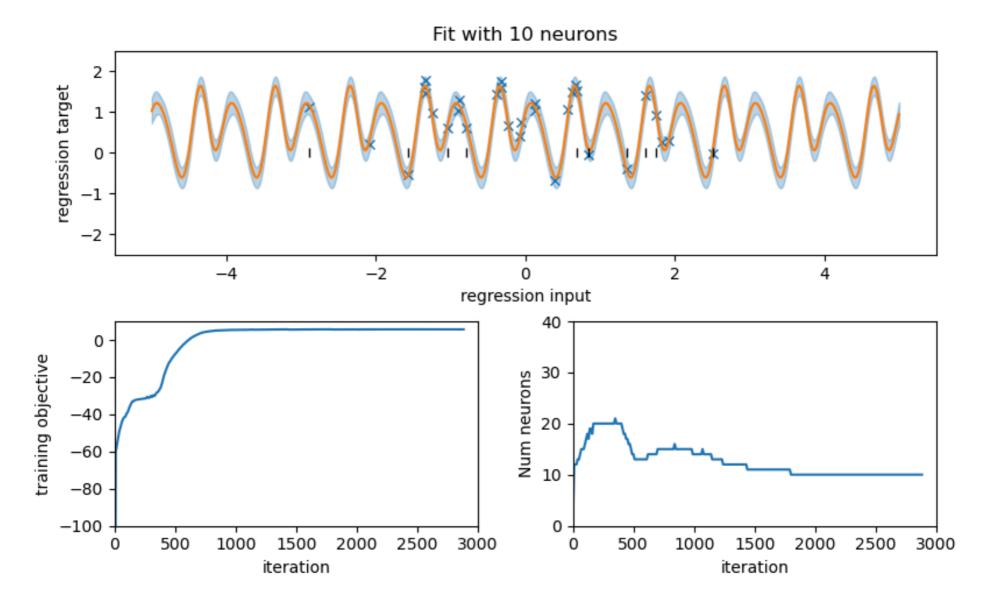


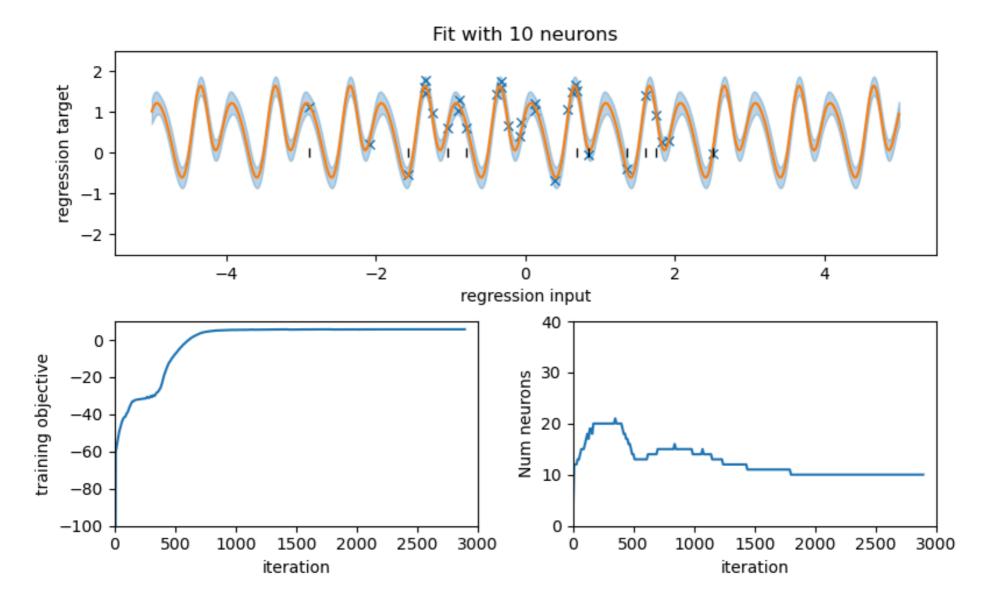


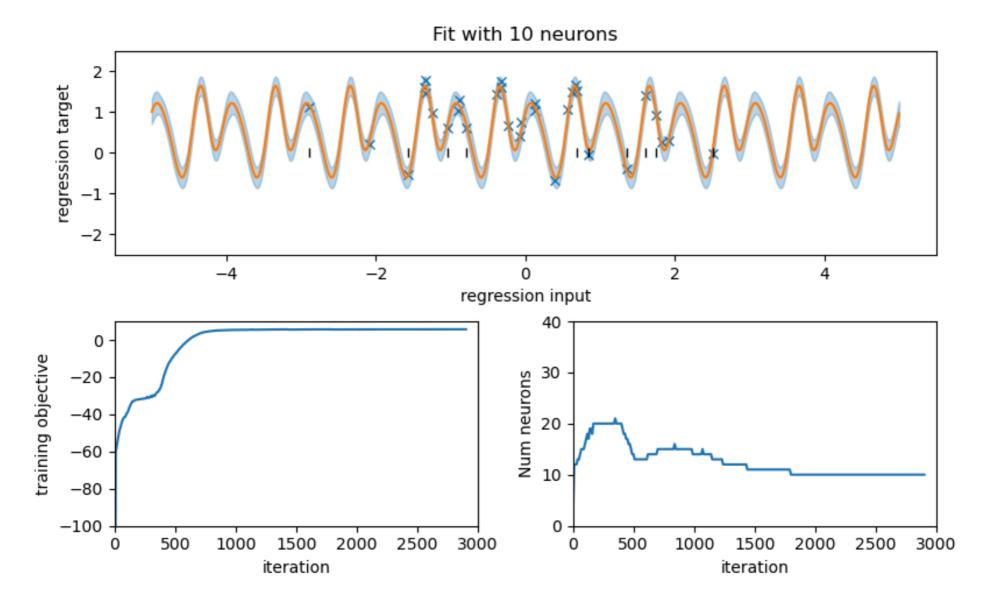


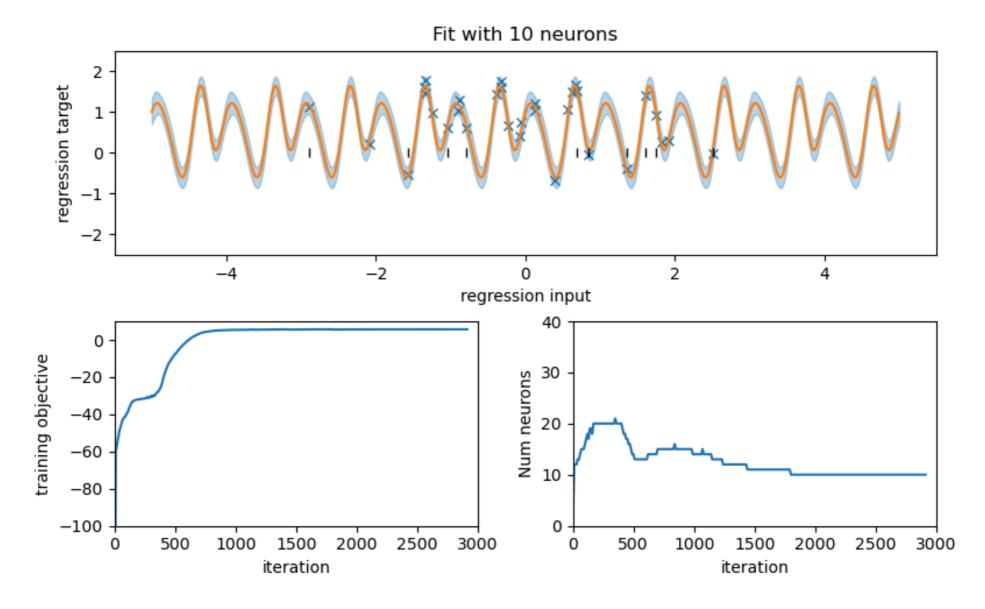


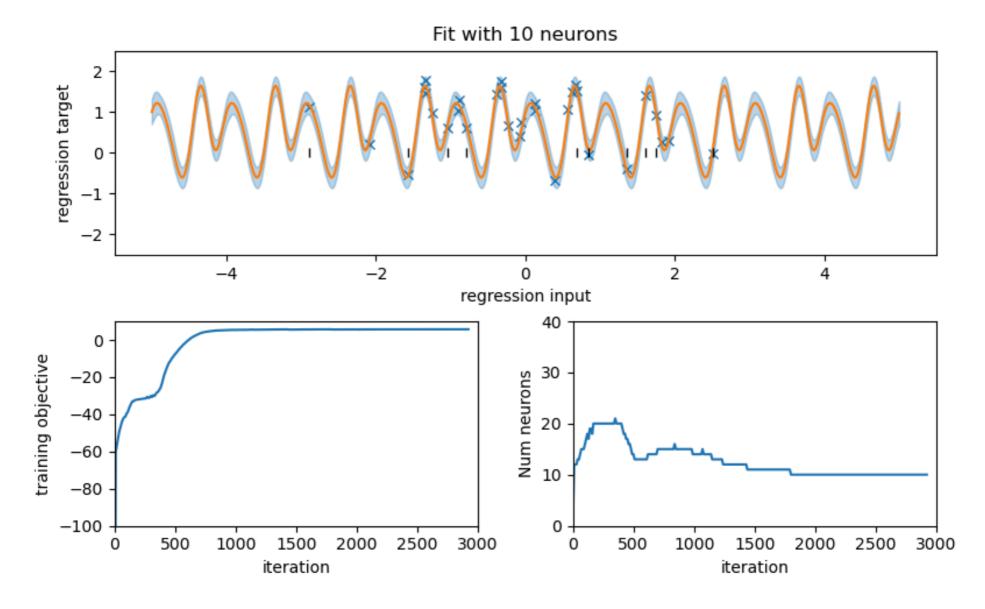


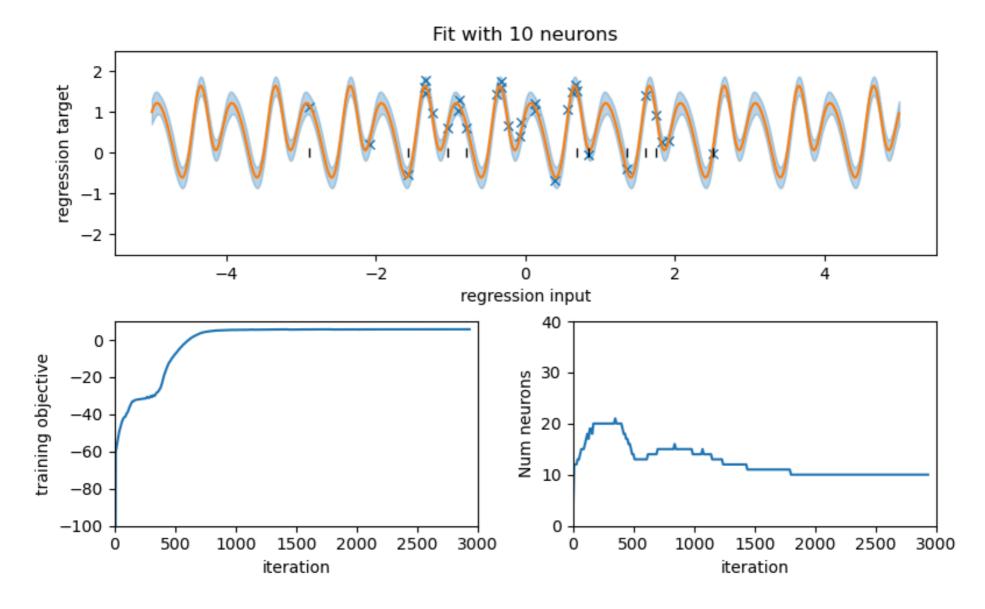


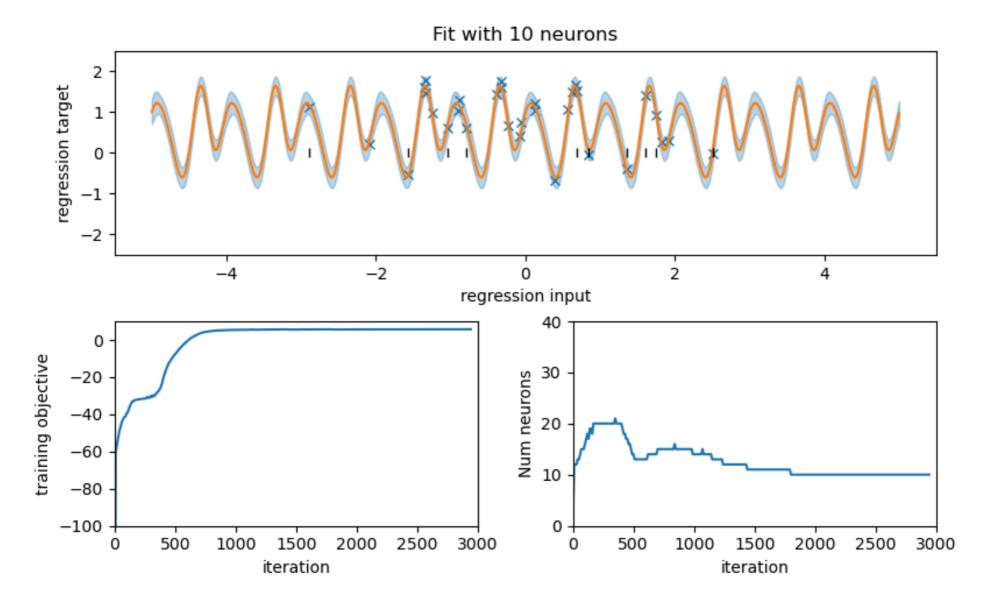


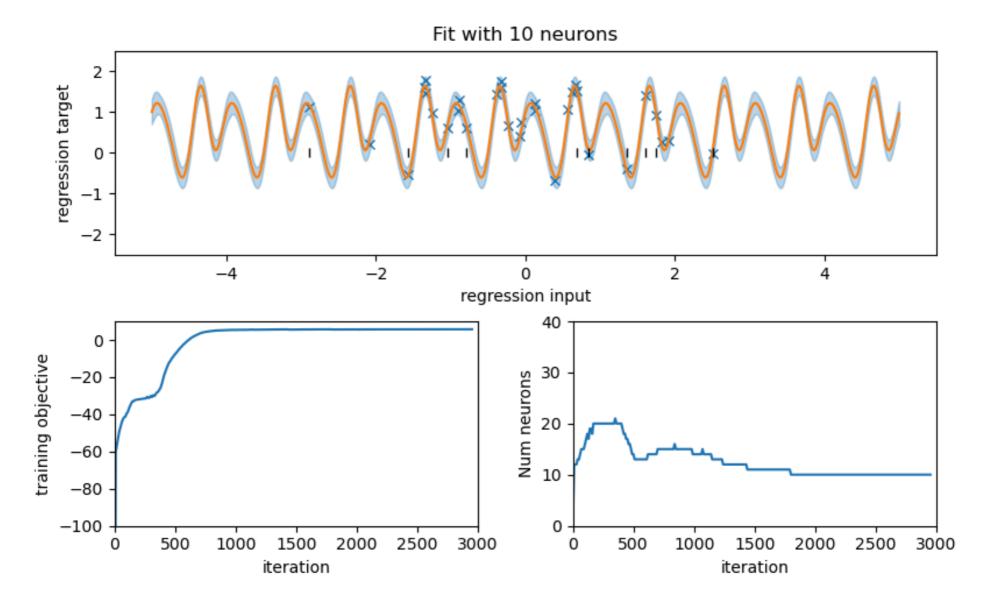


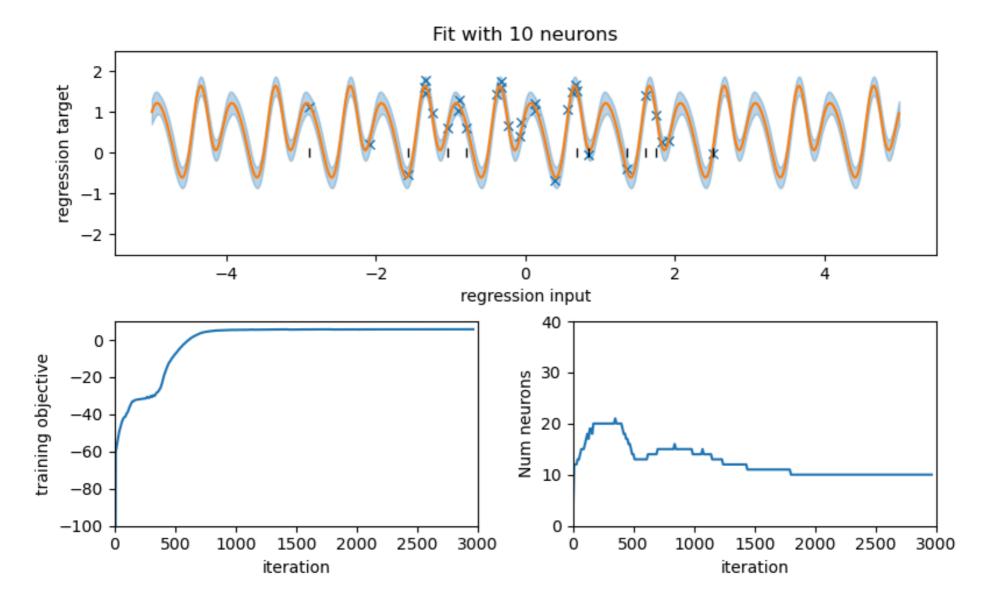


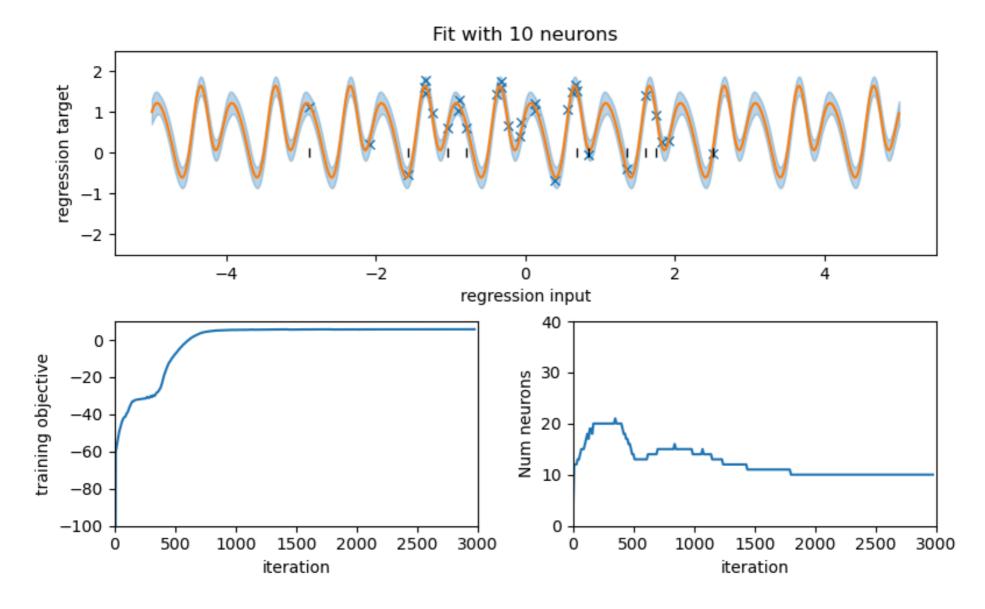


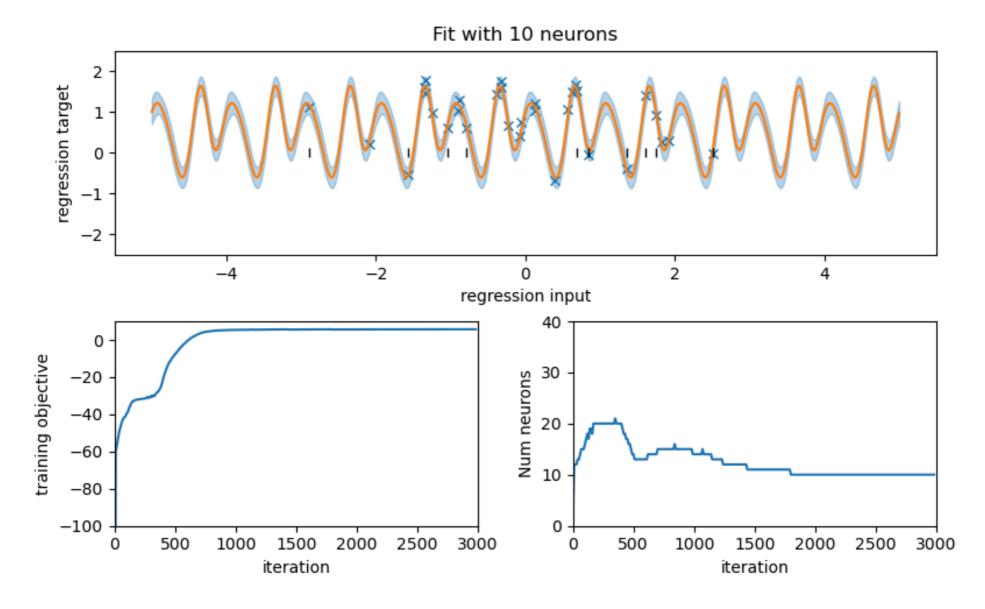


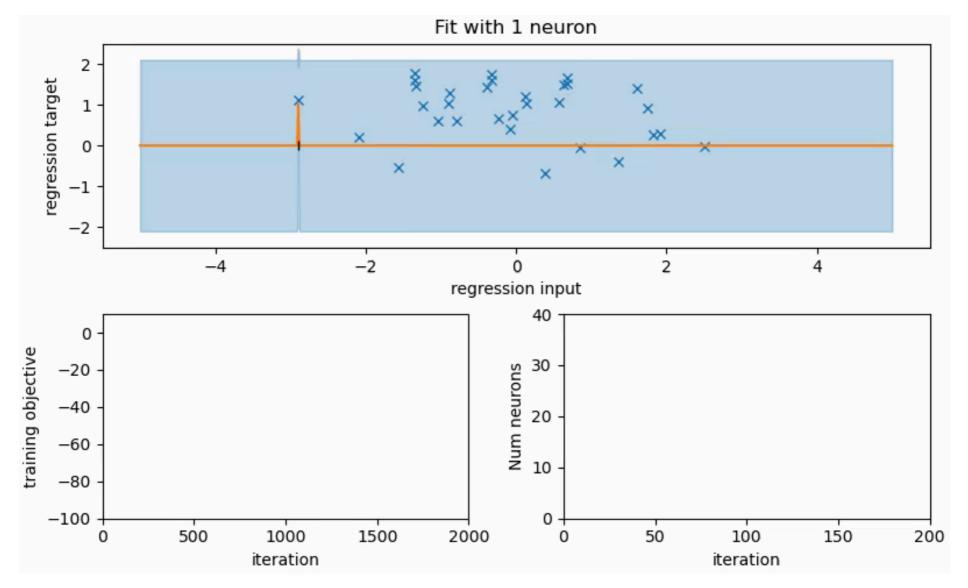


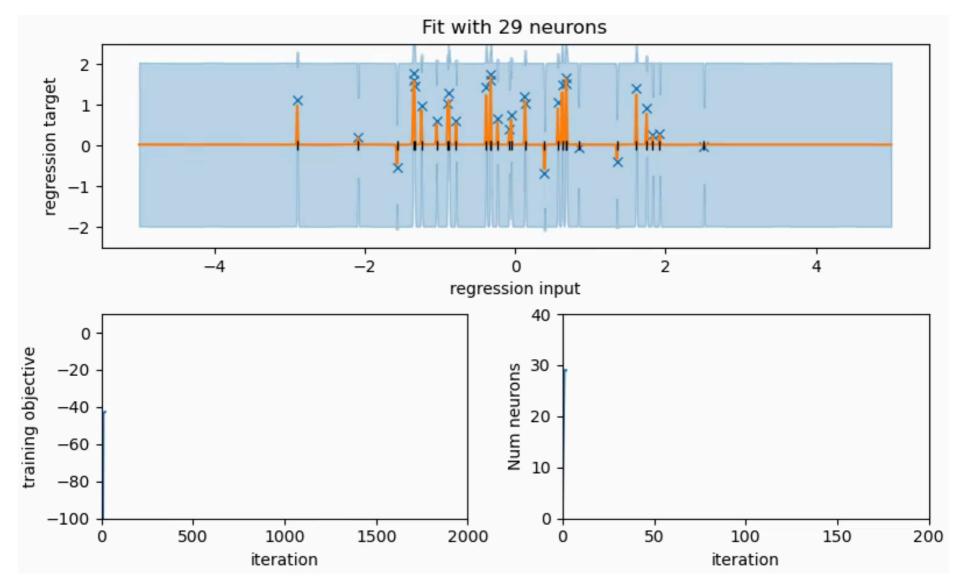


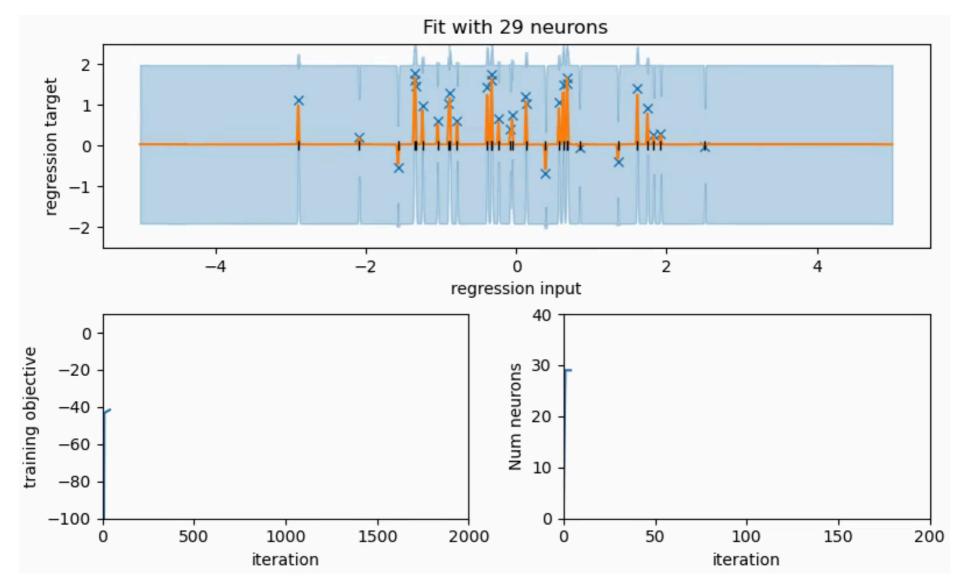


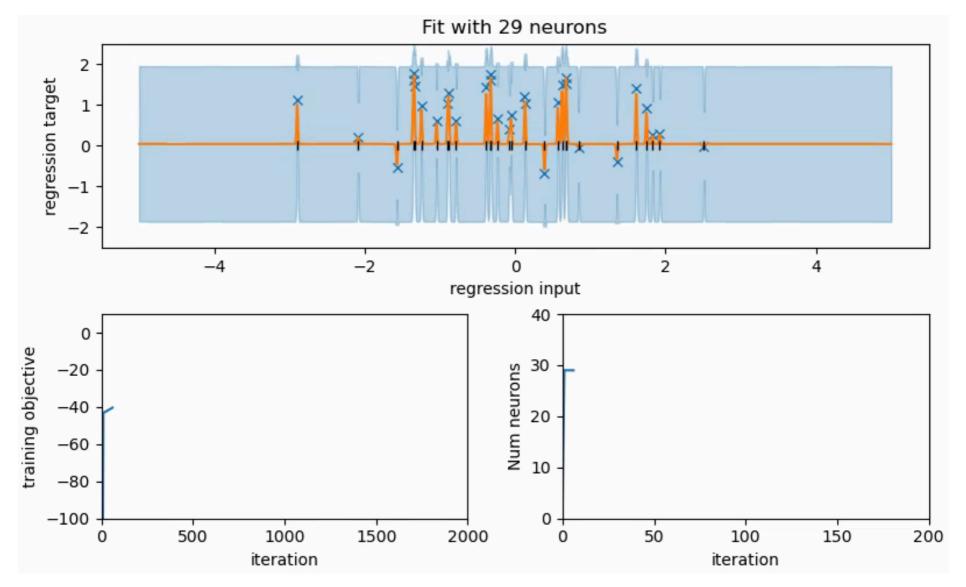


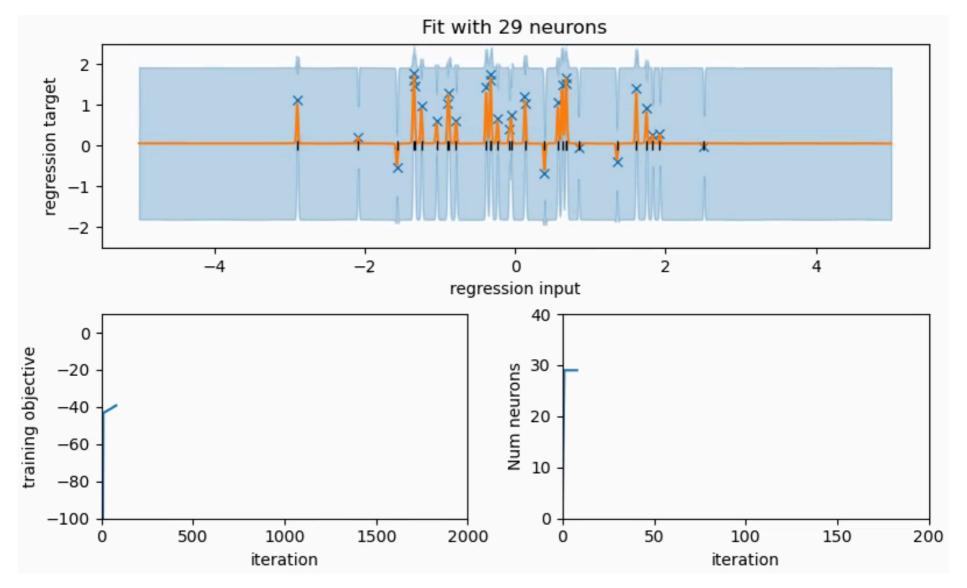


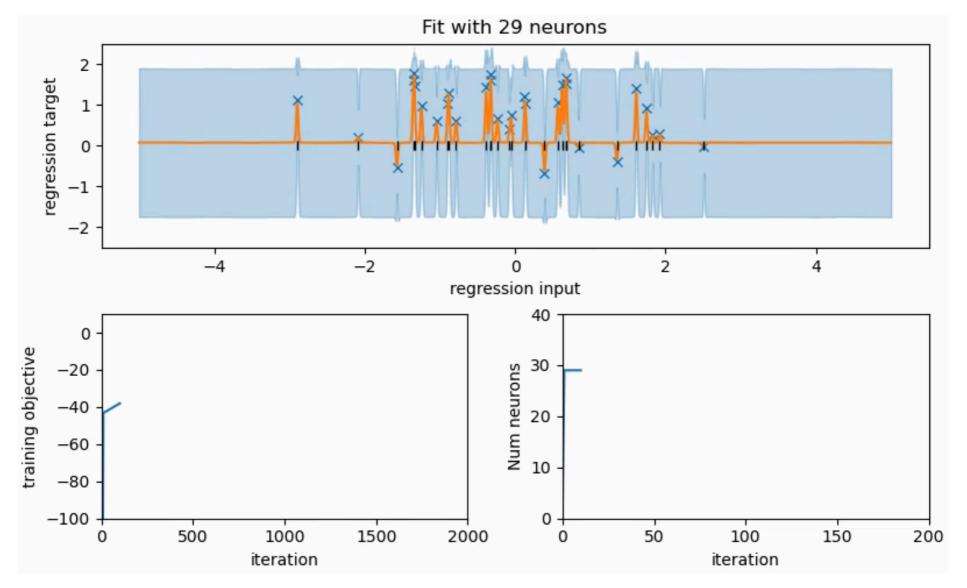


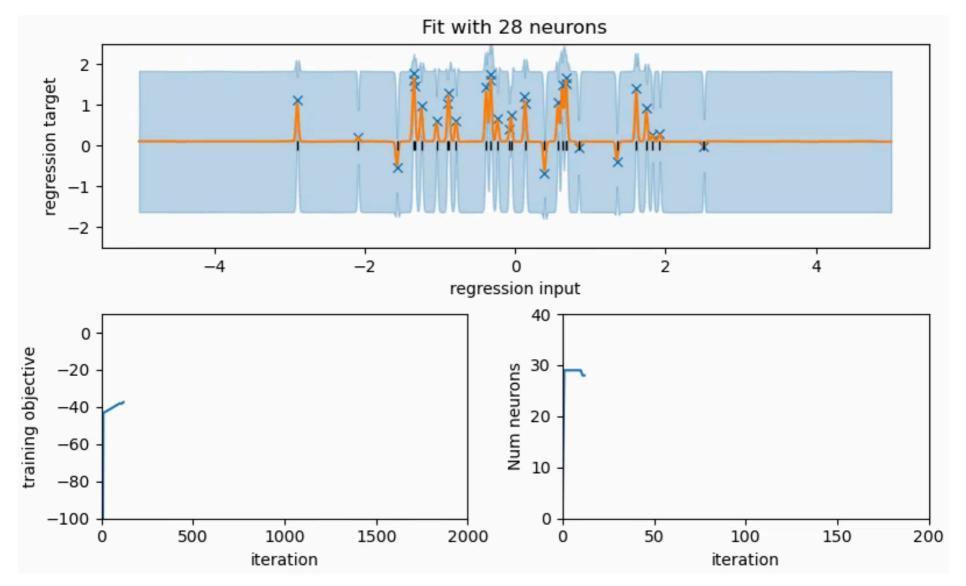


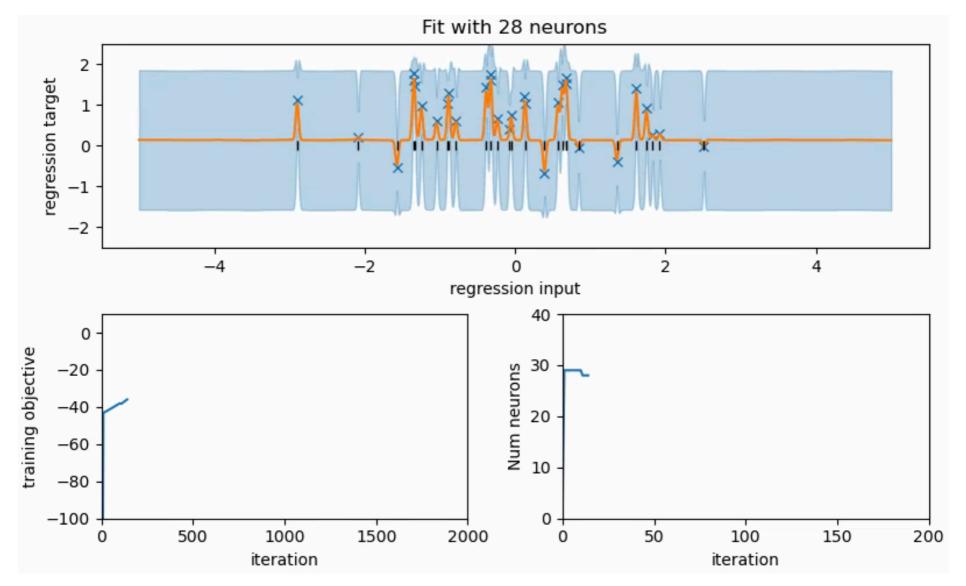


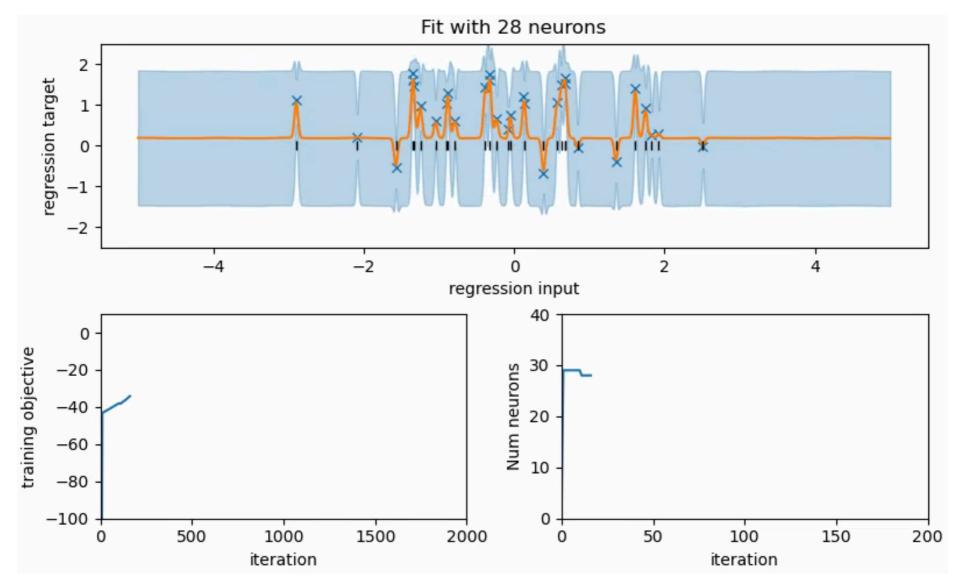


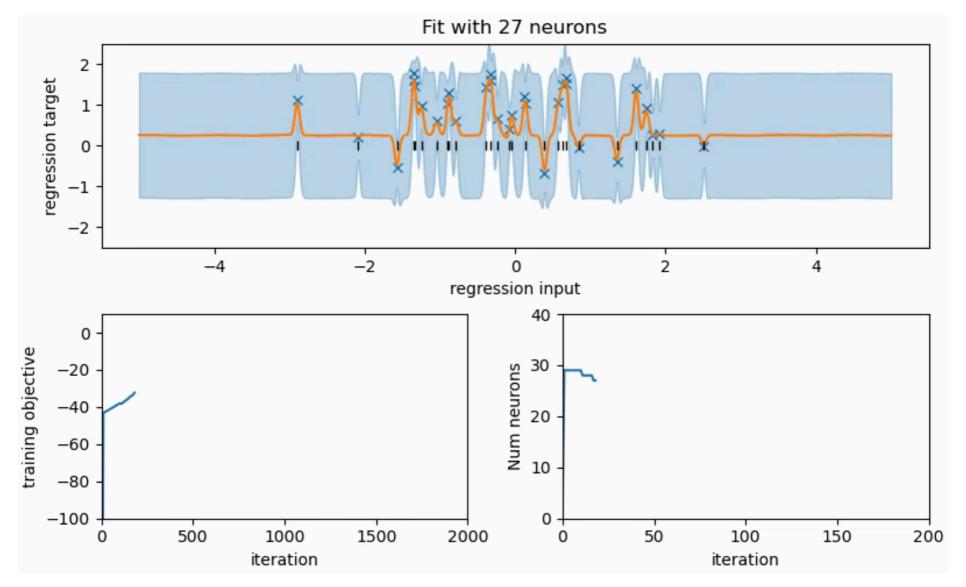


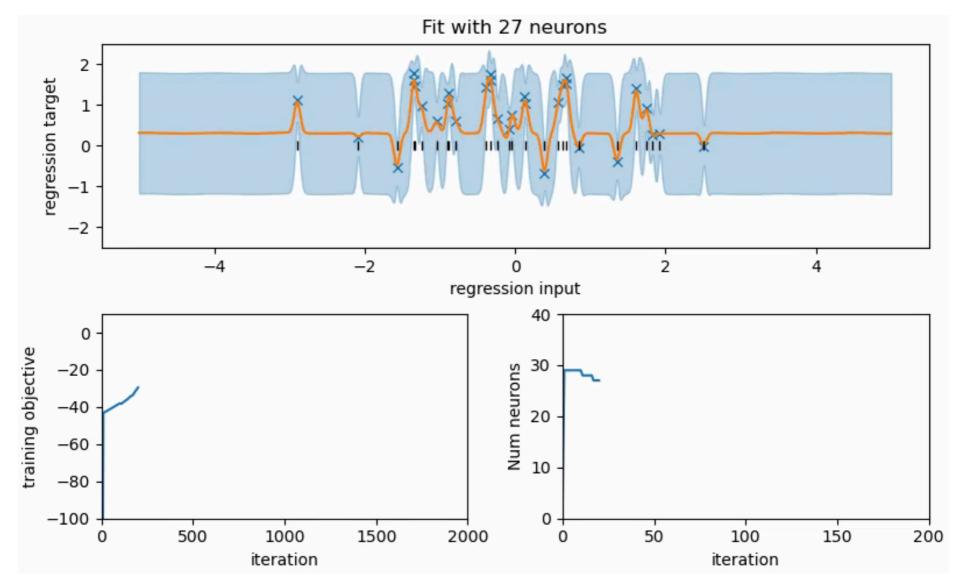


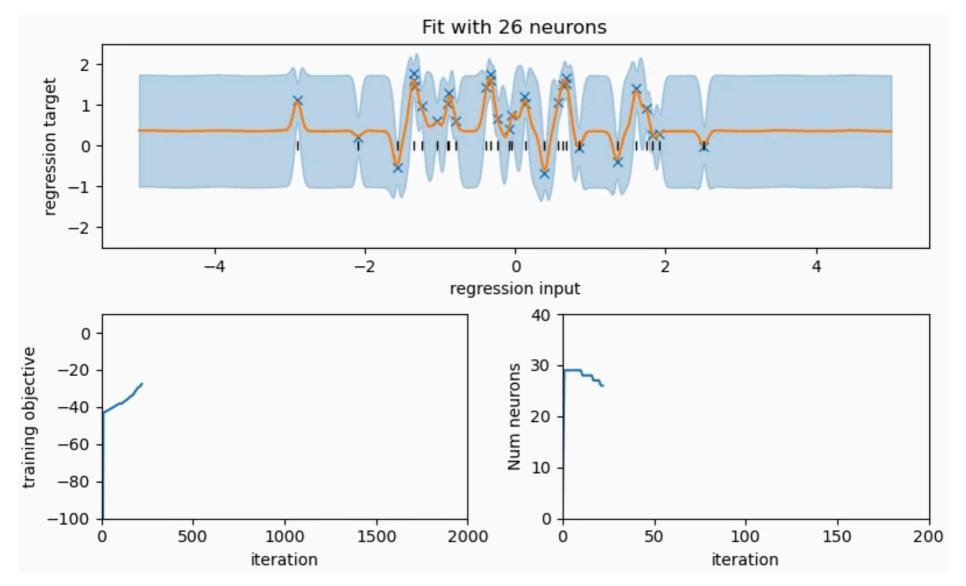


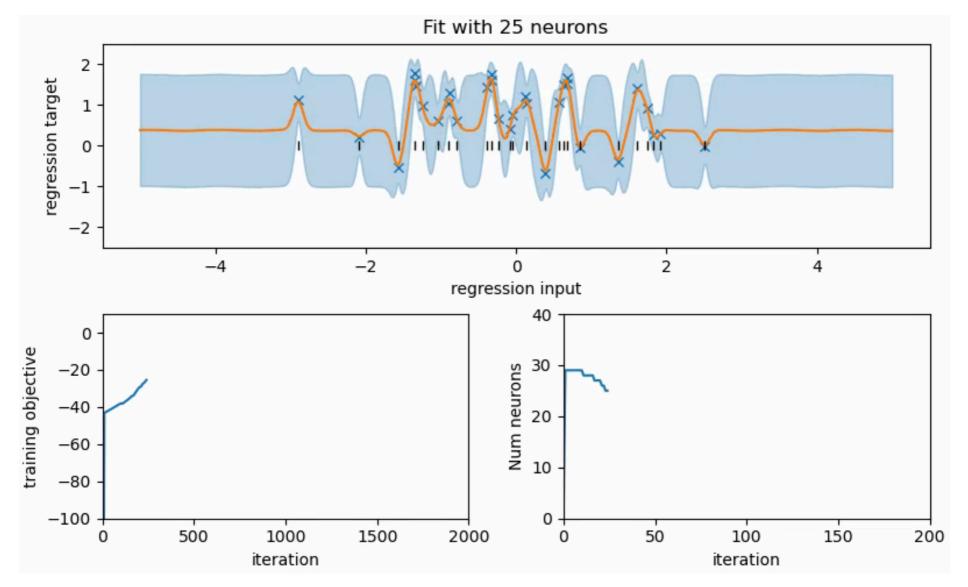


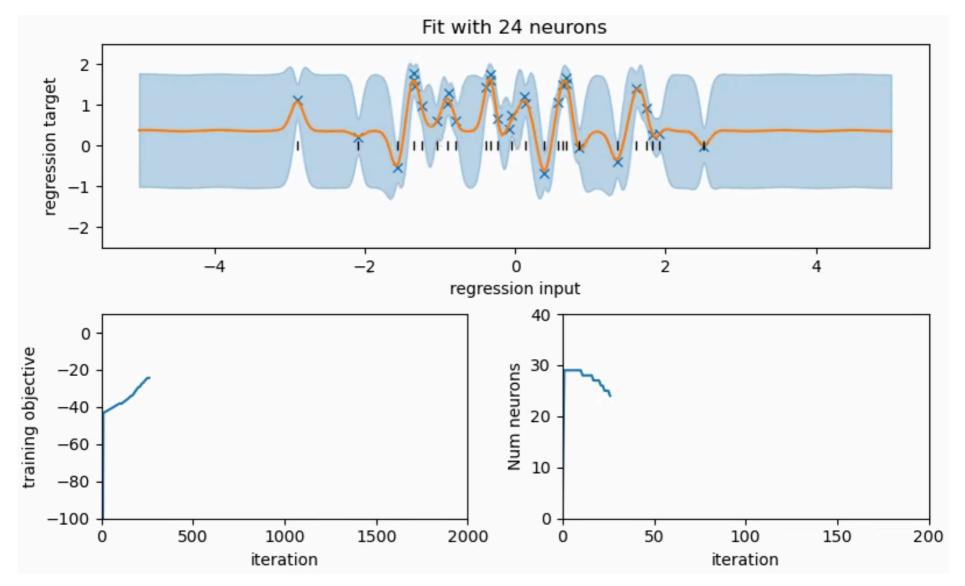


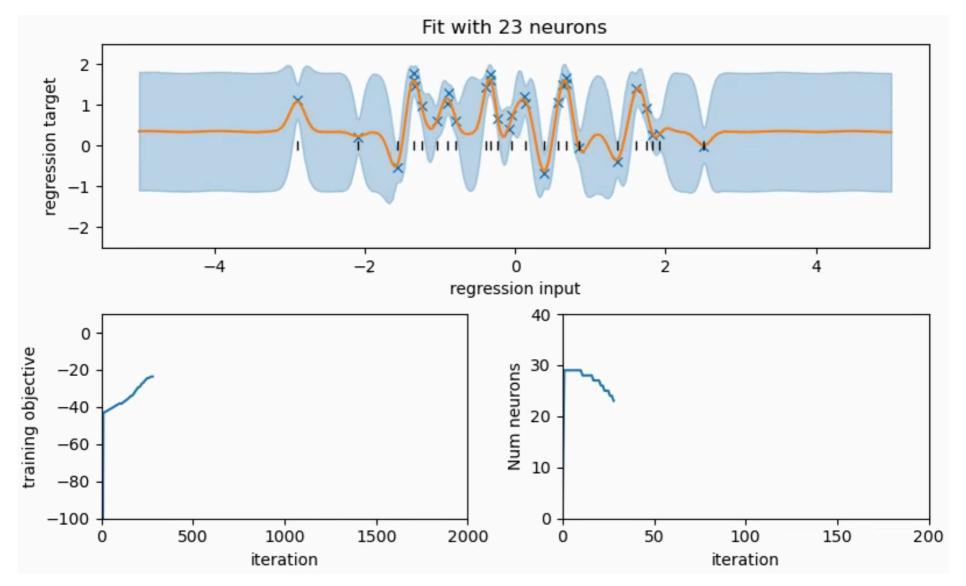


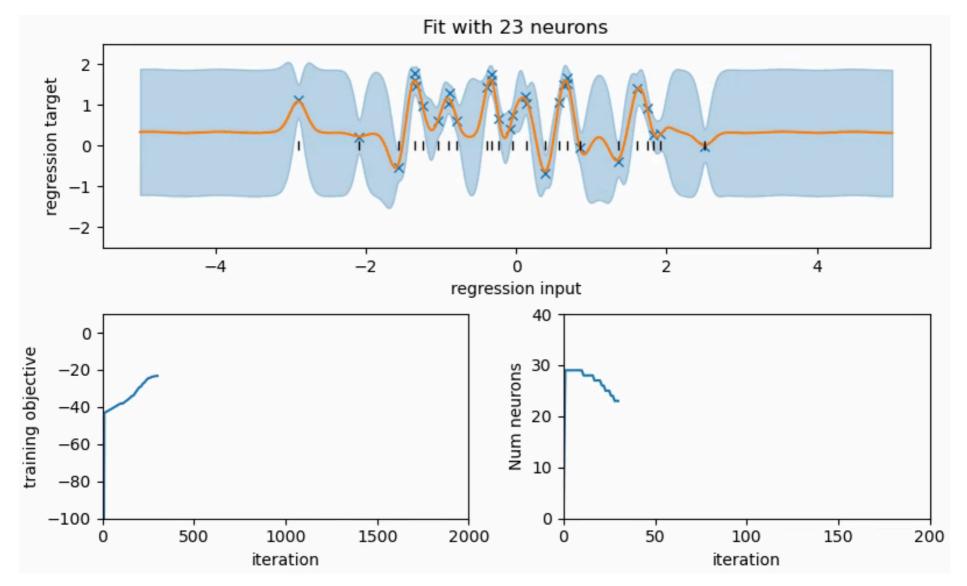


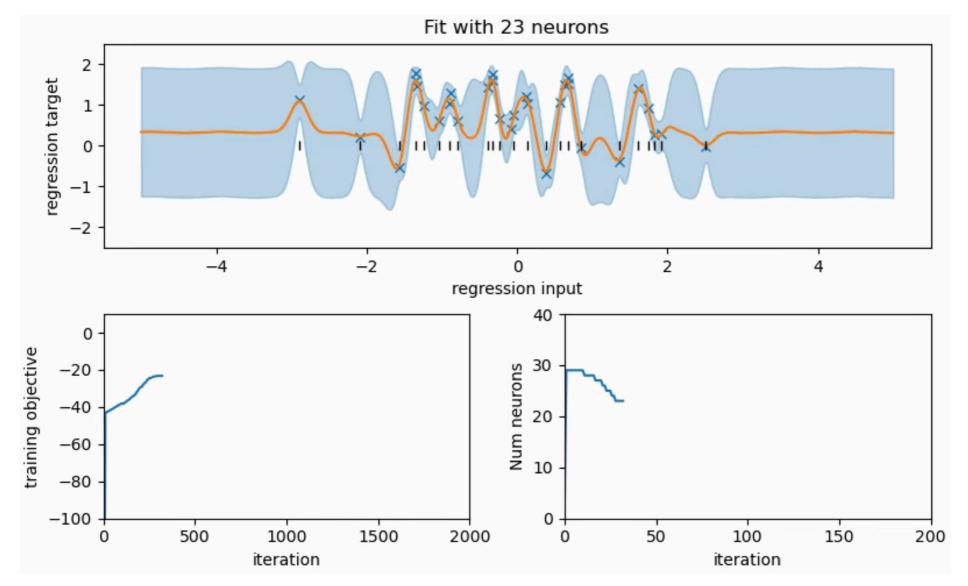


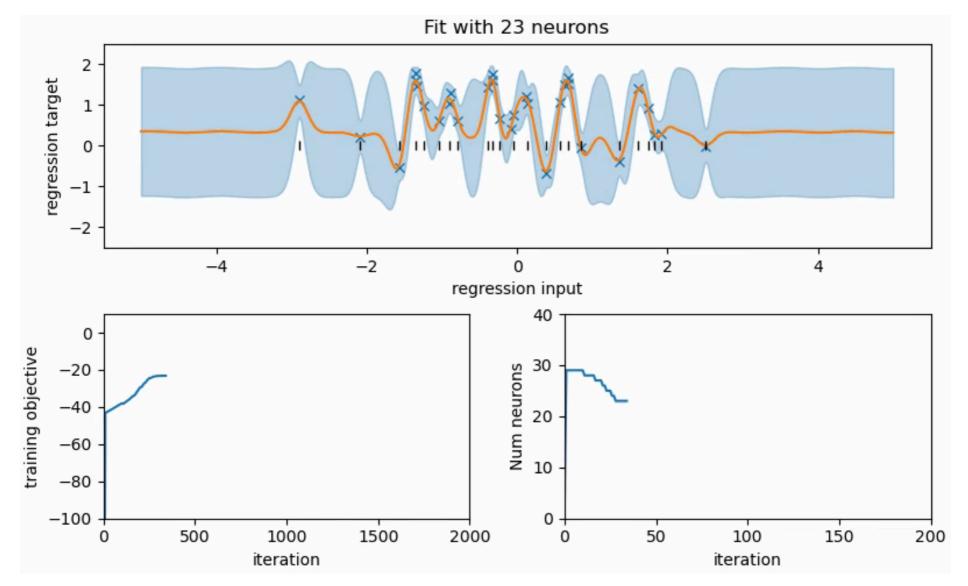


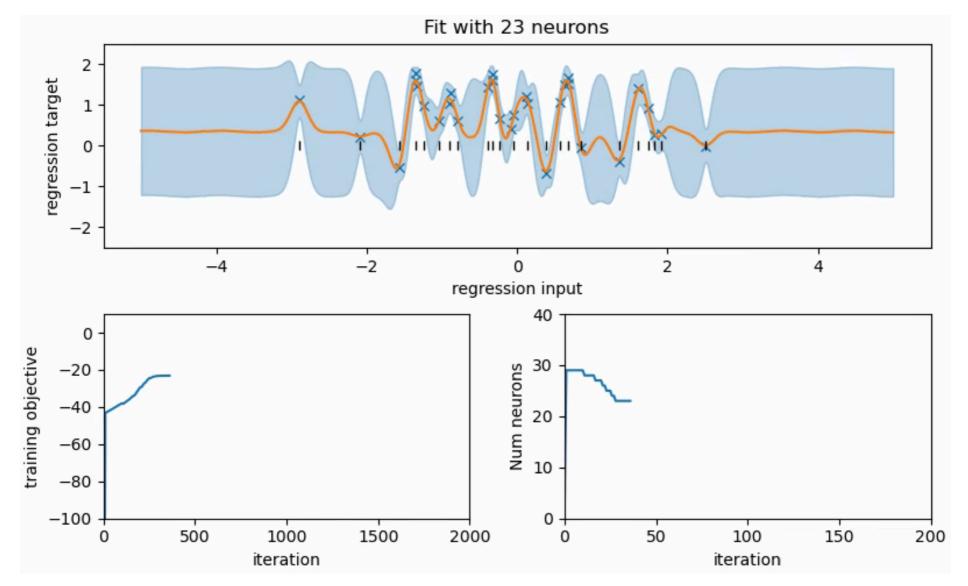


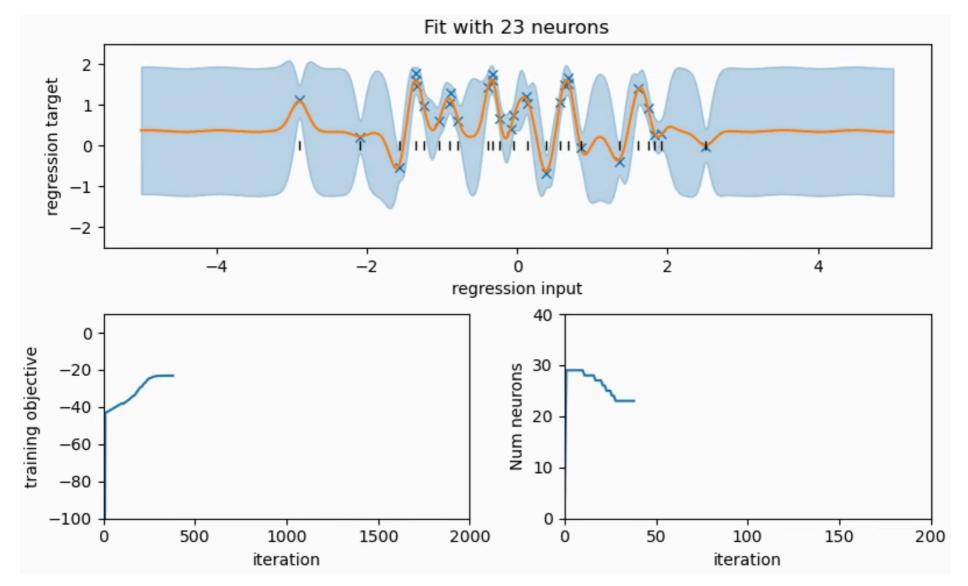


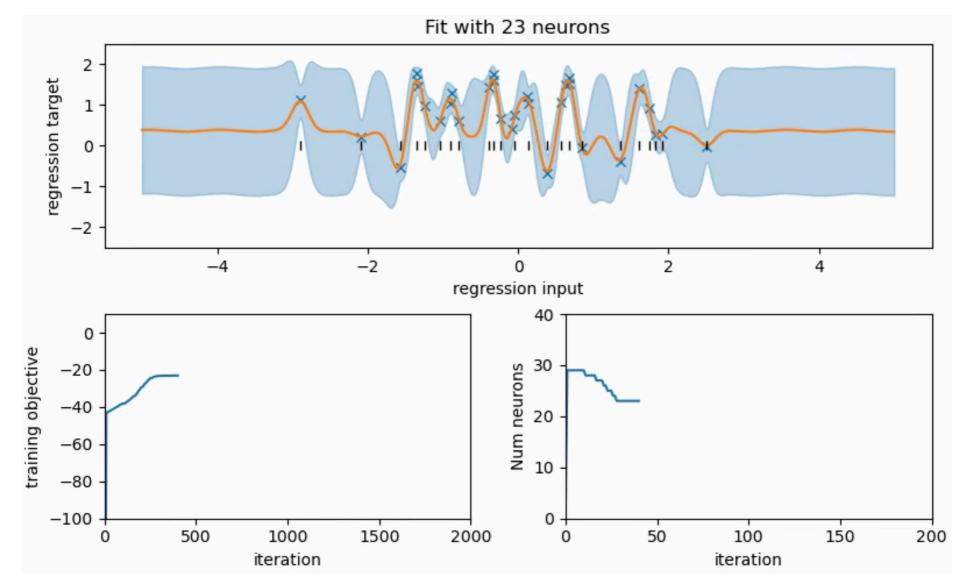


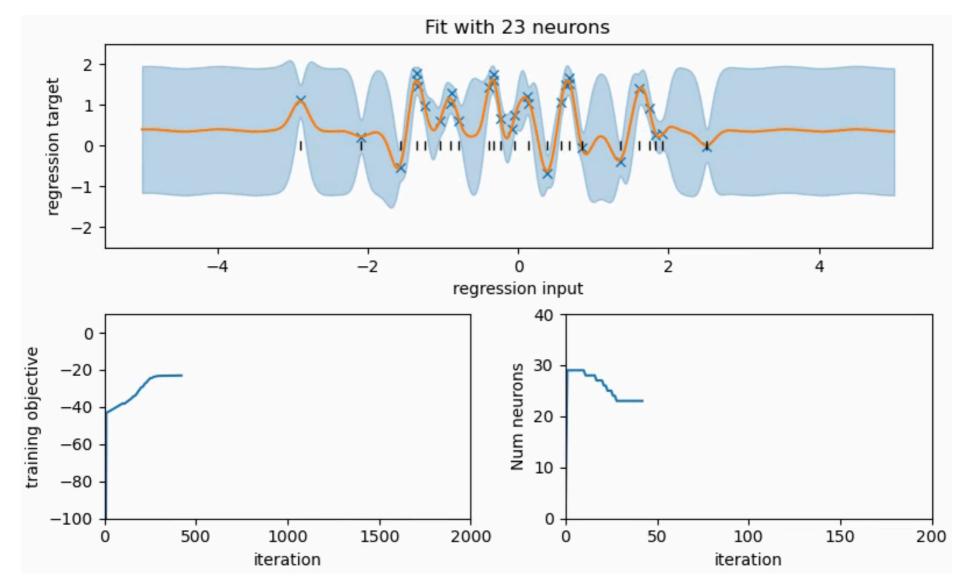


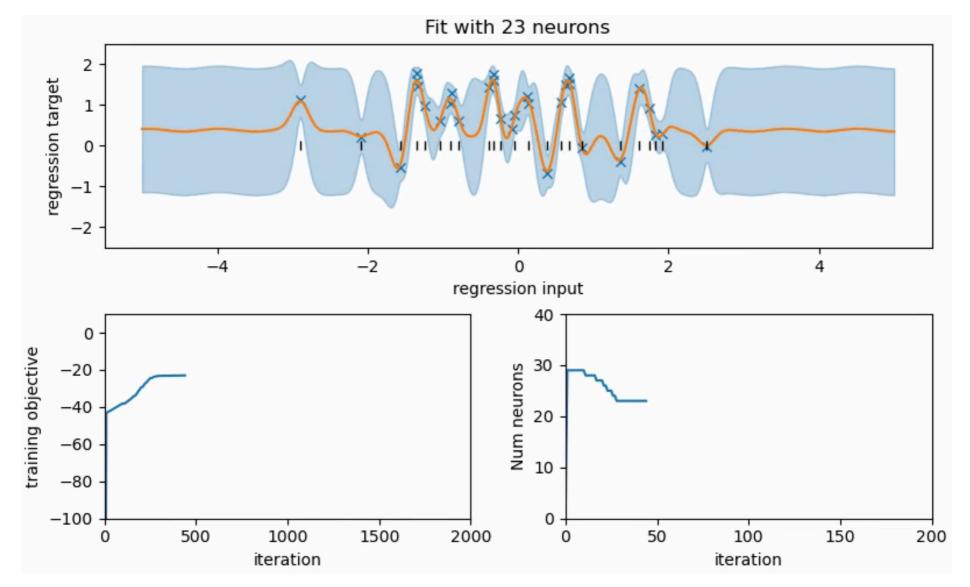


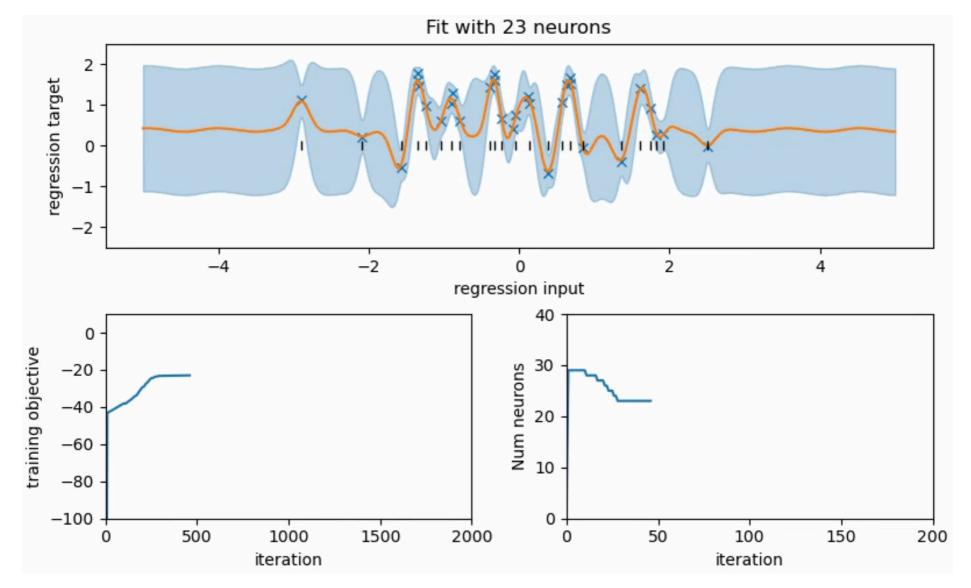


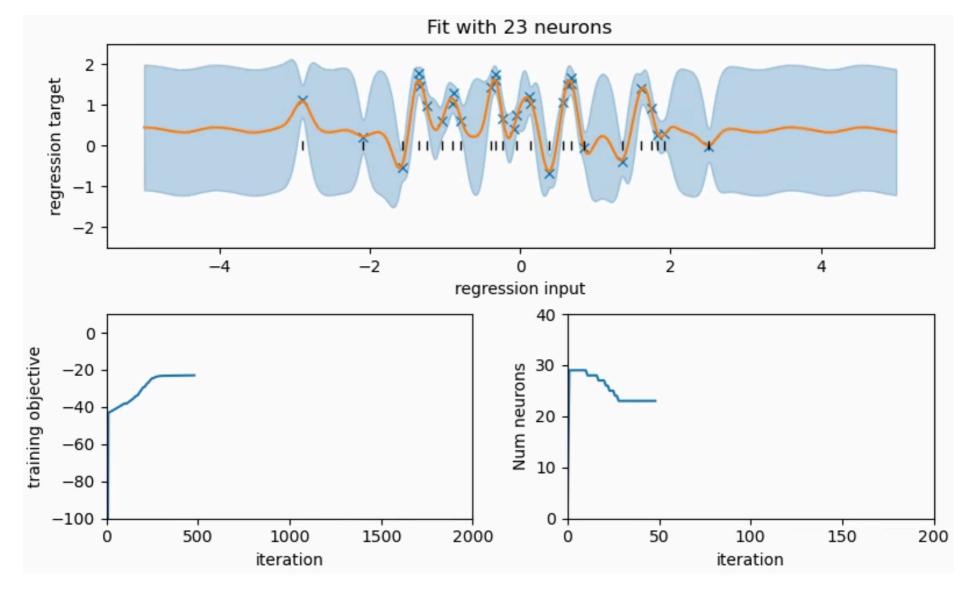


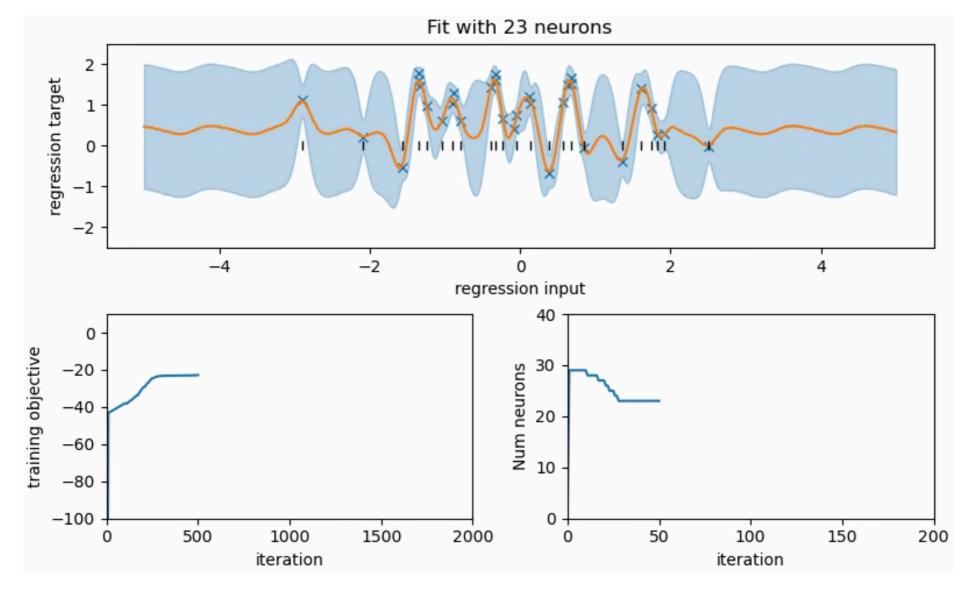


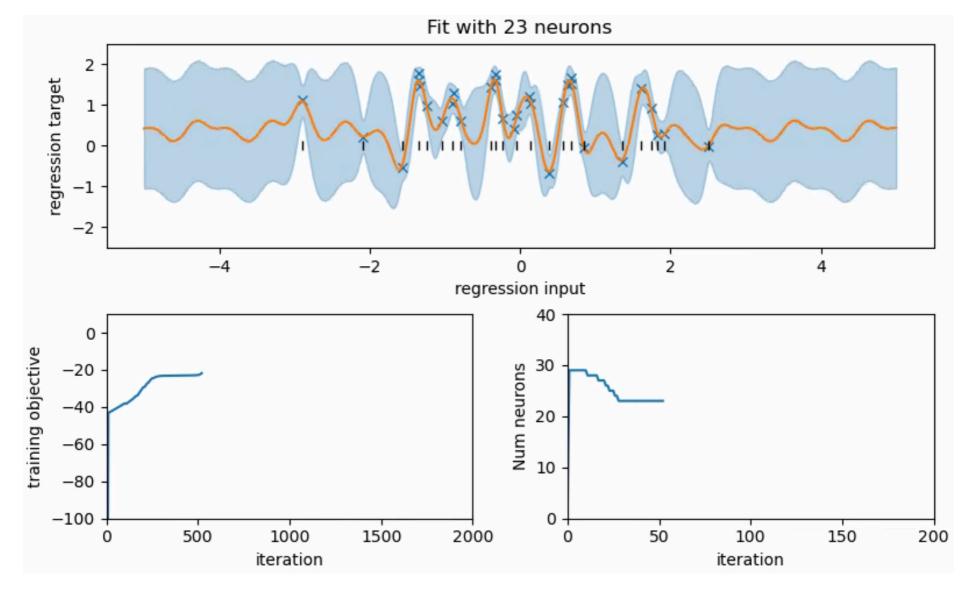


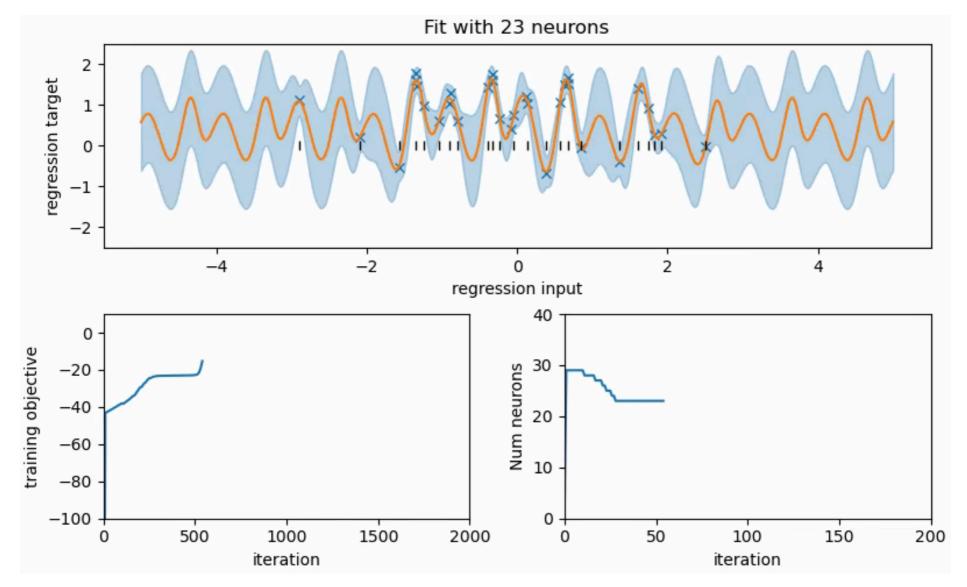


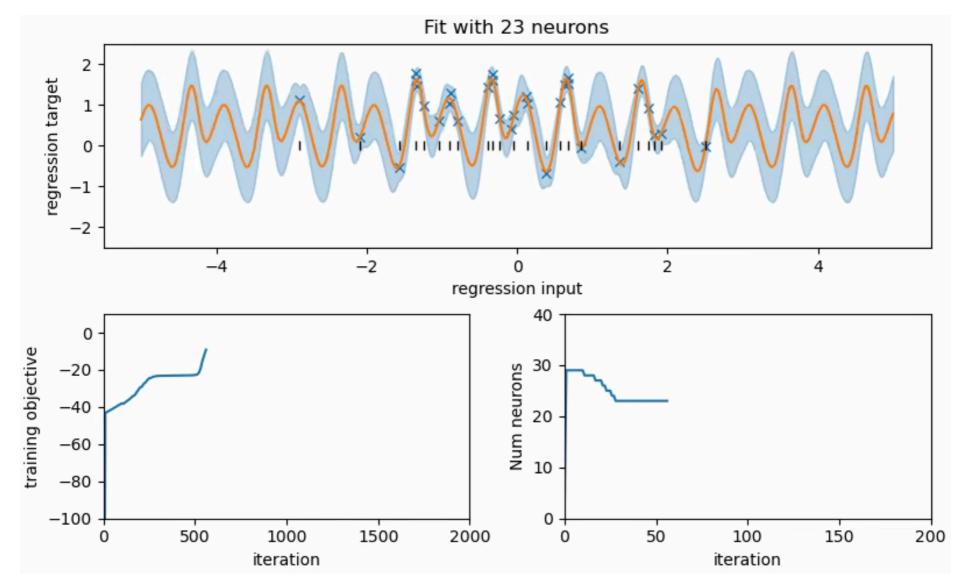


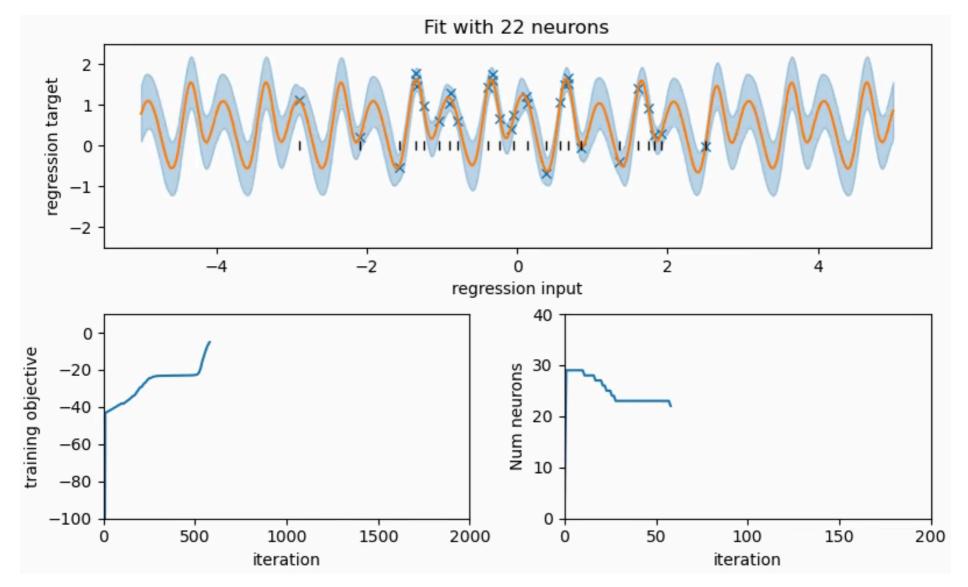


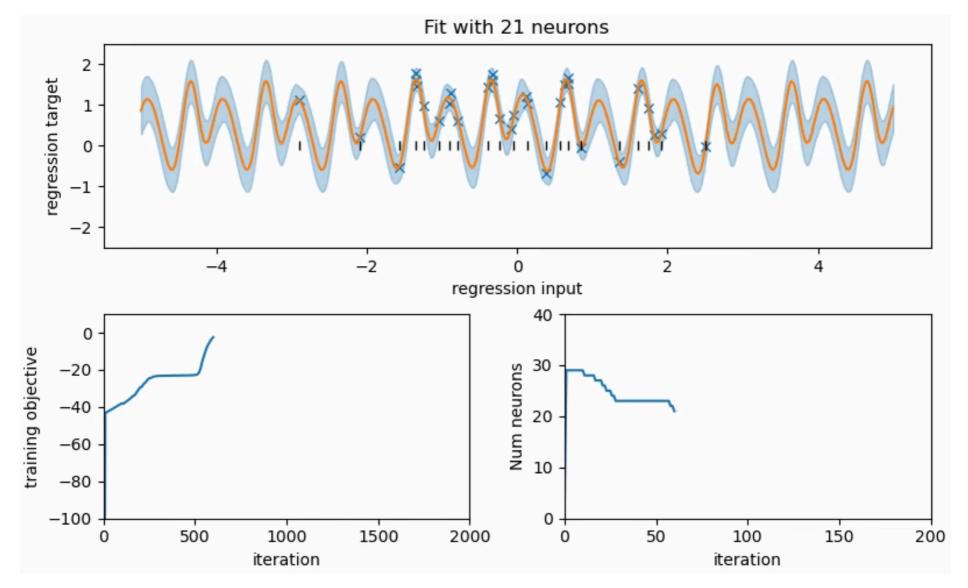


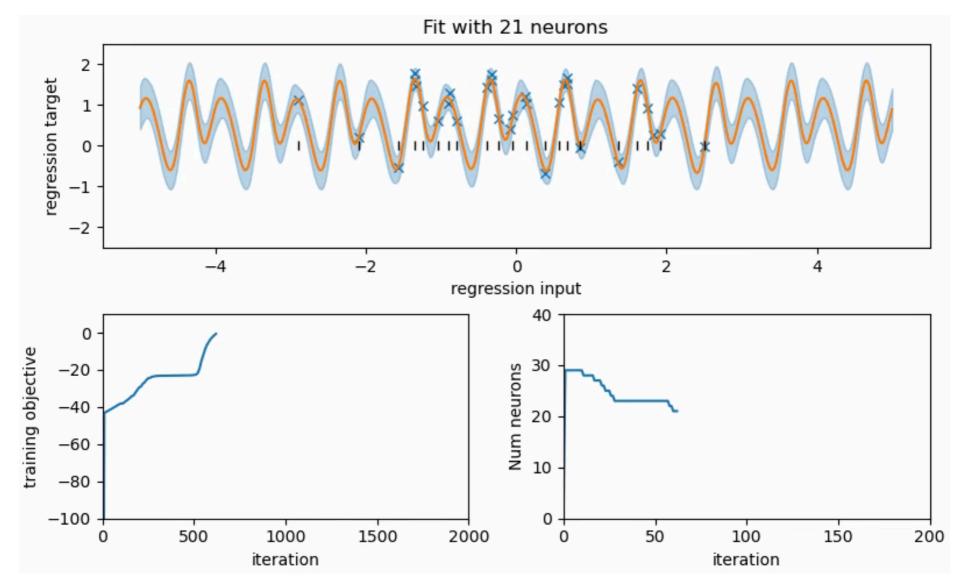


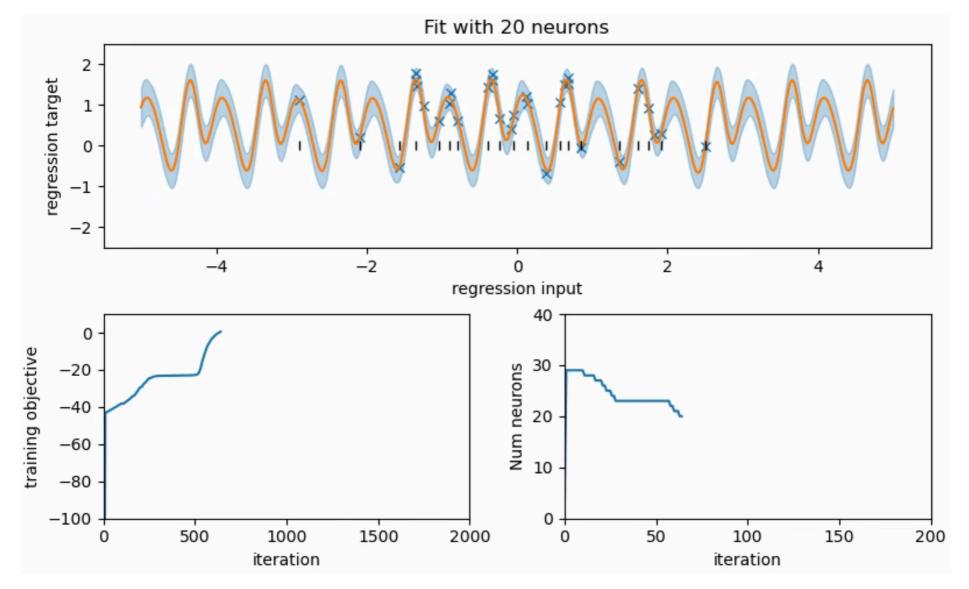


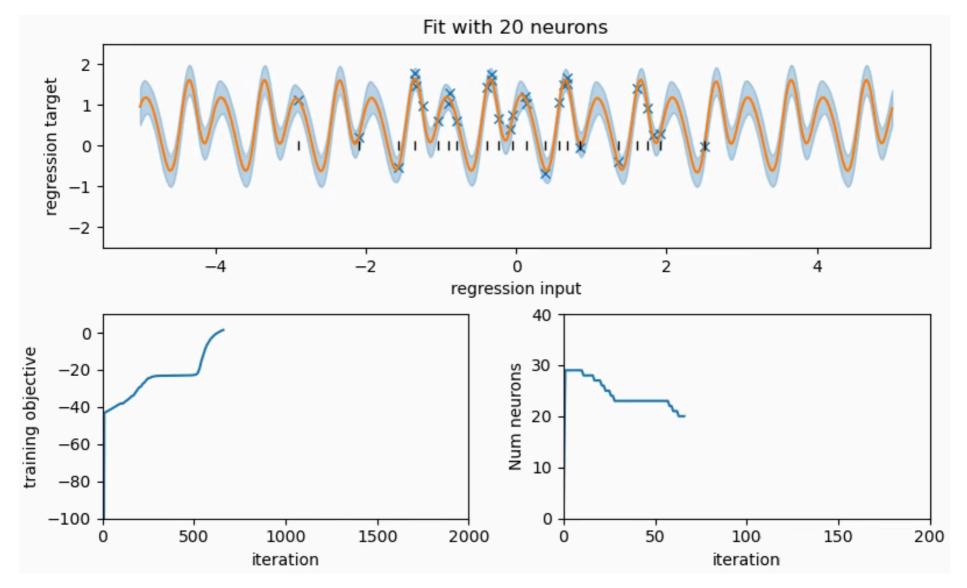


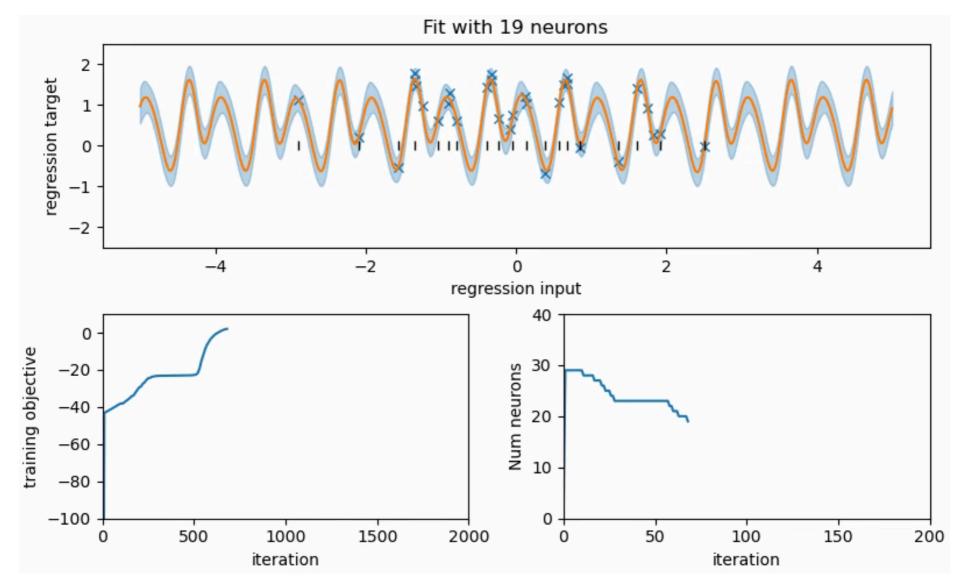


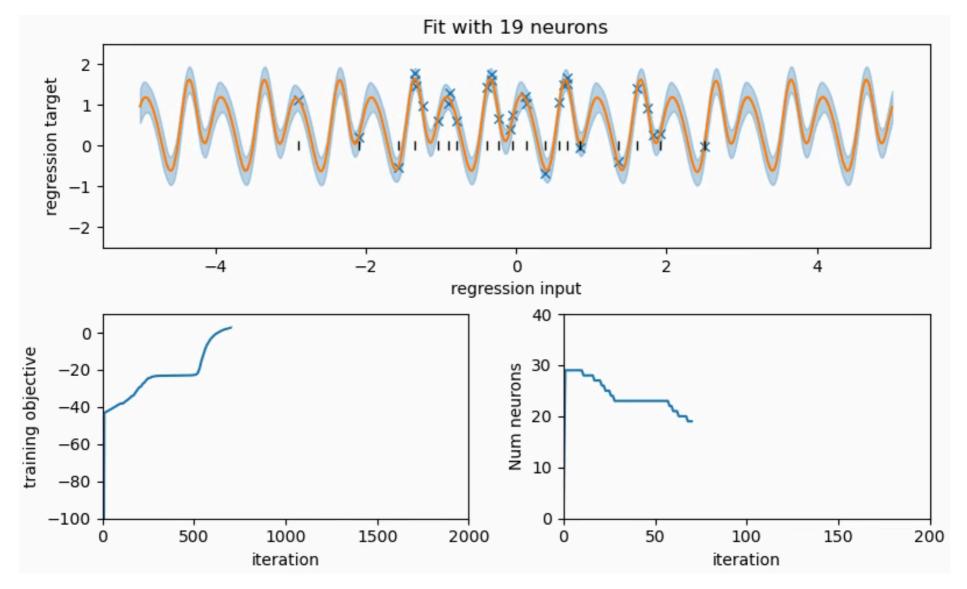


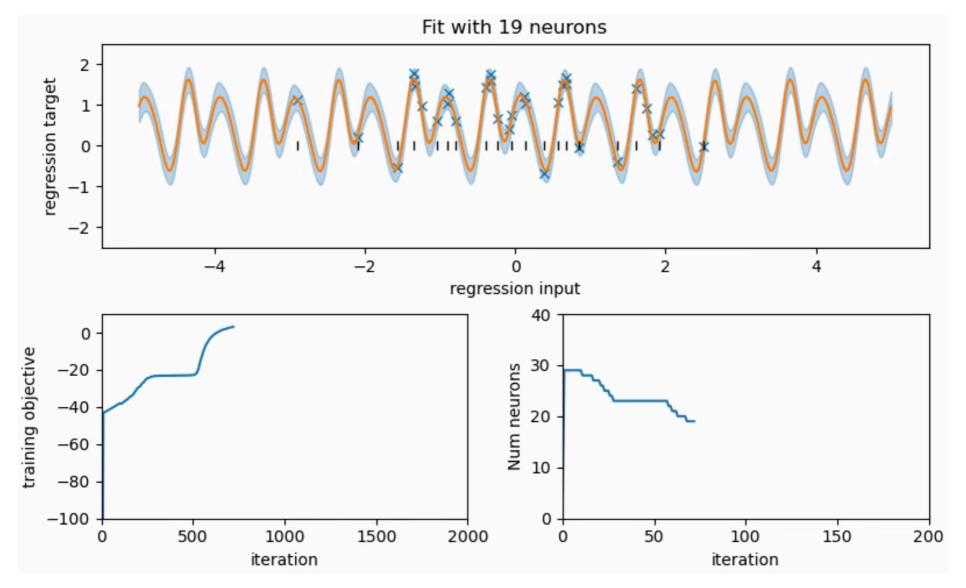


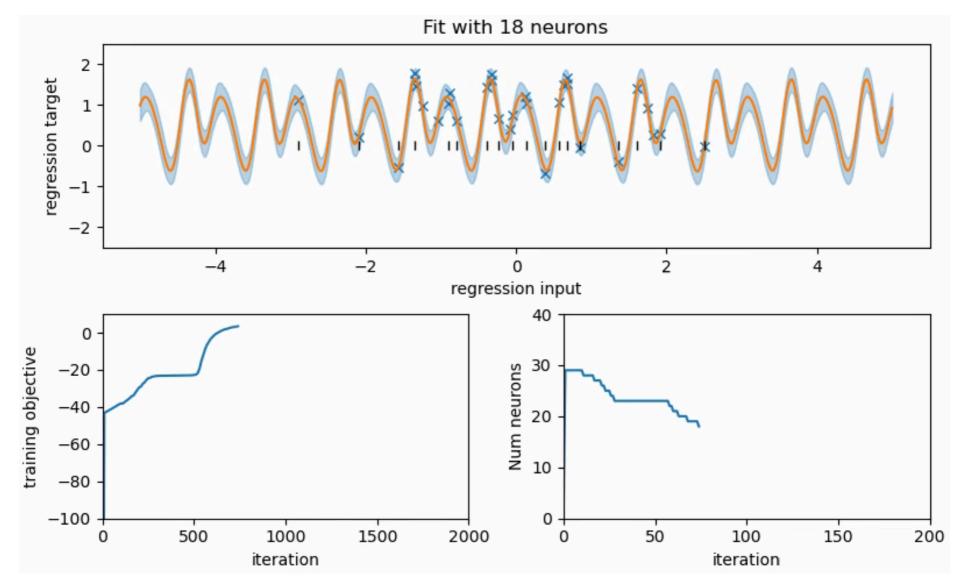


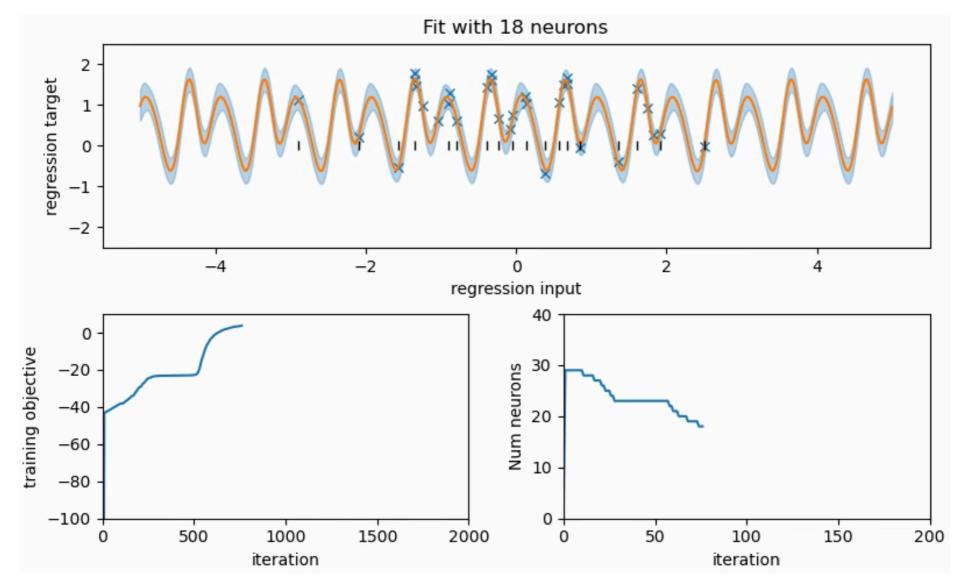


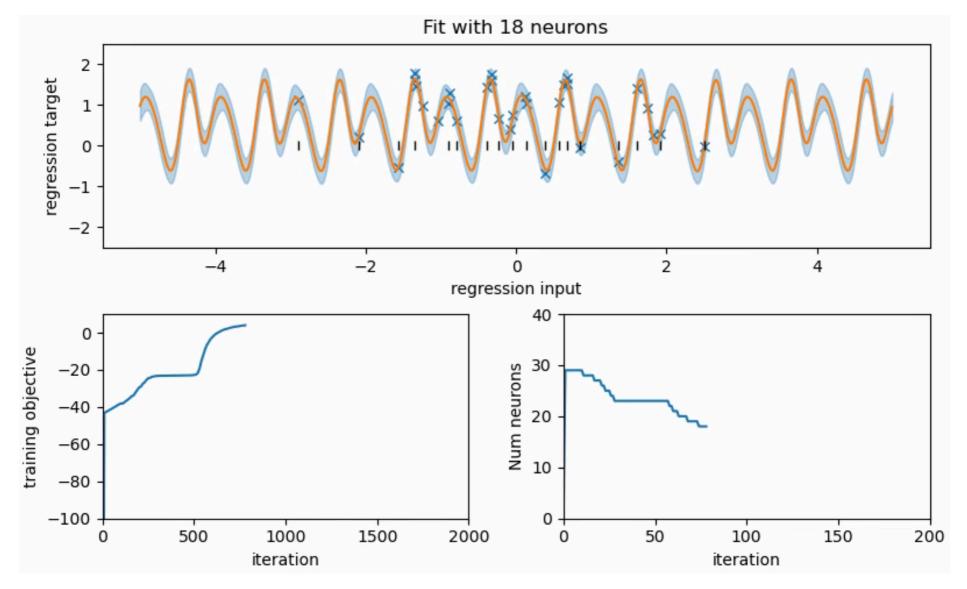


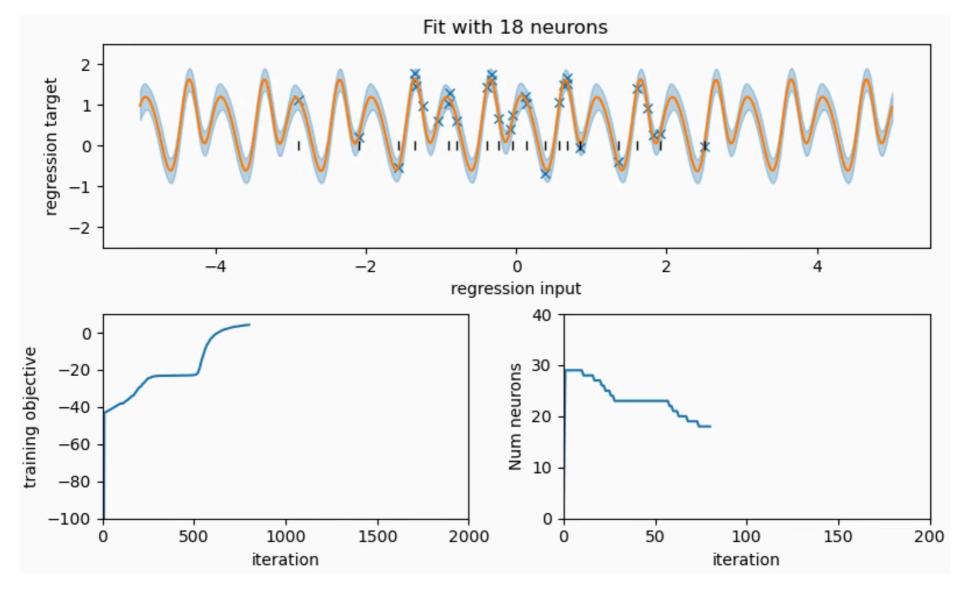


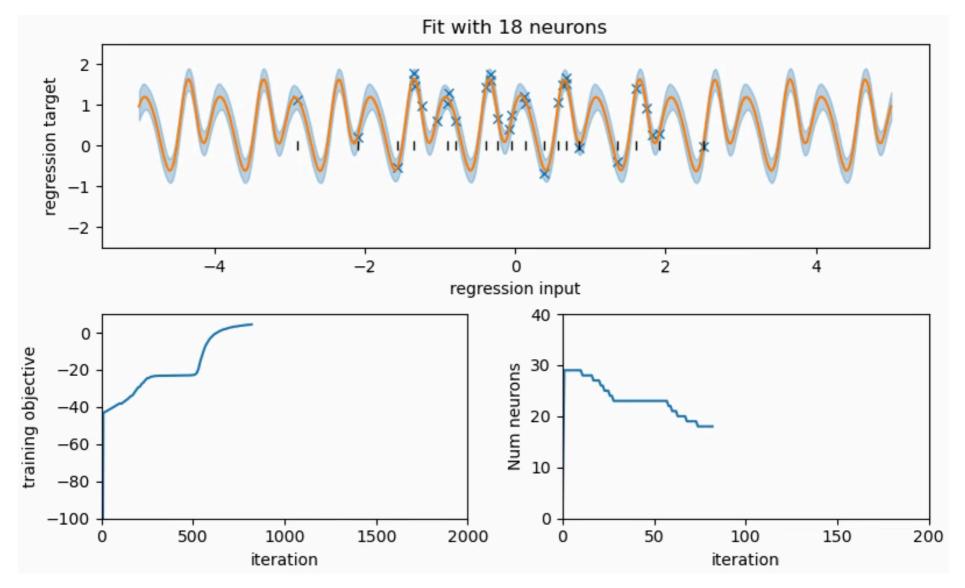


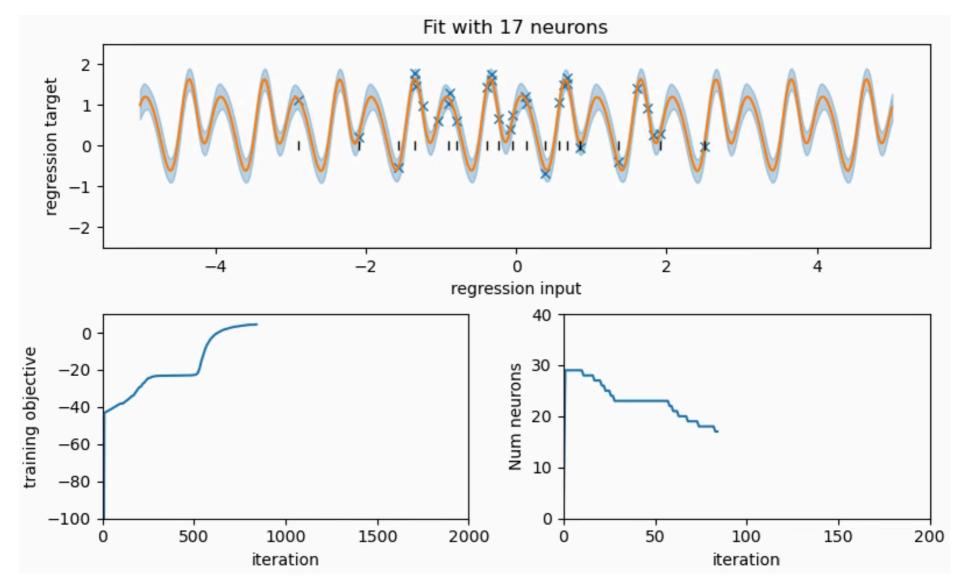


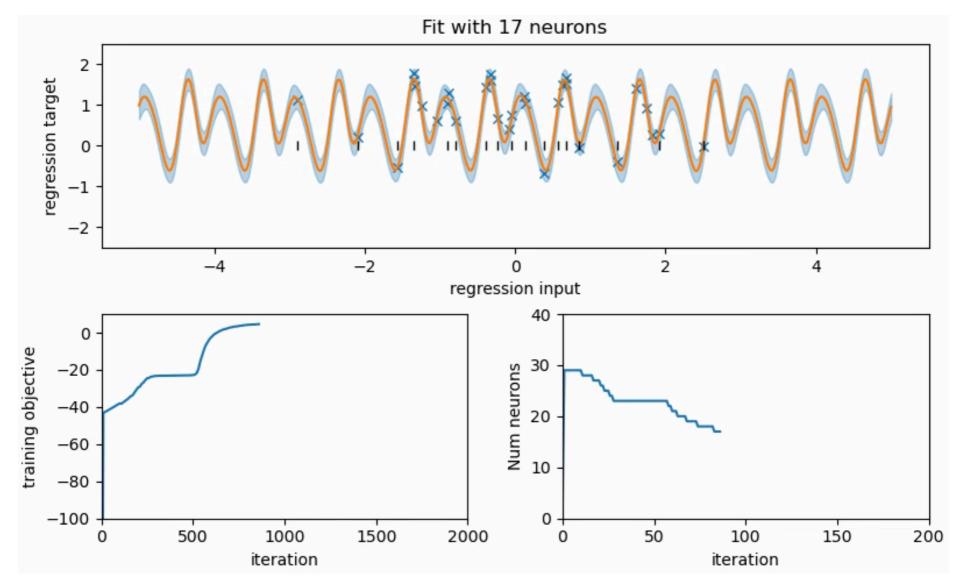


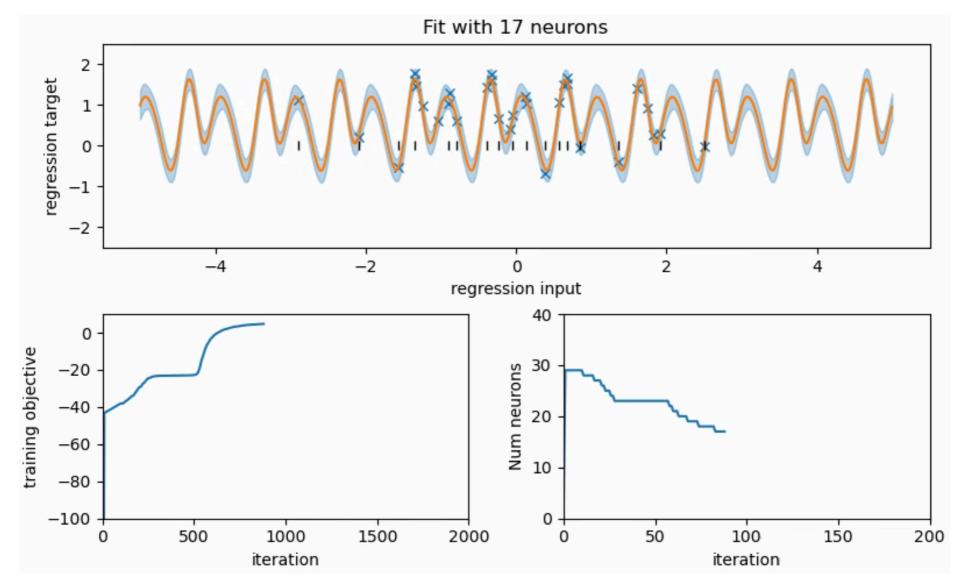


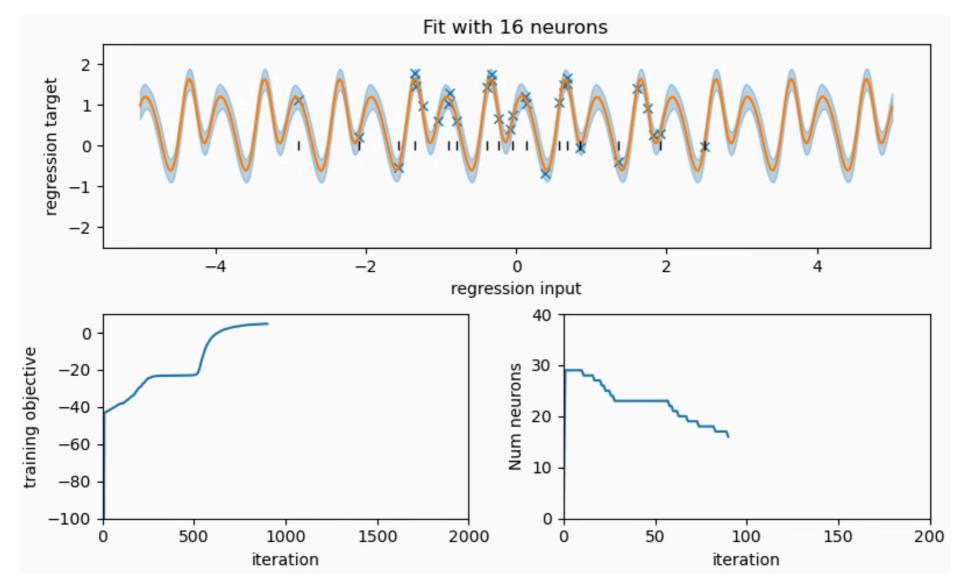


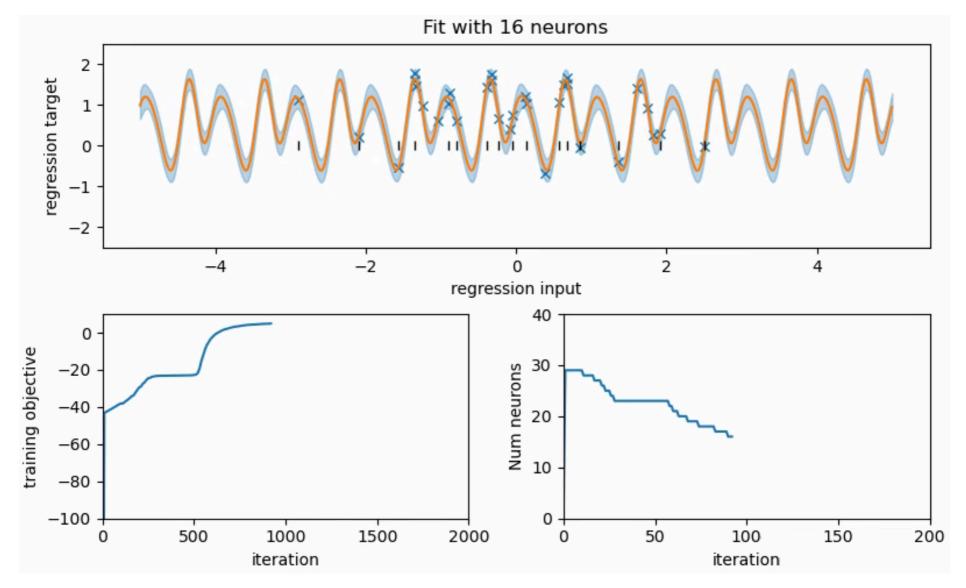


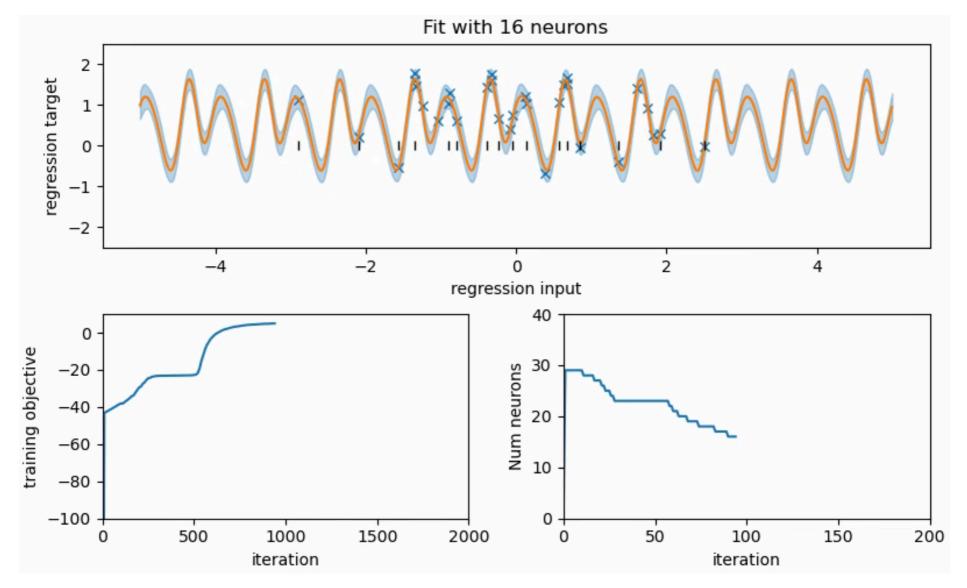


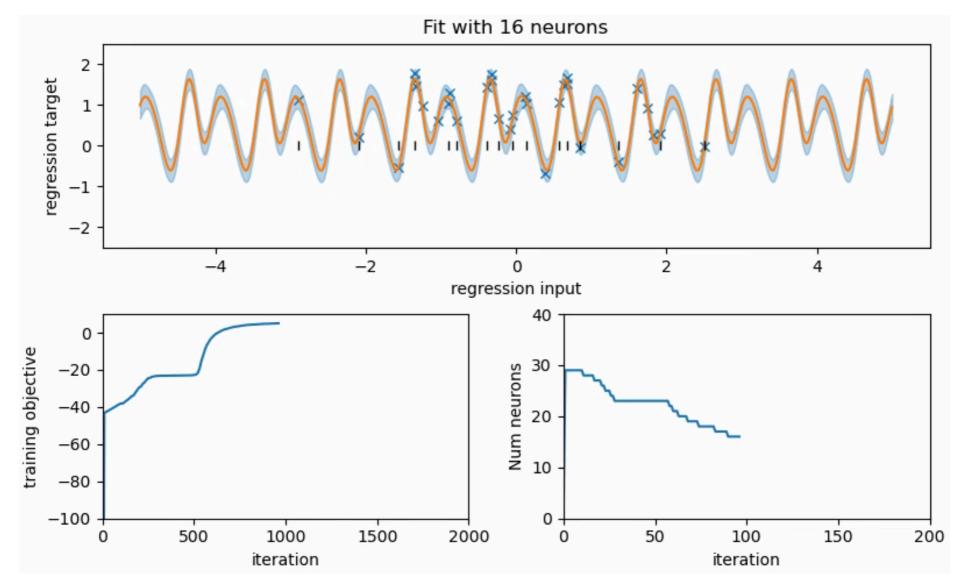


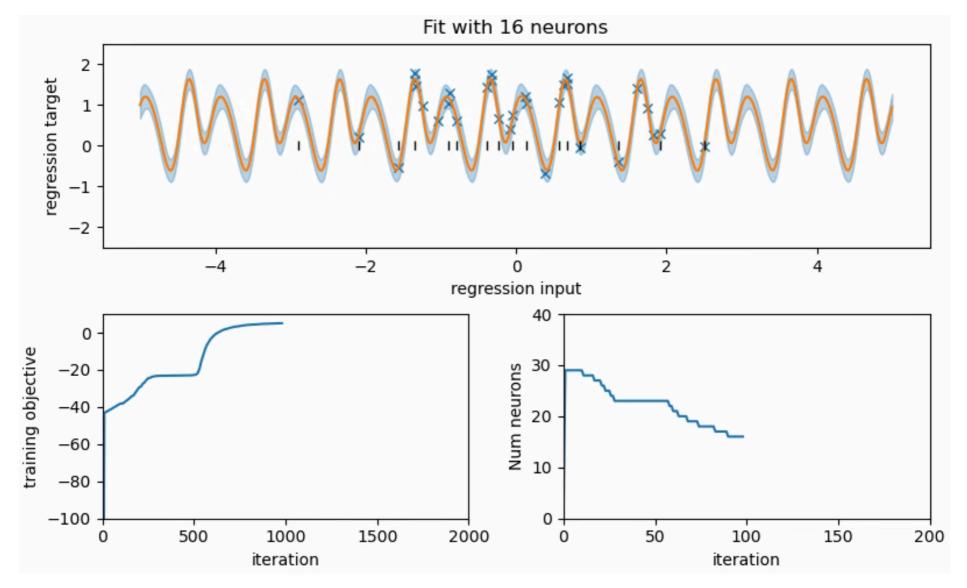


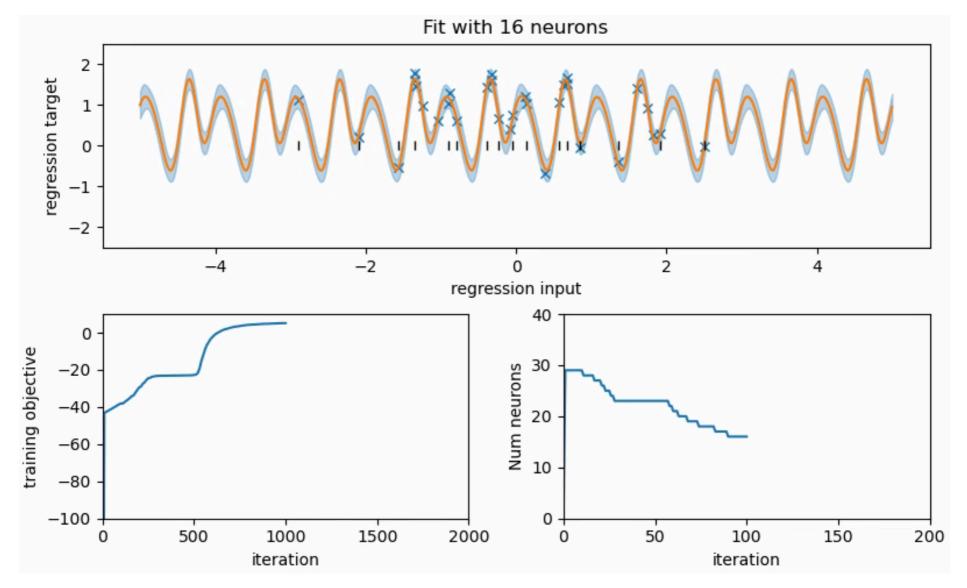


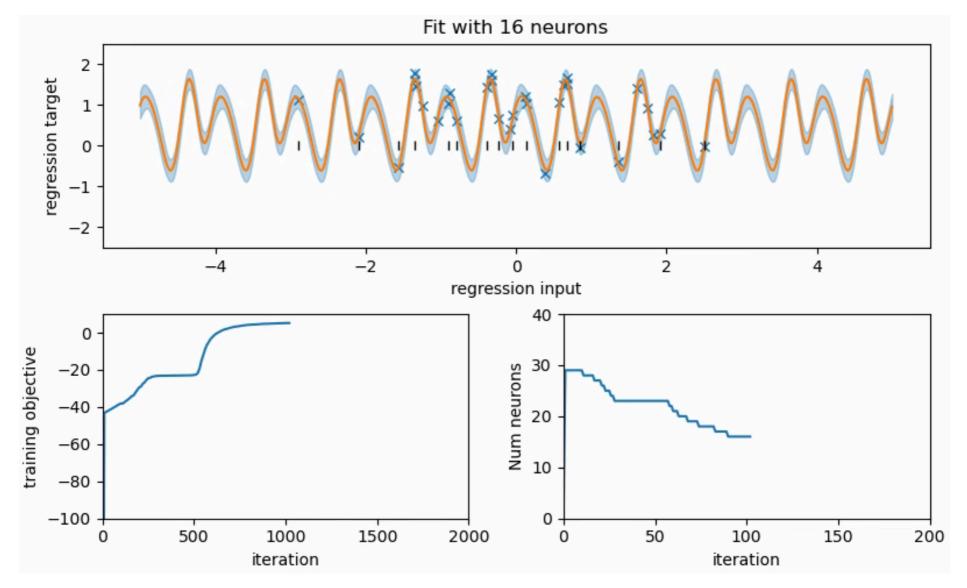


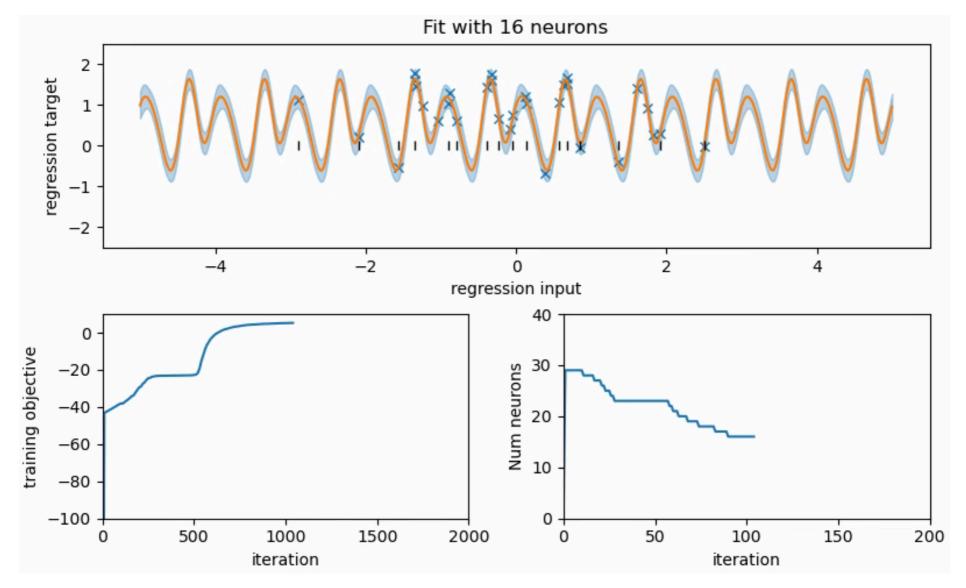


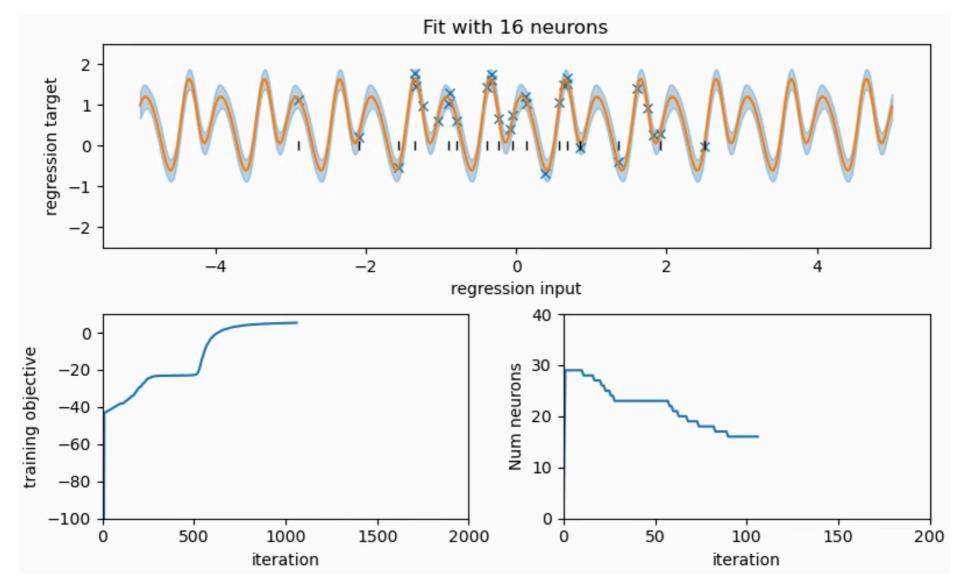


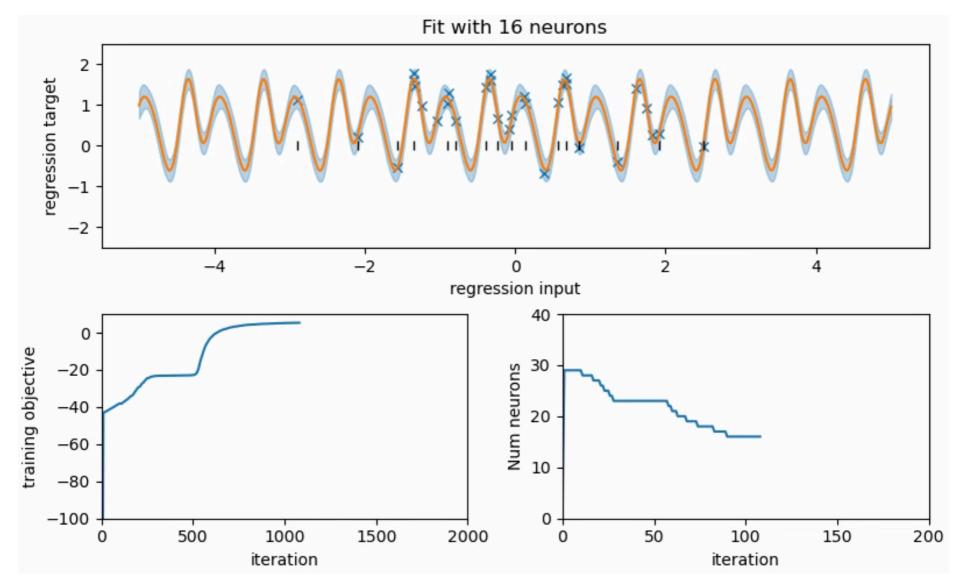


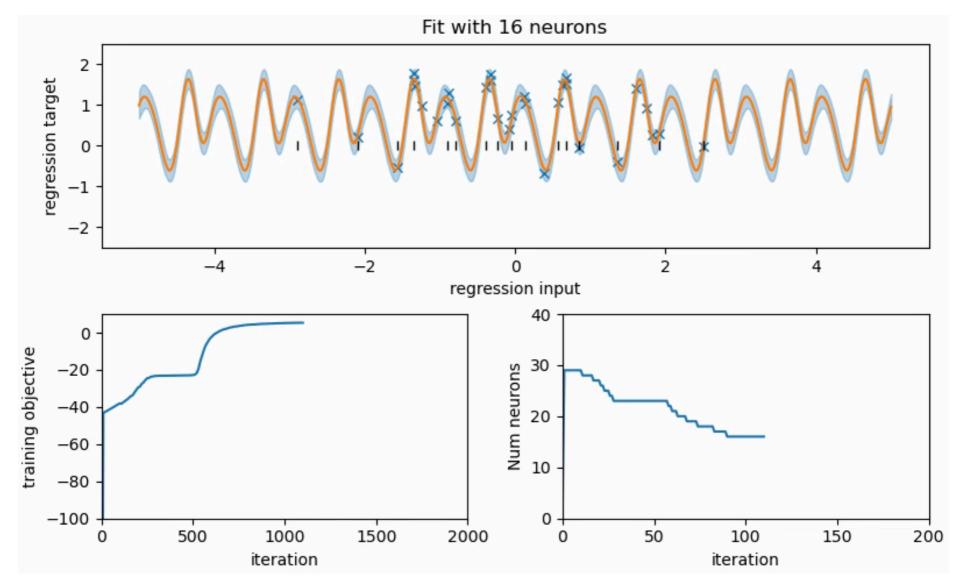


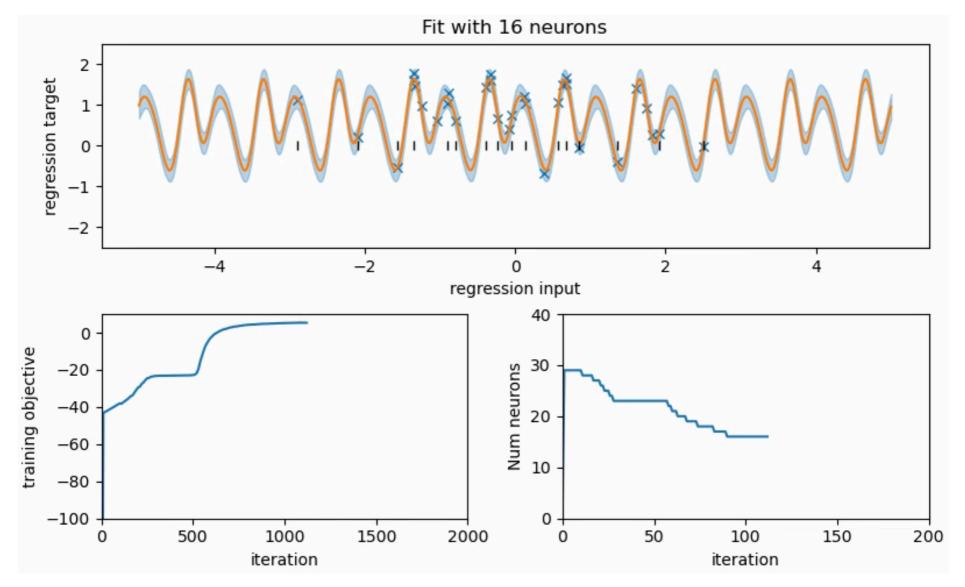


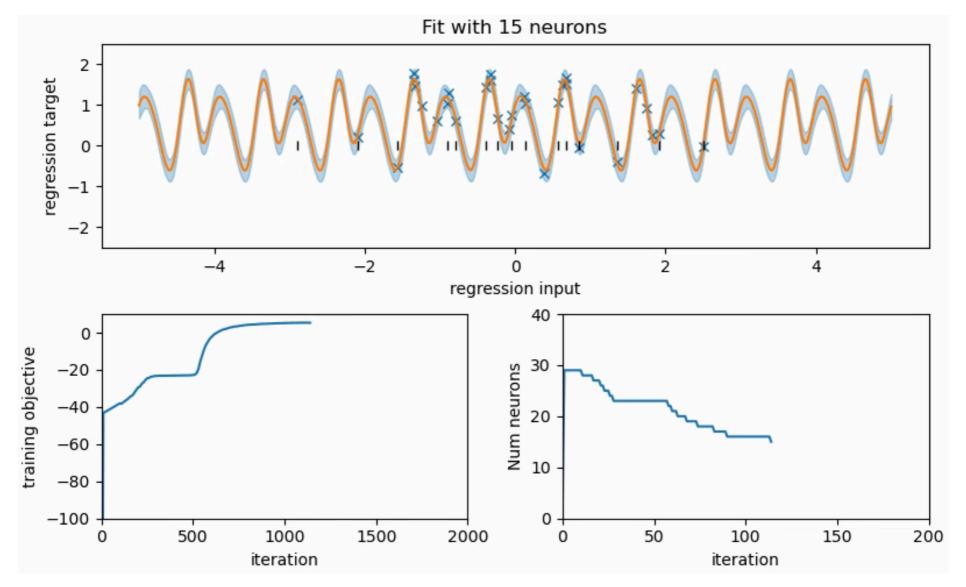


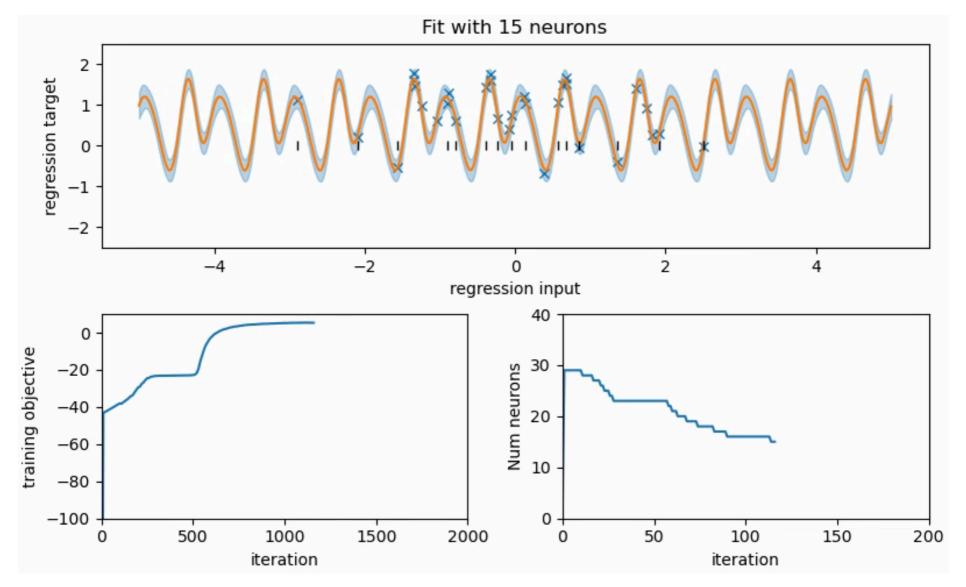


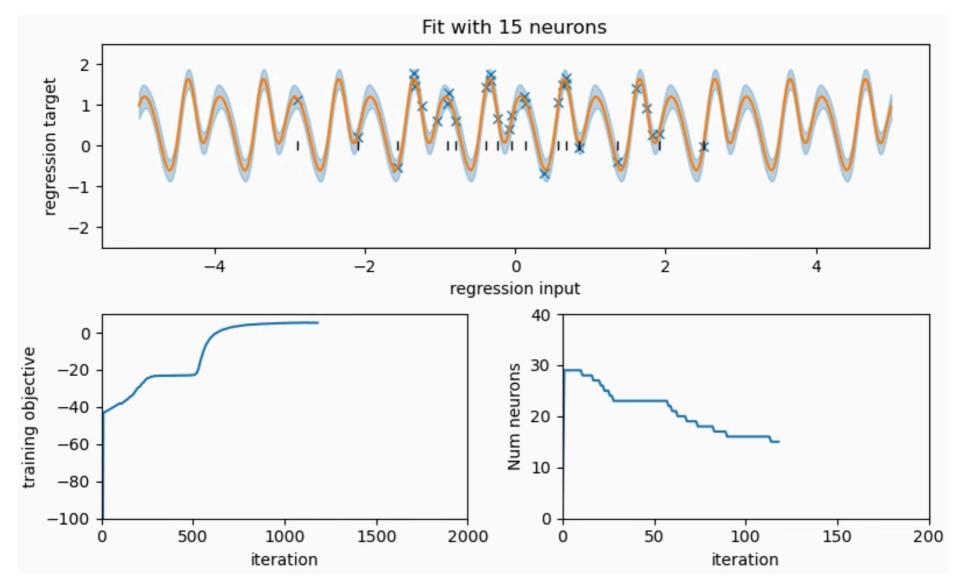


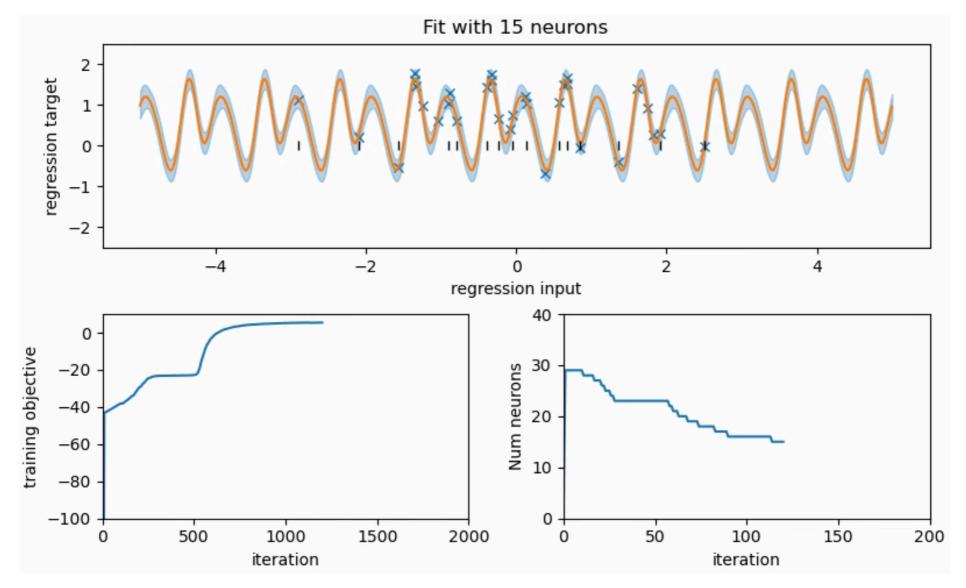


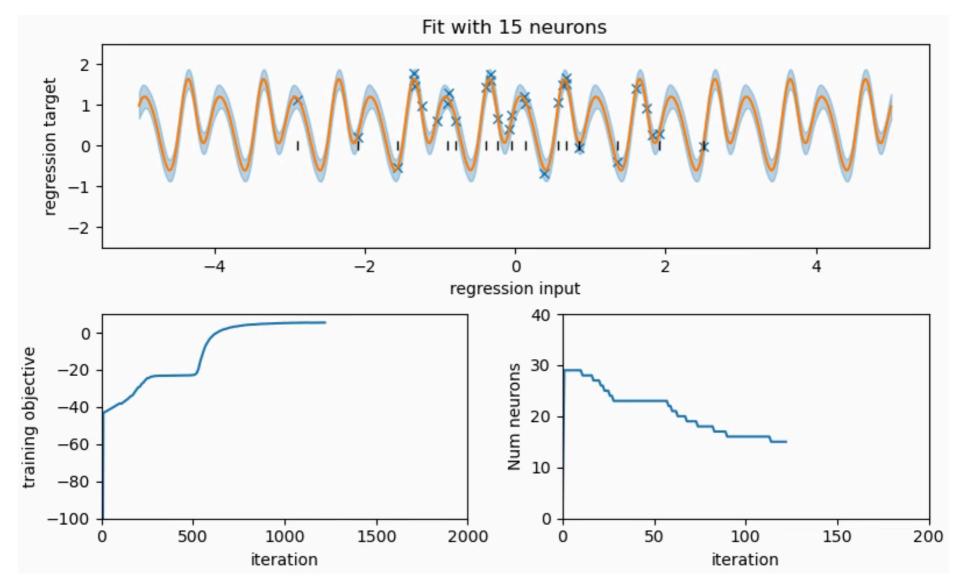


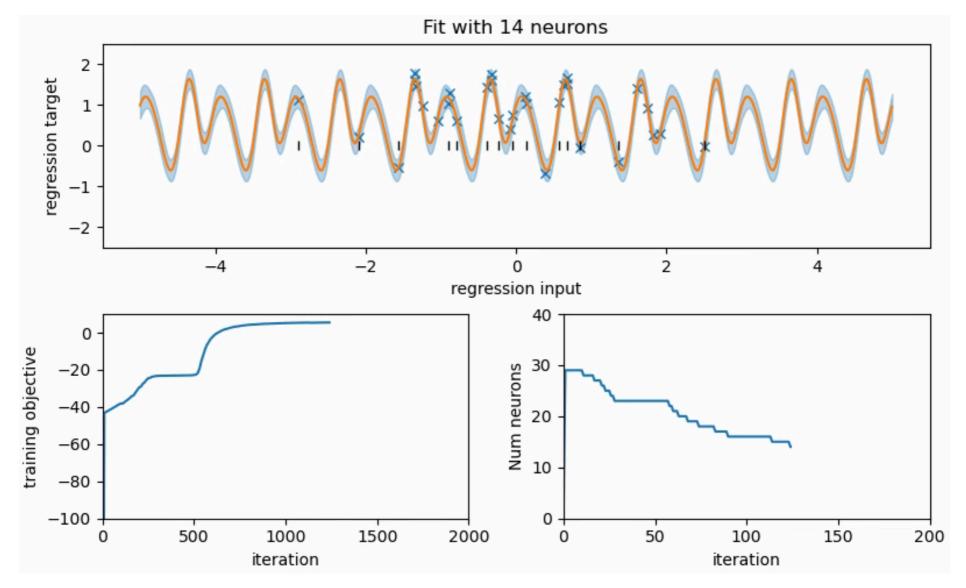


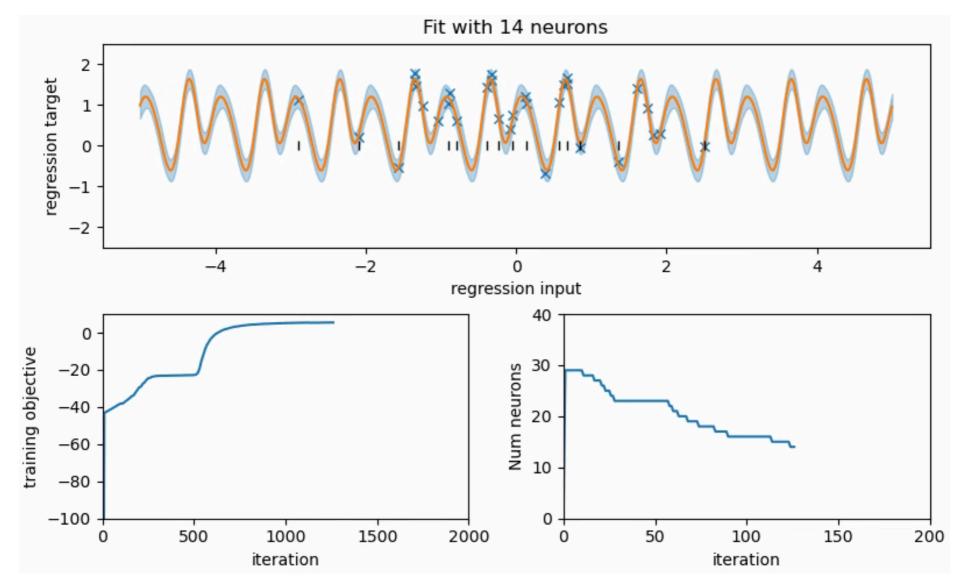


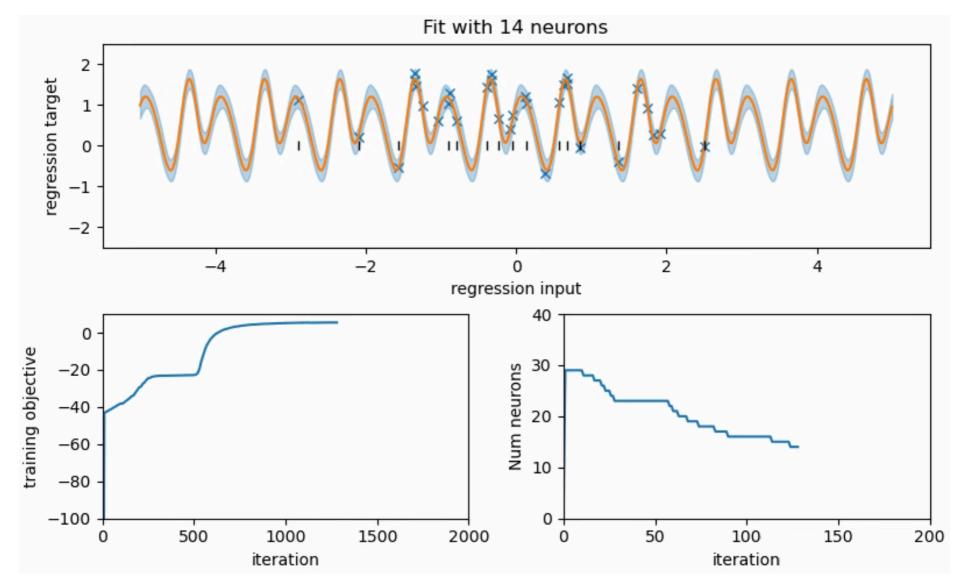


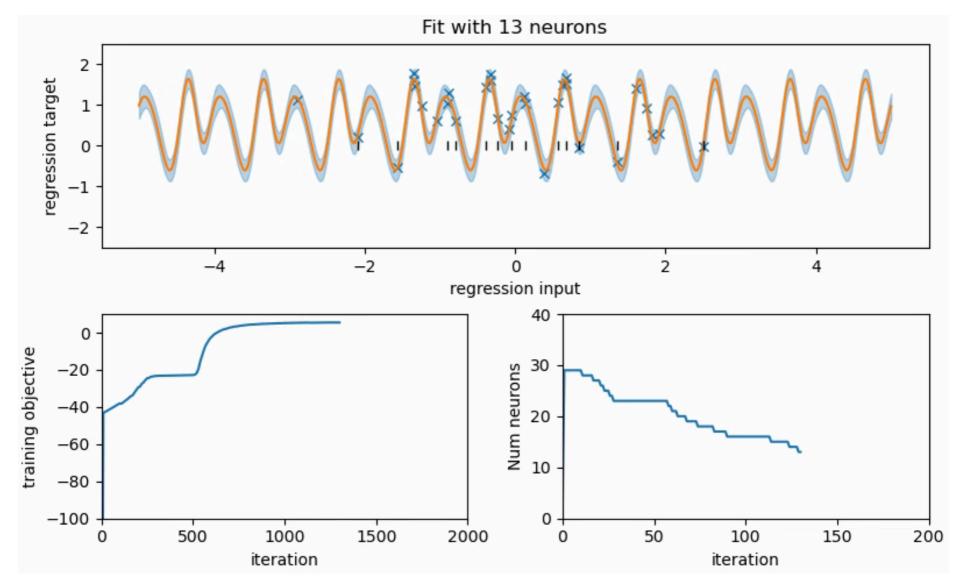


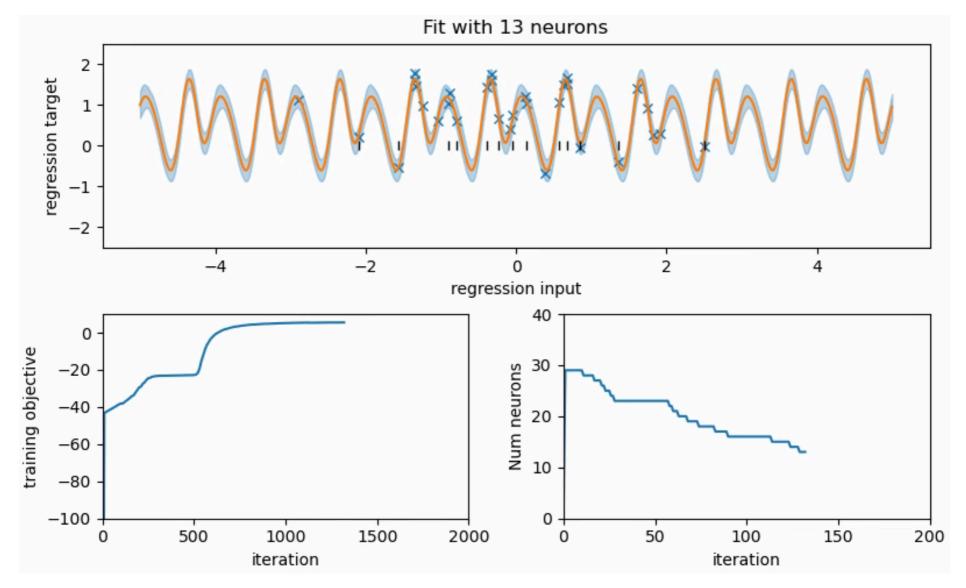


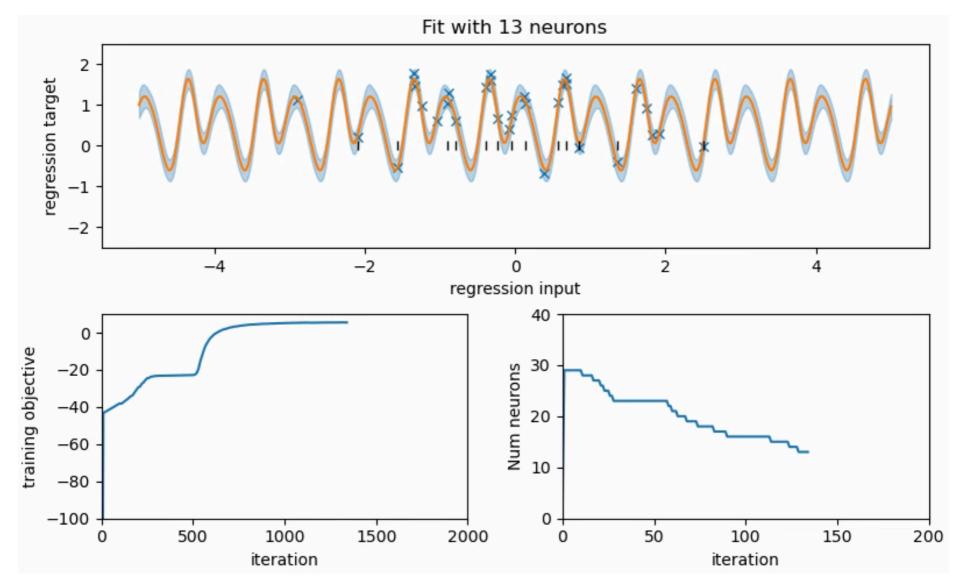


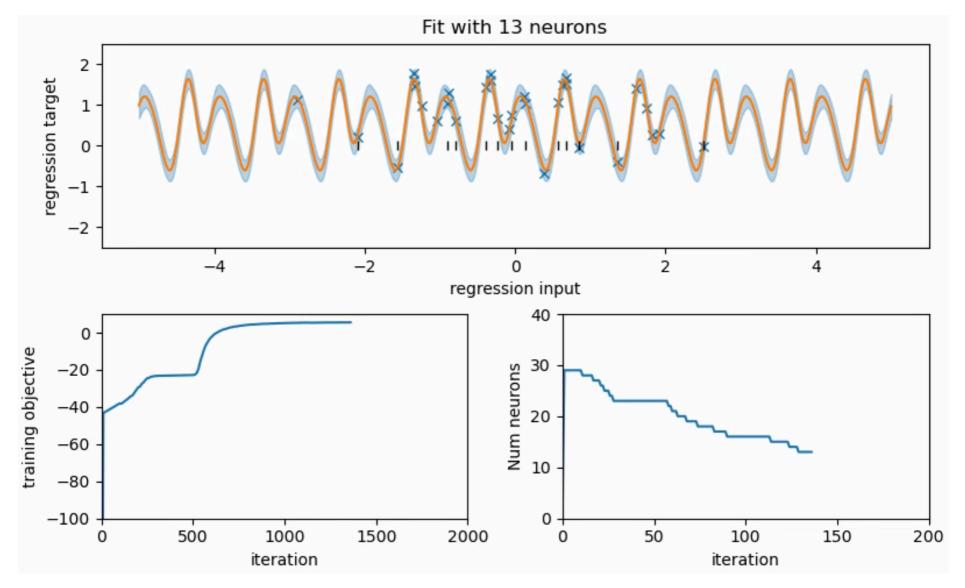


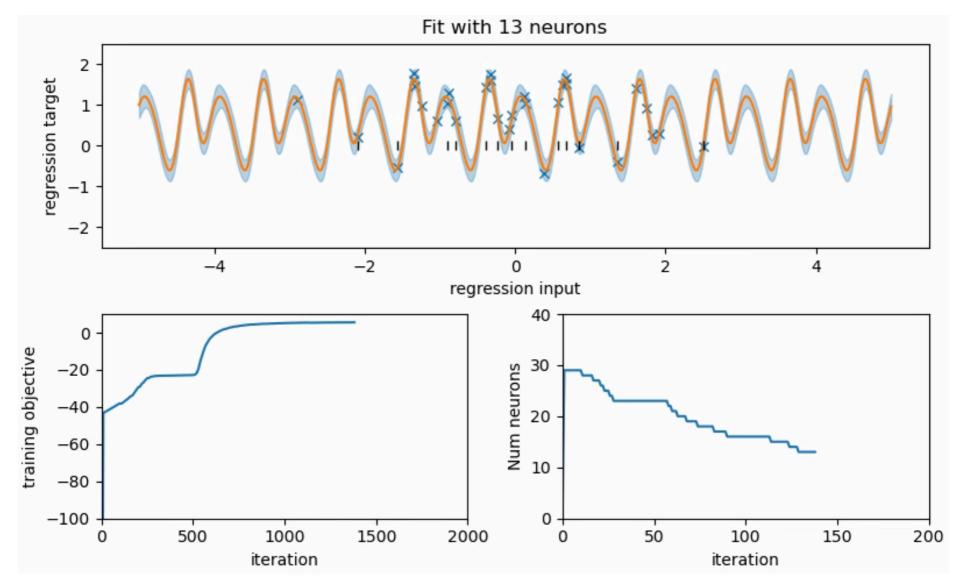


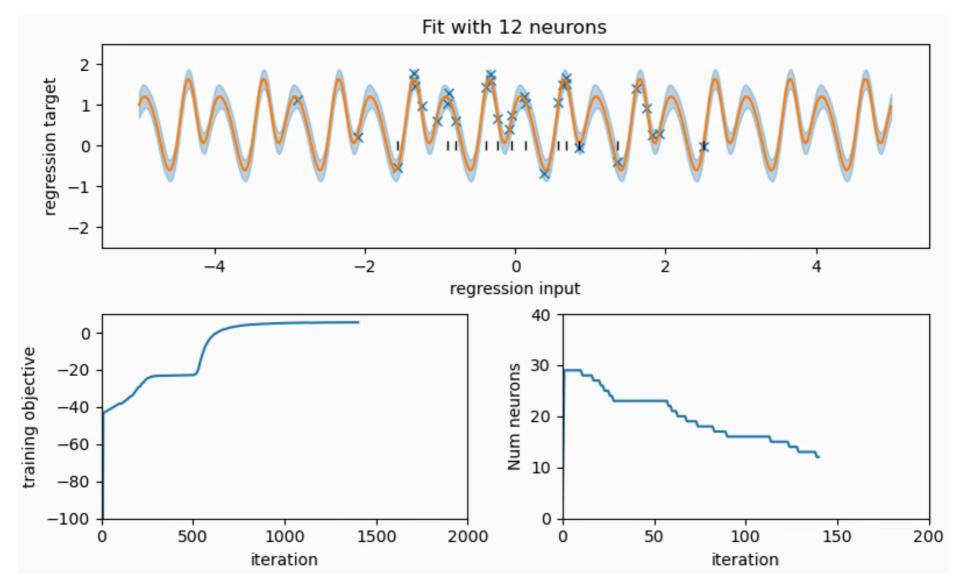


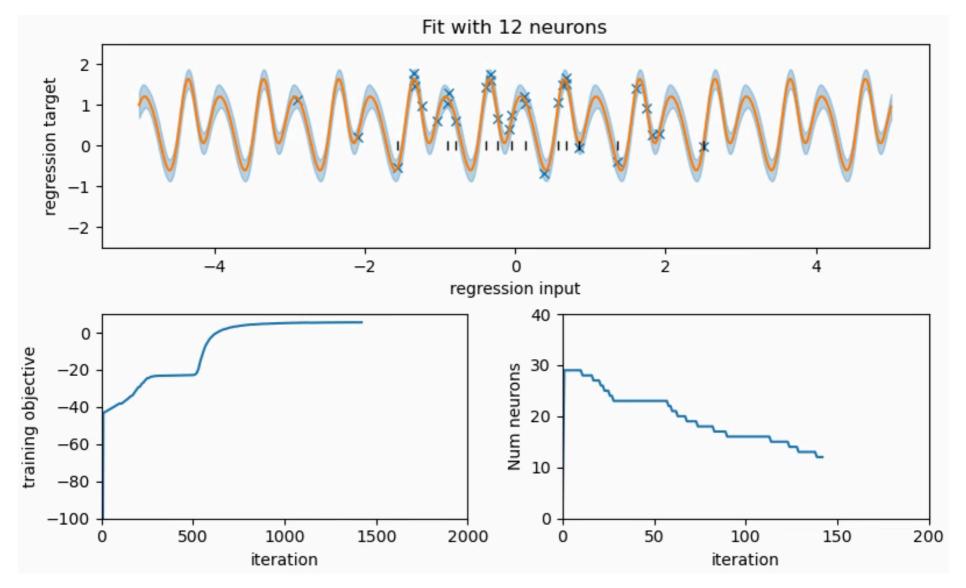


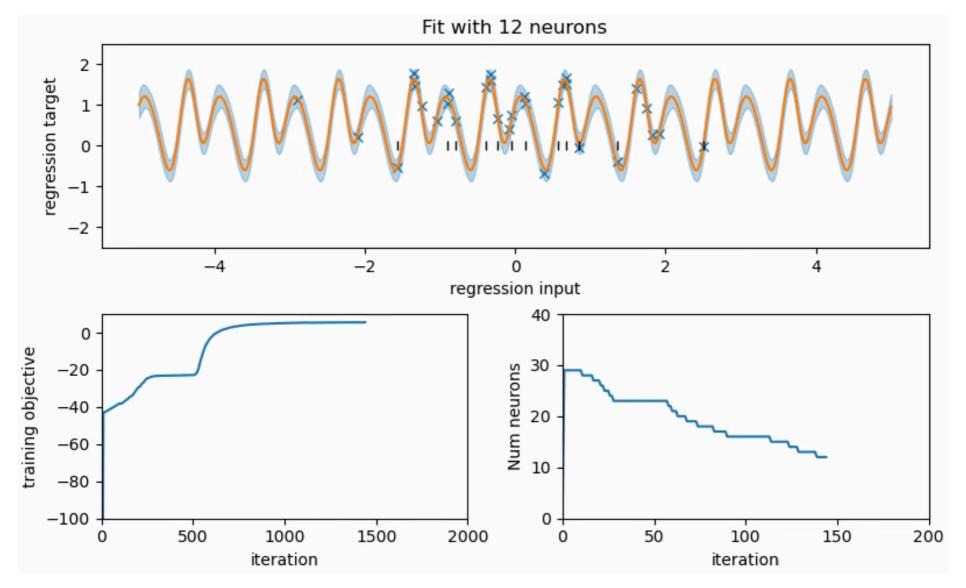


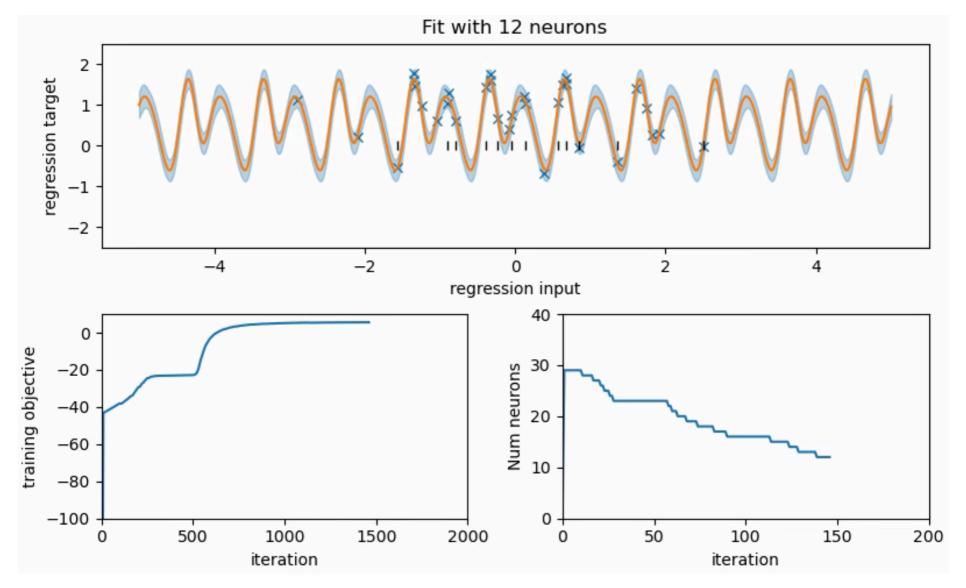


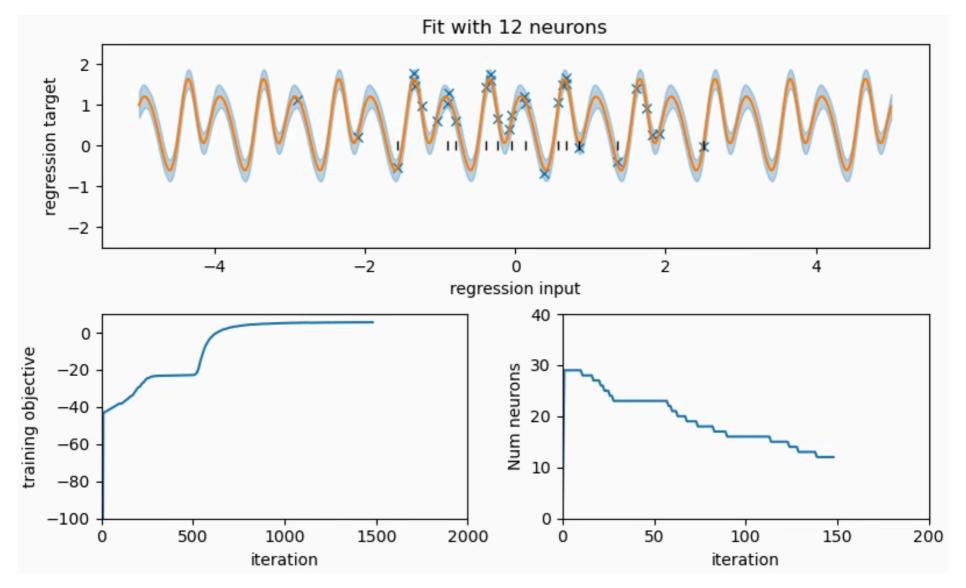


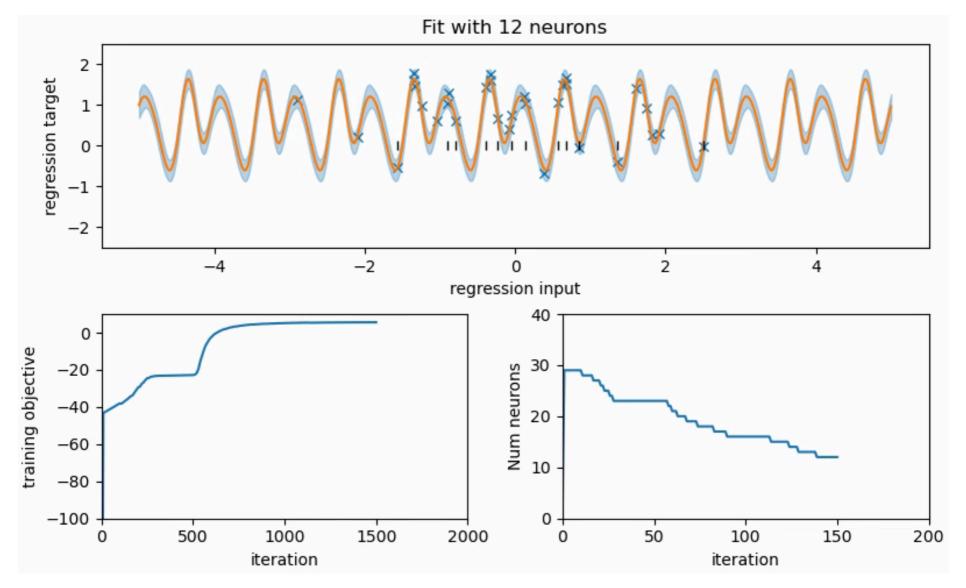


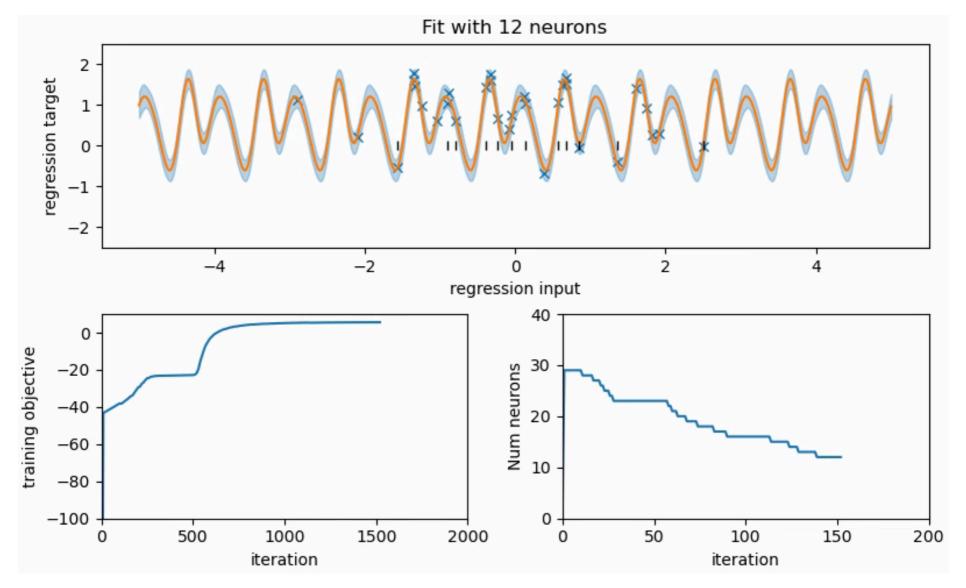


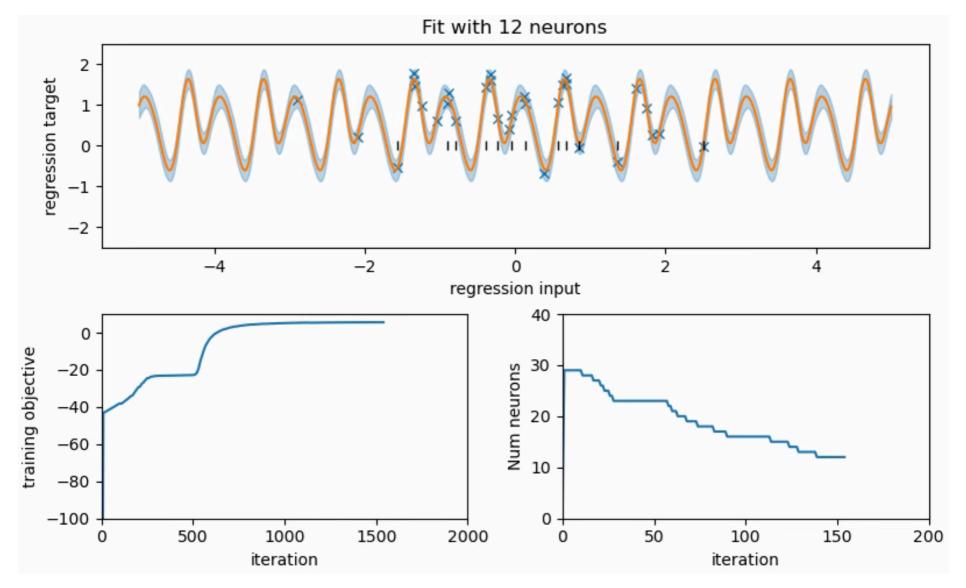


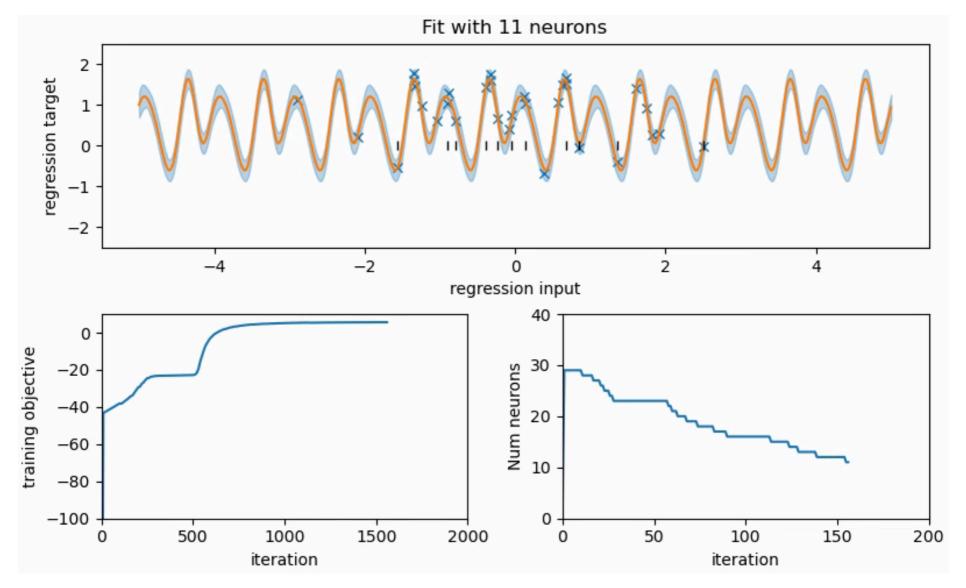


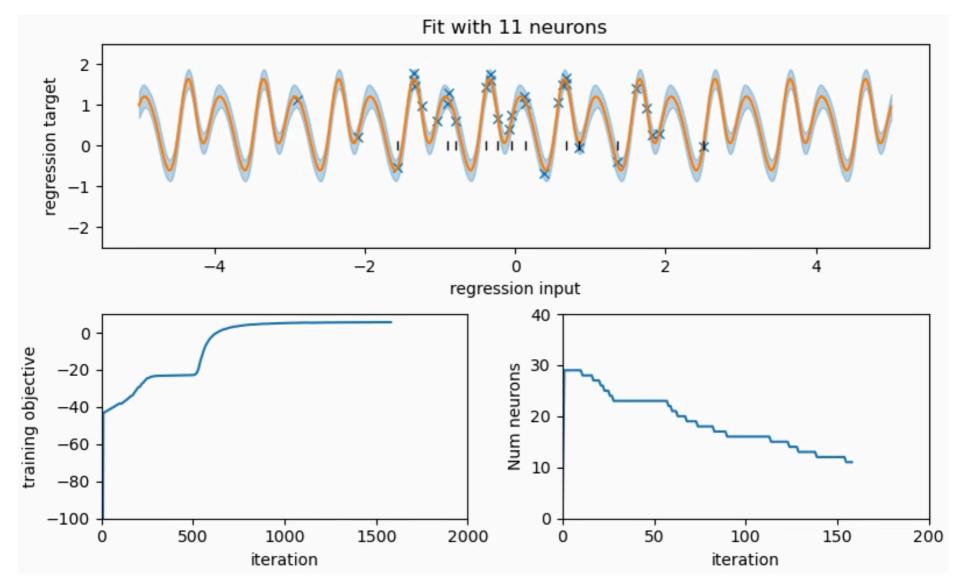


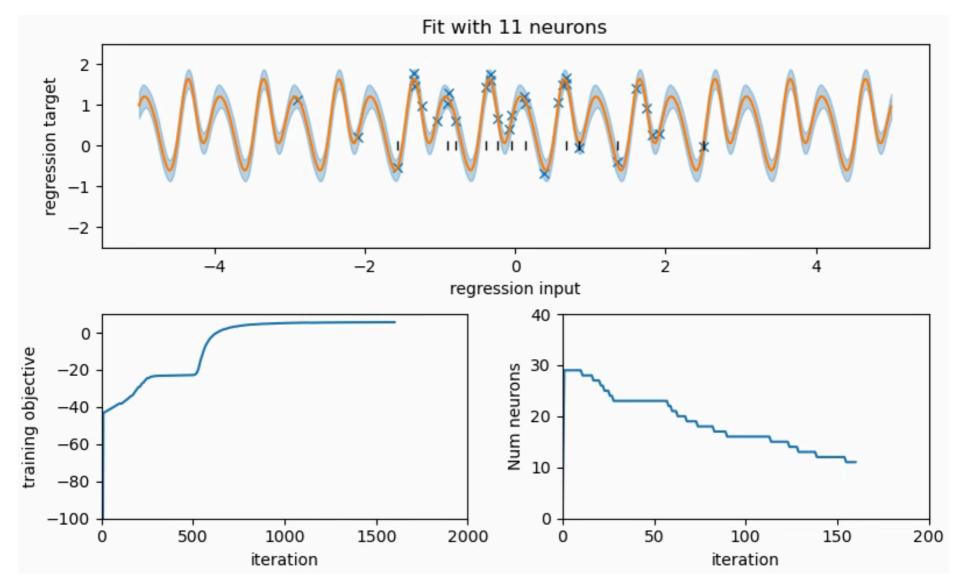


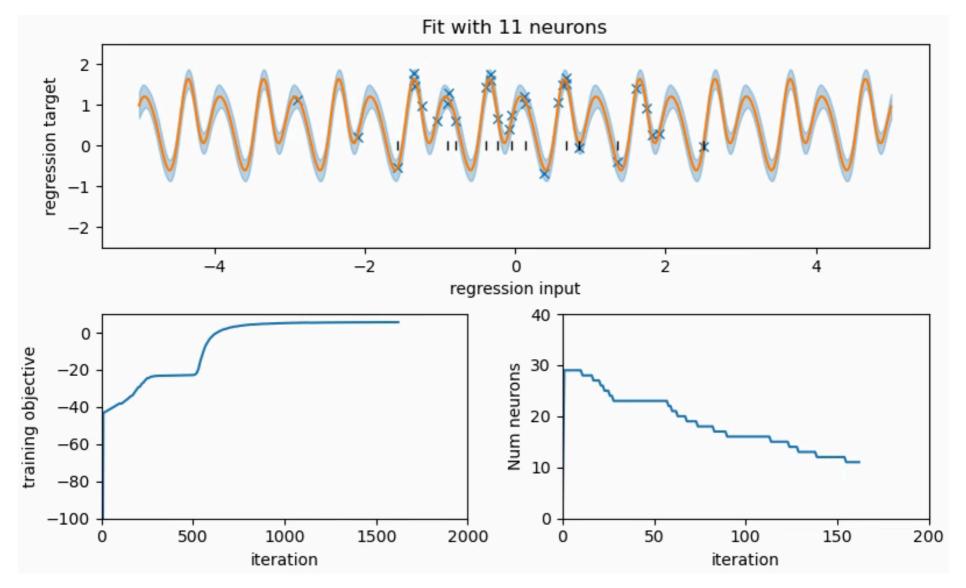


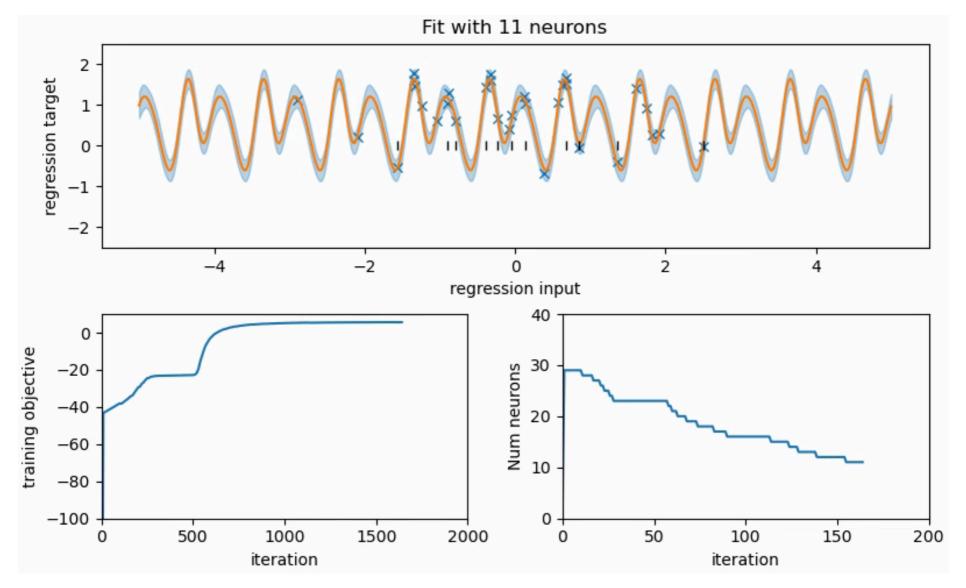


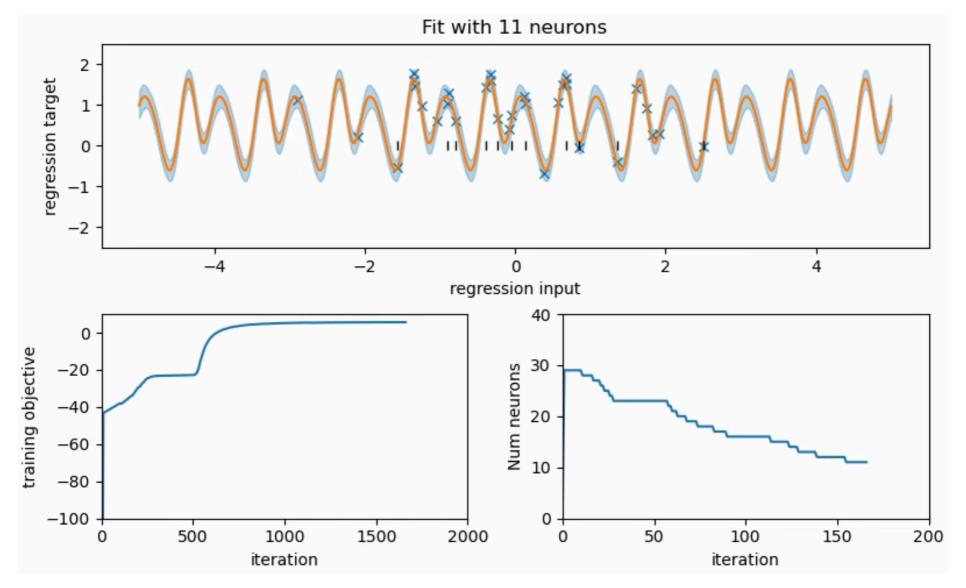


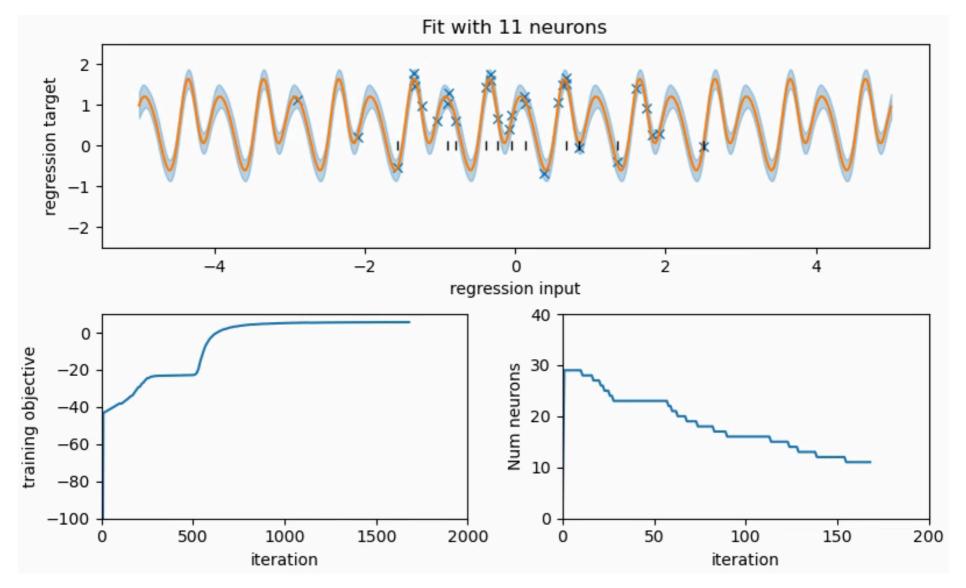


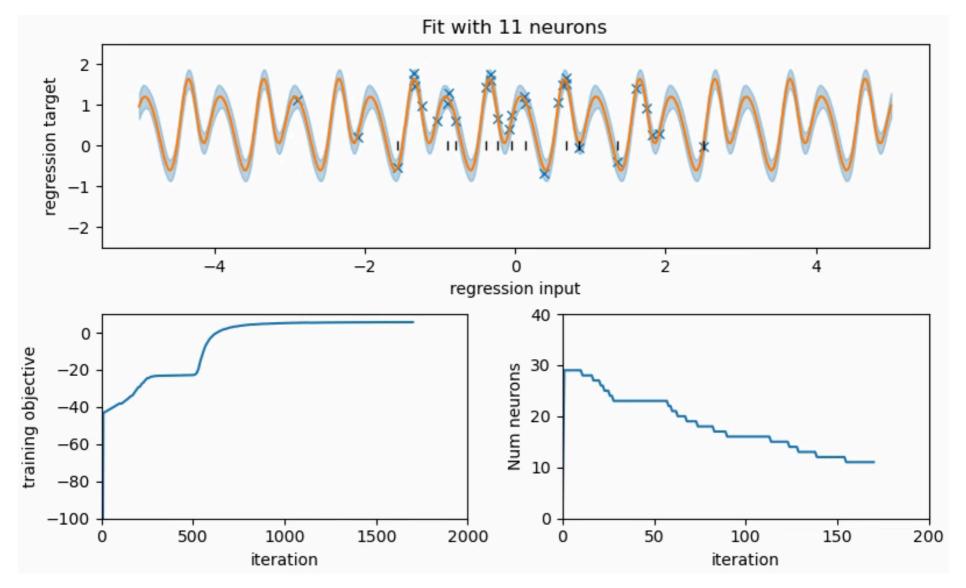


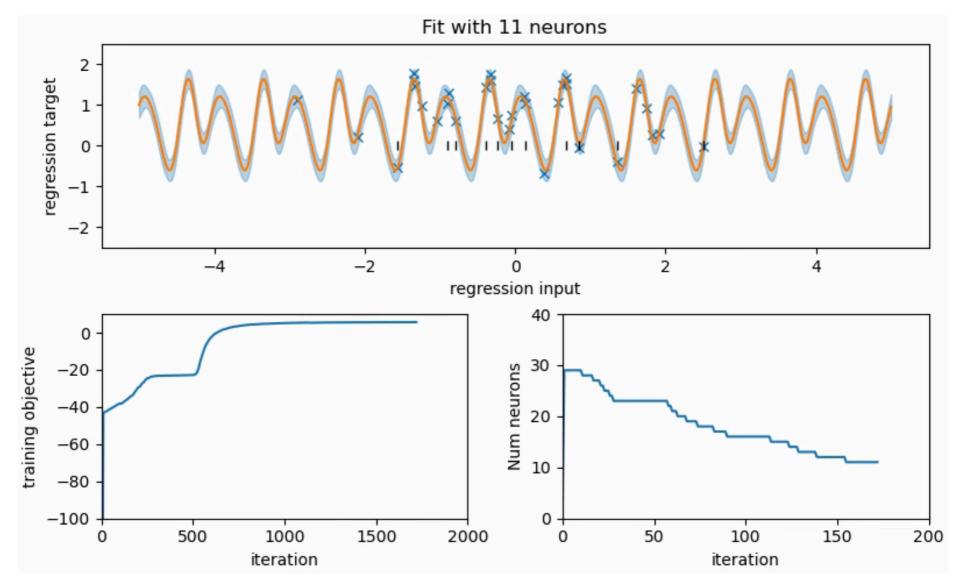


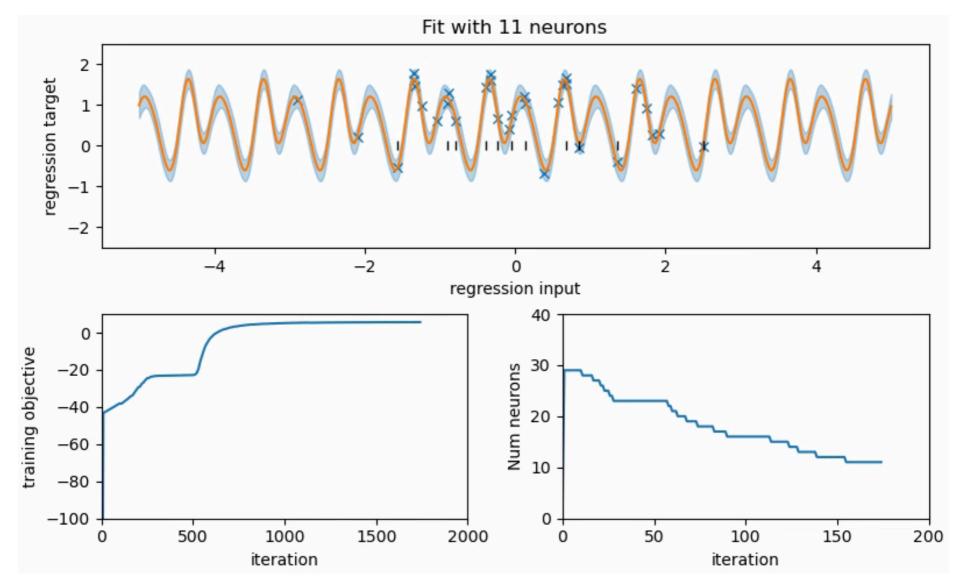


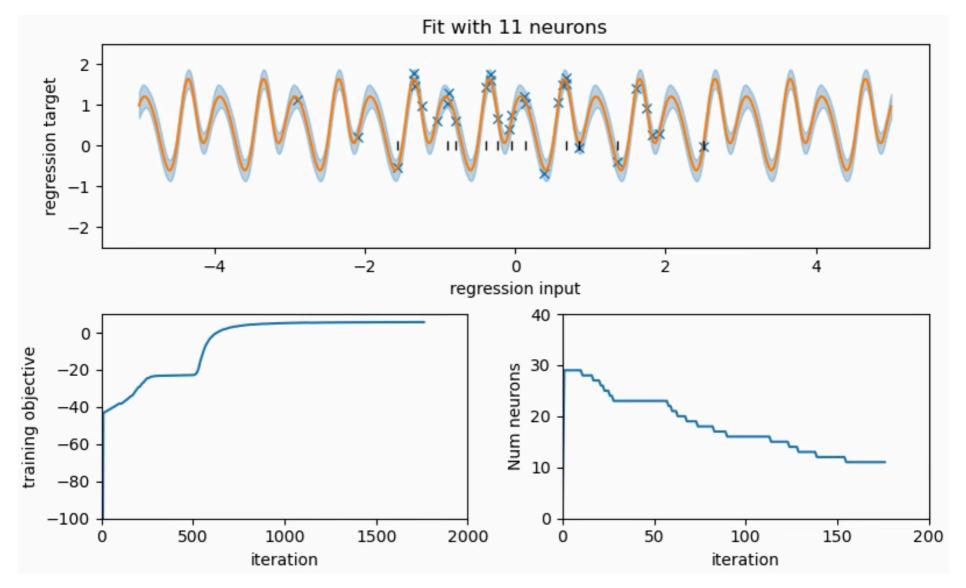


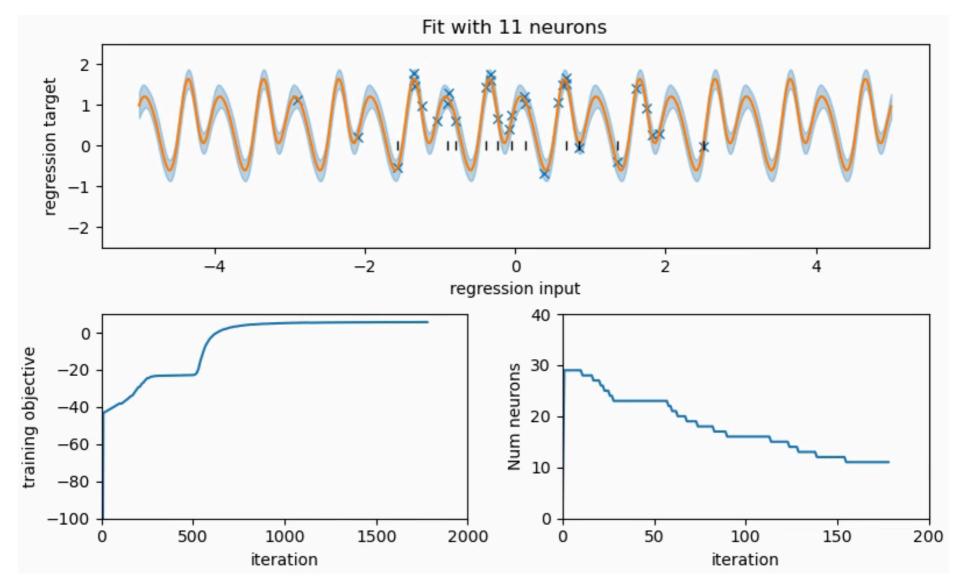


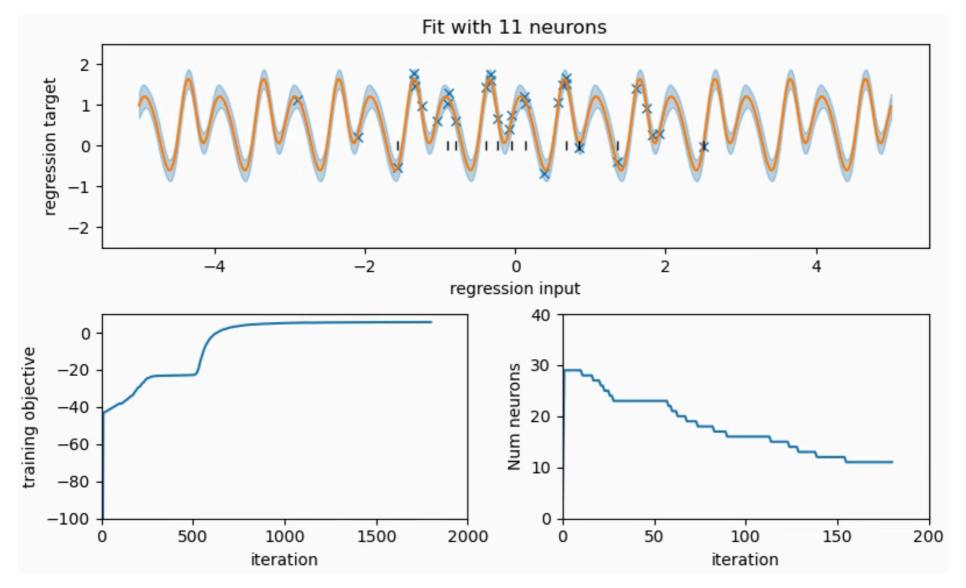


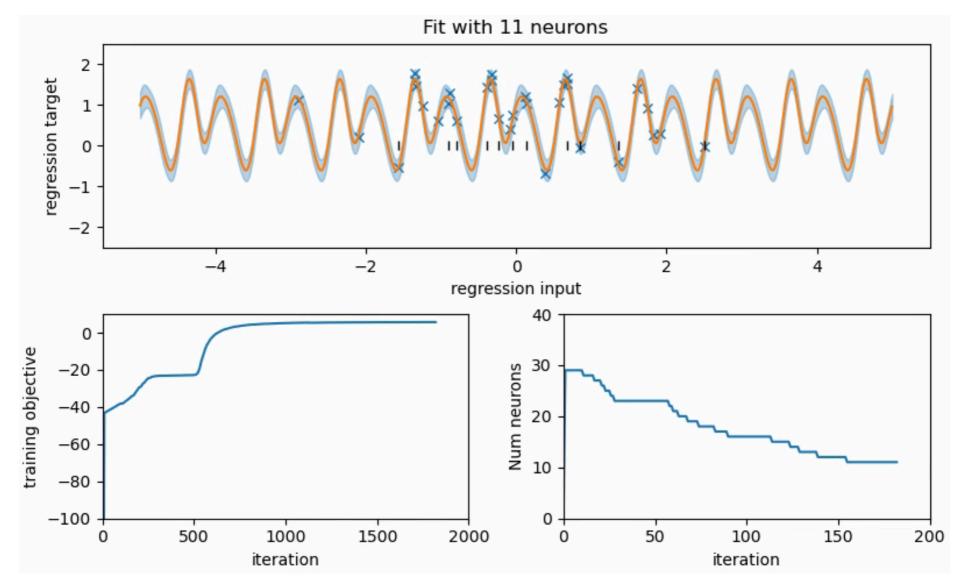


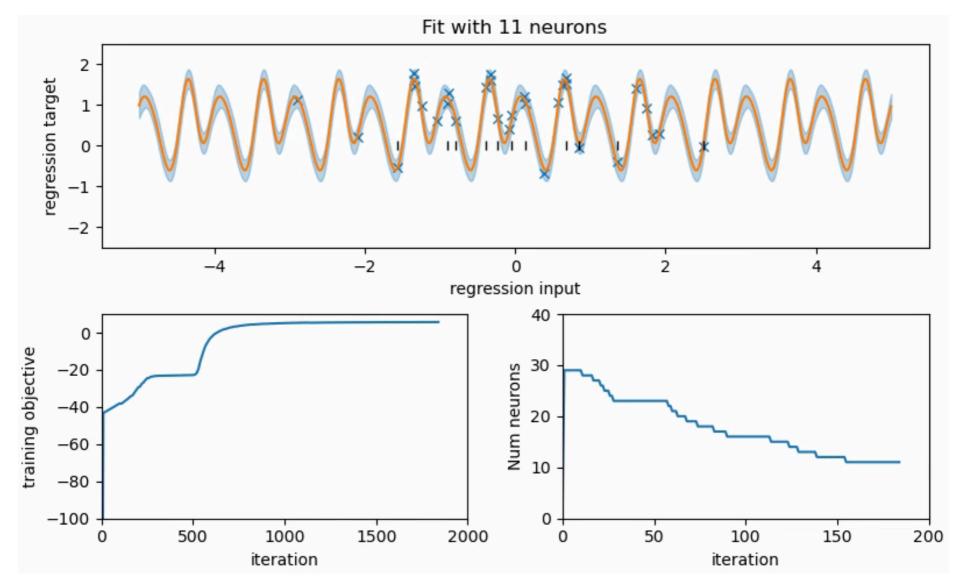


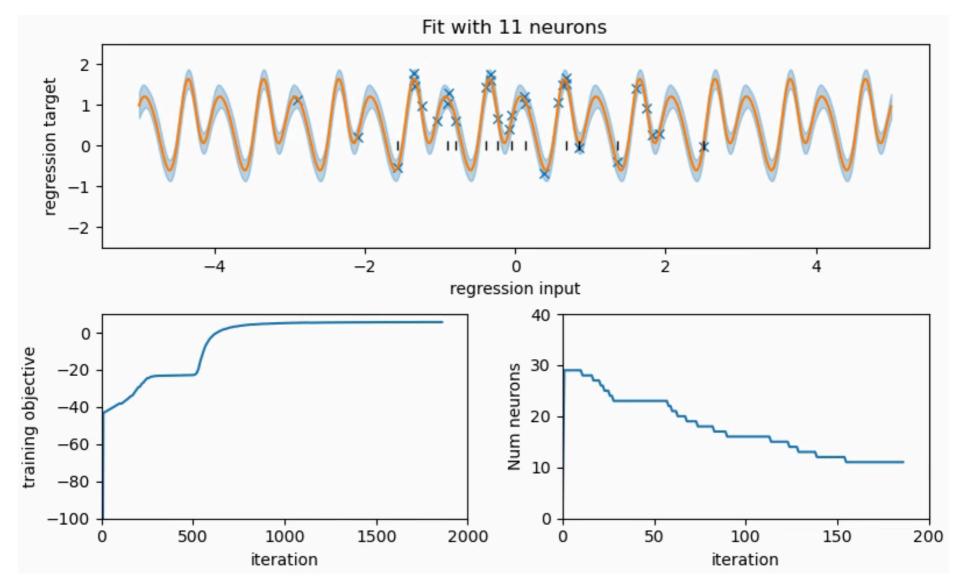


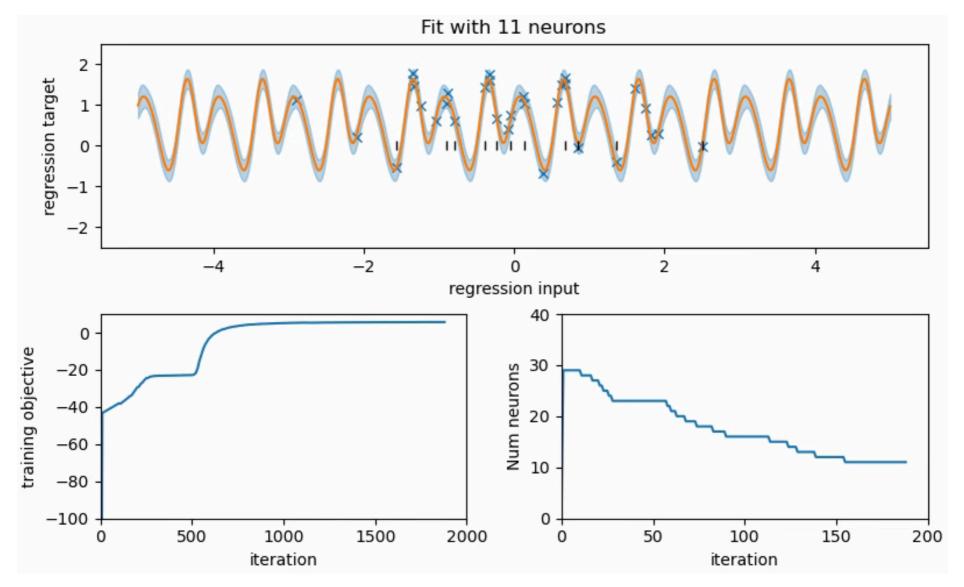


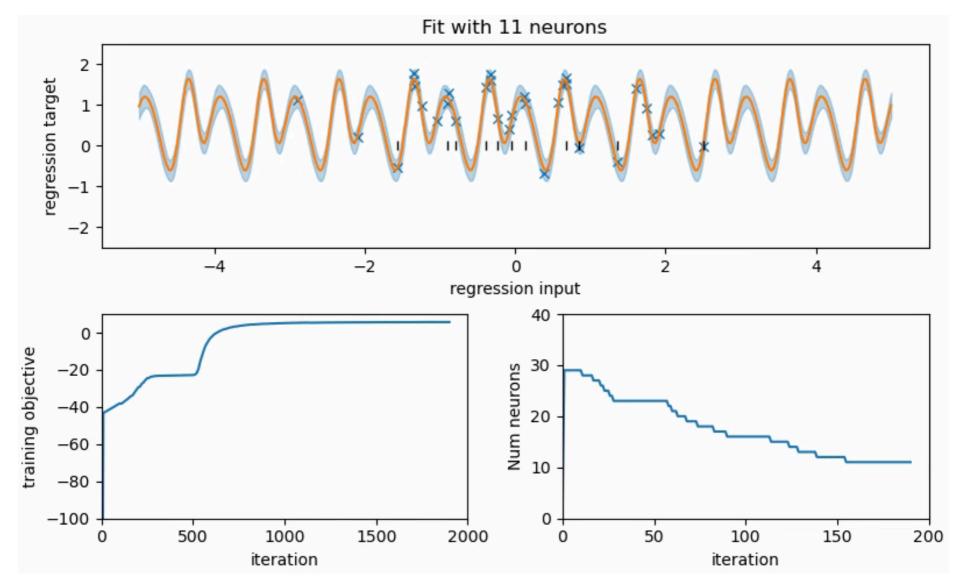


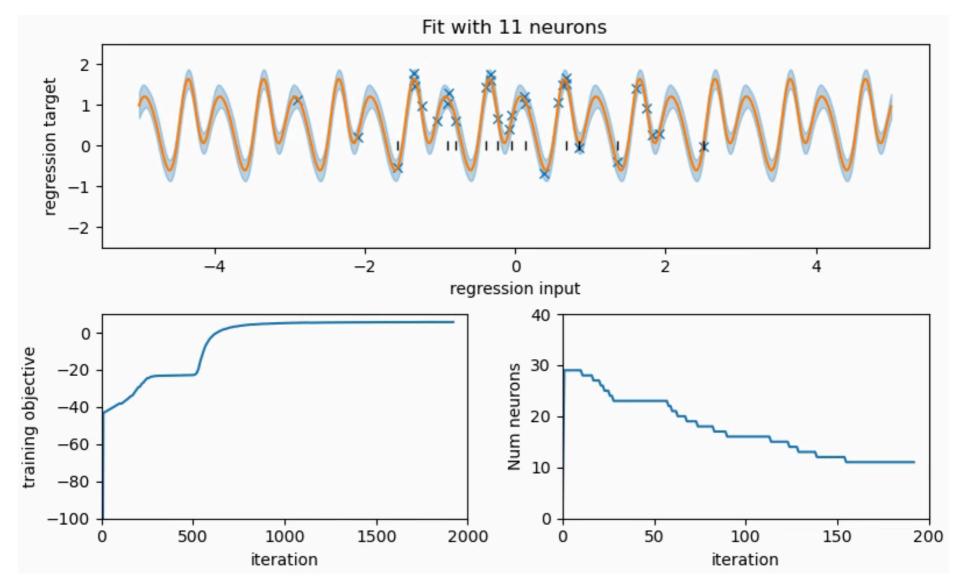


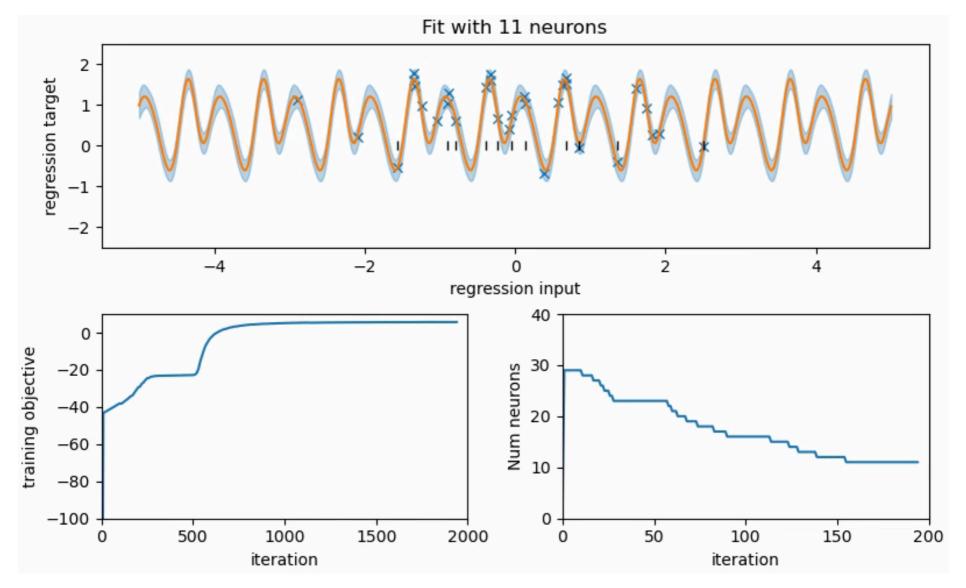


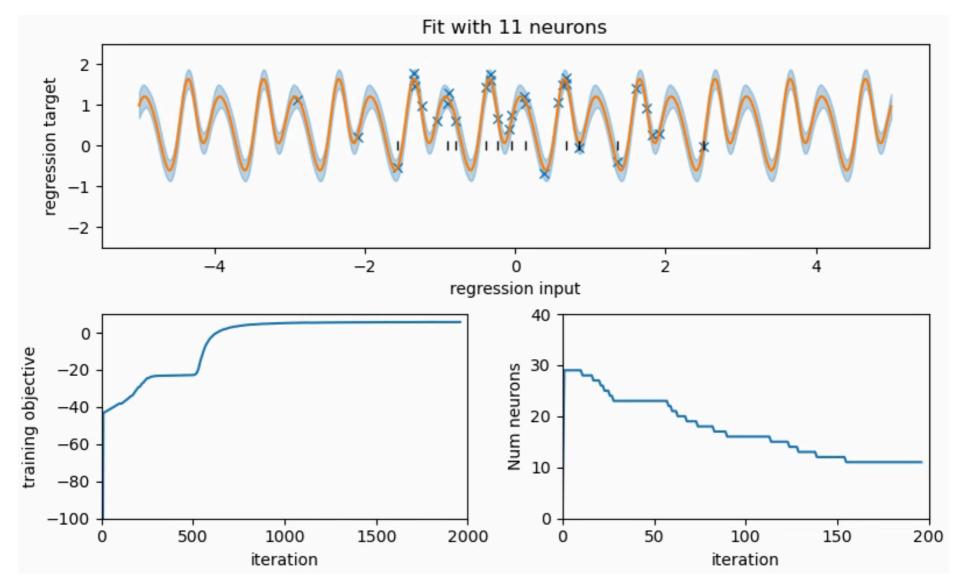


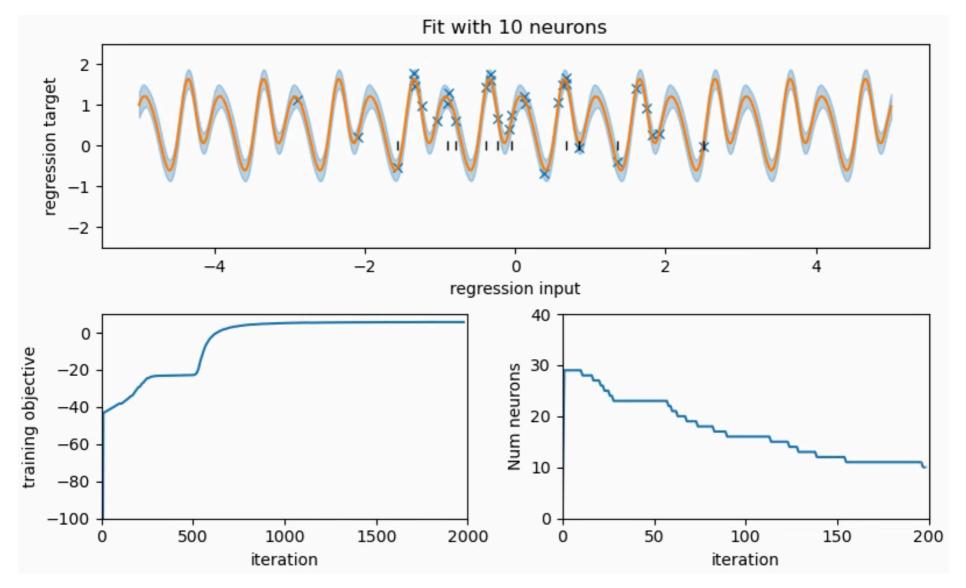












We saw:

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but not *model size*.

- •

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We can have our cake and eat it

We can *define* an infinite-sized model, but near-perfectly approximate it with *just* the right amount of computational resources!

Markov Services of the service of t

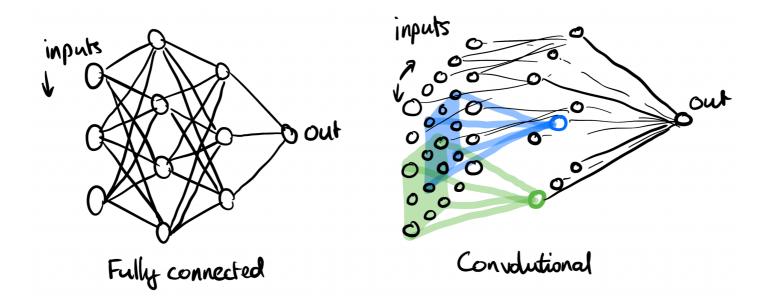
Can we automatically find:

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Mew procedures for training neural networks!

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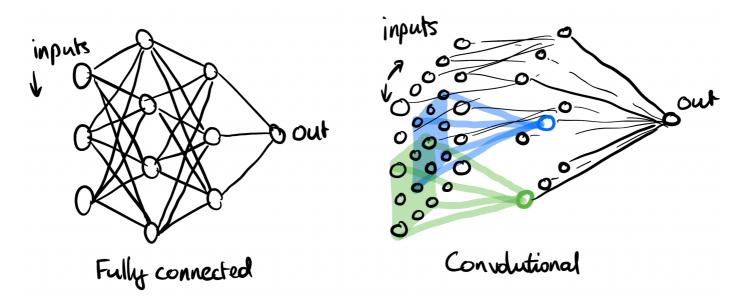
• Inductive bias / connectivity structure / architecture



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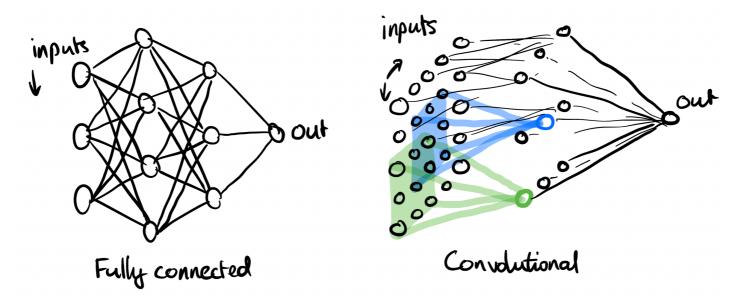


• Choose network size (how many neurons)

Mew procedures for training neural networks!

Can we automatically find:

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• Choose network size (how many neurons)

More efficient, more adaptive, more automatic!

Papers

Gaussian processes:

- For an overview of Titsias/Hensman's (Hensman et al., 2013; Titsias, 2009) method for VI in GPs, see my thesis (van der Wilk, 2019)
- Proof of accuracy of variational approximation (basis for when to stop adding inducing variables / basis functions) (Burt et al., 2019; 2020)
- Adaptive model size for continual learning (Pescador-Barrios et al., 2024)
- Overall narrative of this talk (online soon!)

Bayesian Model Selection in Neural Networks:

- Bayesian Model Selection (Laplace approximation) recovers ResNets, without explicit human design (Ouderaa et al., 2023)
- See more by Tycho van der Ouderaa!

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